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Key Points:

- Interior models and amplitude patterns of diurnal tidal stresses are calculated
- The diurnal tidal stress pattern is compliant with cryovolcanic candidate areas
- A warm, low-ammonia ocean could increase Titan's habitable potential

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Structural and tidal models of Titan and inferences on cryovolcanism

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Abstract Titan, Saturn's largest satellite, is subject to solid body tides exerted by Saturn on the timescale of its orbital period. The tide-induced internal redistribution of mass results in tidal stress variations, which could play a major role for Titan's geologic surface record. We construct models of Titan's interior that are consistent with the satellite's mean density, polar moment-of-inertia factor, obliquity, and tidal potential Love number k_2 as derived from Cassini observations of Titan's low-degree gravity field and rotational state. In the presence of a global liquid reservoir, the tidal gravity field is found to be consistent with a subsurface water-ammonia ocean more than 180 km thick and overlain by an outer ice shell of less than 110 km thickness. The model calculations suggest comparatively low ocean ammonia contents of less than 5 wt % and ocean temperatures in excess of 255 K, i.e., higher than previously thought, thereby substantially increasing Titan's potential for habitable locations. The calculated diurnal tidal stresses at Titan's surface amount to 20 kPa, almost comparable to those expected at Enceladus and Europa. Tidal shear stresses are concentrated in the polar areas, while tensile stresses predominate in the near-equatorial, midlatitude areas of the sub- and anti-Saturnian hemispheres. The characteristic pattern of maximum diurnal tidal stresses is largely compliant with the distribution of active regions such as cryovolcanic candidate areas. The latter could be important for Titan's habitability since those may provide possible pathways for liquid water-ammonia outbursts on the surface and the release of methane in the satellite's atmosphere.

1. Introduction

Titan, Saturn's largest satellite, is the only satellite with a substantial atmosphere mainly composed of nitrogen and is in several aspects quite similar to our own planet (in terms of atmospheric composition, surface pressure, and organic chemistry in particular) in spite of the satellite's ice-rich bulk composition. Titan is tidally locked with respect to Saturn and subject to periodic tidal forcing of its interior and surface, resulting in diurnal stresses at the satellite's surface. In addition, with one hundred Titan flybys to date, the Cassini-Huygens mission exploring the Saturnian system since 2004 has revealed the remarkable geologic diversity of Titan's surface, exhibiting a number of features morphologically similar to what is found on our own planet [e.g., Jaumann *et al.*, 2009; Coustenis and Hirtzig, 2009; Solomonidou *et al.*, 2013], albeit composed of different materials (ice instead of rock, hydrocarbons in different phases instead of water). The geologic surface features are partly attributed to exchange processes between the satellite's interior, its surface, and its atmosphere [Grasset *et al.*, 2010].

From the Cassini spacecraft, Titan's landscape has been observed by multiple flybys, examining the surface expressions through radar and infrared instrumentation. The images obtained using the Cassini Synthetic Aperture Radar instrument and the Imaging Science Subsystem (ISS) revealed that Titan hosts a complex surface characterized by mountains, drainage networks, dunes, faults, and possibly volcanic-like features [Jaumann *et al.*, 2008; Lopes *et al.*, 2010, 2013; Solomonidou *et al.*, 2013, and references therein], which resemble Earth-like geologic structures and terrains [e.g., Coustenis and Hirtzig, 2009]. Only a few impact craters have been identified on Titan owing to intense resurfacing [Wood *et al.*, 2010]. Furthermore, the visual and infrared mapping spectrometer (VIMS) on board the Cassini spacecraft provides spectral imaging of Titan's surface at specific wavelengths in the 0.8 to 5.2 μm range. These are indicative of the diversity of the geologic terrain types, which are subject to complex erosional and depositional processes. The

surface properties can be inferred from such observations using narrow methane spectral “windows” located in the near-infrared and centered at 0.93, 1.08, 1.27, 1.59, 2.03, 2.79, and 5.00 μm , where the methane absorption is weak enough to allow for probing of the surface [McKay *et al.*, 1989; Griffith *et al.*, 1991]. When atmospheric scattering and absorption effects are properly accounted for, information on the nature of the surface can be extracted using radiative transfer codes [e.g., Hirtzig *et al.*, 2013].

The nonspherical part of Titan’s static gravitational field is predominated by spin and tidal contributions. Using different flyby geometries of the Cassini spacecraft, *less et al.* [2010] determined the polar oblateness and equatorial ellipticity of the static gravity field independently from each other. Titan’s ratio of the corresponding tidal and spin gravity coefficients $C_{2,2}$ and J_2 is close to the theoretical prediction of 3/10 for a synchronously rotating satellite in hydrostatic equilibrium, from which *less et al.* [2010] infer an upper bound of 0.34 for Titan’s axial moment-of-inertia (Mol) factor. If nonhydrostatic contributions are tentatively attributed to the degree-3 terms, Titan’s Mol factor may be as low as 0.33 [see *less et al.*, 2010] (supporting information), which is still inconsistent with fully differentiated interior models of Titan that would produce even smaller Mol factors [e.g., Grasset *et al.*, 2000; Sohl *et al.*, 2003; Tobie *et al.*, 2005]. Nimmo and Bills [2010] explain Titan’s shape or long-wavelength topography [Zebker *et al.*, 2009] and the small magnitude of associated gravity anomalies [less *et al.*, 2010] in terms of lateral thickness variations of a conductive floating outer ice shell with isostatically compensated ice topography and about 100 km thick on average.

Titan’s significant orbital eccentricity and obliquity cause periodic variations of the nonspherical part of the static gravitational field resulting in diurnal stresses at the satellite’s surface. These diurnal tides could play a major role for Titan’s geologic surface record. For example, the formation of cycloidal features and strike-slip faults on synchronous satellites such as Europa is attributed to diurnal tidal stresses induced by nonzero orbital eccentricity, nonzero spin-axis obliquity, and physical librations of their outer shell being mechanically decoupled from the deep interior [Hurford *et al.*, 2009; Jara-Orué and Vermeersen, 2011]. A measure for the tide-induced internal redistribution of mass is the degree-2 body tide Love number k_2 that is related to the radial density distribution and rheological structure of Titan. Radio science data from six close flybys of the Cassini spacecraft allowed *less et al.* [2012] to infer two solutions for k_2 of 0.589 ± 0.15 and 0.637 ± 0.224 (both with 2σ errors), respectively, corresponding to tidal variations of about 4 % relative to the static degree-2 terms, which is consistent with the existence of a global ocean at depth. Baland *et al.* [2011] and Bills and Nimmo [2011] invoke the presence of an outer ice shell, mechanically decoupled from the deep interior by a subsurface ocean, as plausible explanation for Titan’s notable spin axis obliquity of about 0.3° relative to the orbit pole [Stiles *et al.*, 2008, 2010].

In the present study, we focus on the distribution of diurnal tidal stresses at the satellite’s surface and possible links to geologic surface features on Titan. In section 2, we describe the construction of structural models of Titan’s interior based on Cassini gravity data and how the corresponding tidal stress pattern at Titan’s surface is calculated. Results are presented in section 3 and put into perspective with morphotectonic surface features and related geologic processes in section 4. Finally, section 5 discusses possible connections between the diurnal tidal stress pattern and volcanic-like and tectonic-like surface features on Titan with implications for the satellite’s habitable potential.

2. Model Description

Structural models of Titan’s interior are required to satisfy the global parameters that are listed in Table 1. In the absence of seismological observations, gravitational field and rotational data provide important information on the satellite’s radial mass distribution and rheological structure. The gravitational field and rotational data collected by the Cassini mission suggest that Titan is in almost perfect hydrostatic equilibrium with its tidal and centrifugal potential. Furthermore, the orientation of Titan’s spin pole is consistent with the assumption that the satellite’s outer ice shell is partly decoupled from the deep interior by a subsurface ocean (see Appendix A).

less et al. [2010] concluded that the Cassini gravitational field observations could be explained either by incomplete separation of the primordial ice-rock mixture or the presence of a substantially hydrated silicate core. However, the former hypothesis has been challenged by parameterized thermal evolution models, suggesting that Titan’s rock content were sufficiently high to facilitate substantial melting and complete separation of the primordial ice-rock mixture [O’Rourke and Stevenson, 2014], whereas the latter requires

Table 1. Global Parameters of Titan

Parameter	Symbol	Units	Value	Uncertainty
Mean radius ^a	R_s	km	2575.5	± 2.0
Total mass ^a	m_t	10^{23} kg	1.3452728	± 0.0000058
Surface pressure ^b	P_s	bar	1.467	± 0.001
Surface temperature ^b	T_s	K	93.65	± 0.25
Degree-2 gravity coefficient ^c	J_2	—	33.46	± 0.63
Degree-2 gravity coefficient ^c	$C_{2,2}$	—	10.02	± 0.07
Moment-of-inertia factor ^c	Mol	—	0.3414	± 0.0005
Degree-2 Love number ^d	k_2	—	0.589	$\pm 0.15(2\sigma)$
Free orbital eccentricity ^d	e	—	0.028	—
Obliquity ^e	v	deg	-0.32	± 0.02
Orbit inclination ^f	i	deg	0.28	—
Mean orbital motion ^g	ω	10^{-6} s^{-1}	4.56	—
Orbital period ^g	P_o	day	15.945	—
Nodal regression period ^f	P_n	year	607.56	—

^a*Sohl et al.* [2009, and references therein].^b*Fulchignoni et al.* [2005].^c*less et al.* [2010].^d*less et al.* [2012].^e*Baland et al.* [2011].^f*Bills and Nimmo* [2008].^g*Sohl et al.* [2003, and references therein].

efficient removal of long-lived radiogenic heat sources such as potassium from the core to delay the onset of silicate dehydration [Castillo-Rogez and Lunine, 2010; Fortes, 2012].

In the present study, we consider hydrated silicate cores because fully differentiated interior structure models are difficult to maintain considering Titan's inferred axial moment of inertia [less et al., 2010]. We note that compositional details regarding the long-term stability of hydrated silicates, e.g., the accumulation of sodium and potassium leached early in Titan's history at the ice-rock interface during ocean freezing [Zolotov, 2007; Sohl et al., 2010], are not central to the present study because we are mainly interested in the outer part of Titan's mechanical structure that determines the satellite's tidal response at the surface.

We here assume that Titan is close to hydrostatic equilibrium and that the satellite's present interior structure can be characterized by four chemically homogeneous reservoirs, consisting of a hydrated silicate core (Appendix B), a high-pressure pure water-ice mantle (Appendix C), and a subsurface water-ammonia ocean overlain by a conductive floating outer ice shell composed of low-pressure water-ice Ih and sl methane hydrate (Appendix D).

