

Automation in production integrated NDT using thermography

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Abstract. Since the last decade the demand of CFRP parts is rapidly increasing in the aerospace industry. Besides the challenges in design and engineering, the manufacturing quality plays a key role. In order to achieve a higher quality, to decrease scrap rate and lowering manufacturing costs, the need for process integrated measurement techniques such as Lock-In Thermography are obligatory. One of the deficits so far is that Thermography lacks implementation on industrial scale. The approach at DLR Augsburg is a robot based measuring system for industrial applications such as measuring large CFRP structures of future aircraft generations (see Figure 1). Research at the DLR-Center for Lightweight-Production-Technology in Augsburg focuses on this and will give insight into the challenges and current work with this paper.

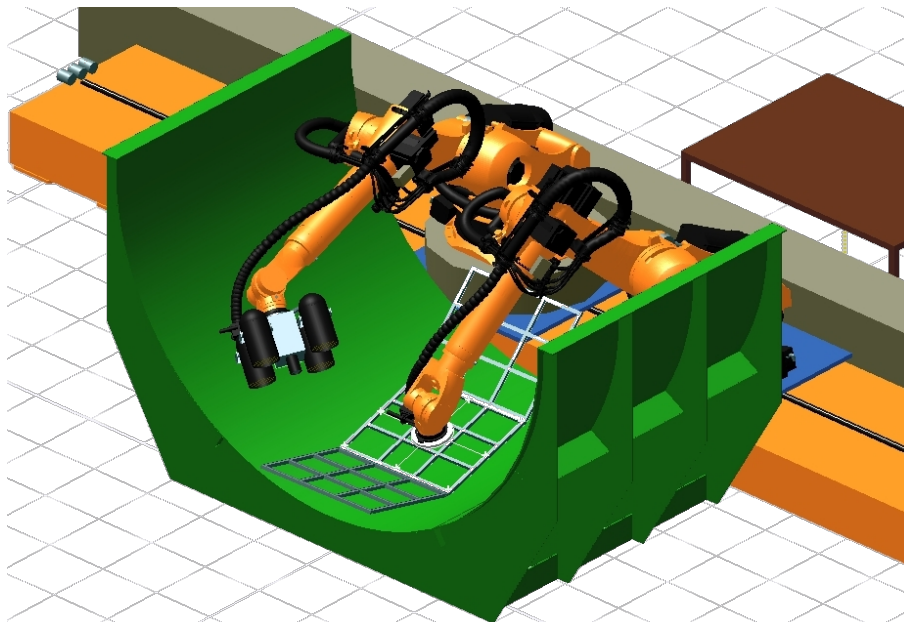


Figure 1 Scenario of automated thermography within production environment

Introduction

State of the Art in Aerospace production and testing

Figure 2 shows the classical production process for the textile/ infusion technology. Most of the process steps are still manual work as described above. Inspection in between each step is only visual or acoustic on a very qualitative scale. Quality assurance takes place but is more or less only documentation if each step had been done, but neither how accurate it was nor what size or location of anomaly had been detected.

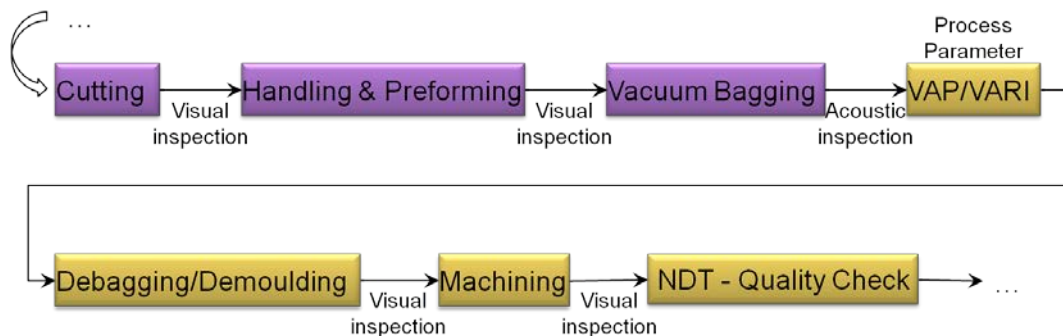


Figure 2 Present production strategy in textile/infusion technology

The final quality check is usually performed by classical ultrasonic inspection. In nearly all cases water coupled ultrasonic inspection is the choice. The inspection machines reach from gantry solutions with linear and rotational axis using submersion and squirter technology. Sampled phased array in transmission and pulse/echo finds a very wide spread. Examples for each technology as shown below.



