

#### **Experimental Radar Modes with TerraSAR-X and TanDEM-X**

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### Outline

Experimental Radar Modes of TerraSAR-X and TanDEM-X with potential Applications in Oceanography and Glaciology

#### ✓ Modes with higher coverage

- → 8 Beam ScanSAR
- ➔ 8 WideBeam ScanSAR

#### ➤ Modes for Surface Movement Measurement

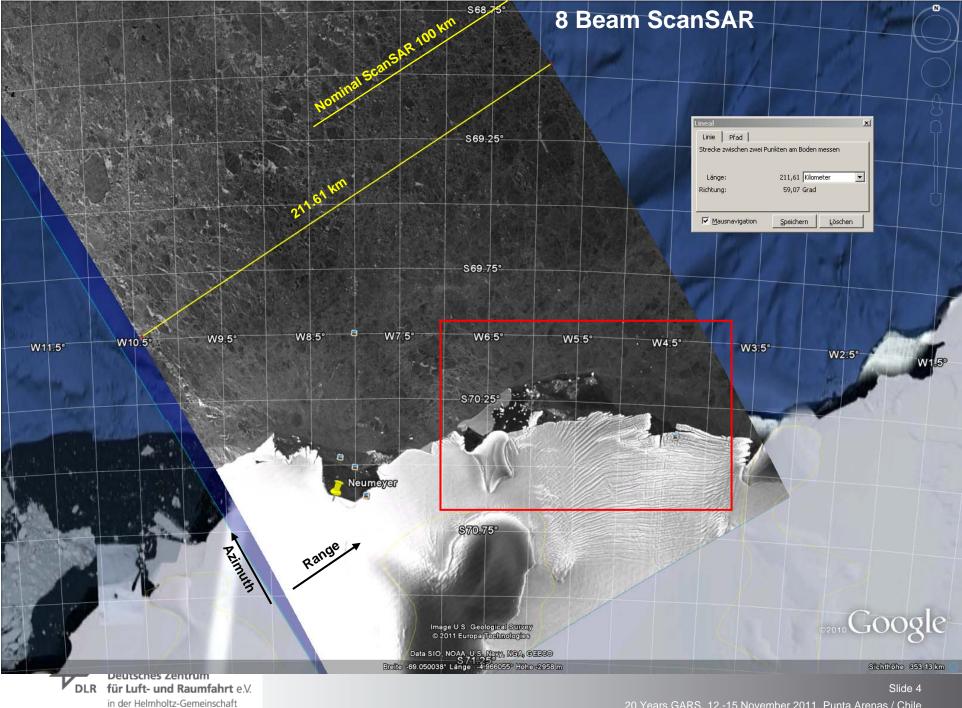
- → ATIS 0.1 ms time separation
- ✓ Pursuit Monostatic 3 s time separation
  - → StripMap
  - → ScanSAR
- → BiDiSAR 6 s time separation
- ✓ Crossing Orbits 1 d or 5 d or 6 days time separation



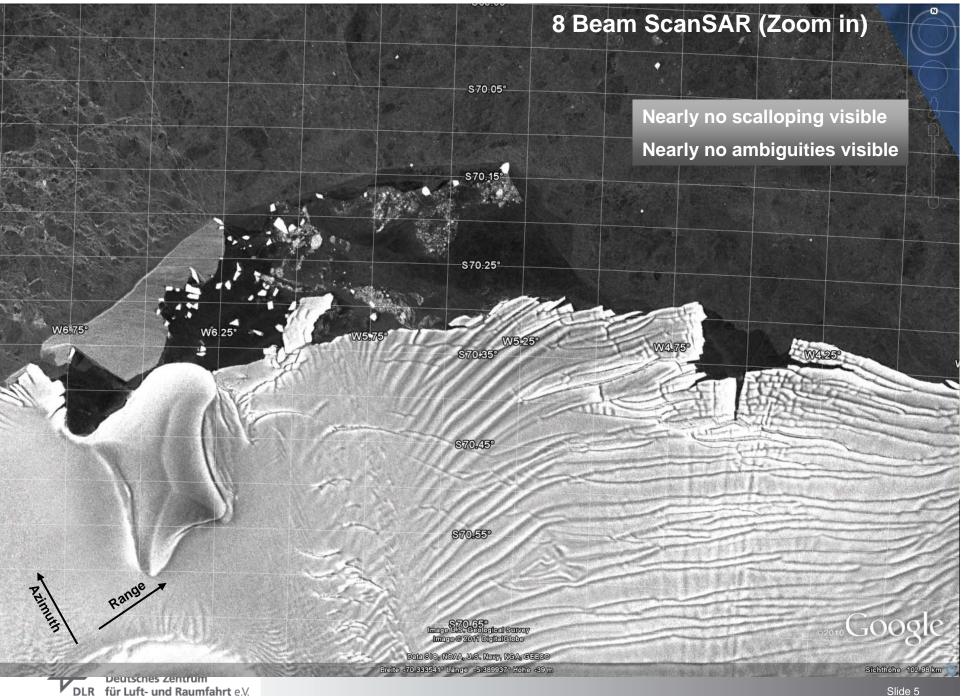
### • Modes with higher Coverage I (200 km swath width)