The set of differential equations for mass m , moment of inertia I , gravitational acceleration g , and hydrostatic pressure P can be derived from fundamental principles:

$$\frac{dm}{dr} = 4\pi r^2 \rho, \quad (1)$$

$$\frac{dI}{dr} = \frac{8}{3}\pi r^4 \rho, \quad (2)$$

$$\frac{dg}{dr} = 4\pi G \rho - 2\frac{g}{r}, \quad (3)$$

$$\frac{dP}{dr} = -g\rho + \frac{2}{3}\omega^2 r \rho, \quad (4)$$

where r is the radial distance from Titan's center, G is the gravitational constant, ω is Titan's rotational angular frequency, and ρ is the local density, which will be explained in detail further below.

Throughout the silicate core and the high-pressure water-ice shell, we calculate the thermal structure by solving the following two differential equations for heat flux q and temperature T in thermal steady state:

$$\frac{dq}{dr} = \epsilon\rho - 2\frac{q}{r}, \quad (5)$$

$$\frac{dT}{dr} = -\frac{q}{Nu_r k_c}, \quad (6)$$

where k_c is the thermal conductivity and Nu_r is the local Nusselt number. Here the subscript r explicitly indicates that the quantity is a local function of pressure, temperature, and composition. The specific heat production rate ϵ is adjusted to meet Titan's surface temperature T_s of 94 K.

The local Nusselt number parameterizes the strength of the convective heat flux and can be expressed as [Wagner *et al.*, 2011]

$$Nu_r = \left(1 + \frac{k_v}{k_c}\right) \left(\frac{q}{q - k_v \nabla T_s}\right), \quad (7)$$

where k_v is an effective thermal conductivity due to convection [Kimura *et al.*, 2009; Wagner *et al.*, 2012] and $\nabla T_s = -g\alpha T/C_p$ is the adiabatic temperature gradient, with the thermal expansivity α and the specific heat capacity C_p . The effective thermal conductivity k_v is dependent on viscosity and obtained from the modified mixing length theory developed by Sasaki and Nakazawa [1986] to model low Reynolds number flow in solid planetary bodies. The viscosity of the silicate core is adjusted such that the central temperature will not exceed a critical threshold temperature of about 900 K for silicate dehydration [e.g., Perrillat *et al.*, 2005; Castillo-Rogez and Lunine, 2010].

The mixing length approach allows to formulate a localized stability criterion for the onset of thermal convection, which is based on the comparison between the local temperature gradient and the adiabatic temperature gradient. If the local temperature gradient is superadiabatic, k_v is greater than zero, buoyant material will rise due to the density contrast to the surrounding matter, resulting in a local Nusselt number (equation (7)) larger than unity. If the local temperature gradient is subadiabatic, k_v is zero, the fluid material is stably stratified with respect to thermal convection, and the local Nusselt number equals one. Although this treatment slightly overestimates the heat flux at very low Rayleigh numbers [Abe, 1995], the extended mixing length theory has been successfully applied in previous studies [e.g., Sasaki and Nakazawa, 1986; Abe, 1997; Senshu *et al.*, 2002; Kimura *et al.*, 2007, 2009; Tachinami *et al.*, 2011; Wagner *et al.*, 2012].

For the sake of simplicity, the thermal structure of the outer ice shell and the subsurface water-ammonia ocean is imposed by assuming a fixed thermal gradient from the given surface temperature T_s of 94 K to the temperature of the subsurface water-ammonia ocean T_o that is taken to be constant. The temperature gradient is given by the ratio between the temperature contrast and the thickness of the ice shell. With that simplified approach, we also ignore the possible existence of a thin convective sublayer at the base of the outer ice shell.

Successful models are required to satisfy Titan's global parameters listed in Table 1. While the central conditions are $m(0) = 0$, $l(0) = 0$, $g(0) = 0$, $P(0) = P_c$, $q(0) = 0$, and $T(0) \leq 900$ K, the surface conditions are $m(R_s) = m_t$, $l(R_s) = (0.34 \pm 0.005)m_t R_s^2$, $g(R_s) = Gm_t/R_s^2$, $P(R_s) = 1.467$ bar, $q(R_s) = q_s$, and $T(R_s) = 94$ K. Furthermore, the radius of the silicate core is derived from mass balance constraints, whereas the radial extent of the subsurface water-ammonia ocean sandwiched between low- and high-pressure ice shells is calculated in accordance with the phase diagram of the H_2O-NH_3 system.

2.1. Density and Elastic Moduli

The differential equations described above are dependent on the local density ρ , which can be obtained from an equation of state. Apart from the outer ice shell, the density is calculated by using Murnaghan's integrated linear equation of state [Murnaghan, 1967]:

$$\rho(T, P) = \rho_0(T) \left(1 + K'(T) \frac{P}{K_0(T)}\right)^{1/K'}, \quad (8)$$

where ρ_0 and K_0 are the density and isothermal bulk modulus at the reference pressure ($P = P_0 = 0$ Pa), respectively, and K' is the first pressure derivative of the isothermal bulk modulus K .

The isothermal bulk modulus can be assessed by expanding K to the first order in pressure P :

$$K(T, P) = K_0(T) + K'P. \quad (9)$$

K' is explicitly dependent on temperature in the water-ammonia ocean and is taken constant in the silicate core, high-pressure ice layer, and outer ice shell. Furthermore, the rigidity μ , the adiabatic bulk modulus K , and the density ρ are related to the velocities of the compressional and shear wave v_p and v_s , respectively,

$$v_p = \sqrt{\frac{K + (4/3)\mu}{\rho}}, \quad (10)$$

$$v_s = \sqrt{\frac{\mu}{\rho}}, \quad (11)$$

where we assume that the adiabatic and isothermal bulk modulus are approximately equal, i.e., $K_S \sim K_T = K$, under the relatively low temperature and pressure conditions prevalent in the interior of Titan.

For the hydrated silicate core, we apply the Guinan-Steinberg model to calculate the pressure dependent shear modulus at depth [Guinan and Steinberg, 1975]:

$$\mu(P) = \mu_0 + \mu' \frac{P}{x^{1/3}}, \quad (12)$$

where μ_0 and μ' are the shear modulus and its pressure derivative at zero pressure, respectively, and x denotes the compression ratio ρ/ρ_0 . The temperature dependency of the shear modulus has been omitted owing to the relatively low temperatures that must be expected in Titans interior ($T(0) \leq 900$ K). The Guinan-Steinberg model is a well-established approach to predict the shear modulus of materials at high pressures. We use the Guinan-Steinberg model in the same way as we use an equation of state (EoS) and fit it to data obtained from high-pressure experiments or first principles calculations to determine the reference parameters for equation (12) as listed in Table B1. Hence, the obtained relationships are only valid to the limited pressure range (up to about 5 GPa) they have been fitted for and should not be used for extrapolation beyond the fitted range. The seismic velocities v_p and v_s are then obtained according to equations (10) and (11).

Gagnon *et al.* [1990] measured sound wave velocities in water-ice VI via Brillouin spectroscopy. They found the following pressure-dependent relationships:

$$v_p = 4.193 + 0.0456(P/\text{kbar}), \quad (13)$$

$$v_s = 1.987 + 0.0463(P/\text{kbar}), \quad (14)$$

where v_p and v_s are compressional and shear wave speed, respectively. We use both equations to calculate the seismic velocities within the high-pressure water-ice layer and obtain the depth-dependent rigidity μ using equation (11).

Since the shear modulus μ of a liquid vanishes, equation (10) simplifies to the bulk sound velocity

$$v_p = \sqrt{\frac{K}{\rho}}, \quad (15)$$

which we use to calculate the compressional wave velocity v_p within the subsurface water-ammonia ocean.

The outermost ice shell is assumed to be composed of water-ice Ih and sl methane hydrate. Using a linear planar fit, Helgerud *et al.* [2009] report equation of state and elastic parameters that are based on laboratory data:

$$F(T, P) = A^*T + B^*P + C^*, \quad (16)$$

where F is the desired value (e.g., the local density ρ and elastic moduli K and μ).

Modeling details for each structural layer are presented in the Appendices B, C, and D.

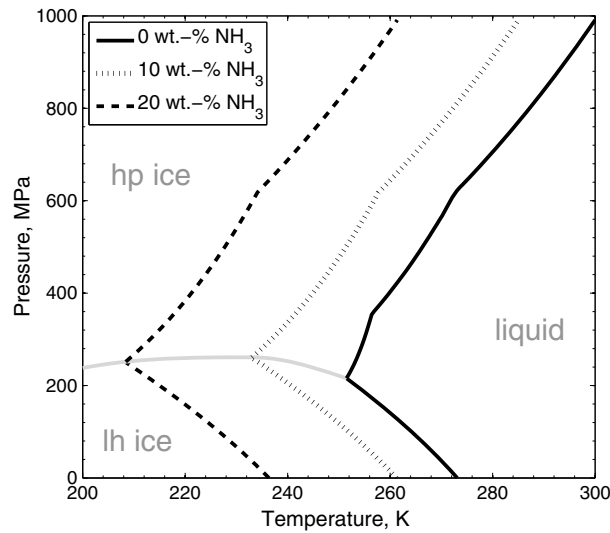


Figure 1. Liquidus curves of the water-ammonia ($\text{H}_2\text{O}-\text{NH}_3$) system for NH_3 concentrations of 0, 10, and 20 wt %. See text for further details.

derived by Leliwa-Kopystyński et al. [2002] as follows:

$$T_m(P_m, \chi) = T_{\text{ref}} - aP_m - bP_m^2 - c\chi - d\chi^2 - eP_m\chi, \quad (17)$$

where T_{ref} is a reference temperature of 273.1 K and a , b , c , d , and e are experimentally determined fit parameters. The corresponding fit parameters for the low-pressure melting curve of a $\text{H}_2\text{O}-\text{NH}_3$ mixture are $a = 7.95 \times 10^{-8} \text{ K Pa}^{-1}$, $b = 9.6 \times 10^{-17} \text{ K Pa}^{-2}$, $c = 53.8 \text{ K}$, $d = 650 \text{ K}$, and $e = 4 \times 10^{-8} \text{ K Pa}^{-1}$ [Leliwa-Kopystyński et al., 2002].

When considering the high-pressure phases of water-ice (III, V, and VI), a similar parameterization relating the melting temperature T_m to pressure P_m and ammonia content χ is given by [Choukroun and Grasset, 2007, 2010]

$$T_m(P_m, \chi) = T_{\text{ref}} \left(\frac{P_m - P_{\text{ref}}}{a} + 1 \right)^{1/c} - b\chi^d, \quad (18)$$

where T_{ref} and P_{ref} are reference values, respectively, and a , b , c , and d are fit parameters. The latter term of equation (18) has been obtained from Figure 5 in Choukroun and Grasset [2010]. It roughly quantifies the reduction in melting temperature of the high-pressure water-ice polymorphs when ammonia is added into the water liquid. We list the corresponding values with respect to the appropriate water-ice phases in Table 2.

The interface between the water-ice-dominated mantle and the silicate core is then completely constrained by the global properties of Titan described in the previous section. In other words, the radius of the core is

determined from mass balance constraints and Titan's physical properties as listed in Table 1.

