



Calculating the IR radiation distribution in a large 3D scene

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ITBM&S 2010, Ettlingen



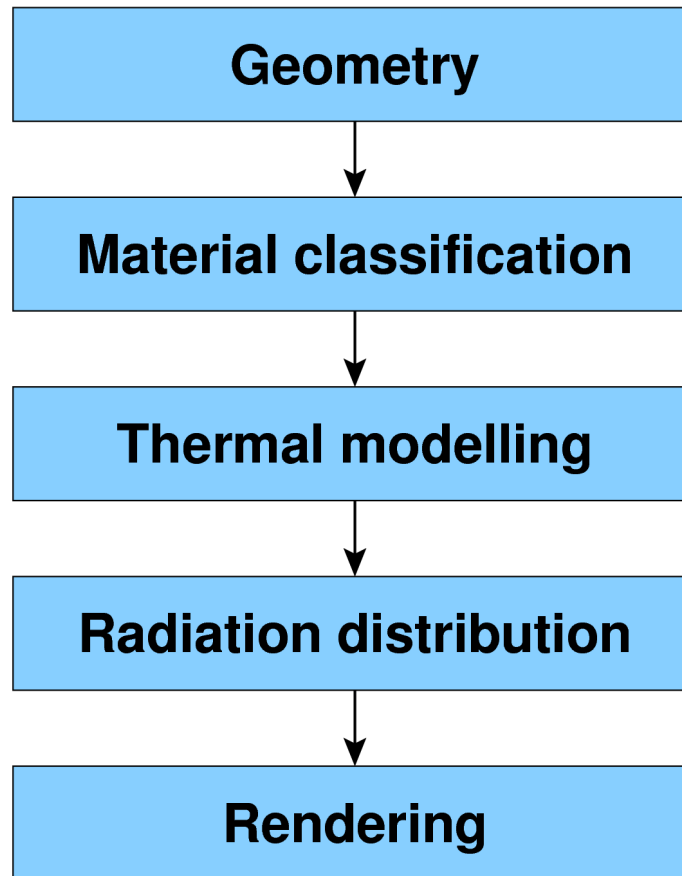
DLR

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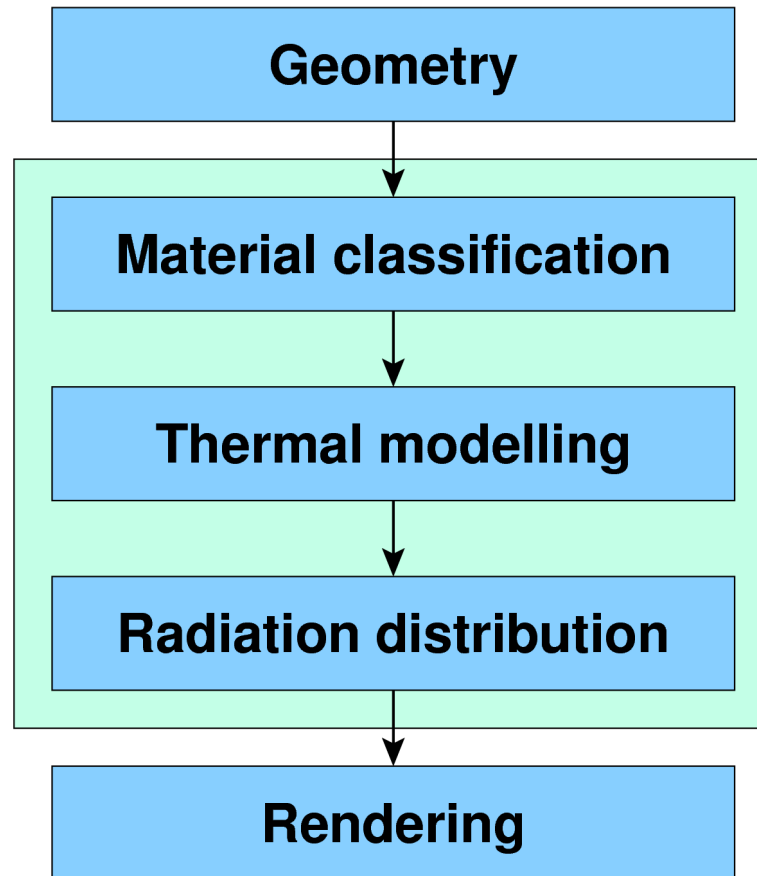
MBDA