Figure 3 Examples for water coupled ultrasonic inspection (sources: National Composites Network, Premium Aerotec, IntelligeNDT, HPI)

Challenges for NDT

Besides final inspection of components, NDT can be used during manufacturing in terms of monitoring and even control of process quality. Picking up the drawbacks from nowadays quality assurance for existing production scenarios one can identify the challenges for future NDT. NDT has to deliver proper indicators to evaluate the quality of a part or structure. Quality assurance with NDT combines the advantages of both classical methods of process control. On the one hand monitoring of process variables will guarantee the quality of the product and on the other hand the collected statistics data will assist to develop the manufacturing process. The Aerospace industry relies on non-destructive testing (NDT) methods to detect and characterise the manufacturing failure and damages. As a part of the production integrated NDT for CFRP components it is necessary to automate the NDT Inspections system. Taking the knowledge that derives from a detailed documentation it allows to improve the manufacturing process know how. This should lead to a closed engineering loop and therefore a continuous improvement. Consequently an improved rework rate is the outcome.

Due to the lack of fully an automatic production chain, the industry is presently not being able to fulfil the drastically increasing demand of the components. All items mentioned above will put pressure on the development of future NDT to achieve the desired cost efficiency. The goal is to improve the automation level in the manufacturing technology, reduce the manufacturing cost and improve the part's quality. An improved rework rate will lead towards a higher output rate of production. It might actually be imaginable to decrease the amount of testing at the final stage. A final quality approval based on a few samples or random checks could be possible. Such a major change in a QA strategy needs to be certified for sure. Nevertheless a higher degree of flexible automation in measurement and evaluation is necessary to enable a continuous improvement. An integrated production and quality assurance rather than local improvements seem to play a key role.

Projecting this on the process chain mentioned earlier, research at ZLP Augsburg aims at two process steps that want to be covered with current work as depicted in Figure 4.

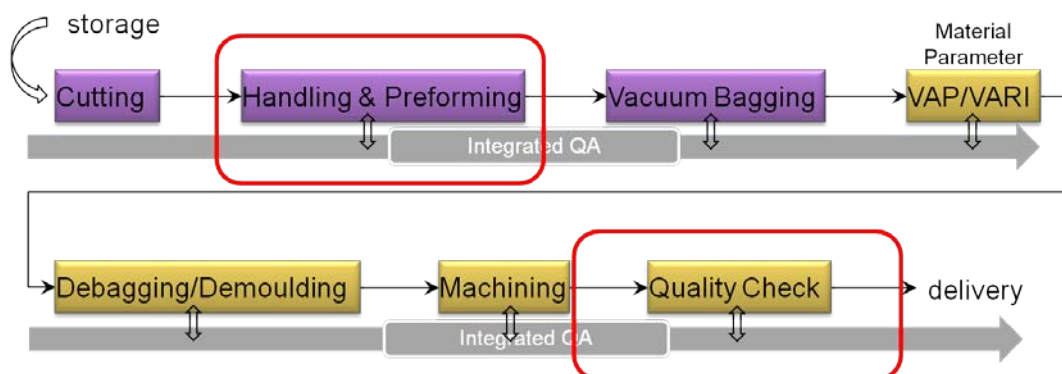


Figure 4 future QA strategy in textile/infusion technology

Every processing step in the production line should be monitored to improve the added value without derogating the quality of the components. Implementing new measuring and evaluation technology throughout the production line could be the key to avoid or minimize the manufacturing irregularity. One such measurement system must meet the following criteria like being contactless, having higher measurement speed as well as easy-to-interpret, being automatic and obviously economic. Inspection tools also must meet measurement specifications for complex and large components at high speeds. On the other side process integrated NDT has to fulfil the requirements of industrial production concerning integratebility and data management.

There are several approaches of non-destructive measuring method, which are applied here in DLR to expose the complete manufacturing process. This paper is focusing on automated non-destructive Thermography, which exposes the “handling & preforming” and as well as component “quality check”.