Table 2. Parameters for the High-Pressure Melting Curve of $\text{H}_2\text{O}-\text{NH}_3$ Mixtures

T_{ref} (K)	P_{ref} (MPa)	a (MPa)	b^a (K)	c	d^a
251.15	209.5	101.1	350	42.86	1.37
256.43	355.0	373.6	350	8.66	1.37
272.73	618.4	661.4	350	4.69	1.37

^aEstimated from Figure 5 in Choukroun and Grasset [2010]. References: [Choukroun and Grasset, 2007, 2010].

2.2. Interfaces

The interface between nearby chemical reservoirs is determined by the water-ammonia phase diagram and Titan's global parameters as listed in Table 1.

The thickness of the subsurface water-ammonia ocean sandwiched between low- and high-pressure ice shells is calculated in accordance with the phase diagram of the $\text{H}_2\text{O}-\text{NH}_3$ system shown in Figure 1. As a consequence, the intersections of the calculated local geotherm and the melting conditions for a fixed ocean temperature determine the radial extent of the chemical reservoirs within Titan's water-ice/liquid shell above the silicate core.

For the low-pressure water-ice (Ih), the melting temperature T_m as a function of pressure P_m and ammonia content χ was

2.3. Diurnal Tides and Tidal Stresses

Titan is subject to time-varying radial and librational tides exerted by Saturn on the timescale of its orbital period. Disregarding small contributions due to obliquity tides, the main tidal potential is given by

[Segatz et al., 1988; Moore and Schubert, 2000; Wahr et al., 2009; Jara-Orué and Vermeersen, 2011; Hussmann et al., 2011; Beuthe, 2013]

$$\Phi_e(r, \theta, \phi, t) = r^2 \omega^2 e \times \left[-\frac{3}{2} P_2^0(\cos \theta) \cos \omega t + \frac{1}{4} P_2^2(\cos \theta) (3 \cos \omega t \cos 2\phi + 4 \sin \omega t \sin 2\phi) \right], \quad (19)$$

where r is the radial distance from the center of Titan and ω and e are Titan's mean motion and orbital eccentricity, respectively. $P_2^0(\cos \theta) = 1/2(3 \cos^2 \theta - 1)$ and $P_2^2(\cos \theta) = 3(1 - \cos^2 \theta)$ are associated Legendre polynomials of second degree. θ and ϕ are colatitude and longitude with zero longitude at the sub-Saturnian point, and t is time. Owing to the external gravitational perturbation by Saturn the equipotential surface at Titan is radially shifted by Φ_e/g_s with g_s the surface gravity.

In general, the satellite's tidal response depends on its interior structure, thermal state, tidally effective rheology, and the frequency of tidal forcing, and is parameterized in terms of the degree-2 body tide Love numbers h_2 , k_2 , and l_2 . We assume that the satellite's outer ice shell responds elastically to the tidal forces exerted by Saturn. This assumption is justified since diurnal tidal stresses are stored mostly elastically in the cold, stagnant outermost part of the ice shell and is widely insensitive to the specific rheology and thickness of the ice shell [Wahr et al., 2009; Jara-Orué and Vermeersen, 2011]. We solve for the radial displacement Love number h_2 , the potential Love number k_2 , and the Shida number l_2 by numerical integration of the linearized field equations for small elastic deformations in a spherical, incompressible, and self-gravitating body, accounting for certain continuity and boundary conditions [see Segatz et al., 1988; Hussmann et al., 2011, and references therein]. As model inputs we use the calculated radial profiles of density and elastic moduli as described in section 2.1. The ocean is modeled as an inviscid fluid layer by assuming a low rigidity and low viscosity while making sure that the tidal response is short as compared to the corresponding Maxwell time defined by the ratio of steady state viscosity and rigidity. For detailed descriptions of more general cases such as radially stratified, viscoelastic, and self-gravitating spherical body and the solution of the equivalent elastic problem in the frequency domain, we refer the reader to Cheng and Toksöz [1978], Wahr et al. [2009], Jara-Orué and Vermeersen [2011], and Beuthe [2013].

Since we are interested in global amplitude patterns of diurnal tidal stresses, we calculate the maximum tensile (areal) stress [Zürn and Wilhelm, 1984]

$$\sigma_{\text{areal}} = \frac{1}{2}(\sigma_{\theta\theta} + \sigma_{\phi\phi}) \quad (20)$$

and maximum shear stress

$$\tau_{\text{shear}} = \left[\left(\frac{\sigma_{\theta\theta} - \sigma_{\phi\phi}}{2} \right)^2 + \tau_{\theta\phi}^2 \right]^{1/2} \quad (21)$$

at Titan's surface, whereas the mean tidal stress $\bar{\sigma}_{\text{tide}}$ is given by

$$\bar{\sigma}_{\text{tide}} = \left[\frac{1}{2} (\sigma_{\theta\theta}^2 + \sigma_{\phi\phi}^2 + 2\tau_{\theta\phi}^2) \right]^{1/2}. \quad (22)$$

The diurnal tidal stresses $\sigma_{\theta\theta}$, $\sigma_{\phi\phi}$, and $\tau_{\theta\phi} = \tau_{\phi\theta}$ are specified by the nonzero components of the stress tensor in latitudinal ($\sigma_{\theta\theta}$), longitudinal ($\sigma_{\phi\phi}$), and cross directions ($\tau_{\theta\phi} = \tau_{\phi\theta}$) and related to the time-variable tidal potential Φ_e at the satellite's surface (see Appendix E).

3. Interior Structure and Tidal Stresses

We have constructed 60 models of Titan's present interior structure. Shown in Figure 2 are color-coded thicknesses of Titan's icy crust, d_c , and its subsurface water-ammonia ocean underneath, d_o , as a function of the satellite's degree-2 body tide Love number k_2 and mean moment-of-inertia factor Mol, respectively. In general, structural information, i.e., Mol, k_2 , and radial extent of outer ice shell (Figure 2a) and subsurface ocean (Figure 2b), is conveyed by the figure axes and color scale, whereas additional information about the bulk chemistry, i.e., NH_3 content and average core density, is encoded through symbol shape and size.

In Figure 2a, it can be distinguished between thin (bluish), intermediate (greenish), and thick (reddish) outer ice shells. They correspond, respectively, to deep (reddish), intermediate (turquoise), and shallow (bluish)

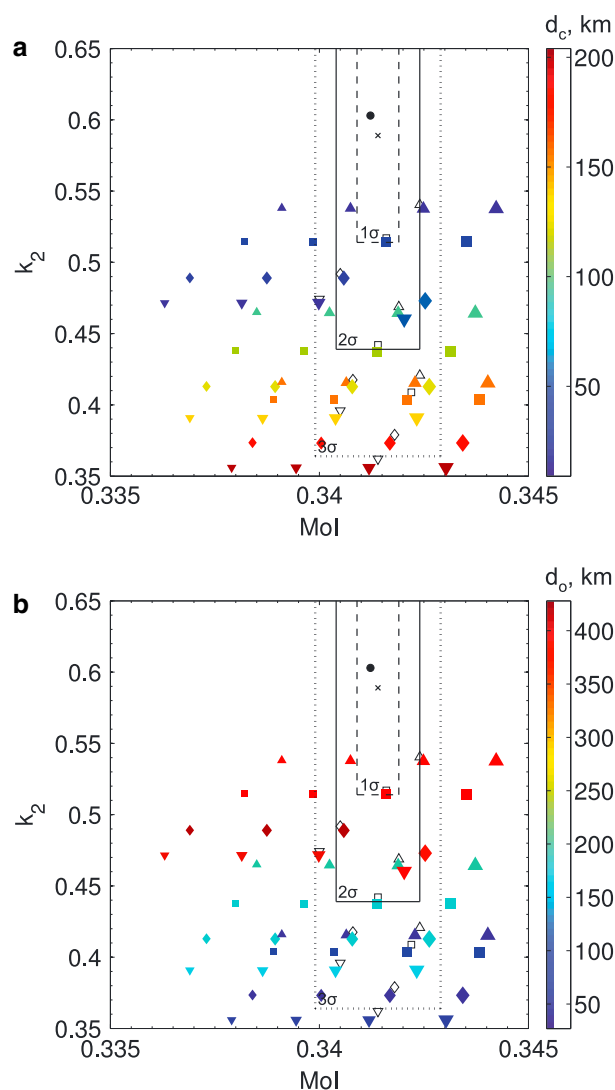


Figure 2. Model determinations of (a) crustal thickness d_c and (b) subsurface ocean thickness d_o as a function of moment-of-inertia factor Mol and degree-2 Love number k_2 within their observational uncertainties of 1σ (dashed), 2σ (solid), and 3σ (dotted) according to solution 1 of *Jess et al.* [2012], $k_2 = 0.589 \pm 0.15$ (2σ). The black cross denotes the center of the boxes, and the black dot represents the ammonium sulfate ($(\text{NH}_4)_2\text{SO}_4$) ocean case [Fortes et al., 2007]. See text for further details.

al. [2007]. Solutes leached from the hydrated silicate core (e.g., Cl^- , HCO_3^- , SO_4^{2-} , Na^+ , Ca^{2+} , Mg^{2+}) could increase the density of Titan's subsurface water ocean. However, a number of hydrated salts would precipitate again upon ocean freezing and sink to the ocean floor. It must be also taken into account that the concentration of solutes in subsurface water oceans is probably significantly less than 10 wt % [e.g., Tobie et al., 2012] with only little effect on the density of the liquid. As a consequence, melting point reduction by ammonia-water solutions is a valid explanation to facilitate the possible existence of liquid water subsurface reservoirs on icy bodies in the outer solar system [e.g., Sohl et al., 2010].

In general, models yielding thinner crusts and substantial subsurface oceans are found to correspond to larger body tide Love numbers k_2 and vice versa. Largely extended icy crusts can be ruled out, however, since models with ice shell thicknesses of more than 110 km are difficult to reconcile with the observational constraints imposed by the Cassini gravitational field data (black boxes) [Jess et al., 2010, 2012]. In turn, valid models of Titan produce subsurface oceans that are at least 180 km thick. This is illustrated in Figure 3, in

subsurface water-ammonia oceans shown in Figure 2b. Furthermore, form and size of each symbol represent specific ammonia (NH_3) contents within the subsurface ocean and average densities of the silicate core, respectively. From top to bottom, the pyramid, square, diamond, and triangle marks denote an increase in NH_3 concentration varying among 0, 5, 15, and 25 wt %. From left to right, core density decreases with increasing symbol size.

Filled symbols represent models with a water-ice crust, while open symbols correspond to cases with a crust composed of water-ice and methane clathrate in equal amounts by mass. The latter are shifted slightly to larger values of k_2 and Mol with respect to the former, thereby indicating that methane-clathrate crusts tend to be denser and less rigid than pure water-ice crust layers. This becomes even more pronounced with increasing thickness of Titan's outer ice shell. It is seen that k_2 is strongly related to both the crustal thickness d_c and the subsurface ocean thickness d_o , respectively. With increasing ocean density, e.g., in the presence of salty constituents and/or suspended sediment loads, valid models will be shifted to even larger k_2 values, thereby allowing for thicker outer ice shells. In terms of interior structure, we obtain similar results if the ammonia-water ocean is replaced by a saltwater ocean with an NaCl content of 5 wt % (ocean density 1.15 g cm^{-3}), similar to terrestrial oceans.

