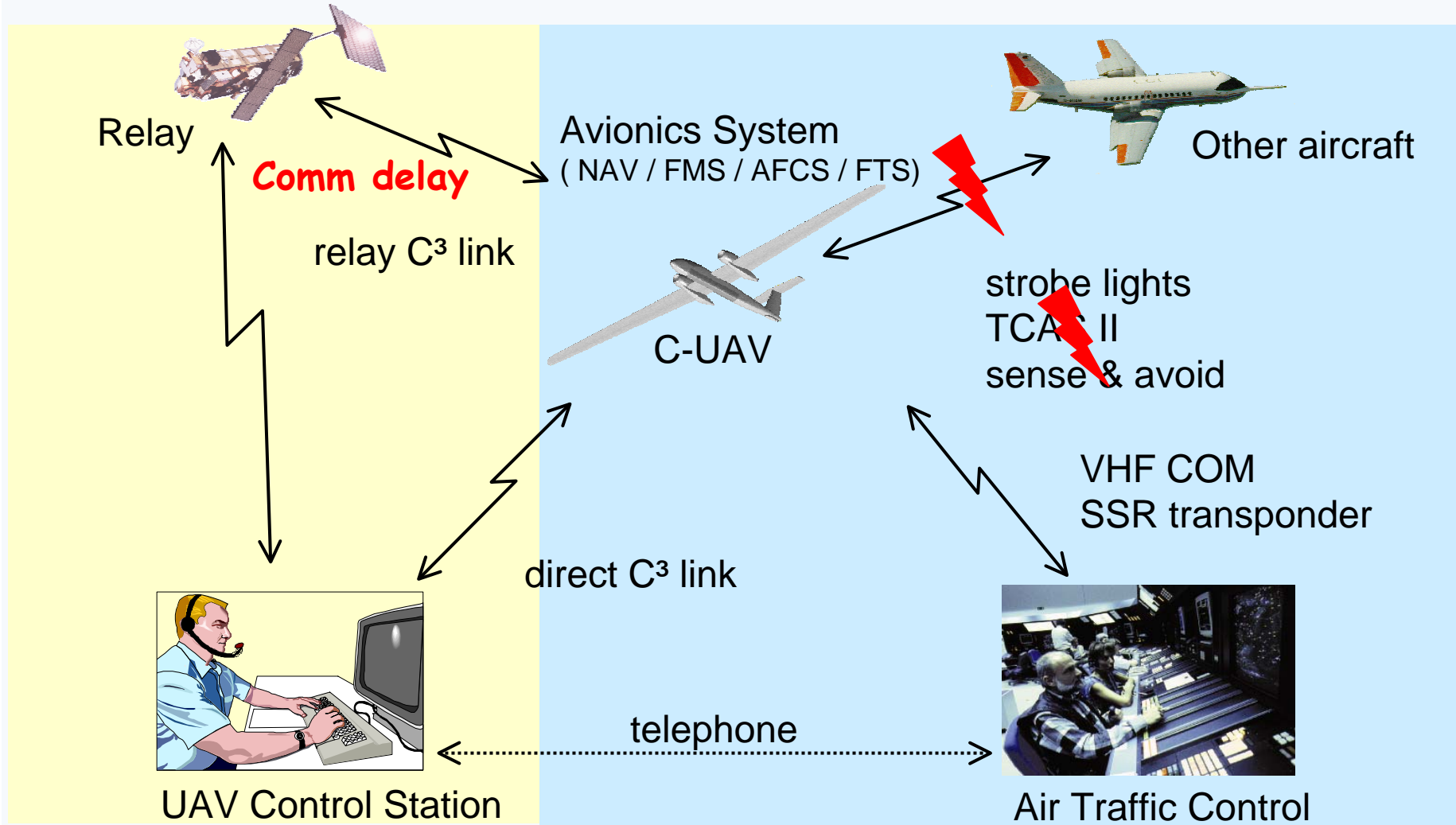


# Integration of UAV into ATC/ATM Introduction in the simulation demonstration

Workshop 19.02.2004

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## Simulation Concept for UAV Integration



## UAV events to be evaluated by simulations

- Loss of Thrust (or other emergency case) : squawk 7700
- Communication Failure
  - Transmitter Failure; squawk 7600
  - Total Communication Failure; squawk 7600
- Data-Link Loss; squawk 7600
- Communication Failure and Data-Link Loss; squawk 7600
- Transponder Failure (loss of altitude information)
- Avoidance of a severe weather ( Thunderstorm )
- Loss of Separation (to be defined)

## Objectives of ATC/ATM Real Time Simulations

Evaluation of the UAV integration concept:

- Normal operations
- Emergency Operations:
  - Standard emergency procedures:
    - Comm Loss
    - Thrust Loss
  - UAV specific emergency procedures
    - (additional emergency codes)

Investigation of UAV specifics:

- Communication delay for voice and data

## Evaluation Methods

### Subjective Measurements

- ISA (Instantaneous Self Assessment)