MISSILE SYSTEMS

Workflow



Workflow





Evaluation of radiation distribution (RD) / rendering

- Often calculation of RD and rendering is just one step
- But radiation can be split into
 - a **view-independent** component, which is calculated **once** for a scene → **radiosity method**
 - a **view-dependent** component, which has to be **re-calculated** each time the viewer changes position or direction → **raytracing**



Radiosity Method

- Objective: calculation of the radiation distribution
- Assumptions: 1) Every reflection is **Lambertian**
2) Geometry is **discretized** into small polygons
(= *patches*)
- Advantages: 1) **Isotropic** problem
2) Integration is replaced by a physically sensible **summation** (over patches)

Radiosity Method

- Rendering equation turns into **radiosity equation**

$$B_i = E_i + \rho_i \sum_j F_{ij} B_j$$

- B_i = **radiosity** of patch i

- E_i = **emittance** of patch i

- ρ_i = **reflectivity** of patch i

- F_{ij} = **form factors**: "how much does patch i see of patch j ?"

For N patches in the scene, $2N^2$ form factors have to be calculated!

Implementation of radiosity method

➤ Radiosity algorithm from scratch?

- input/output data format ?
- several algorithms have to be implemented (occlusion, form factors, numerical solution of the radiosity equation)

→ ***Use existing software, RadThermIR's signature solution***

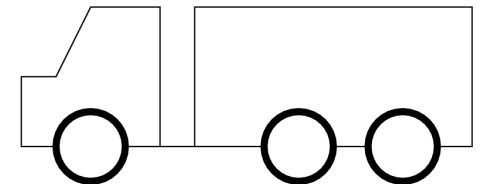
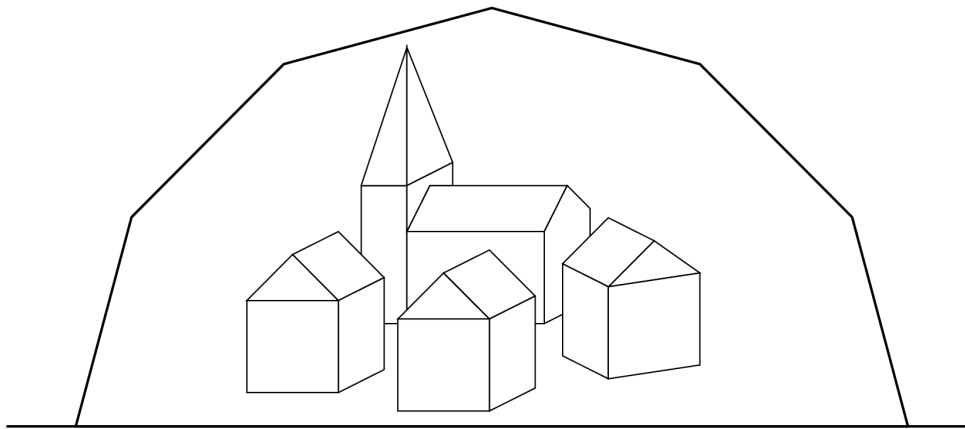
- + thermal solver output can be processed directly
- + all necessary algorithms contained

But how can large scenes be loaded and computed by RadThermIR?