Since extensive leaching of Titan's hydrated silicate core cannot be excluded, we show in Figure 2 an example for a dense ocean composed of ammonium sulfate ($(\text{NH}_4)_2\text{SO}_4$) (density 1.35 g cm^{-3}) based on a model proposed by Fortes et

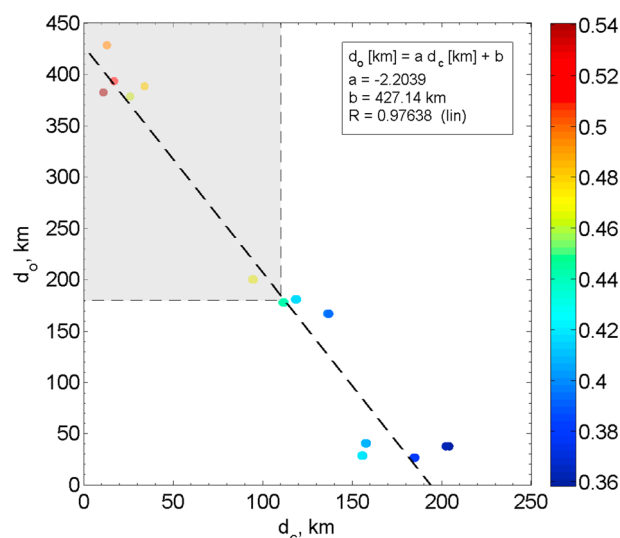


Figure 3. Degree-2 Love number k_2 (color coded) as a function of thickness for outer ice shell d_c and subsurface ocean d_o , respectively. Shown are only models compliant with the 2σ constraint imposed on the moment-of-inertia factor Mol. The shaded box illustrates the range in which models also fulfill the 2σ observational uncertainties of k_2 .

to the core because of the smaller density contrast between the surface and the deep interior. In the presence of a subsurface ocean, the density distribution within the silicate core has a negligible effect on the body tide Love number k_2 , owing to the mechanical decoupling of the outer ice shell from the deep interior.

Moreover, the ammonia (NH_3) concentration within the subsurface ocean provides bounds on the ocean temperature that are compliant with successful models of Titan's interior. The NH_3 concentration in the ocean (represented by the form of a symbol) likewise affects the Mol factor and the degree-2 body tide Love number k_2 . It is seen from inspection of Figures 2a and 2b that for lower NH_3 concentrations the symbols shift to larger values of each Mol and k_2 . For models corresponding to rather deep oceans with thicknesses of at least 370 km and relatively thin outer ice shells a few tens of kilometers thick, no firm constraints on the ocean composition (in terms of NH_3 content) can be imposed with respect to the reported 2σ error margins of Mol and k_2 , respectively. Depending on the actual NH_3 content, ocean temperatures down to 220 K are possible for NH_3 concentrations up to 25 wt %. However, models with intermediate-sized oceans of about 200 km depth and significant ice shells with thicknesses of about 100 km satisfy these observational constraints only if low NH_3 concentrations in the range of 0 to 5 wt % are present, corresponding to relatively warm oceans with temperatures in excess of 255 K.

We consider the reference model illustrated in Figure 4 as a plausible fiducial model of Titan's present interior structure that satisfies the 2σ observational data of the Mol factor and the degree-2 body tide Love number k_2 based on Cassini gravity data. The model parameters are summarized in Table 3. The construction of the reference temperature profile requires three fixpoints, namely, the ocean temperature (prescribed), the surface temperature (94 K), and the central temperature (900 K). We then vary two core parameters—the effective specific heat production and the average viscosity—such that (i) the central temperature in the core stays below the critical temperature of silicate dehydration and (ii) the mean surface temperature of Titan is met. The calculated values of the Mol factor and the degree-2 body tide Love number k_2 are 0.34 and 0.44, respectively, commensurate with the low end of the reported 2σ error margins of the latter [Joss et al., 2012]. The silicate core is about 2080 km in radius with an average density of 2.55 g cm^{-3} . This is in good agreement with the core radius range of 1980 to 2120 km and the corresponding density range of 2.57 to 2.46 g cm^{-3} obtained by Fortes [2012] for a broad suite of compositional models of Titan's interior. The specific heat production rate of the core is about half of that what would be expected for a chondritic bulk composition, consistent with the early leaching of radioactive isotopes [Castillo-Rogez and Lunine, 2010]. While the central pressure is 4.9 GPa, the pressure at the core-mantle boundary is about 0.8 GPa. A significant

which we explicitly show how the calculated body tide Love numbers k_2 depend on the thicknesses of both outer ice shell and subsurface water-ammonia ocean. It is even possible to construct valid models with subsurface oceans of about 430 km thickness, corresponding to structural models with vanishing high-pressure water-ice layers between the silicate core and the liquid ocean itself. In other words, in these cases the subsurface ocean were in direct contact with the silicate core with important implications for Titan's habitable potential [Castillo-Rogez and Lunine, 2010; Fortes, 2012].

Furthermore, inspection of the symbols and their sizes in Figure 2 reveals that Titan's Mol factor is partly controlled by the density of the silicate core, shifting to larger Mol values with decreasing core density. For example, the satellite's moment of inertia will increase if less dense material is added

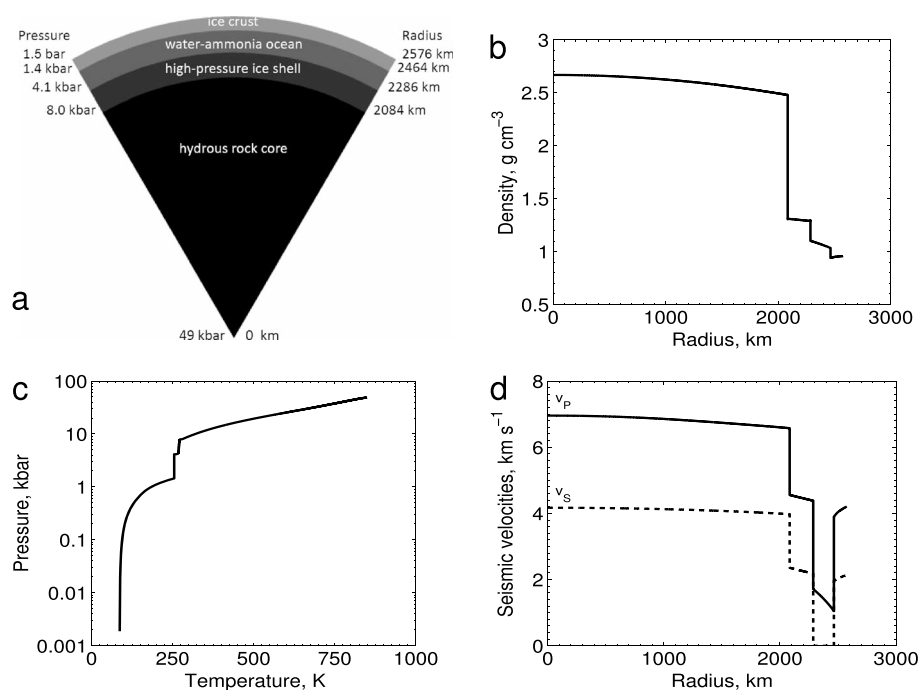


Figure 4. Reference model of Titan's interior structure used in the present study: (a) radial structure, (b) density distribution, (c) temperature-pressure diagram, and (d) seismic velocities.

high-pressure water-ice layer about 200 km in thickness with an average density of 1.3 g cm^{-3} is retained. For the subsurface water-ammonia ($\text{H}_2\text{O-NH}_3$) ocean we obtain a thickness of about 180 km. The average ocean density is 1.1 g cm^{-3} . The ocean temperature is 255 K at an NH_3 content of 5 wt %. The outer ice shell is 110 km thick with an average density of 0.95 g cm^{-3} , in agreement with compensated floating ice shell

Table 3. Structural Parameters of the Reference Model

Parameter	Symbol	Unit	Value
Core mass fraction	CMF	wt %	72.0
Specific heat production rate	ϵ	$10^{-12} \text{ W kg}^{-1}$	2.3
Core viscosity	η_r	Pa s	10^{25}
Central pressure	P_0	GPa	4.88
Pressure core-mantle boundary	P_{cmb}	GPa	0.798
Moment-of-inertia factor	Mol	—	0.340
Degree-2 tidal potential Love number	k_2	—	0.437
Degree-2 radial displacement Love number	h_2	—	1.29
Degree-2 Shida number	l_2	—	0.336
Tidal strain factor	s_2	—	0.564
Core radius	R_r	km	2084
Thickness high-pressure ice shell	d_i	km	202
Thickness subsurface ocean	d_o	km	178
Thickness outer ice shell	d_c	km	111
Heat flux core mantle boundary	q_{cmb}	mW m^{-2}	4.08
Heat flux (in the) ocean	q_{in}	mW m^{-2}	3.94
Heat flux (out of the) ocean	q_{out}	mW m^{-2}	3.39
Surface heat flux	q_s	mW m^{-2}	3.11
Density silicate core	ρ_r	g cm^{-3}	2.55
Density high-pressure ice shell	ρ_i	g cm^{-3}	1.30
Density subsurface ocean	ρ_o	g cm^{-3}	1.07
Density outer ice shell	ρ_c	g cm^{-3}	0.951
Rigidity silicate core	μ_r	GPa	42.1
Rigidity high-pressure ice shell	μ_i	GPa	6.66
Rigidity subsurface ocean	μ_o	GPa	0.
Rigidity outer ice shell	μ_c	GPa	4.05