Approach – production integrated, automated Thermography as a choice

The future challenges are the basics for the approach. Searching a NDT method that is suitable to cover all needs, such as contactless, accurate, of high performance, able to integrate into existing production scenarios, research at ZLP Augsburg had been focused on active Thermography. Using industrial robots as manipulators one could achieve a very flexible and highly accurate solution with the highest rate of automation as shown in Figure 5.

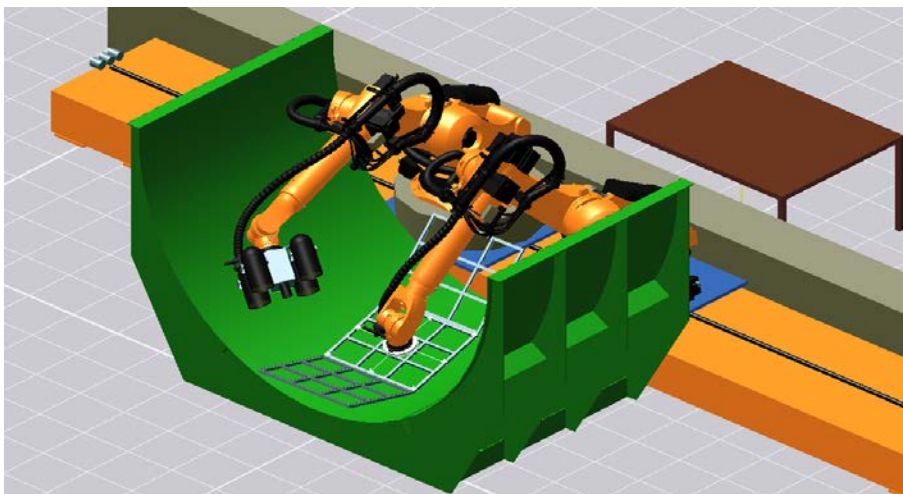
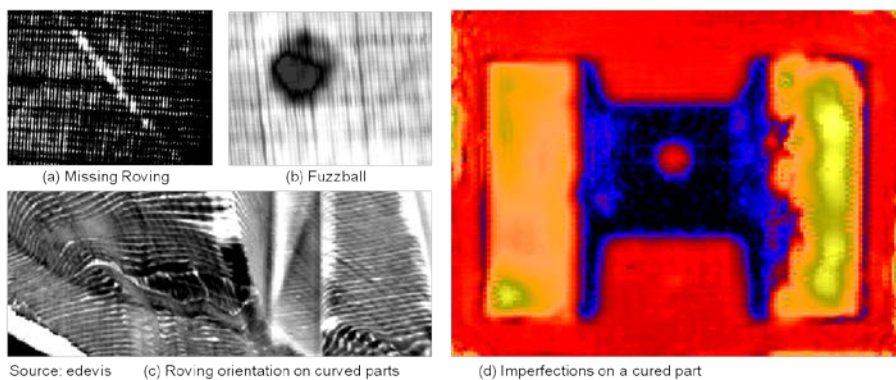


Figure 5 Approach - production integrated, automated Thermography

The choice on active Thermography has been made because it is capable to visualize defects on dry carbon fiber performs as well as cured parts. This capability fulfills the requirements to detect features like missing rovings, fuzzballs or even the fiber orientation on textile performs. The more common use is to detect anomalies in cured parts such as delaminations, dry spots, porosity or disbondings. Examples for both cases are shown in the following Figure 6. There are more applications imaginable like using Thermography to survey the process of infusion and how the flow front evolves. But is not a prime topic that will be investigated.



Source: edevis

Figure 6 Examples for measuring carbon fibre performs (a, b, c) and cured parts (d)

The choice on industrial robots is self evident as they are used as manipulators in our production environment as well. Through their kinematics they allow a high degree of flexibility combined with an adequate accuracy. Not to mention, that both features are the determining factor especially as a standard industrial robot is comparably inexpensive.

Realization

At ZLP Augsburg, a highly flexible robotic work cell for future composite production has been developed and built. This work cell allows research on an industrial scale as the dimensions for possible structures are enormous. The work cell consists of 4 major gantry portals. Each of them has move- and tiltable vertical axis with a robotic arm at its end. The entire working volume can be split in quadrants to allow parallel work on different projects. The main goal is to demonstrate and perform active Thermography within this work cell. For a detailed view, please refer to Figure 7.