### Objective Measurements

- Time for Communication
- Others

### Questionnaires

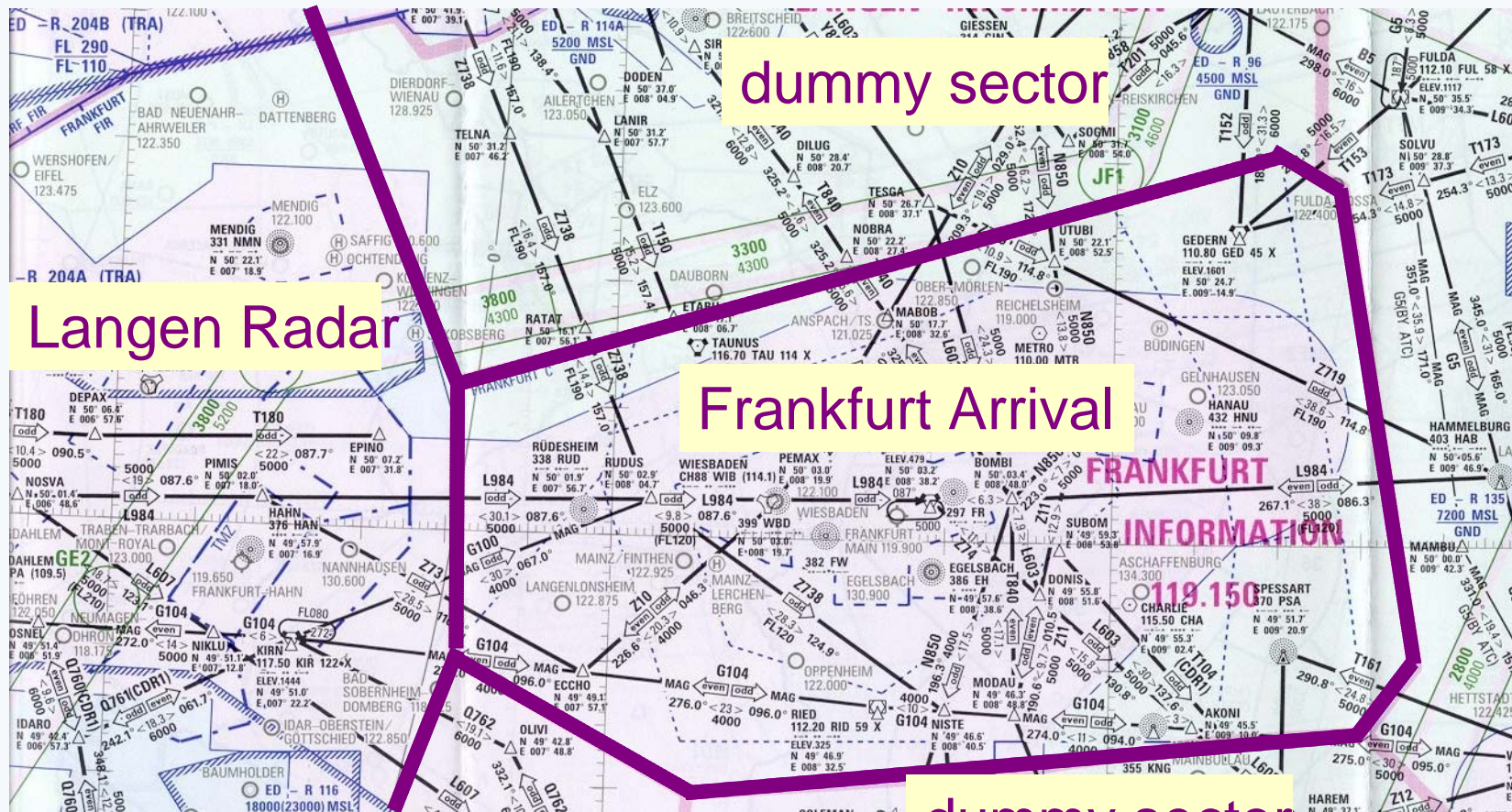
- Post Run Debrief
  - NASA-TLX
  - DFS questionnaire
- Final Debrief Questionnaire

## Simulated Centres

- Frankfurt Arrival (ARR) and Frankfurt Area Control Centre (ACC)
  - west-sector "Langen Radar"
  - radar approach controller "Frankfurt Arrival"

## Simulated Airspace

### FIR Frankfurt: TMA Frankfurt & Sector West (modified)

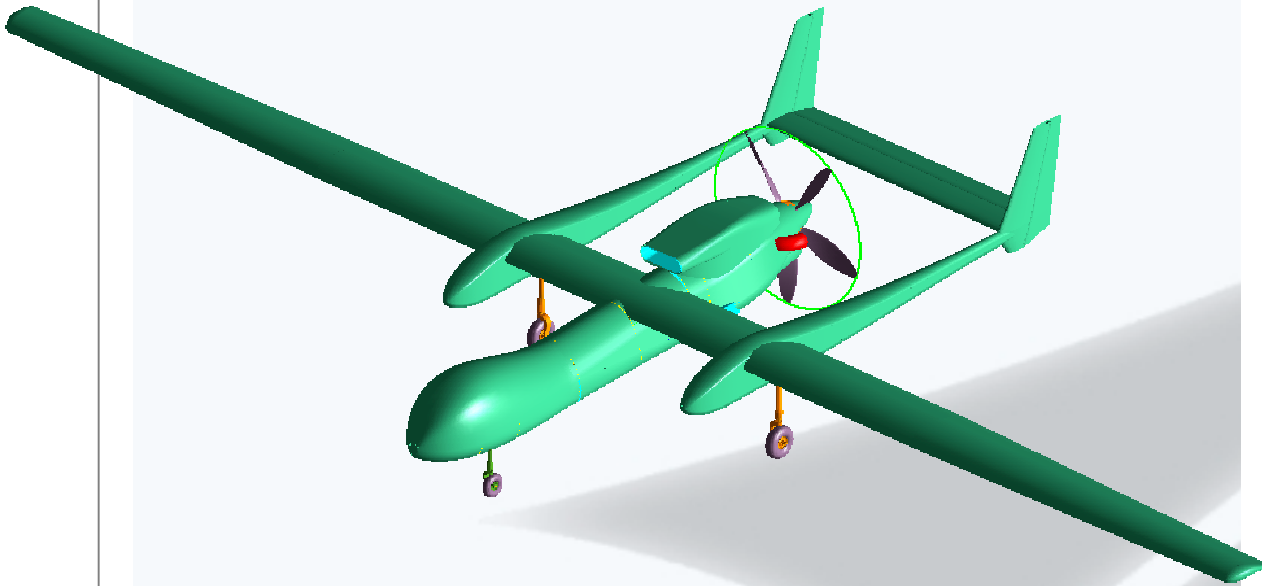


## Simulated Traffic

- Arrival traffic EDDF
- Departure traffic EDDF
- Overflights
- UAV Traffic

Fixed wing MALE departure from West or North from Frankfurt  
Mission requires crossing of TMA Frankfurt