Table 4. Tectonic-Like and Volcanic-Like Features on Titan

Location	Name	Description	Tectonic-Like Features
57°N, 62°W	Misty Montes	^a Mountain chain	RADAR bright-dark pairing (T23/Jan 2007)
52°N, 347°W	—	^b Mountain block	1400 m elevation from the surroundings (T30/May 2007)
47°N, 39.5°W	Rohe Fluctus	^{c,d} Flow-like feature	Bright-rimmed, oval-shaped caldera (TA/Oct 2004–T3/Feb 2005)
40°N, 118°W	Ara Fluctus	^{c,d} Flow-like feature	Noncircular depression (T3/Feb 2005)
20°N, 87°W	—	^e Ridges	Interplay with lineaments (T3/Feb 2005)
20°N, 70°W	T3 flows	^{c,f} Flow-like feature	Flowing downhill (T3/Feb 2005)
10°N, 15°W	—	^g Blocks of mountains	Linear morphology (T3/Feb 2005)
15°N, 45°W	—	^g Blocks of mountains	Linear morphology (T3/Feb 2005)
0°N, 180°W	—	^h Joints and/or faults	Rectangular drainage classification (T13/Apr 2006–T44/May 2008)
10°S, 145°W	—	^h Joints and/or faults	Rectangular drainage classification (T13/Apr 2006–T44/May 2008)
2°S, 127°W	—	^b Ridges	Parallel formations (T43/May 2008)
5°–12.5°S, 63°–67°W	—	^{b,g,i} Curvilinear mountains; ridges	Linear-like traces (T8/Oct 2005)
10°S, 210°W	—	^j Mountainous region	(T9/Dec 2005–T13/Apr 2006)
10°S, 140°W	Western Xanadu flows	^{c,k} Flow-like feature	(T13/Apr 2006)
10°S, 192°W	—	^m Linear fault patterns; canyon-like formations	Linear faults (Huygens-DISR/Jan 2005)
10.4°S, 192.4°W	—	^{l,m} Ridges	(Huygens-DISR/Jan 2005)
12°S, 38.5°W	Mohini Fluctus	^c Lobate flows	(T25/Feb 2007–T28/Mar 2007)
14.5°S, 40.5°W	Doom Mons	^c Volcanic-like peak	Topographic high, mountain-like structure (T25/Feb 2007–T28/Mar 2007)
14.5°S, 40°W	Sotra Patera	^c Deep pit	Ovoid caldera/pit (T25/Feb 2007–T28/Mar 2007)
15°S, 100°W	—	ⁿ Lithospheric fault-blocks	(model)
15°S, 155°W	—	^o Conjugate-like faults	Trending lineaments (T0/Jul 2004–TA/Oct 2004–TB/Dec 2004)
20°S, 130°W	Tui Regio	^{c,p} Flow-like region	Trending dark linear marks on VIMS data (TA/Oct 2004–TB/Dec 2004)
26°S, 78°W	Hotei Regio	^{c,q} Volcanic-like terrain; radial fault system	Circular tectonic features (T47/Nov 2008)
30°S, 107°W	—	^b Mountains	(T43/May 2008)
30°S, 315°W	—	^r Mountain ranges	Lineaments with tectonic control (T20/Oct 2006)
40°S, 340°W	—	^s Hills	(T7/Sep 2005)

^aCook *et al.* [2013].

^bMitri *et al.* [2010].

^cLopes *et al.* [2013].

^dLopes *et al.* [2007].

^eWilliams *et al.* [2011].

^fLe Corre *et al.* [2009].

^gRadebaugh *et al.* [2007].

^hBurr *et al.* [2009].

ⁱLopes *et al.* [2010].

^jBarnes *et al.* [2007].

^kWall *et al.* [2009].

^lTomasko *et al.* [2005].

^mSoderblom *et al.* [2007].

ⁿRadebaugh *et al.* [2011].

^oPorco *et al.* [2005].

^pBarnes *et al.* [2006].

^qSoderblom *et al.* [2009].

^rSotin *et al.* [2007].

^sLunine *et al.* [2008].

2013]. The tectonic-like origin of surface expressions like mountains, faults, and volcanic structures are suggestively related to ice rafts of altered densities moving on a liquid layer, thereby producing convergent or divergent surface features due to stresses caused by endogenic activity. In any event, it cannot be excluded that endogenic dynamics has played an important role for Titan's geologic activity.

Additional types of surface features that are particularly interesting due to their uncertain formation history are those that seem to be surface expressions of Titan's possible internal activity, i.e., geologic structures

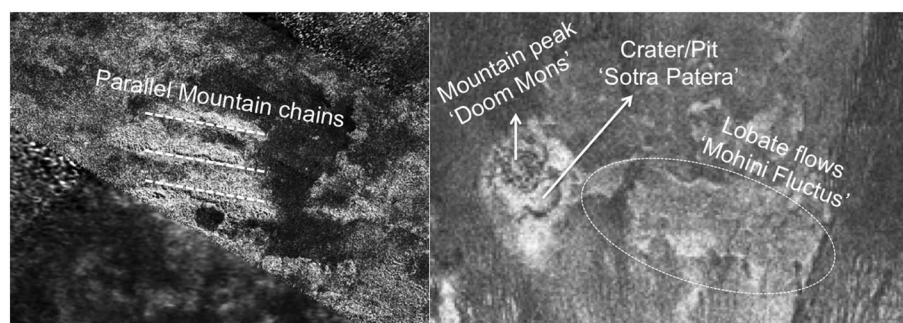


Figure 6. Possible tectonic and volcanic features on Titan. (left) Parallel mountain chains (2°S , 127°W) almost up to 2 km in height, formed possibly due to folding of the upper crust (tectonic-like motion) (Image credit: NASA/JPL-Caltech). (right) A possible cryovolcanic area, named Sotra Patera (15°S , 40°W), consisting of subareas with volcanic-like features such as a pit crater and lobate flows [Lopes et al., 2013] (Image credit: NASA/JPL-Caltech/ASI).

resulting from upwelling or fracturing of the upper crust caused by endogenic dynamics. Representative features of this type are morphotectonic features [Solomonidou et al., 2013] and candidate cryovolcanic sites (Figure 6). Cryovolcanism has been hypothesized on Titan as a means of replenishing methane in Titan's atmosphere [e.g., Tobie et al., 2006], and it can also explain changes reported in surface brightness or morphologically volcanic-like features [e.g., Lopes et al., 2007; Soderblom et al., 2009; Lopes et al., 2013; Solomonidou et al., 2013]. Other possibilities to explain these surface expressions prefer exogenic formation processes such as fluvial or lacustrine [Barnes et al., 2011; Moore and Howard, 2010; Moore and Pappalardo, 2011].

In any event, some areas on Titan's surface are likely to have exhibited brightness changes over time (cryovolcanic candidates) and/or have morphologies closely related to Earth's tectonic manifestations (e.g., mountains, faults). They are mostly located at equatorial latitudes between 30°S and 30°N and are likely associated with the surface stress field [Soderblom et al., 2009; Lopes et al., 2013; Solomonidou et al., 2013]. The mountainous regions were found to have elevations from 200 to 2000 m [Radebaugh et al., 2007; Mitri et al., 2010; Lorenz et al., 2013] and are characterized as mountain chains, hills, and ridges depending on their size, shape, and extension (see Table 4 and Figure 6 (left)). On Earth such features are mainly attributed to lateral motions of lithospheric plates, a geologic phenomenon that is largely unlikely to occur on Titan in the same fashion as it does on Earth. In spite of being a consequence of crustal movements, some blocks of mountains may have originated from impact ejecta [Radebaugh et al., 2007].

Other interesting areas on Titan are the so-called "active" regions with reported changes in brightness and/or color over time [Nelson et al., 2009; Wall et al., 2009]. In Table 4 the characteristics of these cryovolcanic candidate sites are listed, among which are Tui Regio (20°S , 130°W), a 1500 km long flow-like figure [Barnes et al., 2006], Hotei Regio (26°S , 78°W), a 700 km wide volcanic-like terrain [Soderblom et al., 2009], and Sotra Patera region (15°S , 40°W) (formerly known as Sotra Facula), and currently including Mohini Fluctus, Doom Mons, and the Sotra Patera pit [Lopes et al., 2010, 2013]. These areas together with others (see Table 4) have anomalous spectral and morphological properties that are possibly caused by dynamic geologic processes [Jaumann et al., 2009; Lopes et al., 2010, 2013]. Among others, deep craters (Sotra Patera), lobate flows (Mohini Fluctus), and caldera-like formations (in Hotei Regio) have been observed by Cassini RADAR and VIMS. In addition, VIMS data processing provided indications for brightness or surface albedo variations within a period of one to 3.5 years.

In analogy with terrestrial morphotectonic structures, the shape, size, and morphology of Titan's observed mountains, ridges, hills, and linear features such as faults, major fractures, and canyons probably originate through some form of compressional and extensional tectonic activity. Titan's rigid outer ice shell and the probable existence of a subsurface ocean create an analogy with terrestrial, at least surficial, plate tectonics. In this work, we have focused on the possible relations between solid body tides on Titan and observed geologic features on Titan's surface. Shown in Figure 7 is a map including both the diurnal tidal stress and geologic information. On this map we see the morphotectonic features of Titan which are the current identified major types of tectonic-like features (see Table 4) and their distribution on the surface. These are the elevated features such as mountains (green), faults and fractures (blue), and the candidate cryovolcanic

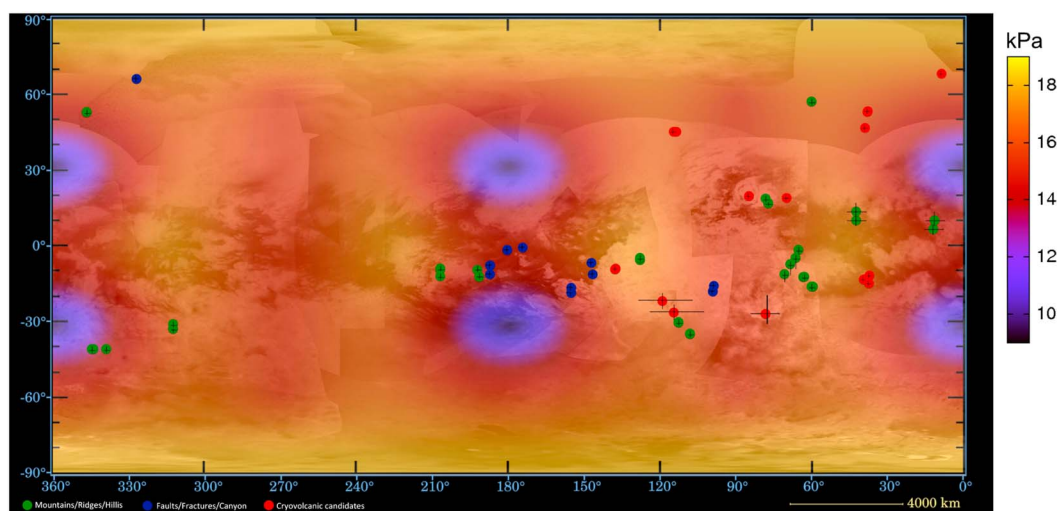


Figure 7. Global amplitude pattern of maximum diurnal tidal stresses, $\bar{\sigma}_{\text{tide}}$, color coded in units of kPa (Figure 5c) overlaid onto a base map of Titan's surface produced from Cassini ISS images (PIA14908 background map credit: NASA/JPL-Caltech/Space Science Institute). Symbols indicate characteristic geologic features possibly related to tectonics on Titan. Mountains and ridges (green), linear features such as faults and fractures (blue), candidate cryovolcanic features (red).

features (red). On this map is also overplotted the global amplitude pattern of maximum diurnal tidal stresses, $\bar{\sigma}_{\text{tide}}$, as shown in Figure 5c. This map reveals the correlation between features that are possibly tectonic and/or volcanic in origin and zones of intense tide-induced surface deformation concentrated at midlatitudes.