- ✓ ScanSAR with 8 Beams i.e. 8 subswathes instead of standard 4 Beams
  - ✓ Swath width increases from 100 km to 200 km
  - ✓ Switching faster from subswath to subswath since cycle time remains
  - → Burstlength per subswath is shorther
    - ➤ Resolution becomes worse, e.g. 40 m
  - - ✓ More complex
    - ➤ Higher onboard resource consumption (programming steps)
    - → 32 Basic States are needed for a timing change (echo window)
    - Commanding will fail in case of large DataTake length and terrain variations, i.e. 255 Basic States are exceeded





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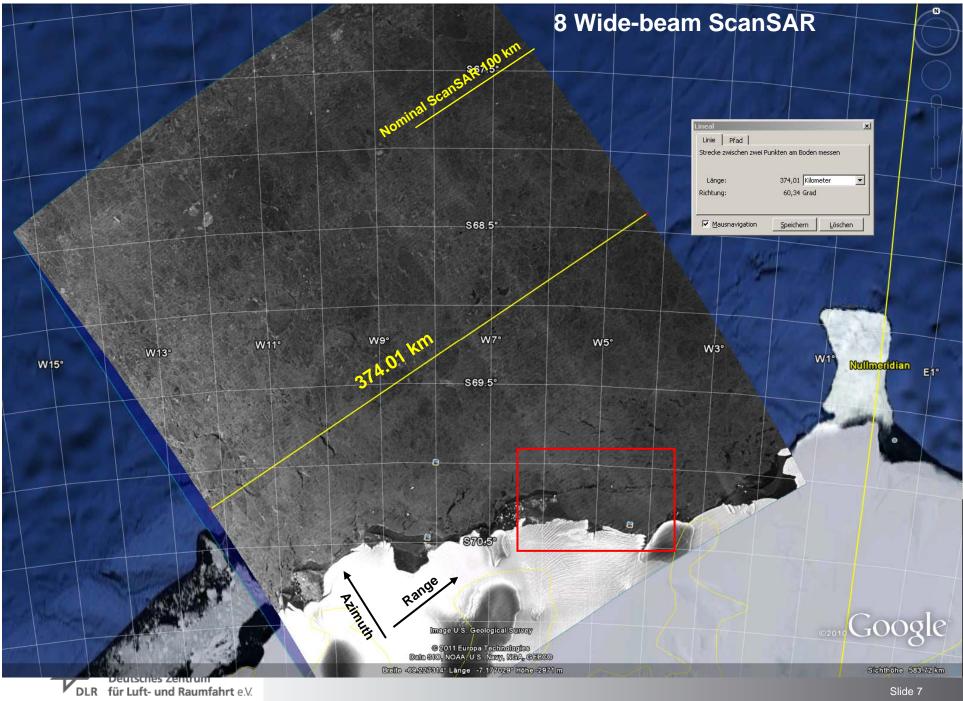
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#### • Modes with higher Coverage II (370 km swath width)

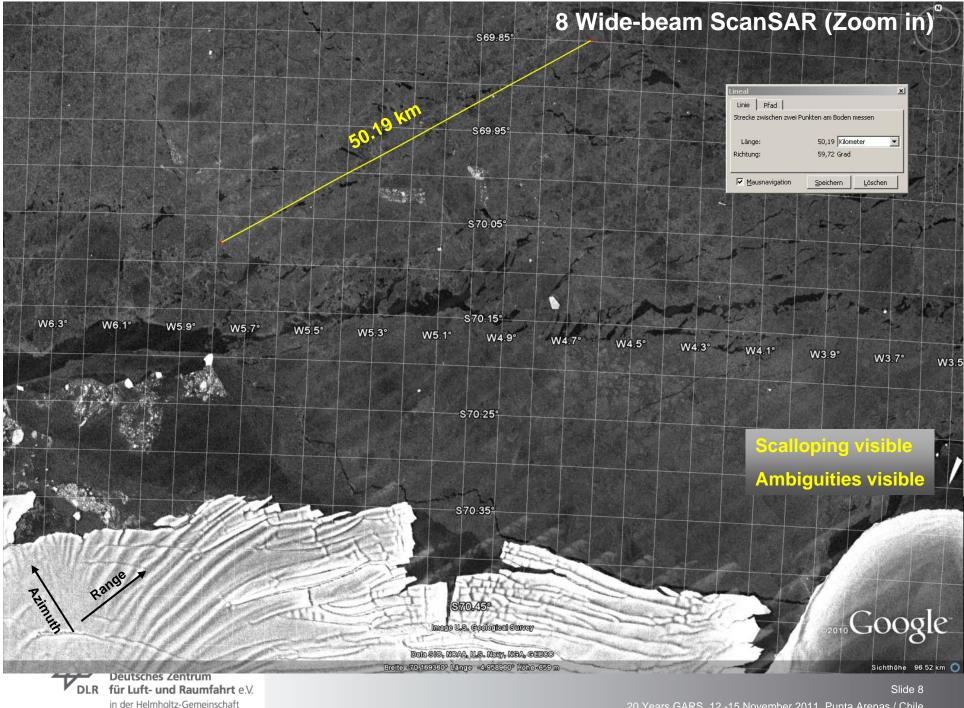
- ScanSAR with 8 Wide Beams i.e. 45km subswathes instead of standard 30km subswathes
  - ✓ Expand footprint of each subswath by phase patterns
    - ➤ Less energy per area
    - ✓ Worse SNR
  - ✓ Decrease of TX pulse length to increase echo window length
    - ➤ Less transmitting energy
    - ✓ Worse SNR
  - ✓ Decrease PRF to increase echo window length
    - → Higher azimuth ambiguities