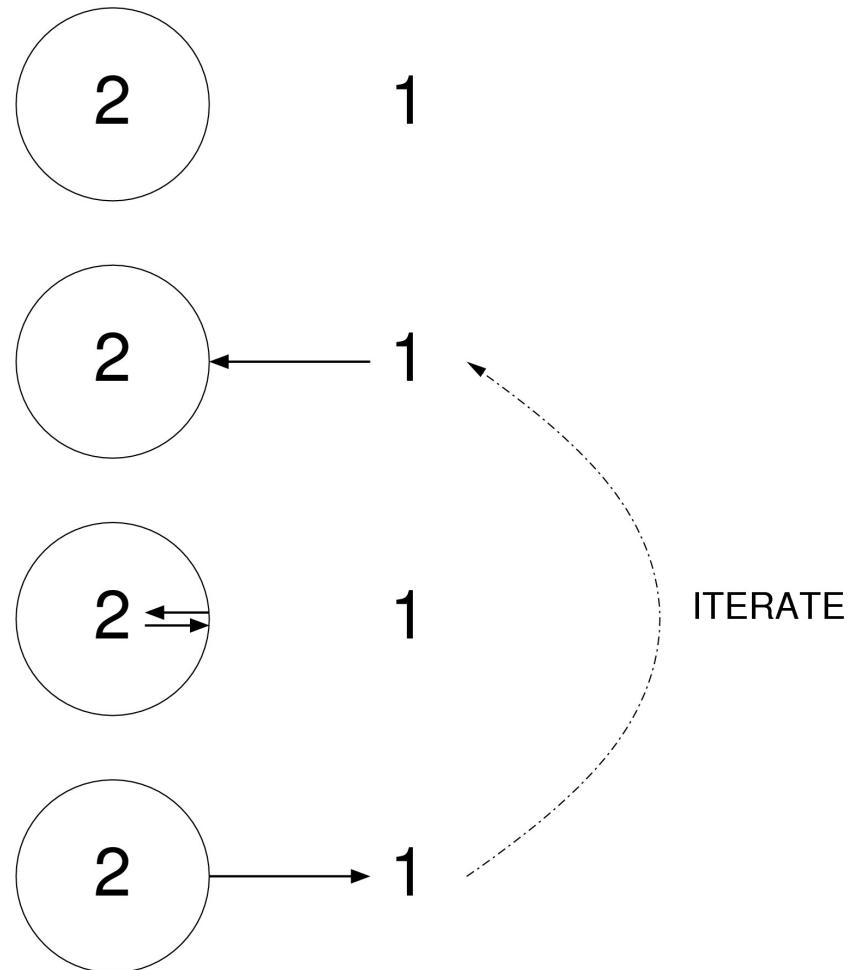
Clustering method

- **subdivision of the scene**
- fine-structured regions are replaced by domes (= clusters)
- these clusters are modeled separately in RadThermIR (thermal and radiative)
- use an iterative scheme for interaction of subscenes and large scene



Clustering method

➤ Scheme of interactions:





Clustering method

- What are the benefits?
 - number of patches per calculation is reduced
 - less form factors have to be computed
 - parts of the scene can be created independently of the rest