Four midlatitudes (50°S to 50°N) centered at (a) 40°, (b) 120°, (c) 230°, and (d) 310° west longitude, respectively, are the most amplified ones in terms of tidal flexure and stress accumulation, indicating zones of potentially high internal influence (Figure 7). As seen in the overplotted maps, we find that most of the sites listed in Table 4 are located within $\pm 30^\circ$ latitude from the equator in the leading hemisphere and therefore preferentially located within the strongly tidally flexed zones. This is particularly true for the mountains and the cryovolcanic candidates, while exceptions mainly concern the faults (blue dots on the map of Figure 7) and a couple of highlands in the high northern latitudes around 60°N. We note that the volcanic-like sites are concentrated in strongly tidally flexed zones as follows: Sotra Patera is located in the center of the (a) zone, confirming suggestions that rank this area as the most favorable candidate cryovolcanic region [Lopes *et al.*, 2013]; Tui Regio is located within the limits of the (b) zone; and Hotei Regio is located on the border between these two zones of amplified tidal distortion.

5. Discussion and Conclusions

We have studied present-day structural models of Titan's interior that are consistent with Cassini gravitational field data and simultaneously satisfy the satellite's inferred axial moment-of-inertia factor and degree-2 body tide Love number k_2 at the low end of the reported error margins of the latter [Joss *et al.*, 2012]. In order to explain larger k_2 values than the average of the measured k_2 , one may invoke ad hoc density hypotheses such as (i) relatively dense liquids [e.g., Mitri *et al.*, 2014] or (ii) mushy lower ice layers, but their possible existence is not supported by observations at this point. The first class of models has the difficulty that oceans composed of almost saturated salty solutions or suspensions were required, resulting in the precipitation of dense or suspended constituents over time. On the other hand, the existence of a mushy ice layer on Titan would result in a phase shift between primary and secondary tidal potential that to our knowledge is not supported by Cassini gravity field observations. More accurate time-variable gravity field data are required to resolve this issue.

Amplitude patterns of both diurnal tidal tensile and shear stresses and their superposition were calculated and are compared to the spatial distribution of tentative volcanic-like and tectonic-like surface features on Titan. Though alternative explanations prefer an exogenic origin [e.g., Moore and Pappalardo, 2011], the correlation between the tidal stress patterns illustrated in Figure 7 and the surface features seen on Titan may

rather suggest an endogenic origin of the latter. The calculated diurnal tidal stresses are on the order of a few tens of kPa, comparable to the magnitude of maximum possible nonhydrostatic deviatoric stresses on Titan [Gao and Stevenson, 2013], but the accumulation of tectonic stresses could eventually help exceed the tensile strength of fractured ice [Kimura *et al.*, 2007; Smith-Konter and Pappalardo, 2008]. True polar wander of the spin axis due to large-scale redistribution of mass on the surface or within the interior and nonsynchronous rotation of the decoupled shell moving slowly across the satellite's permanent tidal bulge may cause the buildup of long-term stresses and the formation of geologic surface features on a global scale [e.g., Jara-Orué and Vermeersen, 2011, and references therein]. Furthermore, in the event of stress hysteresis owing to transient creep phenomena [e.g., Shoji *et al.*, 2013], the incomplete relaxation of tidal stresses could play a role for stress buildup over several tidal cycles. Similar to the tide-induced seismicity of the Moon, episodic stress release accompanied by localized tectonic quakes may occur where a certain threshold stress limit value is exceeded.

Recent laboratory experiments in the low-temperature range below 220 K indicate that the resistance of polycrystalline water ice to tensile failure is strongly dependent on temperature, composition, grain size, and porosity [Litwin *et al.*, 2012]. For consolidated pure ice and ice contaminated by solid impurities, tensile strength is reported to increase by a factor of a few times the commonly used value of 1 MPa, which could impede tide-induced tectonism under Titan surface conditions. However, crustal porosity and the presence of near-surface liquids would considerably reduce the ice resistance to fracture. Furthermore, these authors suggest that fracture toughness is more important than tensile strength in the event of low strain rates where fracture propagation rather than fracture initiation is the strength-limiting factor. It is therefore conceivable that a porous ice crust soaked with liquids and subject to tide-induced surface deformation would be conducive to the formation of zones of weakness near strongly tidally flexed areas as shown in Figure 7. The possible existence of crustal zones of weakness on Titan may cause episodic cryovolcanic activity induced by positive buoyancy through exsolution of volatiles upon decompression, and the subsequent ascent along fluid-filled fractures in analogy to dikes [Lopes *et al.*, 2013]. Another mechanism to promote localized cryovolcanism might be shear heating by tide-induced strike-slip fault motion as suggested by Nimmo *et al.* [2007] to explain the heat and vapor production within the tiger-stripe regions near the south pole of Enceladus.

Equally to the leading hemisphere, two near-equatorial zones of strong tidal flexure and stress concentration are present on the trailing hemisphere. The apparent absence of cryovolcanic candidate features on the trailing hemisphere could be caused by the current observational bias toward the leading hemisphere. This is indicated in a recent multispectral map of Cassini VIMS and RADAR/SARtopo and altimetry data [Lorenz *et al.*, 2013] that is based on extrapolation from the still relatively scarce data basis with several large gaps to be filled by future Cassini observations. Alternatively, the apparent hemispheric asymmetry of tectonic-like and volcanic-like features could be linked to erosional and depositional processes since Titan's surface is subject to intense resurfacing. The global distribution and characteristics of fluvial erosion on Titan indeed indicates seasonal climatic asymmetries between both hemispheres [Langhans *et al.*, 2012]. Our findings further reveal that future Cassini observations of Titan's surface should focus on the tidally flexed regions in the trailing hemisphere and the polar areas that are more conducive to strike-slip motions. It must be expected that these regions could bear additional marks of the satellite's endogenic activity.

Titan is a dynamic satellite at present, as evidenced by the recent albedo changes observed in the Sotra Patera region and Tui Regio and the extensive surface changes spanning more than 500,000 km² in the wake of a seasonal storm [Turtle *et al.*, 2011]. Dynamic activity is thought to be conducive to habitable conditions on a planetary body as it allows the recycling of minerals and potential nutrients and provides localized energy sources by warm upwelling material. In a habitable environment, not only polymeric chemistry but also a fluid and semistable environment have to be present, as well as an energy source [Schulze-Makuch and Irwin, 2008]. Here we show that tidal forces are a constant and significant source of internal deformation on Titan. Furthermore, our model calculations suggest comparatively low ocean ammonia contents of less than 5 wt % and ocean temperatures in excess of 255 K, i.e., higher than previously thought, thereby substantially increasing Titan's potential for habitable locations.

When addressing Titan's habitability, understanding its interior structure is of critical importance. In this study, we have adopted new laboratory data for the parameterization of the water-ammonia (H₂O-NH₃) phase diagram [Choukroun and Grasset, 2007, 2010] to determine the sizes of Titan's bulk reservoirs (crust,

ocean, and deep interior) by assuming an isothermal subsurface ocean. It is important to remember that the thicknesses of the outer ice shell and of the subsurface ocean are linked to each other through the pressure-temperature phase relationships (phase diagram) of the water-ammonia system. Therefore, higher ocean temperatures yield larger ocean thicknesses and thinner ice shells and vice versa. For reasonable amounts of NH_3 (< 25 wt %), the ocean temperatures of successful structural models of Titan's interior are dependent on the ammonia concentration in the ocean. Smaller ammonia concentrations lead to warmer subsurface oceans and vice versa. A thinner crust would clearly be more conducive to putative life, because it could result in frequent cryovolcanism and upwelling of ammonia-water pulses near or onto the surface. Evidence for cryovolcanism was observed previously [Sotin et al., 2005; Lopes et al., 2007; Wall et al., 2009]. The diurnal tidal stresses as modeled for Titan could be large enough to result in geologic surface features: Liquid water-ammonia outbursts on the surface of Titan would clearly be a sign of a dynamic planetary body and may also provide suitable environmental niches for life, at least on a temporary basis. As a first step, our results indicate that one should look for such manifestations at the surface to bring additional evidence for the presence of the liquid water ocean.

Our modeling results also provide some constraints on the thickness of the water-ammonia ocean. For our reference model, we obtain a large ocean of about 180 km thickness, which would provide a huge reservoir of liquid water and ammonia. However, the ocean would be sandwiched between two layers of ice (Figure 4a), and needed inorganic ions, which play a central role in Earth biology including redox chemistry (Fe, Cu, Mn, Co, Mo, Se, S), acid-base catalysis (Zn, Ni), transmission and storage of energy and information (S, B, Si), and cell structure and homeostasis (Ca, Na, K), may be hard to come by [e.g., Fortes, 2000]. If the ammonia-water solvent were in direct contact with the rocky core, as some models shown in Figure 2 suggest, hydrothermal vent communities as observed on Earth and modeled for Europa [e.g., Irwin and Schulze-Makuch, 2003] may represent a feasible possibility for Titan's subsurface.

Our findings for a large, warm subsurface ocean with possibly a thin crust above enhance the habitability and astrobiological potential of Titan, but even more make it a special target for future exploration as an object with unique properties in our solar system.

Appendix A: Hydrostaticity and Spin Pole Orientation

The ratio between the degree-2 gravity coefficients $C_{2,2}$ and J_2 of a synchronously rotating satellite ($p = 1$) in hydrostatic equilibrium can be related to the spin and orbit parameters without a priori assumptions about the inertia tensor [Correia and Rodríguez, 2013]:

$$\frac{C_{2,2}}{J_2} = \frac{3H(p, e) \cos^4(\nu/2)}{(2p)^2 + (6 - 9 \sin^2 \nu)(1 - e^2)^{-3/2}}, \quad (\text{A1})$$

where ν is the obliquity of the spin axis relative to the orbit pole, e is orbital eccentricity, and $H(1, e) = 1 - \frac{5}{2}e^2 + \frac{13}{16}e^4$. Whereas ν was determined from Cassini RADAR data [Stiles et al., 2008, 2010], J_2 and $C_{2,2}$ were independently derived from Doppler radio science data collected during close encounters using suitable flyby geometries [Joss et al., 2010]. Insertion of the observational values collected in Table 1 on both sides of equation (A1) indicates that these observations are in excellent agreement with the assumption of hydrostaticity given by the theoretical prediction of 3/10.