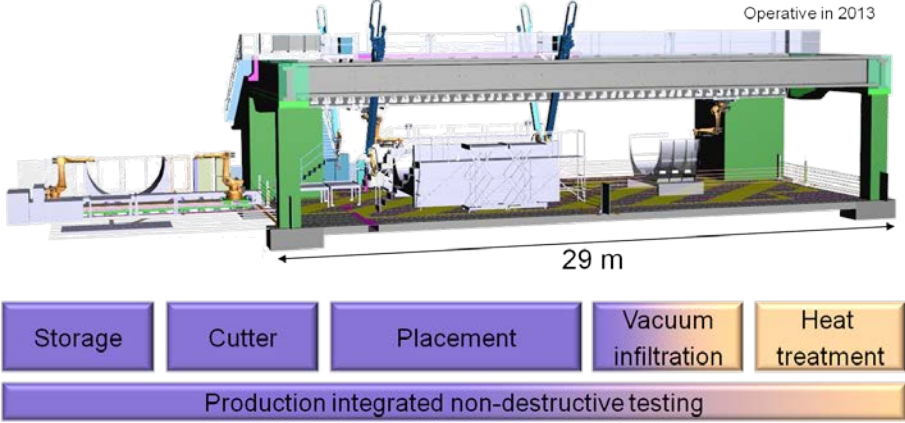


Figure 7 robotic work cell for future composite production and integrated NDT

As the above mentioned work cell is huge in its dimension, the decision has been made to proceed in several steps. One of the reasons is risk mitigation; therefore first concepts had been started on a smaller scale. As shown in Figure 8 integration of the Thermography setup has been started on a work cell that consists of a linear axis which is mounted on the ground. The linear axis carries to robots. Both have a nominal reach of R3000 at a load capacity of 210kg. The developed Thermography measuring system based on industrial robots carries the halogen lamps and an IR camera. This measuring system is designed to achieve homogenous excited measuring filed and convenient to measure complex 3D components.

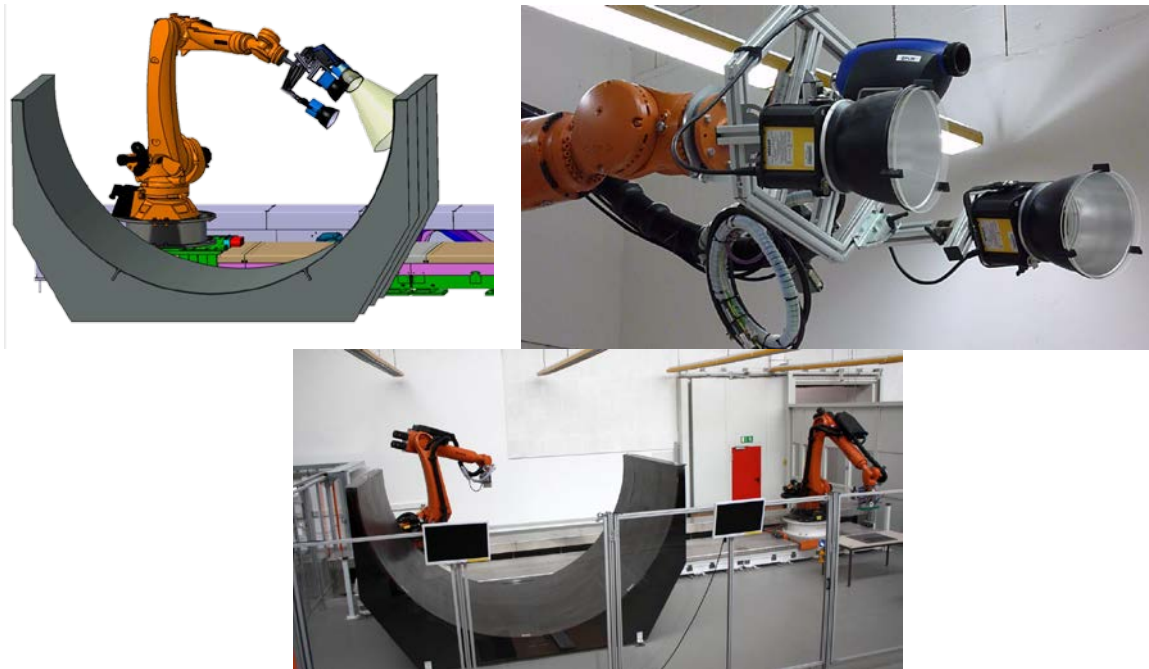


Figure 8 Experimental set up for risk mitigation

As a matter of principle there are a number of scenarios possible to integrate a system for active Thermography on the shown robot. All concepts can be categorized in three different types which had been investigated in depth focusing on feasibility, practical use, measurement scenarios and future application. The choice had been made and the scenario chosen shown in Figure 9.