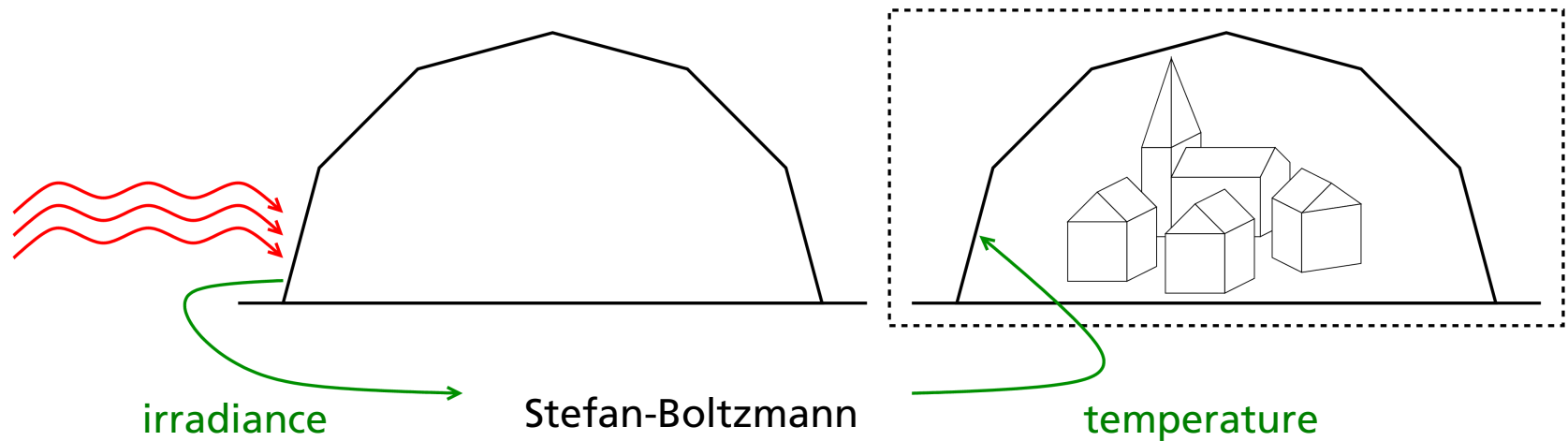
Clustering method

➤ Thermal solving

- domes are black bodies
- thermal radiation received by each dome patch is read off via tdfio library function
- translate these irradiances into temperatures via Stefan-Boltzmann law
- set these as initial temperatures for the dome in the cluster
- after processing the cluster, temperatures are transferred back to the main scene in the same way

Clustering method

➤ transferring thermal radiation





Clustering method

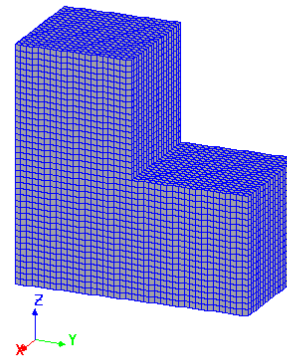
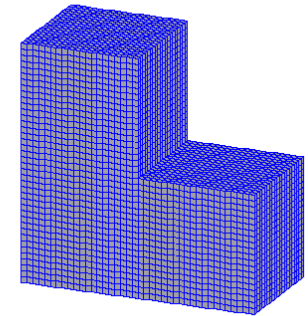
➤ signature solution

- proceed analogously to the case of thermal solving
- open problem: spectral radiances on the dome cannot be set by tdfio directly

Clustering method

- original scene
- 2 CUBI models, scaled by factor 100 (i.e. base 100 m x 50 m)
- Distance 500 m

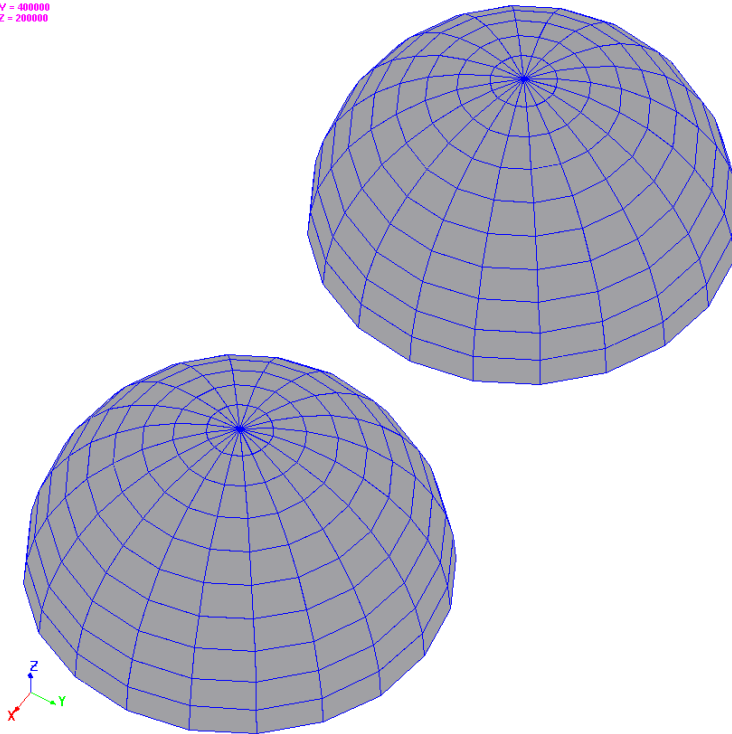
Model size (mm):
X = 550000
Y = 100000
Z = 100000