If Titan occupies a Cassini spin state, its spin axis and orbit normal precess at a uniform rate and remain coplanar with the normal of the invariable plane such that the magnitude of the angular distance between Titan's spin and orbit poles could impose additional constraints on Titan's interior structure [Bills and Nimmo, 2008, 2011; Baland et al., 2011]. In the event of coplanar precession, the spin obliquity ν and orbit inclination i satisfy the Cassini condition [Peale, 1969, 1977]:

$$(\alpha \cos \nu + \beta) \sin \nu = \sin(i - \nu) = \sin i \cos \nu - \sin \nu \cos i, \quad (\text{A2})$$

which is equivalent to

$$(\cos i + \alpha \cos \nu + \beta) \sin \nu = \sin i \cos \nu \quad (\text{A3})$$

or

$$\tan \nu = \frac{\sin i}{\cos i + \alpha \cos \nu + \beta} = \frac{\tan i}{1 + \frac{\alpha \cos \nu + \beta}{\cos i}}. \quad (\text{A4})$$

The parameters α and β are given by [Peale, 1969, 1977]

$$\alpha = \frac{3}{2} \frac{\omega}{c\dot{\Omega}} (J_2 + 2C_{2,2}) \left(1 + \frac{3}{2}e^2\right) \quad (\text{A5})$$

and

$$\beta = \frac{3}{2} \frac{\omega}{c\dot{\Omega}} C_{2,2} \left[1 - \frac{5}{2}e^2 - \left(1 + \frac{11}{2}e^2\right) \cos v\right], \quad (\text{A6})$$

where ω is the mean orbital motion, $\dot{\Omega}$ is the node precession rate, and c is the dimensionless moment-of-inertia (Mol) factor of the outer ice shell. In the limit of small inclination i and obliquity v , $\cos i \sim \cos v \sim 1$, and equation (A4) simplifies to

$$\tan v = \frac{\tan i}{1 + \alpha + \beta}. \quad (\text{A7})$$

From insertion of equations (A5) and (A6) in equation (A7), we obtain the ratio between both angles:

$$\frac{i}{v} = 1 + \frac{3}{2} \frac{\omega}{c\dot{\Omega}} \left[\left(1 + \frac{3}{2}e^2\right) (J_2 + 2C_{2,2}) - 8e^2 C_{2,2} \right], \quad (\text{A8})$$

which is slightly different from equation (26) reported in *Bills and Nimmo* [2008]. If quadratic terms in e are neglected and the hydrostatic ratio $C_{2,2}/J_2 = 3/10$ is incorporated from equation (A1), we finally obtain

$$\frac{i}{v} = 1 + 8 \frac{\omega}{c\dot{\Omega}} C_{2,2}. \quad (\text{A9})$$

Upon insertion of the rate ratio $\omega/\dot{\Omega} = -1.391 \times 10^4$, the orbit inclination $i = 0.28^\circ$ [Bills and Nimmo, 2008], and the degree-2 gravity coefficient $C_{2,2} = 10.02 \times 10^{-6}$ [less et al., 2010], principal bounds on Titan's obliquity ranging between $v = -0.16^\circ$ in the homogeneous case (Mol factor $c = 2/5$) and $v = -0.42^\circ$ in the thin-shell case (Mol factor $c = 2/3$) are obtained. The corresponding precession period of the spin pole, Γ , is given by

$$\Gamma = \frac{2\pi}{\dot{\Omega}(\alpha + \beta)} = P_n \left(\frac{i}{v} - 1 \right), \quad (\text{A10})$$

where $P_n = 2\pi/\dot{\Omega}$ denotes the nodal regression period listed in Table 1 and may range from 220 years (Mol factor $c = 2/5$) to 365 years (Mol factor $c = 2/3$). Bills and Nimmo [2008, 2011] inferred that Titan's outer ice shell is likely decoupled from the deep interior by an ocean since the radar-observed obliquity of -0.32° [Stiles et al., 2008, 2010; Baland et al., 2011] falls within the obliquity range defined by the limiting model cases.

The Mol factor of a spherical shell is given by

$$c = \frac{\delta C}{\delta M R_s^2} = \frac{2}{5} \frac{1 - \left(\frac{R_b}{R_s}\right)^5}{1 - \left(\frac{R_b}{R_s}\right)^3}, \quad (\text{A11})$$

where R_b is the radial distance of the interface between the outer ice shell and the subsurface ocean, R_s is the surface radius, and δC and δM are shell moment of inertia and mass, respectively. From substitution of the shell thickness $d_c = R_s - R_b$ and second truncation of the resultant binomial series approximation in equation (A11), the following thin-shell approximation is obtained:

$$c = \frac{\delta C}{\delta M R_s^2} = \frac{2}{3} \left[1 - \frac{d_c}{R_s} + \frac{2}{3} \left(\frac{d_c}{R_s} \right)^2 \right]. \quad (\text{A12})$$

According to equations (A9) and (A10), Titan's radar-observed obliquity corresponds to a shell Mol factor of $c = 0.595$ and a spin-pole precession period of $\Gamma = 328$ years, respectively. Based on the assumption that dynamic and gravitational coupling effects can be neglected in this initial analysis, equation (A12) yields a shell thickness d_c in agreement with Titan's rotational state on the order of 300 km, still at odds with the interpretation of the low-degree gravitational field [less et al., 2010] and long-wavelength topography data [Zebker et al., 2009].

Table B1. Modeling Parameters of the Silicate Core^a

Parameter	Symbol	Units	Value
<i>Serpentine</i>			
Reference density ^d	ρ_0	g cm^{-3}	2.558
Reference bulk modulus ^d	K_0	GPa	67.27–0.017
Pressure derivative of the bulk modulus ^d	K'	—	4.0
Reference shear modulus ^e	μ_0	GPa	45.04
Pressure derivative of the shear modulus ^e	μ'	—	0.78
Thermal expansivity ^d	α	K^{-1}	2.00×10^{-5}
Thermal conductivity	k_c	$\text{W m}^{-1} \text{K}^{-1}$	— ^b
Specific heat capacity ^f	C_p	$\text{J kg}^{-1} \text{K}^{-1}$	$1987 - 1.39T^{-0.5} - 3.22 \times 10^{-3}T^{-2} + 4.204 \times 10^{-4}T^{-3}$
<i>Brucite</i>			
Reference density ^g	ρ_0	g cm^{-3}	2.403 ^c
Reference bulk modulus ^g	K_0	GPa	50.6 – 0.01147 ^c
Pressure derivative of the bulk modulus ^g	K'	—	4.7 ^c
Reference shear modulus ^h	μ_0	GPa	35.5 ^c
Pressure derivative of the shear modulus ^h	μ'	—	2.4 ^c
Thermal expansivity ^f	α	K^{-1}	5.00×10^{-5}
Thermal conductivity	k_c	$\text{W m}^{-1} \text{K}^{-1}$	— ^b
Specific heat capacity ^f	C_p	$\text{J kg}^{-1} \text{K}^{-1}$	$2346.4 - 0.92107T^{-0.5} - 7.4793 \times 10^{-3}T^{-2} + 9.4769 \times 10^{-5}T^{-3}$
<i>Olivine</i>			
Reference density ^d	ρ_0	g cm^{-3}	3.343
Reference bulk modulus ^d	K_0	GPa	131.1 – 0.02237
Pressure derivative of the bulk modulus ^d	K'	—	3.8
Reference shear modulus ⁱ	μ_0	GPa	82 ^c
Pressure derivative of the shear modulus ⁱ	μ'	—	0.84 ^c
Thermal expansivity ^d	α	K^{-1}	2.66×10^{-5}
Thermal conductivity	k_c	$\text{W m}^{-1} \text{K}^{-1}$	— ^b
Specific heat capacity ^f	C_p	$\text{J kg}^{-1} \text{K}^{-1}$	$1696.2 - 1.4225T^{-0.5} - 8.2620 \times 10^{-6}T^{-3}$

^aThe olivine data are given for comparison.^bCalculated using a thermal diffusivity κ of 10^{-6} for each mineral, respectively.^cValue refitted to the appropriate equation of state.^dFortes [2012, and references therein].^eMookherjee and Stixrude [2009], Mookherjee and Capitani [2011].^fBerman and Brown [1985].^gXia et al. [1998].^hJiang et al. [2006].ⁱStixrude and Lithgow-Bertelloni [2011].

Appendix B: The Hydrated Silicate Core

For serpentine ($\text{Mg}_{48}\text{Si}_{34}\text{O}_{85}(\text{OH})_{62}$) and brucite ($\text{Mg}(\text{OH})_2$) a Murnaghan equation of state is used to calculate the density as a function of depth. The corresponding parameters for this equation of state are summarized in Table B1.

Internal heat generation is considered only due to the decay of long-lived radiogenic nuclides in the rocky core, for which we assume a present-day specific heat production rate ϵ of $5.0 \times 10^{-12} \text{ W kg}^{-1}$, implying a chondritic bulk composition [e.g., Spohn and Schubert, 2003]. Additional heat sources are not taken into account, e.g., the dissipation of tidal energy or latent heat release due to crystallization processes.

To assess the thermal structure of the rocky core, we need to calculate the thermal expansivity α , the thermal conductivity k_c , and the specific heat capacity C_p for the constituent minerals, respectively. For this purpose, we adopt experimentally obtained relationships from various sources. The corresponding values are collected in Table B1.

The viscosity of the rocky core is adjusted such that the central temperature will not exceed a critical threshold temperature of about 900 K for silicate dehydration [e.g., Perrillat et al., 2005; Castillo-Rogez and Lunine, 2010]. That resulting viscosity is similarly large than the present-day value obtained by Grindrod et al. [2008] using a thermal evolution model with variable viscosity.

Table C1. Modeling Parameters of the High-Pressure Water-Ice Shell

Parameter	Symbol	Units	Value
Reference density ^a	ρ_0	g cm^{-3}	$1.3268 \exp(-1.495 \times 10^{-7} T^{2.2796})$
Reference bulk modulus ^a	K_0	GPa	$17.82 - 0.0385T + 3.625 \times 10^{-5} T^2$
Pressure derivative of the bulk modulus ^a	K'	—	5.40
Thermal expansivity ^b	α	K^{-1}	$3.506 \times 10^{-7} T + 3.783 \times 10^{-6}$
Thermal conductivity ^b	k_c	$\text{W m}^{-1} \text{K}^{-1}$	$-2.757 \times 10^{-7} T^3 + 1.969 \times 10^{-4} T^2 - 0.05119T + 6.557$
Specific heat capacity ^b	C_p	$\text{J kg}^{-1} \text{K}^{-1}$	$-0.0366T^2 + 26.315T - 1896.8$

^aFortes [2012, and references therein].^bGrindrod *et al.* [2008].

Appendix C: The High-Pressure Water-Ice Shell

We use Murnaghan's integrated linear equation of state to determine the local density in the high-pressure water-ice shell. Table C1 lists the parameters used for the appropriate equation of state.

To assess the thermal structure of the high-pressure water-ice shell, we need to calculate thermal expansivity α , thermal conductivity k_c , and specific heat capacity C_p . For this purpose, we adopt the relationships given by Grindrod *et al.* [2008] as derived from fitting experimental water-ice VI data of various sources. The corresponding expressions are compiled in Table C1.

Furthermore, we assume a constant viscosity of 10^{16} Pa s, which is compliant with the viscosity range of 10^{14} to 10^{17} Pa s for water-ice VI suggested by Poirier *et al.* [1981] and slightly lower than the viscosity calculated by Grindrod *et al.* [2008], applying a melting temperature-scaled viscosity relationship.