## Simulated MALE UAV

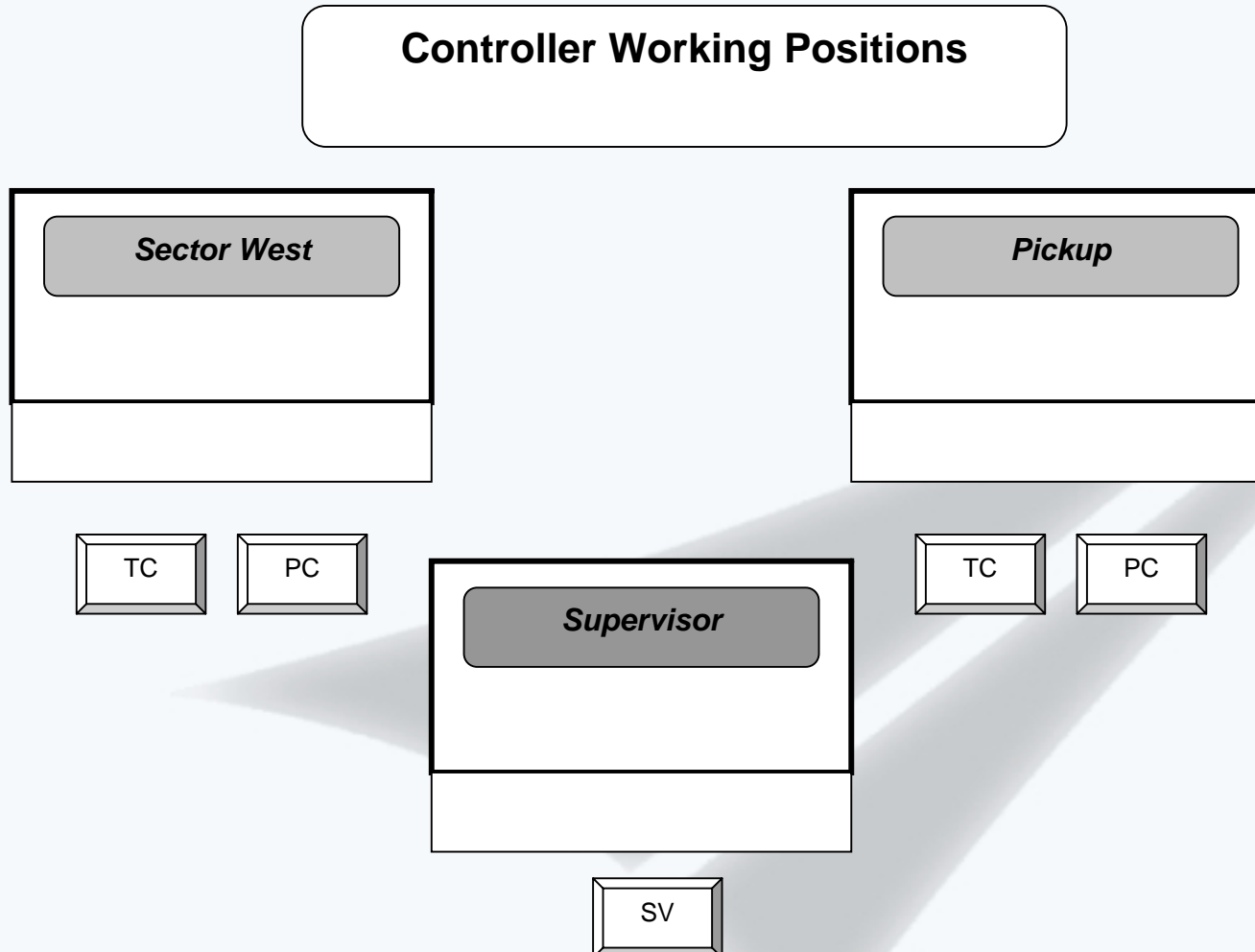


Wing span (m)	22.6
Length (m)	10.68
Normal cruise (kcas)	110
Max. ceiling (ft)	45000

## Controller Working Positions

- Sector West: Langen Radar
- Sector North: dummy
- Sector South: dummy
- TMA: Frankfurt Arrival