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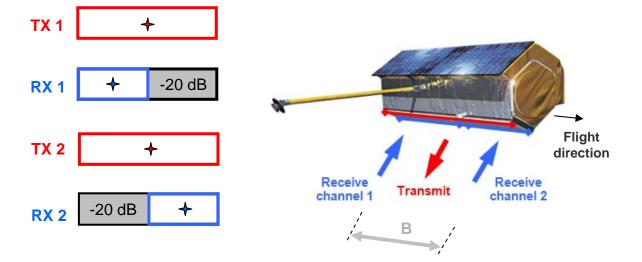


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## Modes for Surface Movement Estimation

by means of Interferometry or speckle tracking

#### • ATIS (Along Track Interferometry by Aperture Switching) Single satellite



#### **Aperture Switching (AS)**

- ✓ Switching between antenna parts on receive
- Constantly available (only nominal electronic used) in contrast to DRA (additional redundant electronic used)
- → ATI baselines B(0.84 m 1.43 m) ca. 0.1 ms time separation
- ✓ Many data takes of surface currents in oceans and rivers successfully acquired and processed





#### Data Acquisitions, Orkney Islands, 2009-2011



Sensor heading  $\alpha$ : 196° from North Imaging time: 6:41 UTC



AS Mode		
Az. sampling freq. prf	6680 Hz	
Range bandwidth B <sub>rg</sub>	300 MHz	
Polarization	VV	
Incidence angle $\vartheta$	31.4°	
ATI baseline <i>B<sub>eff</sub></i>	1.02 m	
Swath width	5 km	

Data takes: 1 each 11 days 10/09-02/11 (with gaps)

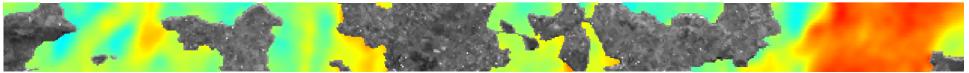
DRA Mode	
Az. sampling freq. prf	3420 Hz
Range bandwidth B <sub>rg</sub>	165 MHz
Polarization	НН
Incidence angle $\mathcal{G}$	31.2°
ATI baseline B <sub>eff</sub>	1.15 m
Swath width	32 km

Data takes: 5 in 2010 (experimental campaign)

