Digital Beamforming and Non-Uniform Displaced Phase Centre Sampling in Bi- and Multistatic SAR

Gerhard Krieger, Nicolas Gebert, Alberto Moreira
Microwaves and Radar Institute, German Aerospace Centre (DLR), Oberpfaffenhofen, Germany

Abstract
The displaced phase centre (DPC) technique will enable a wide swath SAR with high azimuth resolution. In a classic DPC system, the PRF has to be chosen such that the SAR carrier moves just one half of its antenna length between subsequent radar pulses. Any deviation from this PRF will result in a non-uniform sampling of the synthetic aperture. This paper shows that an unambiguous reconstruction of the SAR signal is also possible in case of such a non-optimum PRF. For this, an innovative reconstruction algorithm is derived, which enables a recovery of the unambiguous Doppler spectrum also in case of a non-uniform sampling of the synthetic aperture. This algorithm will also have a great potential for multistatic satellite constellations as well as the dual receive antenna mode in Radarsat 2 and TerraSAR-X.

1 Introduction
Wide swath imaging and high azimuth resolution pose contradicting requirements on SAR system design. To overcome this fundamental limitation, several innovative techniques have been suggested which use multiple receiver apertures to acquire additional samples along the synthetic aperture. The apertures may be either on a single platform like in the classical Displaced Phase Centre (DPC) technique [1]-[6] or on different platforms [7]-[9] leading to a multistatic SAR where the size of each individual receiver is reduced. Fig. 1 shows one example for each scenario, where a single transmitter illuminates a wide swath and n sub-apertures record simultaneously the scattered signal from the illuminated footprint. Under ideal conditions, this will allow for a reduction of the PRF by a factor of n without rising azimuth ambiguities. This reduction of the azimuth sampling rate becomes possible by a coherent combination of the individual receiver signals where the ambiguous parts of the Doppler spectra cancel each other. Note that such an ambiguity suppression can also be regarded as digital beamforming on receive where nulls in the joint antenna pattern are steered to the ambiguous zones. For optimum performance, the along-track displacement of the sub-apertures \( i=\{2,...,n\} \) relative to the first receiver \( (i=1) \) should be chosen as

\[
x_i - x_1 \approx \frac{2v}{PRF} \left( \frac{i-1}{n} + k_i \right) \quad k_i \in Z
\]

which will result in a uniform sampling of the received SAR signal. In this equation, \( PRF \) is the pulse repetition frequency of the transmitter and \( v \) is the velocity of the SAR carrier. Note that for a multistatic constellation the \( k_i \) may be different for each receiver, which enables a great flexibility in choosing the along-track distance between the satellites. In a single platform system, all \( k_i \) will be zero. Since the sub-aperture distance and the platform velocity are fixed in this case, a specific \( PRF \) will be required:

\[
PRF = \frac{2v}{n \cdot \Delta x}
\]

where we assume an antenna with \( n \) sub-aperture elements separated by \( \Delta x=x_{i+1}-x_i \). The \( PRF \) in a single-platform DPC system has thus to be chosen such that the SAR platform moves just one half of the total antenna length between subsequent radar pulses. However, such a rigid selection of the PRF may be in conflict with the timing diagram for some incident angles. It will furthermore exclude the opportunity to use an increased \( PRF \) for improved azimuth ambiguity suppression.
2 General Approach

In the following, an innovative reconstruction algorithm will be derived which allows for an unambiguous recovery of the Doppler spectrum even for a non-uniform sampling of the SAR signal. The only requirement is, that the samples do not coincide. Such an algorithm has a great potential for any multi-aperture system, be it monostatic with sparsely distributed receiver satellite or be it a classic DPCA system like Radarsat 2 [5] or TerraSAR-X [6]. The data acquisition in a multiple aperture SAR can be considered as a linear system with multiple receiver channels, each described by a linear filter \( h_i(t) \) with transfer function \( H_i(f) \) (cf. Fig. 2). For such a system exist a lot of powerful theorems in linear systems theory. Of special importance for the present context is a generalization of the sampling theorem according to which a band-limited signal \( u(t) \) is uniquely determined in terms of the samples \( h_i(nT) \) of the responses \( h_i(t) \) of \( n \) linear systems with input \( u(t) \) sampled at \( 1/n \) of the Nyquist frequency [10]. In order to be valid, the transfer functions of the linear filters may be selected in a quite general sense, but not arbitrarily (for details, see [10]). A block diagram for the reconstruction from the subsampled signals is shown in Fig. 2. The reconstruction consists essentially of the transfer functions of the linear filters \( H_i(f) \) which are individually applied to the subsampled signals of the receiver channels and then superimposed. Each of the reconstruction filters \( P_i(f) \) can again be regarded as a composition of \( n \) bandpass filters \( P_{ij}(f) \) where \( 1 \leq i \leq S \), as shown in [10], the reconstruction filters can be derived from a matrix \( \mathbf{H}(f) \) consisting of the \( n \) transfer functions \( H_i(f) \) which have to be shifted by integer multiples of the PRF in the frequency domain:

\[
\mathbf{H}(f) = \begin{bmatrix}
    H_0(f) & \ldots & H_{S}(f) \\
    H_0(f + PRF) & \ldots & H_{S}(f + PRF) \\
    \vdots & \ddots & \vdots \\
    H_0(f + (n-1) \cdot PRF) & \ldots & H_{S}(f + (n-1) \cdot PRF)
\end{bmatrix}
\]