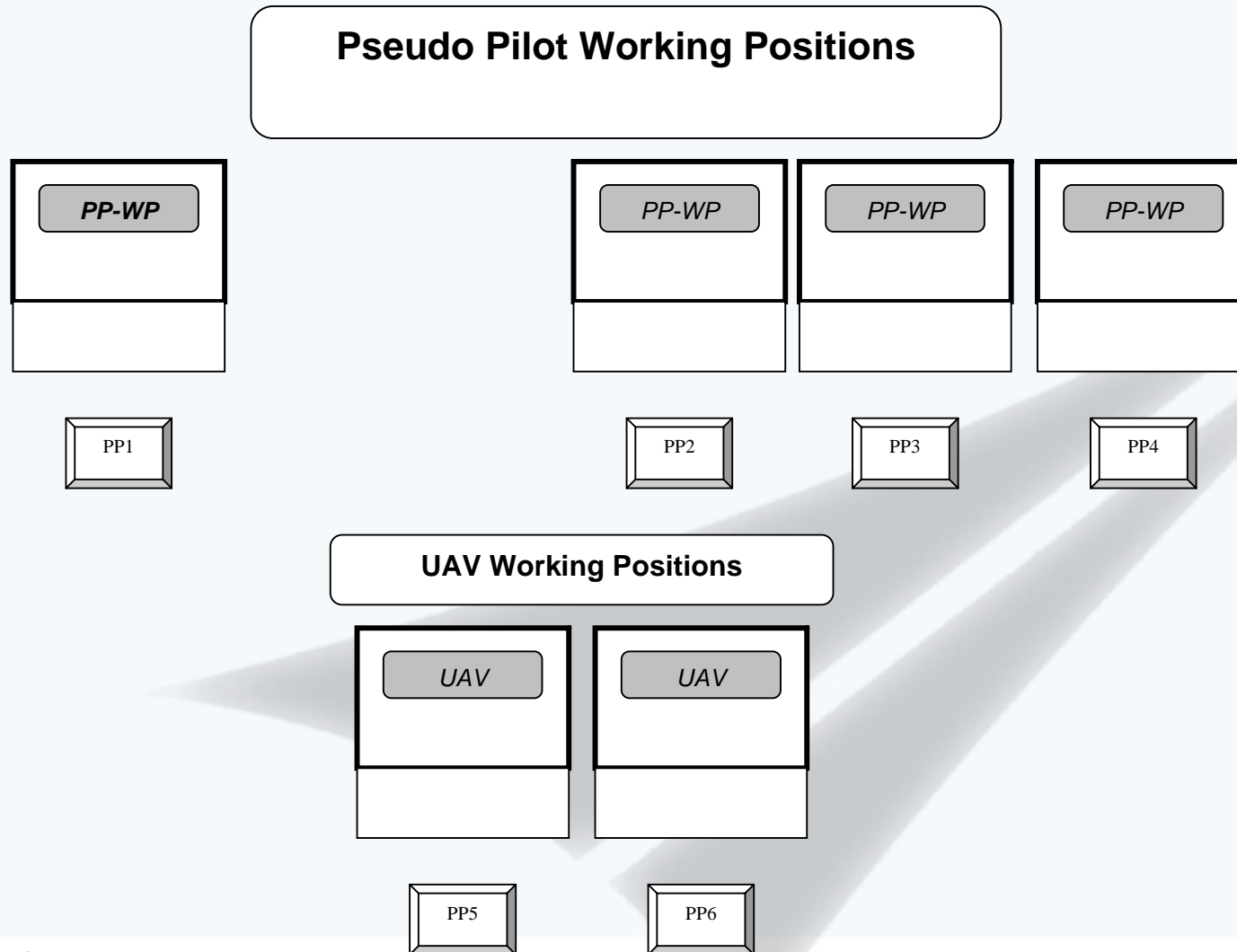
## USICO Simulation Room Layout, CWPs



## Pseudo Pilot Working Positions

- Sector West: 1 pseudo pilot
- Sector North: unmanned, dummy traffic
- Sector South: unmanned, dummy traffic
- TMA: 3 pseudo pilots
- additional: UAV pilots

## USICO Simulation Room Layout, Pseudo Pilots



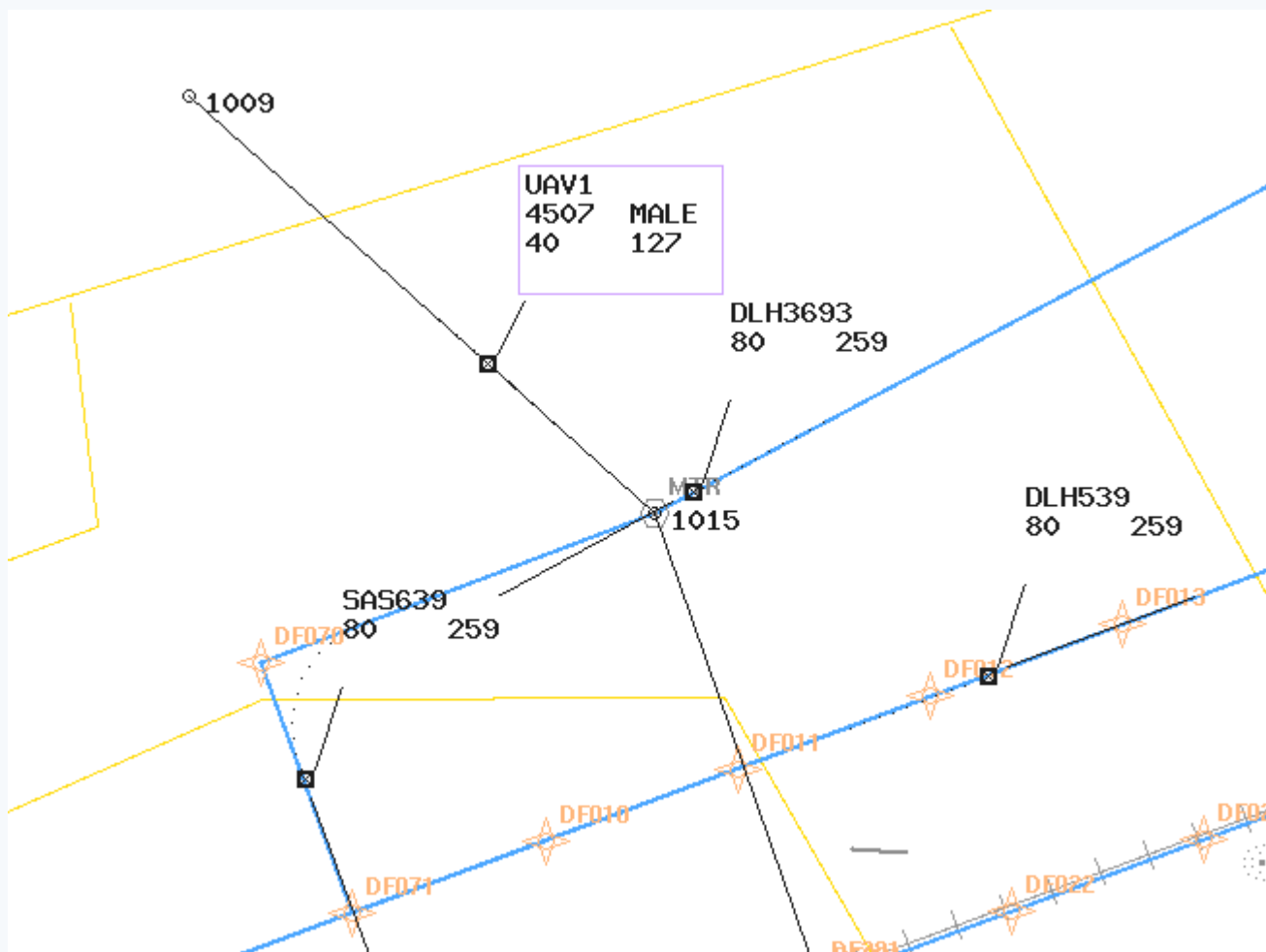
## Simulation Environment

Based on ATMOS-2-CASS.