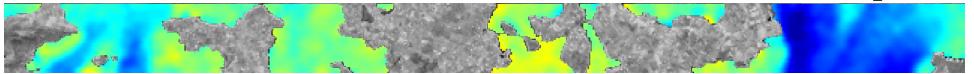


### Surface Current Velocities from TerraSAR-X ATI (AS-Mode) Orkney Islands, 2009

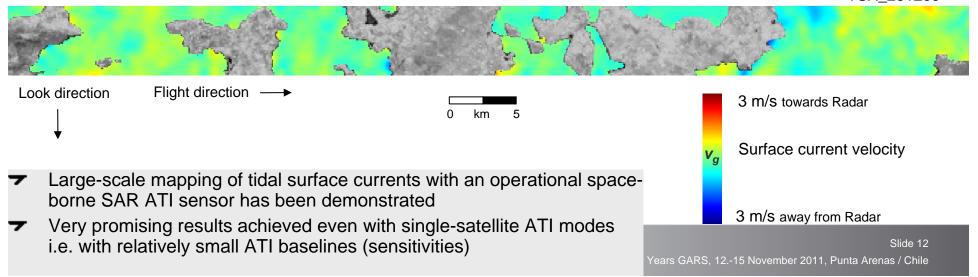
TSX\_121109



TSX 231109

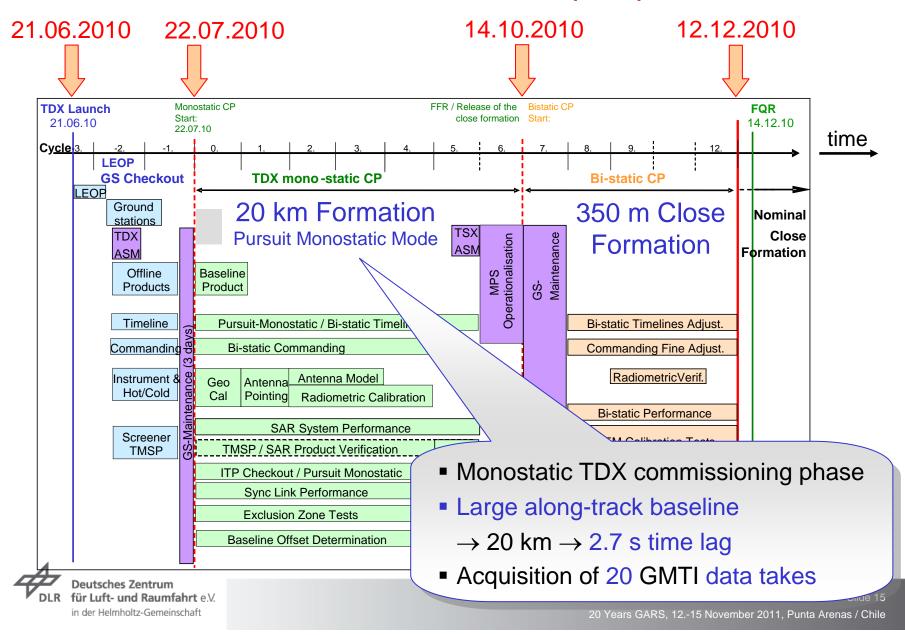


TSX\_261209



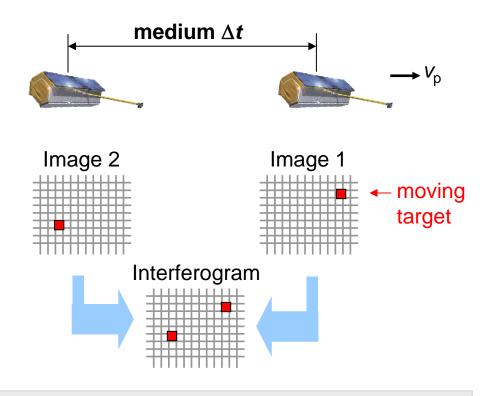


• Pursuit Monostatic TSX-1 TDX-1 Phase (2.7 s), Dual satellite





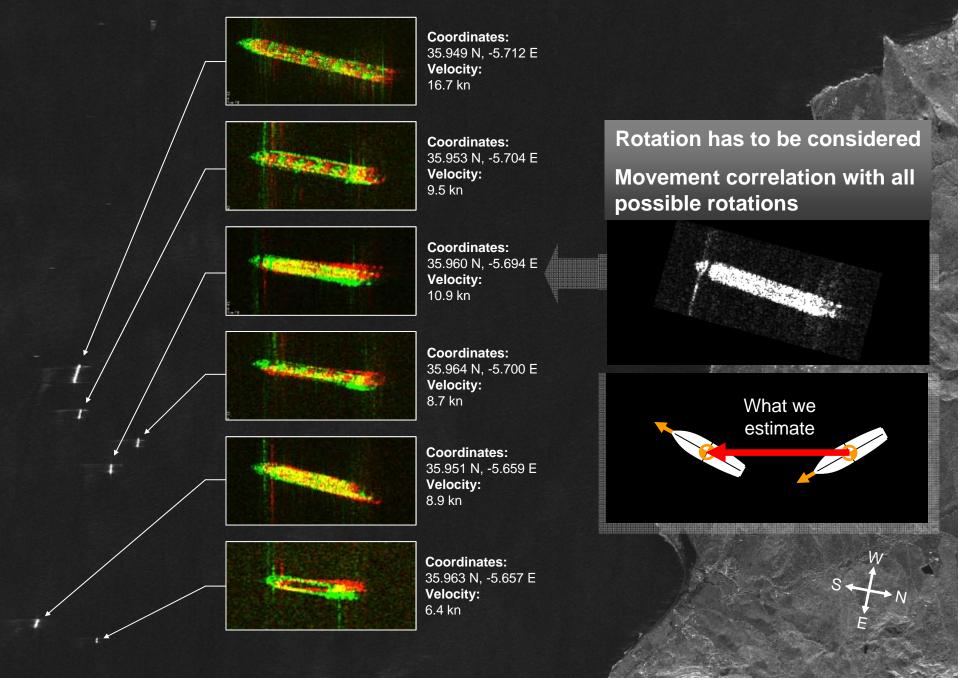
• Medium Along-Track Baseline



- → Medium baseline →  $\Delta t \cong s$ 
  - ➤ Moving target leaves res. cell
  - → 2D velocity estimation, by speckle tracking
  - Medium-Along Track Baseline GMTI