The reconstruction filters \( P_i(f) \) are then derived from an inversion of the matrix \( \mathbf{H}(f) \) as:

\[
\mathbf{H}^{-1}(f) = \begin{bmatrix}
    P_0(f) & P_0(f + PRF) & \ldots & P_0(f + (n-1) \cdot PRF) \\
    P_1(f) & P_1(f + PRF) & \ldots & P_1(f + (n-1) \cdot PRF) \\
    \vdots & \vdots & \ddots & \vdots \\
    P_S(f) & P_S(f + PRF) & \ldots & P_S(f + (n-1) \cdot PRF)
\end{bmatrix}
\]

3 Quadratic phase approximation

In principle, it is possible to use the multi-channel SAR signal model for a complete reconstruction of the scene reflectivity. However, in order to concentrate on the essential steps, we will only consider the azimuth modulation in the following derivation. The azimuth signal of a point target at azimuth time \( t = 0 \) and slant range \( r_0 \) for each individual receiver channel \( i \) may be described as:

\[
h_i(t, \Delta r) = A_{r_i}(v_t) \cdot A_{b_i}(v_t) \cdot \exp \left[ -j \frac{2\pi}{\lambda} \left( \sqrt{v_t^2 + (\Delta r)^2} + \sqrt{v_t^2 + (\Delta r - \Delta v)^2} \right) \right]
\]

where \( A_{r_i} \) and \( A_{b_i} \) define the envelope of the azimuth signal arising from the projection of the transmit and receive antenna patterns on the ground. The phase of the azimuth signal is proportional to the sum of the transmit and receive paths which are here approximated by the two square roots assuming a straight flight path with velocity \( v_t \). A further simplification arises if we expand (5) in a Taylor series up to the second order which will lead to the quadratic approximation:

\[
h_i(t, \Delta r) \approx A_{r_i}(v_t) \cdot A_{b_i}(v_t) \cdot \exp \left[ -j \frac{2\pi}{\lambda} \left( \frac{\Delta v r_0}{2 v_t} \right)^2 + \frac{2 v_t^2}{\lambda} \left( \frac{\Delta v r_0}{2 v_t} \right) \right]
\]

Here, the first exponential describes a constant phase offset for a given slant range \( r_0 \) which is equal for all receivers while the second exponential accounts for an additional constant phase offset which is due to the different along-track displacements between each individual receiver and the transmitter. The time-varying azimuth modulation of the bistatic SAR is then given by the third exponential. By comparing (6) with the point target response of a monostatic SAR

\[
h_{i}(t) = A_{r_i}(v_t) \cdot A_{b_i}(v_t) \cdot \exp \left[ -j \frac{2\pi}{\lambda} \left( \frac{\Delta v r_0}{2 v_t} \right)^2 + \frac{2 v_t^2}{\lambda} \left( \frac{\Delta v r_0}{2 v_t} \right) \right]
\]

it becomes clear that the bistatic azimuth response evolves from its monostatic counterpart by a time delay \( \Delta t = \Delta \tau / 2v \) and a phase shift \( \Delta \phi = -\pi \Delta \tau^2 / 2v_0^2 \) if we substitute the antenna footprints \( A_{r_i} \) and \( A_{b_i} \) by \( A_{TX}(v_t) = A_{r_i}(v_t + \Delta v_t / 2) \) and \( A_{RX}(v_t) = A_{b_i}(v_t + \Delta v_t / 2) \). The bistatic antenna footprint is then given by
Therefore, the multiple aperture system can be regarded as a monostatic SAR which is followed by additional time and phase shifts for each receiver channel. This is illustrated in Fig. 3. Since the joint antenna footprint may be different for each receiver, we have introduced a separate amplitude weighting of the azimuth spectrum in each channel, but it is also possible to separate the joint antenna pattern in two parts where a first weighting function in the monostatic SAR response accounts for a weighting of the Doppler spectrum which is common to all receivers and the second transfer function in each channel accounts for residual deviations between the individual receivers. These deviations may for example result from different Doppler centroids due to the different along-track displacements, inaccuracies in the antenna pointing, or a mutual coupling between the antenna sub-arrays in case of a single platform DPC system. It may be expected, that such a separation in two transfer functions will have an impact on the stability of the signal reconstruction, but this topic deserves further investigation.