### *Radar*

- Horizontal representation of aircraft positions.
- Aircraft labels: callsign, altitude, groundspeed.
- Scale factor, geographical area selected by the controller.
- Optional display items: boundaries, sectors, ATC routes, names of fixes, range rings

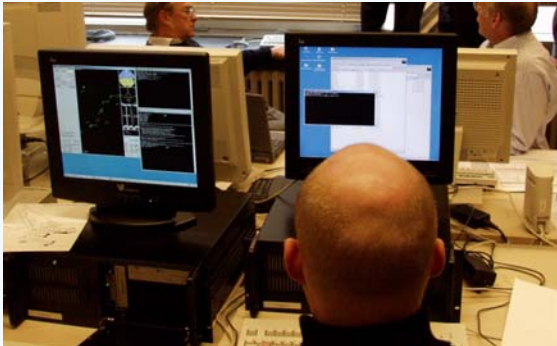
## Label



## Simulation Setup



**Pseudo Pilots**



**UAV Pilot (FHS Sim)**



**Air Traffic Management and Operations Simulator  
ATMOS**

1009

UAV1  
4507 MALE  
40 127

DLH3693  
80 259

MTR  
1015

DLH539  
80 259

SAS639  
80 259

DF076

DF013

DF012

DF011

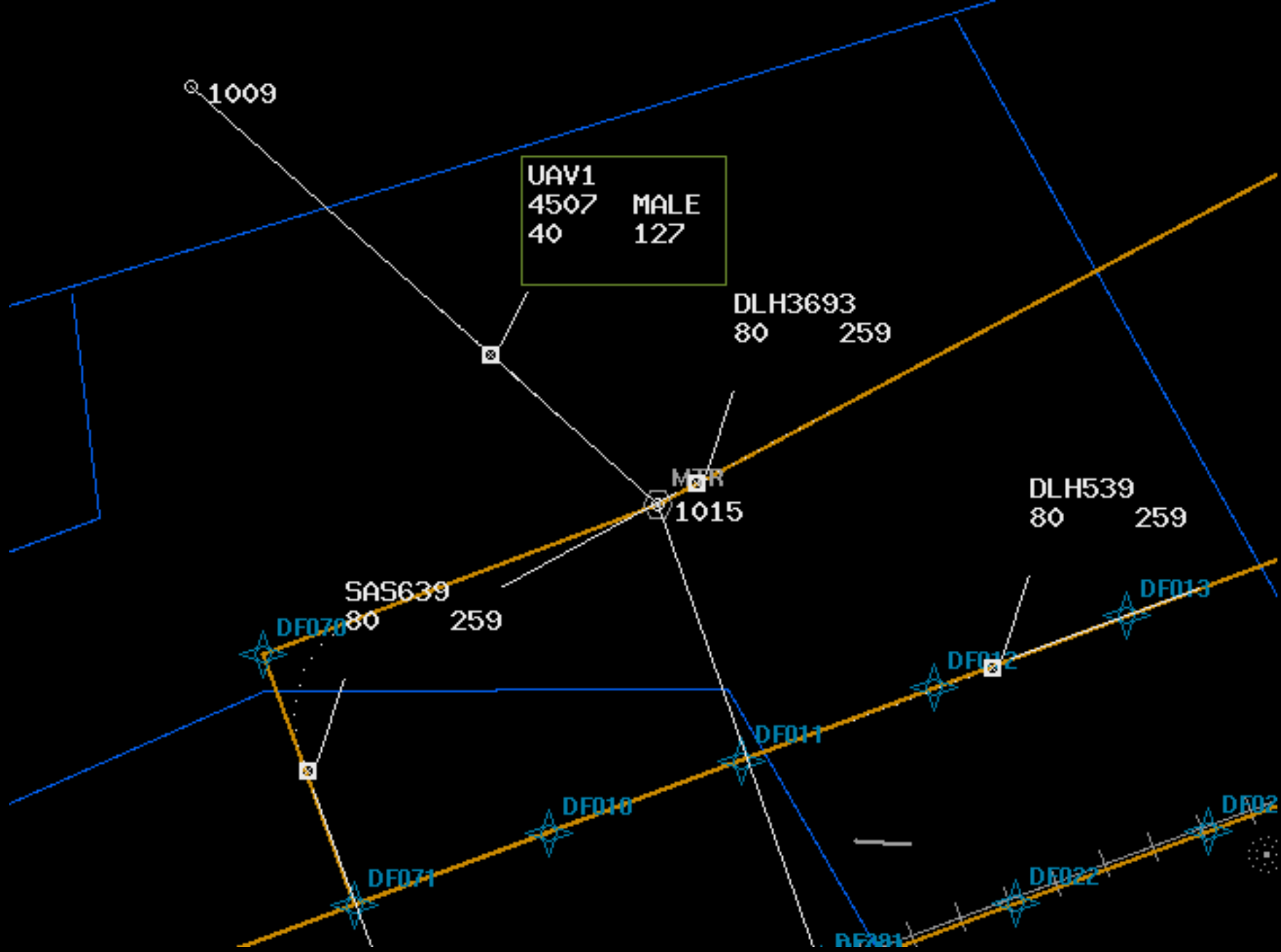
DF010

DF071

DF022

DF02

RF281



ABUMO

UAV81

7700

MALE

37

95

v9



## Simulation Environment

### *Communication*

- Telephone communication between sector controller and arrival controller
- Telephone communication between controller and UAV pilot if requested