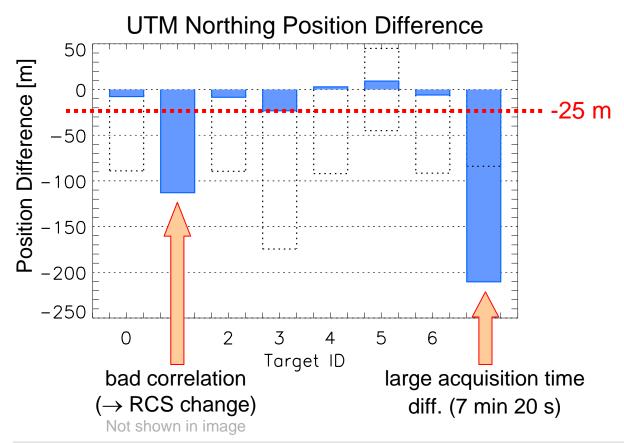
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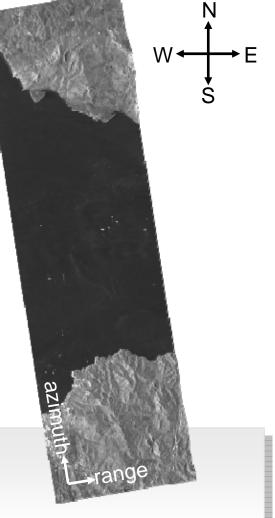
#### First Results: StripMap Vessel Monitoring in the Strait of Gibraltar



### Verification Using AIS Data as Reference $\rightarrow$ First Results (I)

Position estimated with extrapolated AIS velocity

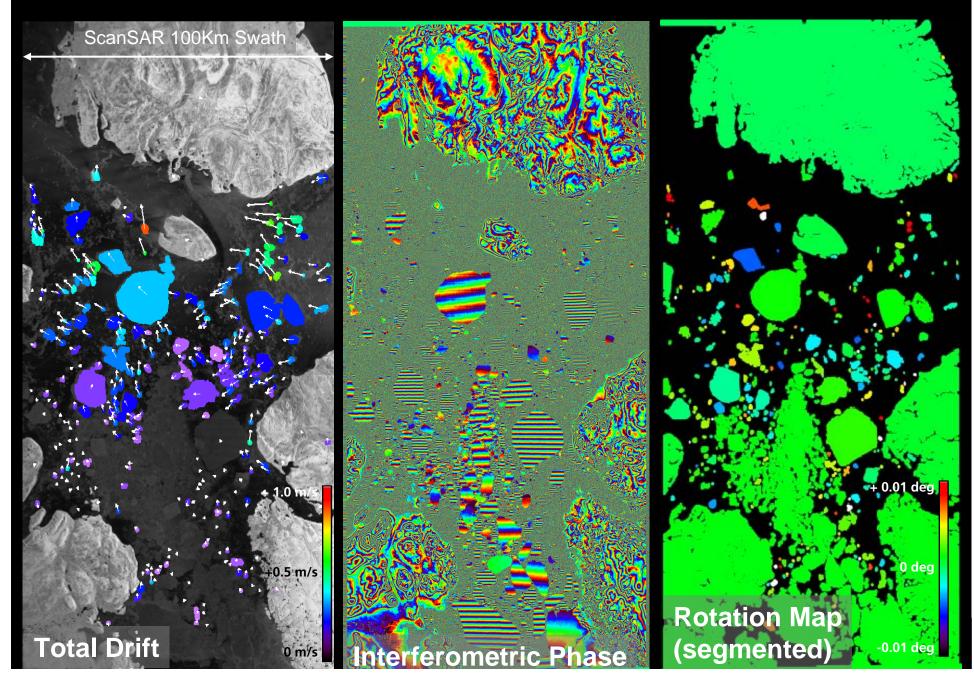




- ✓ Vessels have moved mainly in range direction
  - ➤ Northing pos. difference ~ azimuth re-positioning error
  - ✓ "True azimuth position is more difficult to estimate than range position!"

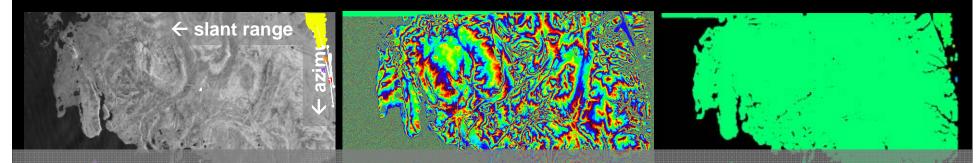
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### Cornwallis-Island: North-West Passage



Aug 2, 2010, 13:13:37

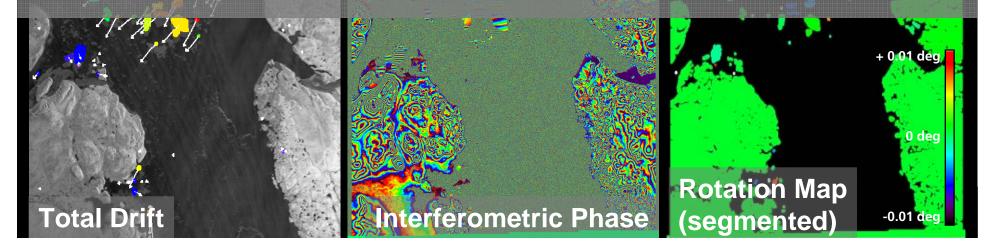
### Cornwallis-Island: North-West Passage