Thermography methods are not yet used in inline testing of CFRP components. Process-integrated Thermography has to meet a variety of requirements like integrateable, automatable, real time capable, reliable and flexible. The system integration contains the development of strategies and the implementation of the mechanics, electronics, and software for the two main tasks, extern control system and flexible enough for single robot, for TEZ and MFZ work cell. In an early phase three different approaches has been proposed for system integration, which demonstrate the advantages and drawbacks. Finally the scenario shown in Figure 9 has emerged as the optimal method.

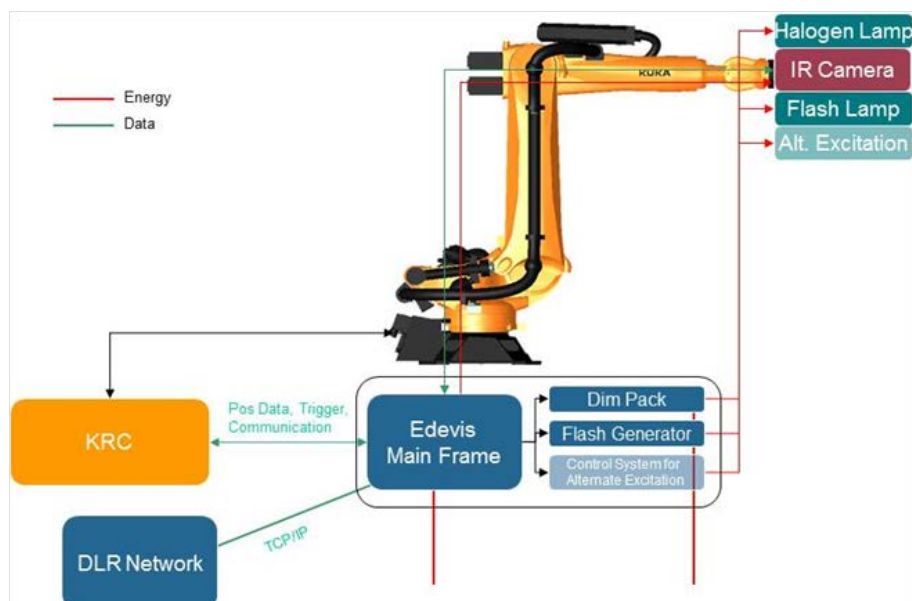


Figure 9 Excitation and camera mounted on robot hand, control system locally separated

The system architecture splits up into 4 main parts: the robot control system (KRC), the Thermography control system including Dim Pack and Flash Generator, the measuring devices including IR camera, halogen lamps and flash lamps and the DLR network system. Each of these four systems contains the relevant electronics, mechanics and software for its special functionality.

Derived from the early phase, to achieve high measuring accuracy in large measuring volume on 3D curved components, the measuring system has to be as simple as possible to locate the centre of gravity of tool, able to measure and evaluate in real time.

Another approach is the real-time model based quality control by monitoring of process measurable. In order to fulfill the boundary conditions for the tasks, alternative strategies for the implementation of the mechanics, electronics and software into a mechatronic system have been evaluated and implemented. Therefore only the measuring devices are mounted on axis no. 6 and are linked via Ethercat with Thermography control system, which stays on ground. Graphical user interfaces were developed to enable the user to interact with the robot in a comfortable way and to ensure electronic documentation.