### *Simulated Radio Telephony*

- Radio telephony for the controller / pseudo pilot voice communication specially designed intercommunication device operation over wire link
- Communication delay for satellite link is implemented:
  - 1.5 s

## USICO Simulation Runs (Example)

<u>Scenario No.</u>	1	
<u>Name</u>		usico_1_uav_ef
<u>Scenario Description</u>		Engine failure of an UAV
<u>UAV Mission Description</u>		tbd
<u>Simulation Area</u>		FIR Frankfurt
<u>Working Positions</u>		
<i>Controller Working Position</i>		
	EDDF, West Sector:	2 controller (TC, PC)
	EDDF, South Sector	dummy
	EDDF, North Sector	dummy
	EDDF, Arrival	2 controller (TC, PC)
	EDDF, Feeder	not used
<i>Pseudo Pilot Working Position</i>		
	Normal Aircraft	4 pseudo pilots
	UAV Traffic	1 UAV pseudo pilot

## USICO Simulation Runs (Example cont)

### Statistics

Total Number of aircraft:	40
Arrival aircrafts:	30
Overflights:	10
UAV:	1

### Percentage

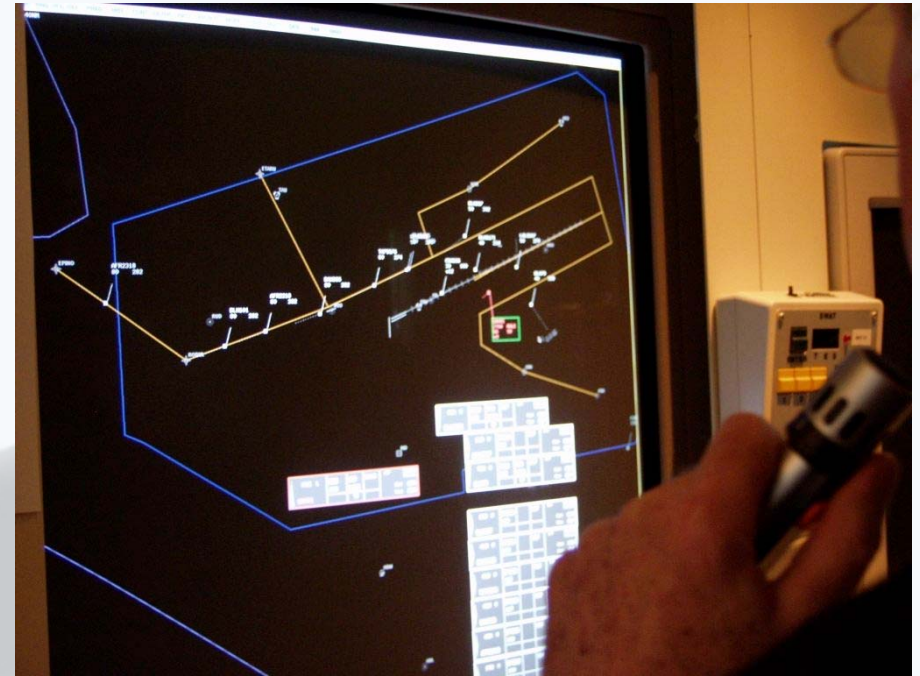
#### Weight Classes

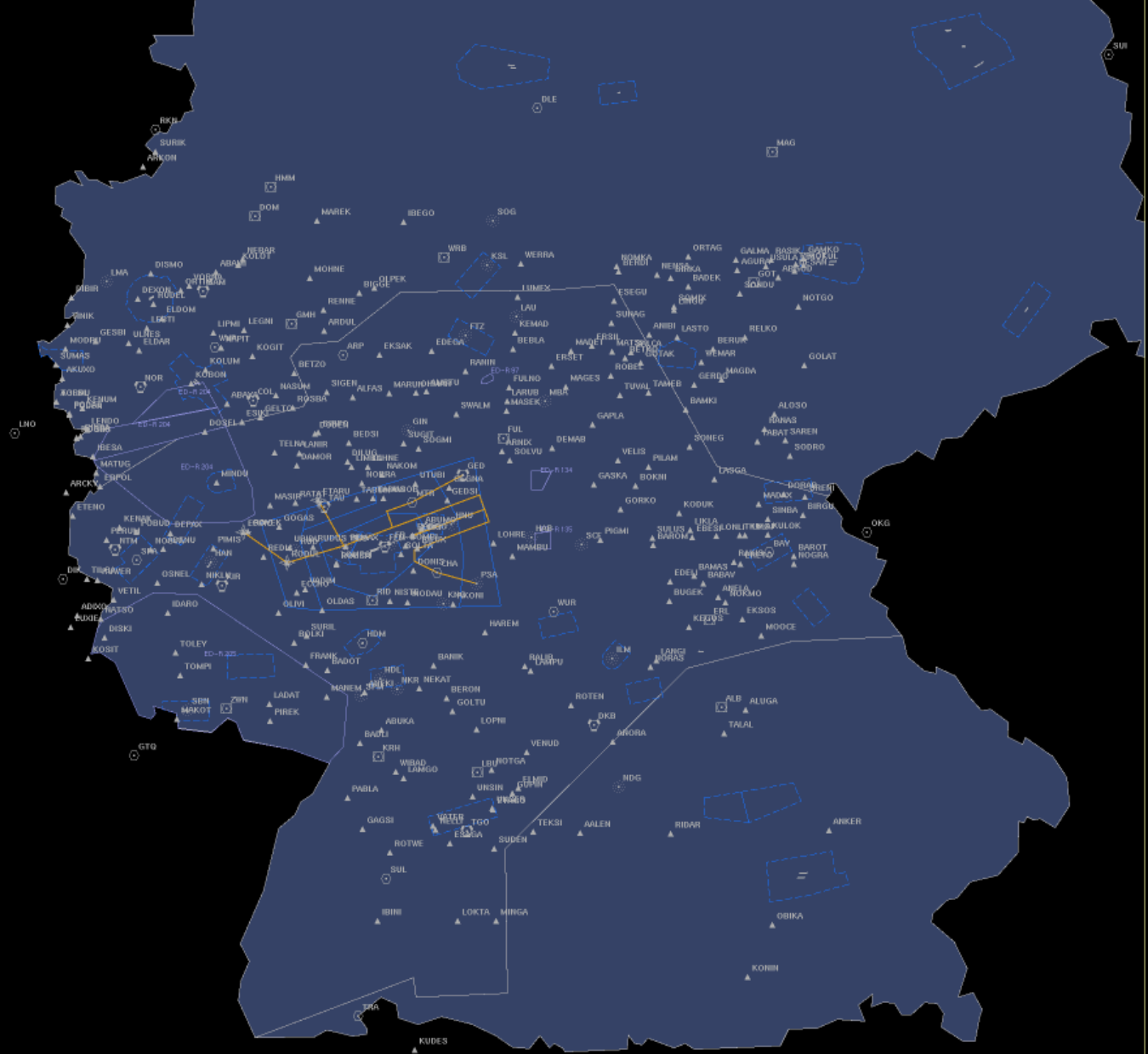
H	30 %,
M	60 %,
L	10 %

#### Sectors

33 % West
33 % North
33 % South

Let's start





SUR

RKN  
SURIK  
ARKON

HMM  
DOM

MAREK  
IBEGO

DLE

MAG

LMA  
DISMO  
ABRA

NEBAR  
DOLGT

MOHRE  
BILAGE

OLPEK  
REHRE

ARDUL  
OMH

ARP  
EKSAK

EDEGAT  
FTZ

LIMEK  
LAW

KEMAD  
BEBLA

ERSIL  
MATESOL

BEOTAK  
ROBEE

AMBI  
LASTO

BERUM  
YEMAR

RELKO  
GOLAT

ALOSO  
DINAS

ABAT SAREN  
SOORO

LHO

LEHDO  
POOR

DOSEL  
ESIK

ABAW  
COL

NASUM  
RUSBA

SIGER  
ALFAS

MARUHO  
AMREU

GIR  
SUGEM

FULNO  
LARIUB

AMASEK  
DAMAB

VELIS  
PILAM