Appendix D: The Ocean-Ice System

The used equation of state parameters for pure water and ammonia are listed in Table D1. These parameters represent a Murnaghan-type fit to experimentally obtained data, respectively. The depth-dependent density of a water-ammonia mixture can then be calculated following the approach described by Croft *et al.* [1988].

A central assumption of the presented model approach is that the temperature within the subsurface ocean is considered as isothermal and does not change with depth. This assumption is justified because of the strong convective flow that must be expected within the ocean. The ocean temperature depends on the prescribed ammonia concentration of the ocean, which has been varied between 0 and 25 wt %.

Table D1. Modeling Parameters for the Subsurface H₂O-NH₃ Ocean

Parameter	Symbol	Units	Value
Water (liquid)			
Reference density ^b	ρ_0	g cm^{-3}	0.9991
Reference bulk modulus ^b	K_0	kbar	$-73.184 + 0.5910T - 9.139 \times 10^{-4} T^2$
Pressure derivative of the bulk modulus ^b	K'	—	$39.999 - 0.2058T + 3.111 \times 10^{-4} T^2$
Thermal expansivity ^c	α	K^{-1}	2.1×10^{-4}
Thermal conductivity ^c	k_c	$\text{W m}^{-1} \text{K}^{-1}$	0.566
Specific heat capacity ^d	C_p	$\text{J kg}^{-1} \text{K}^{-1}$	4200
Ammonia (liquid)			
Reference density ^b	ρ_0	g cm^{-3}	0.6177
Reference bulk modulus ^b	K_0	kbar	$48.503 \exp(-1.0134 \times 10^{-3} T^{1.3067})$
Pressure derivative of the bulk modulus ^b	K'	—	$4.0858 \times 10^{16} T^{-6.6083} + 4.1831$
Thermal expansivity	α	K^{-1}	2.1×10^{-4a}
Thermal conductivity	k_c	$\text{W m}^{-1} \text{K}^{-1}$	0.566 ^a
Specific heat capacity	C_p	$\text{J kg}^{-1} \text{K}^{-1}$	4200 ^a

^aAssumed to be identical to the value of seawater.^bCroft *et al.* [1988].^cHill [1962].^dKirk and Stevenson [1987].

Table D2. Equation of State Parameters for the Water-Ice and Methane-Hydrate Crust According to *Helgerud et al. [2009]*^a

Parameter	Symbol	Units	A*	B*	C*
Water-ice (Ih)					
Density	ρ	g cm^{-3}	-1.5035×10^{-4}	1.0594×10^{-4}	0.91673
Bulk modulus	K	GPa	-1.48×10^{-2}	3.4×10^{-3}	9.07
Shear modulus	μ	GPa	-5.03×10^{-3}	3.0×10^{-4}	3.459
Compressional wave speed	v_p	m s^{-1}	-2.67	0.2	3864
Shear wave speed	v_s	m s^{-1}	-1.244	-0.198	1942.4
Methane hydrate (sl)					
Density	ρ	g cm^{-3}	-2.3815×10^{-4}	1.1843×10^{-4}	0.92435
Bulk modulus	K	GPa	-1.09×10^{-2}	3.8×10^{-3}	8.39
Shear modulus	μ	GPa	-4.2×10^{-3}	9×10^{-5}	3.541
Compressional wave speed	v_p	m s^{-1}	-1.84	0.31	3766
Shear wave speed	v_s	m s^{-1}	-0.892	-0.100	1957.0

^aUnits for A* are the units of the corresponding parameter divided by °C. Units for B* are the units of the corresponding parameter divided by MPa. Units for C* are the units of the corresponding parameter.

For the thermal expansivity α , the thermal conductivity k_c , and the specific heat capacity C_p of the water-ammonia system values, we use values determined for seawater (Table D1), implicitly assuming that the differences between the water-ammonia mixture and seawater are small.

To obtain the elastic moduli K and μ of the outer ice shell, we use linear planar fits to laboratory data reported by *Helgerud et al. [2009]* and calculate the seismic velocities according to equations (10) and (11). Table D2 lists the corresponding fit parameters of both chemical end-members (water ice and methane hydrate), respectively. While the fit parameters A*, B*, and C* for both water-ice Ih and sl methane are listed in Table D2, the corresponding thermal properties, i.e., thermal expansivity α , thermal conductivity k_c , and specific heat capacity C_p , are summarized in Table D3.

The viscosity of the outer ice shell is assumed to be 10^{20} Pa s, in agreement with the assumption that the ice shell is not convecting [*Nimmo and Bills, 2010*].

Appendix E: Diurnal Tidal Stress

Diurnal stress variations at Titan's surface due to body tides are attributed to the satellite's significant orbital eccentricity and obliquity. The diurnal tidal stress can be expressed in terms of shear (τ_s) and normal stress (σ_n), acting on an arbitrarily oriented surface element [e.g., *Turcotte and Schubert, 2002; Smith-Konter and Pappalardo, 2008*]:

$$\sigma_n = \sigma_{\theta\theta} \cos^2 \gamma + \sigma_{\phi\phi} \sin^2 \gamma + \tau_{\theta\phi} \sin 2\gamma \quad (\text{E1})$$

Table D3. Modeling Parameters for the Water-Ice and Methane-Hydrate Crust

Parameter	Symbol	Units	Value
Water-ice (Ih)			
Thermal expansivity ^a	α	K^{-1}	$6.24 \times 10^{-7} T$
Thermal conductivity ^b	k_c	$\text{W m}^{-1} \text{K}^{-1}$	$0.4685 + 4887^{-1}$
Specific heat capacity ^b	C_p	$\text{J kg}^{-1} \text{K}^{-1}$	$7.037T + 185$
Methane hydrate (sl)			
Thermal expansivity ^c	α	K^{-1}	$2.09 \times 10^{-9} T + 3.7 \times 10^{-8}$
Thermal conductivity ^c	k_c	$\text{W m}^{-1} \text{K}^{-1}$	$0.498 - 2.307^{-1} + 4.708T^{-2} - 3.718T^{-3}$
Specific heat capacity ^c	C_p	$\text{J kg}^{-1} \text{K}^{-1}$	$4.971 \times 10^{-5} T^3 - 0.02897T^2 + 11.66T + 55.92$

^a*Kirk and Stevenson [1987]*.

^b*Hillier and Squyres [1991]*.

^c*Grindrod et al. [2008]*.

and

$$\tau_s = \frac{1}{2}(\sigma_{\phi\phi} - \sigma_{\theta\theta}) \sin 2\gamma + \tau_{\theta\phi} \cos 2\gamma, \quad (E2)$$

where the inclination angle γ is measured relative to the longitudinal direction [see *Nimmo et al.*, 2007] (supporting information). In general, the stresses are specified by the nonzero components of the diurnal stress tensor in latitudinal ($\sigma_{\theta\theta}$), longitudinal ($\sigma_{\phi\phi}$), and cross directions ($\tau_{\theta\phi} = \tau_{\phi\theta}$) and further related to the time-variable tidal potential Φ_e at the satellite's surface [Wahr et al., 2009]:

$$\sigma_{\theta\theta} = \frac{2\mu}{g_s R_s (\lambda + 2\mu)} \left\{ h_2 (3\lambda + 2\mu) \Phi_e + I_2 \left[\frac{\lambda}{\sin^2 \theta} \frac{\partial^2 \Phi_e}{\partial \phi^2} + \lambda \cot \theta \frac{\partial \Phi_e}{\partial \theta} + 2(\lambda + \mu) \frac{\partial^2 \Phi_e}{\partial \theta^2} \right] \right\} \quad (E3)$$

$$\sigma_{\phi\phi} = \frac{2\mu}{g_s R_s (\lambda + 2\mu)} \left\{ h_2 (3\lambda + 2\mu) \Phi_e + I_2 \left[\frac{2(\lambda + \mu)}{\sin^2 \theta} \frac{\partial^2 \Phi_e}{\partial \phi^2} + 2(\lambda + \mu) \cot \theta \frac{\partial \Phi_e}{\partial \theta} + \lambda \frac{\partial^2 \Phi_e}{\partial \theta^2} \right] \right\} \quad (E4)$$

$$\tau_{\theta\phi} = \tau_{\phi\theta} = \frac{2\mu I_2}{g_s R_s \sin \theta} \left(\frac{\partial^2 \Phi_e}{\partial \theta \partial \phi} - \cot \theta \frac{\partial \Phi_e}{\partial \theta} \right), \quad (E5)$$

where $\lambda = K - 2/3\mu = 2\mu\nu/(1 - 2\nu)$ is Lamé's first parameter, μ is shear modulus, ν is Poisson's ratio, h_2 is radial displacement Love number, and I_2 is tangential displacement Shida number. The Poisson ratio of the outer ice shell is held fixed at $\nu = 1/3$ for ice Ih [Helgerud et al., 2009], corresponding to the model case $\lambda = 2\mu$.

The diurnal stress tensor can be expressed in terms of orthogonal principal stresses σ_{\max} and σ_{\min} such that shear stresses vanish [e.g., *Turcotte and Schubert*, 2002]

$$\sigma_{\max, \min} = \frac{\sigma_{\theta\theta} + \sigma_{\phi\phi}}{2} \pm \left[\left(\frac{\sigma_{\theta\theta} - \sigma_{\phi\phi}}{2} \right)^2 + \tau_{\theta\phi}^2 \right]^{1/2} \quad (E6)$$

and the orientation angle γ_p of the principal stress axis given by

$$\gamma_p = \frac{1}{2} \arctan \left(\frac{2\tau_{\theta\phi}}{\sigma_{\theta\theta} - \sigma_{\phi\phi}} \right). \quad (E7)$$

Since we are interested in global amplitude patterns of diurnal tidal stresses, we calculate the maximum tensile (areal) stress [Zürn and Wilhelm, 1984]

$$\sigma_{\text{areal}} = \frac{1}{2}(\sigma_{\max} + \sigma_{\min}) = \frac{1}{2}(\sigma_{\theta\theta} + \sigma_{\phi\phi}) \quad (E8)$$

and the maximum shear stress ($\gamma_p = \pi/4$)

$$\tau_{\text{shear}} = \frac{1}{2}(\sigma_{\max} - \sigma_{\min}) = \left[\left(\frac{\sigma_{\theta\theta} - \sigma_{\phi\phi}}{2} \right)^2 + \tau_{\theta\phi}^2 \right]^{1/2} \quad (E9)$$

at Titan's surface, whereas the maximum diurnal tidal stress $\bar{\sigma}_{\text{tide}}$ is obtained from the second invariant of the stress tensor [e.g., *Gerya*, 2010]

$$\bar{\sigma}_{\text{tide}} = \left[\frac{1}{2} (\sigma_{\theta\theta}^2 + \sigma_{\phi\phi}^2 + 2\tau_{\theta\phi}^2) \right]^{1/2}. \quad (E10)$$

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