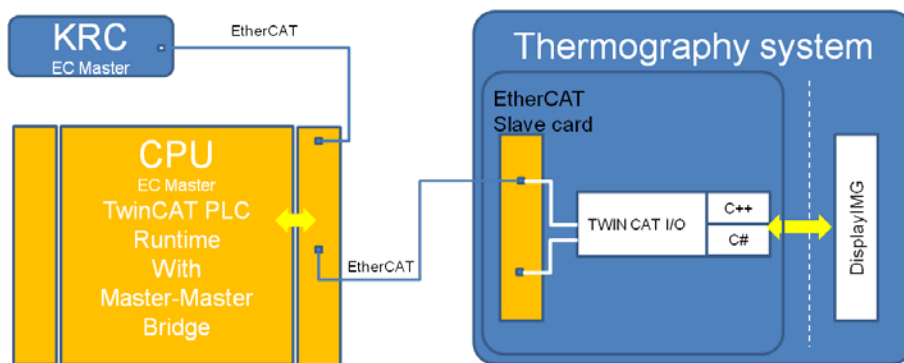


Figure 10 Schematic representation of EtherCAT communication

Figure 10 shows the communication scheme set up using EtherCAT as a protocol. One of the special requirements using EtherCAT is that only one “master” is allowed within the bus system. Therefore a so called Master-Master Bridge has to be developed to allow communication. This enables to set up and perform automated measurements from the robotic environment.

Automation along the process chain

Figure 10 represents in blue section complete manufacturing process and the closed process below that represents the automated closed monitoring system for cutting, handling and performing manufacturing steps. As an open and closed monitoring tool, it allows to detect and discard all nonconforming components. Only good components go to manufacturing process. Consequently, the process limits can be exhausted, allowing increasing productivity. On the other side, process disturbances affecting the product quality can be detected and located directly. The process can be controlled using its quality characteristics as control variables directly. For this purpose diverse information from CAD draping simulation and 3D output are required and used for measurement strategy. For example, to set the measurement parameters and distance in measuring system material properties, components thickness and number of plies are used. After measurement strategy follows the offline programming for path planning relating to robot tool centre point (TCP) and as well as to set the camera and halogen position and orientation. All these information are applied to measurement software to perform the measurement step. Getting the information

from measurement software an automatic evaluation runs to classify and detect the position of defects. This step verifies the process continuation and keeps all raw data for process understanding. In case any kinds of defects are detected, a repair or strategic change is recommended.

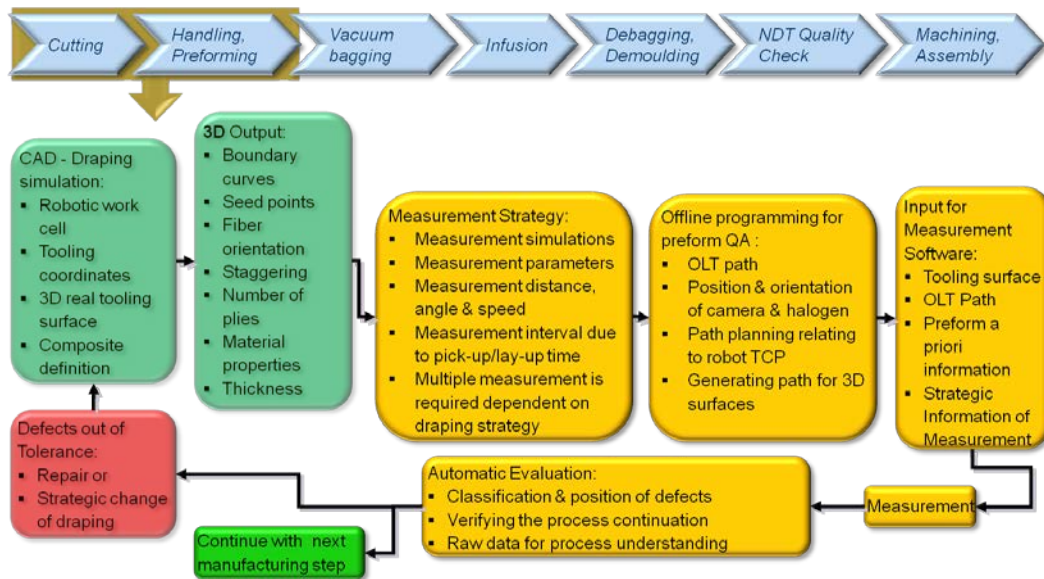


Figure 11 Process monitoring, open and closed loop control with NDT

Conclusion

The case studies have shown, that NDT aided production provides a significant contribution in order to improve product quality, reduce scatter in properties, minimize scrap and improve process economy. In future NDT will be an essential component of a more or less autonomously running production, assuring product and process quality with a minimum of man-machine interaction. As a consequence NDT techniques have to evolve from simple measuring machines to intelligent control systems.

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