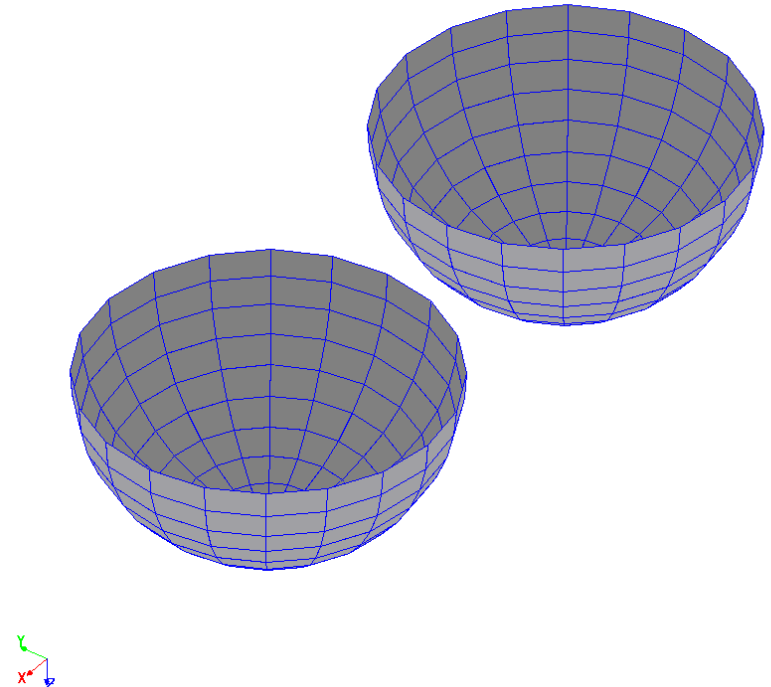
Clustering method

➤ **clustered scene**, 2 domes representing the geometry

Model size (mm):
X = 900000
Y = 400000
Z = 200000



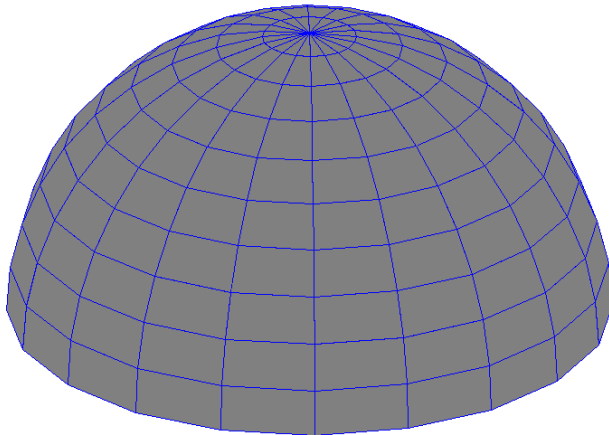
Model size (mm):
X = 900000
Y = 400000
Z = 200000



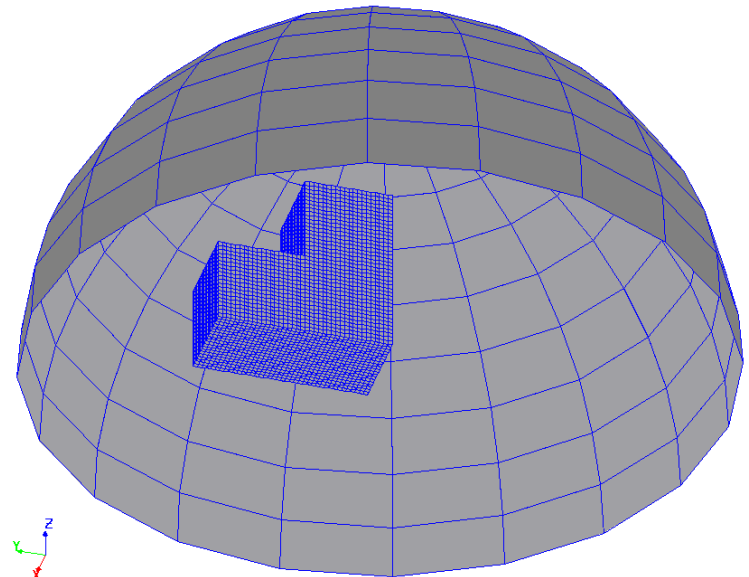
Clustering method

➤ one of the clusters with geometry inside

Model size (mm):
X = 400000
Y = 400000
Z = 200000



Model size (mm):
X = 400000
Y = 400000
Z = 200000





Summary and Conclusion

- IR scene simulation requires knowledge of RD
- thermal influences on RD are modeled by RadThermIR thermal solver and signature solution
- clustering method is useful to calculate large scenes by subdividing them

What has to be done?

- comparison of temperatures and RD in original vs. clustered scene
- automation (placement of clusters, mapping to the original scene)
- integration into workflow

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