4 Analytic Example

As a simple example for an analytic derivation of the reconstruction filters we consider a bistatic SAR with two receiver channels having the same azimuth antenna pattern. This two-channel system may serve as an example for the unambiguous recovery of the Doppler spectrum resulting from a SAR signal recorded by the split antenna technique in TerraSAR-X and Radarsat 2. Since it is possible to incorporate the transfer function due to the antenna pattern into the monostatic SAR response, the remaining difference between the two-channels is given by the two impulse responses

\[ b_1(t;\Delta_x) = \exp\left(-\frac{\pi \Delta_x^2}{2\lambda_0}\right) \delta\left(t - \frac{\Delta_x}{2v}\right) \]

and

\[ b_2(t;\Delta_x) = \exp\left(-\frac{\pi \Delta_x^2}{2\lambda_0}\right) \delta\left(t - \frac{\Delta_x}{2v}\right) \]  

In the frequency domain, these impulse responses correspond to

\[ H_1(f;\Delta_x) = \exp\left(-\frac{\pi \Delta_x^2}{2\lambda_0}\right) \exp\left(-j\frac{\pi \Delta_x}{2\nu}\right) \]

and

\[ H_2(f;\Delta_x) = \exp\left(-\frac{\pi \Delta_x^2}{2\lambda_0}\right) \exp\left(-j\frac{\pi \Delta_x}{2\nu}\right) \]

The reconstruction filters \( P_1(f) \) and \( P_2(f) \) are then

\[ P_1(f) = \frac{\exp\left(j\pi \frac{\Delta_x}{\nu}\right)}{1 - \exp\left[j\pi \frac{\Delta_x}{\nu}\right]} \] for \( -\nu < f < 0 \)

\[ P_2(f) = \frac{\exp\left(j\pi \frac{\Delta_x}{\nu}\right)}{1 - \exp\left[j\pi \frac{\Delta_x}{\nu}\right]} \] for \( -\nu < f < 0 \)

and

\[ P_2(f) = \frac{\exp\left(j\pi \frac{\Delta_x}{\nu}\right)}{1 - \exp\left[j\pi \frac{\Delta_x}{\nu}\right]} \] for \( -\nu < f < 0 \)

\[ P_1(f) = \frac{\exp\left(j\pi \frac{\Delta_x}{\nu}\right)}{1 - \exp\left[j\pi \frac{\Delta_x}{\nu}\right]} \] for \( -\nu < f < 0 \)
5 Simulation Results

First simulation results of the suggested reconstruction algorithm in case of a multistatic satellite array with three receivers have been presented in [11]. Here, we will show some simulation results for the dual receive antenna in TerraSAR-X. The relevant system parameters are summarised in Table 1.

<table>
<thead>
<tr>
<th>Table 1: Parameters for Dual Receive Antenna.</th>
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<tbody>
<tr>
<td>Wavelength</td>
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<tr>
<td>PRF</td>
</tr>
<tr>
<td>Velocity</td>
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<tr>
<td>Antenna Length (Tx)</td>
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<tr>
<td>Number of Subapertures (Rx)</td>
</tr>
<tr>
<td>Sub-Aperture Length (Rx)</td>
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<tr>
<td>Slant Range</td>
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<td>Inter-Channel SNR</td>
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Fig. 4 shows the results for a reconstruction from non-uniform DPCA sampling. For better illustration, an extended scatterer has been chosen in this simulation. Furthermore, independent white noise has been added to each sub-aperture signal to account for differences in the two receiver channels. It becomes clear that the signal from each channel is strongly ambiguous (left) while the coherent reconstruction of the two sub-sampled SAR signals will provide a efficient ambiguity suppression (right). The algorithm has also been tested with real SAR data acquired by the DLR E-SAR system. Since there is currently no displaced phase centre mode in the E-SAR system, monostatic data were used in this example. The data, which have an original sampling frequency $f_s$, were filtered with an ideal low pass of bandwidth $B = f_s / 10$ to get SAR data $u(t)$ over-sampled by a factor of 10. Then, the ambiguous inputs to the two DPCA channels have been formed by taking every 20th sample for each channel. Selecting adjacent samples for the two channels will result in a maximum non-uniform sampling while a distance of 10 samples will yield a uniform sampling. After filtering with $P_j$ and coherent summation, the monostatic SAR processing follows. Fig. 5 compares the reconstruction result for a maximum non-uniform sampling with the SAR image of one ambiguous channel. It is clear, that the ambiguities are well suppressed in the image resulting from the non-uniform DPCA reconstruction.

Fig. 5: Ambiguous image for one channel (left) and reconstruction after non-uniform DPC sampling (right).

6 Conclusions

An innovative algorithm for the suppression of azimuth ambiguities in case of non-uniform DPCA sampling has been derived. This reconstruction algorithm can be regarded as a time-variant digital beamforming on receive, which combines the individual receiver signals in a linear space-time processing. The algorithm is directly applicable to systems relying on the displaced phase centre (DPC) technique, like the Quad Array [2] and HRWS [3] SAR or the dual receive antenna approaches in TerraSAR-X [6] and Radarsat II [5], thereby avoiding any stringent PRF restriction. The algorithm will also be useful for ambiguity suppression in a distributed SAR with multiple receiver satellites. However, any cross-track separation of the receivers will introduce an additional phase in the received signals, which has to be compensated, e.g., via the simultaneous acquisition of a digital elevation model in case of multiple satellites. The processing of these data will then lead to a nonlinear combination of cross-track interferometry and digital beamforming on receive.

7 References