Aug 13. 2010. 13:13:37

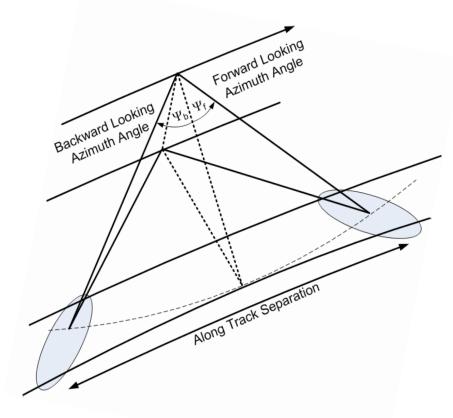
summer, 11 days late

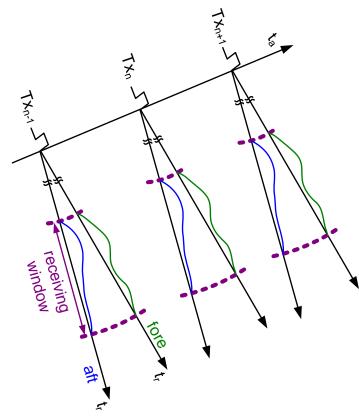
First ever possibility for instantaneous sea ice drift measurements.
Importance of ice sheet rotation, in addition to ice drift measurements.
Possibility of high resolution, short term ice drift predictions.
ScanSAR data acquisition is feasible and essential for large area coverage.
Next possibility for suitable TDX-TSX data acquisition hopefully in 2013.





#### • Bi-directional SAR (BiDi), 6s time separation, Single Satellite





- azimuth beam shaping into two (or more) directions, e.g. forward and backward
- simultaneous reception of both images in time domain
- image separation in Doppler domain

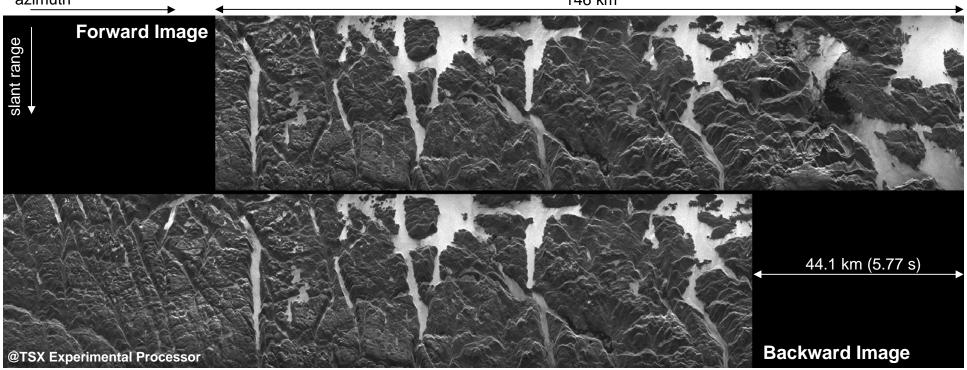




#### **Bi-directional SAR Experiment (July 2009)**

azimuth

146 km



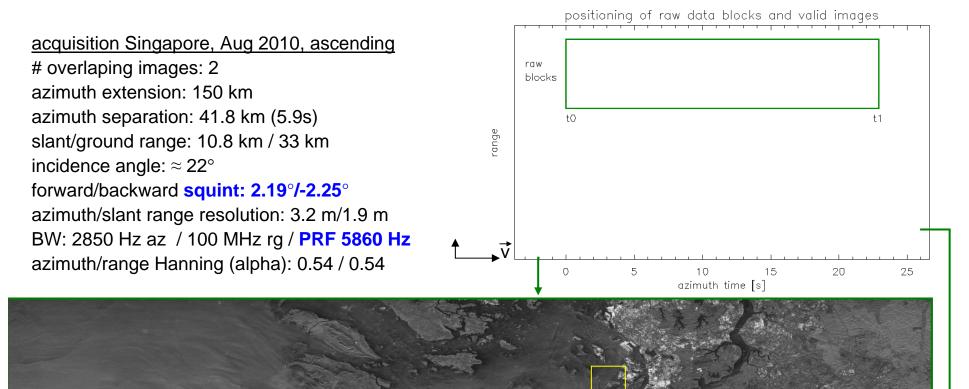
#### BiDi SAR provides repeated acquisitions with one satellite and one channel within seconds

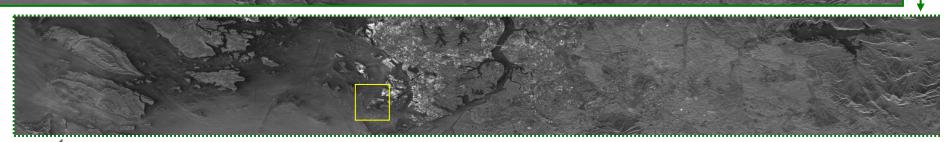
Ref.: J. Mittermayer, S. Wollstadt, "Simultaneous Bi-directional SAR Acquisition with TerraSAR-X", Proc. of EUSAR 2010, Aachen, Germany.

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### **BiDi SAR – Singapore Acquisition Example**





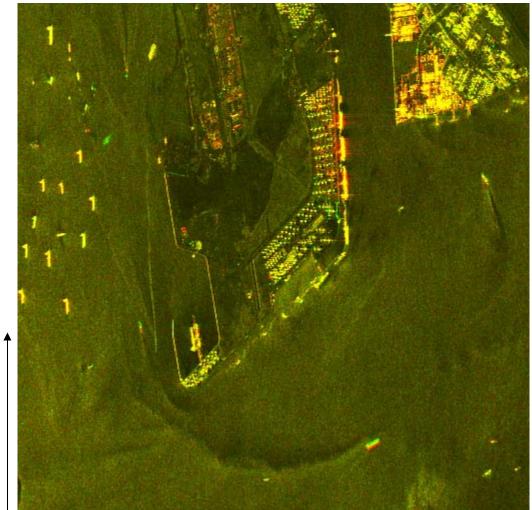




#### Fore and Aft Image Overlay

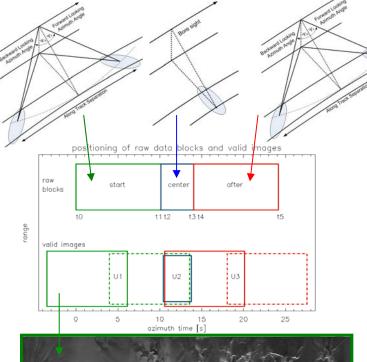
- colour composite of fore (red) and aft (green) image sections from single TerraSAR-X overflight
- equal backscatter combines yellow
- considerably differences in backscatter behaviour at 4.4° aspect angle difference
- motion of ships visible
- 2D motion measurement is principally possible with one satellite, one pass, one channel
- Future: ScanSAR principally possible

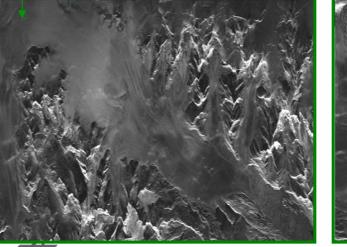
# azimuth



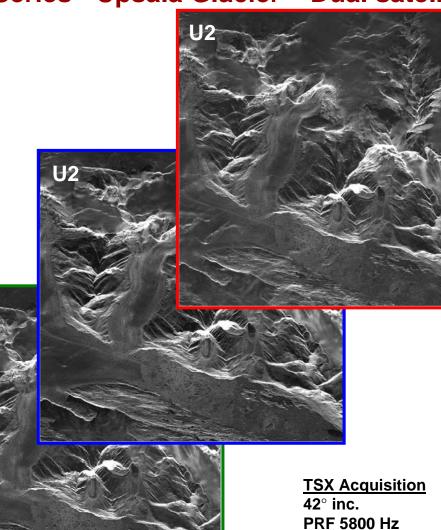








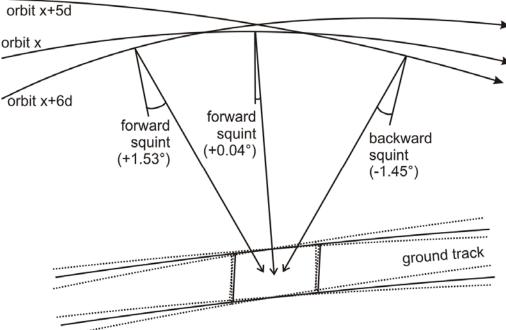
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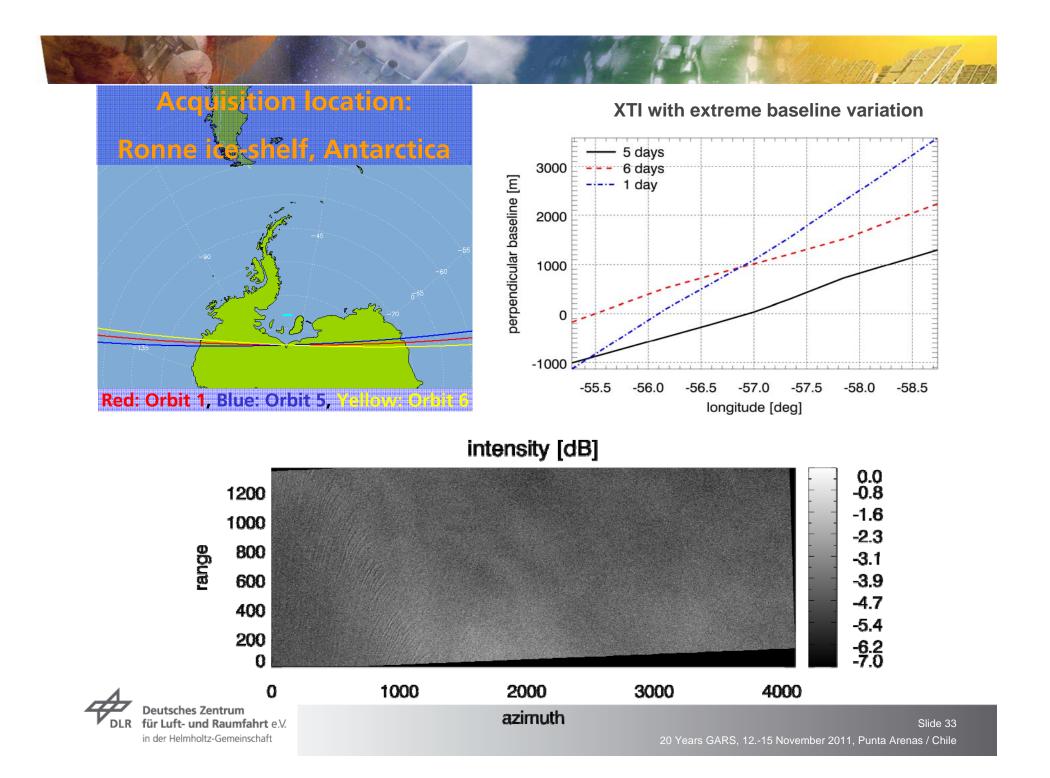
short time series 0s 3.6s 7.2s

### Crossing Orbit Interferometry SAR, 1d or 5d or 6d time separation, Single Satellite

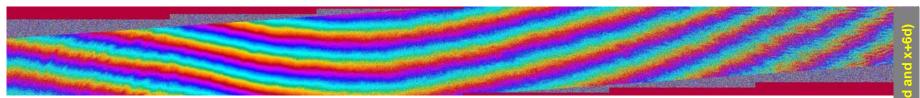
- Motivation
  - ✓ Shorter revisit times than the repeat pass cycle of 11days
- ✓ Method
  - ✓ Utilize neighbored orbits for data acquisition, i.e. overlapping range spectra
  - ➤ Neighbored orbits appear after 5 and 6 days
  - Squinted azimuth beams are enabling the acquisition of scenes with of overlapping ground spectra
- ✓ Crossing angles
  - → 2.1° after 5d and 6d
  - → 4.2° after 1d (x+5d and x+6d)
- → Constraints
  - Only possible at high latitudes
  - ➤ North: 84.5° to 88°
  - → South: -75° to -80°











Zero baseline decorrelation sources: Only noise and temporal decorrelation Large baseline: Large volume decorrelation (geometric decorrelation addressed by azimuth adaptive range spectral filtering)

Zero baseline Decorrelation sources: Only noise and temporal decorrelation

- **7** Fringe rate is proportional to time-lag
  - ✓ Fringes indicate velocity gradients (velocity itself is ambiguous).
  - ✓ Velocity can be estimated from speckle tracking
- Coupling between height uncertainty and varying baseline introduces azimuth phase ramp



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### TanDEM-X first DEM was acquired with crossing orbit method

- Along track (~200 km, 28.5 s) separation results in crossing ground-tracks due to Earth Rotation
- 0.13° relative squint required
- ~2 km resulting effective baseline
- h<sub>amb</sub> = 3.8 m
- Relative height accuracy in the order of 10 cm





#### Conclusions

#### ✓ Modes with higher coverage with single satellite

- → 8 Beam ScanSAR
- - ➤ not so good performance

#### ➤ Modes for Surface Movement Estimation

- ✓ ATIS 0.1 ms time separation, single satellite
- ✓ Pursuit Monostatic 3 s time separation, dual satellite, special formation
  - ✓ StripMap; 2D Velocity and rotation measurements of small targets (ships)
  - ✓ ScanSAR; 2D Velocity and rotation measurements of areas (iceberg)
- → BiDiSAR 6 s time separation; Single and dual satellite
  - ✓ Scattering of different aspect angles
  - ✓ 2D Velocity measurements
- ✓ Crossing Orbits 1 d or 5 d or 6 days time separation; Single and dual satellite
  - ➤ Along-track variable baselines





#### **Experimental Radar Modes with TerraSAR-X and TanDEM-X: Contacts**

- ➤ Modes with higher coverage with single satellite
  - ✓ 8 Beam ScanSAR and 8 WideBeam ScanSAR
- ➤ Modes for Movement Estimation
  - ✓ ATIS 0.1 ms time separation, ocean current measurement with single satellite
  - Pursuit Monostatic 3 s time separation, dual satellite, special formation
    - StripMap; 2D Velocity and rotation measurements of small scatters (ships)
      - ✓ Stefan Baumgartner
    - ➤ ScanSAR; 2D Velocity and rotation measurements of areas (iceberg)
  - → BiDiSAR 6 s time separation; Single and dual satellite

    - ✓ 2D Velocity measurements
  - ✓ Crossing Orbits 1 d or 5 d or 6 days time separation; Single and dual satellite
    - ✓ Time variable baselines