GASKA  
BOKHI

GORKO  
KODUK

MAWAK  
SINBA

OHLETR  
KULOK

BAROT  
ROGRA

OKG

RIESA  
MATUG

ERPOL  
ARCKV

ETERO  
KENBU

DEPAK  
RIM

HODAN  
PIMIS

REDU  
RUSBA

LOHRE  
MAMBU

WUR

PSA

EDEM  
BABAW

BUGEK  
KEGUS

ERL  
EKSOS

MODCE

THAMER  
VETIL

OSHEL  
NIKLUK

IBARD  
DISKI

KOSIT  
TOLEY

TOMP

FRAN  
DADOT

HDL  
BARIK

ROLE  
LAWTU

ROTEN  
DKB

AFORA  
ALB

ALUGA  
TALAL

RIIDAR

ANKER

GTO

SRI  
MAKOT

ZNR

LADAT  
PIREK

ABUKA  
BAKLI

KRH  
WIBAD

JAGGO  
PABLA

GAGSI  
GAGSI

ROTWE  
SUL

IBIH

LOKTA  
MINGA

OSIKA

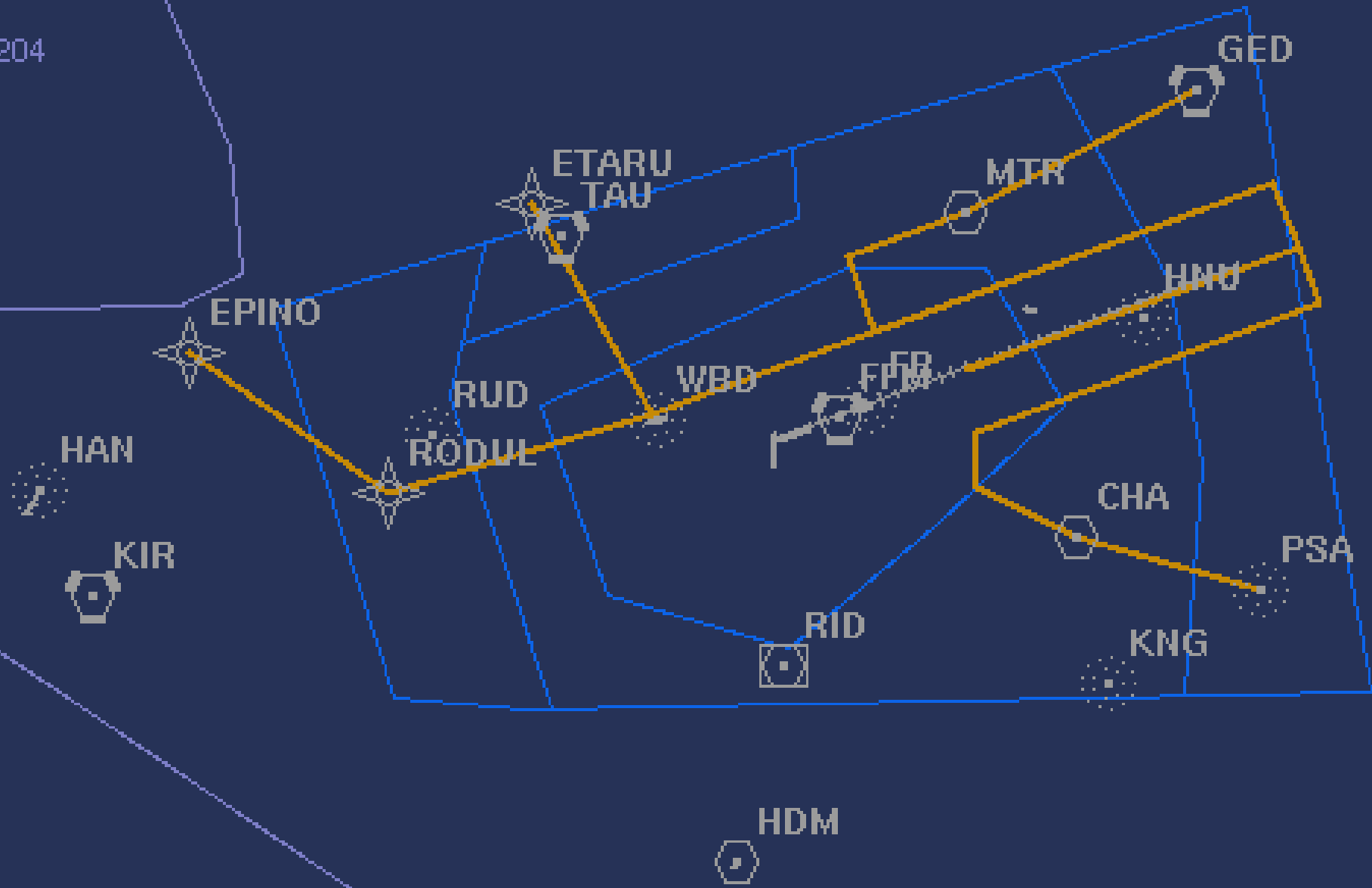
KORIH

TRA  
KUDES





ED-R 204



ED-R 205



DLH4173  
40 266

SBI871  
21 192  
v10

DLH3693  
7 137  
v11

IBE4516  
40 361

ABUMO

HADJIO  
LEDKI

BOMBI

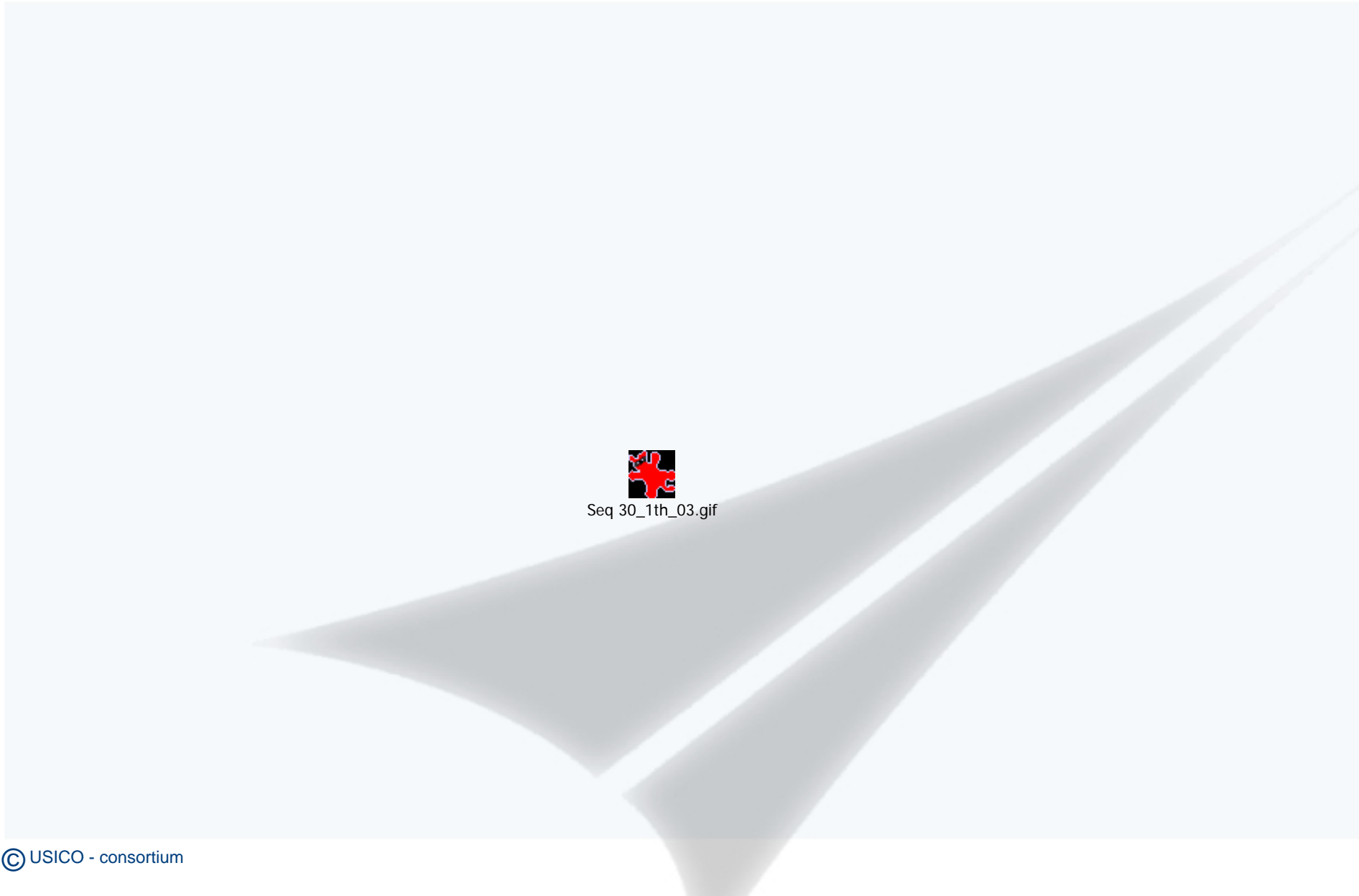
SOLTA

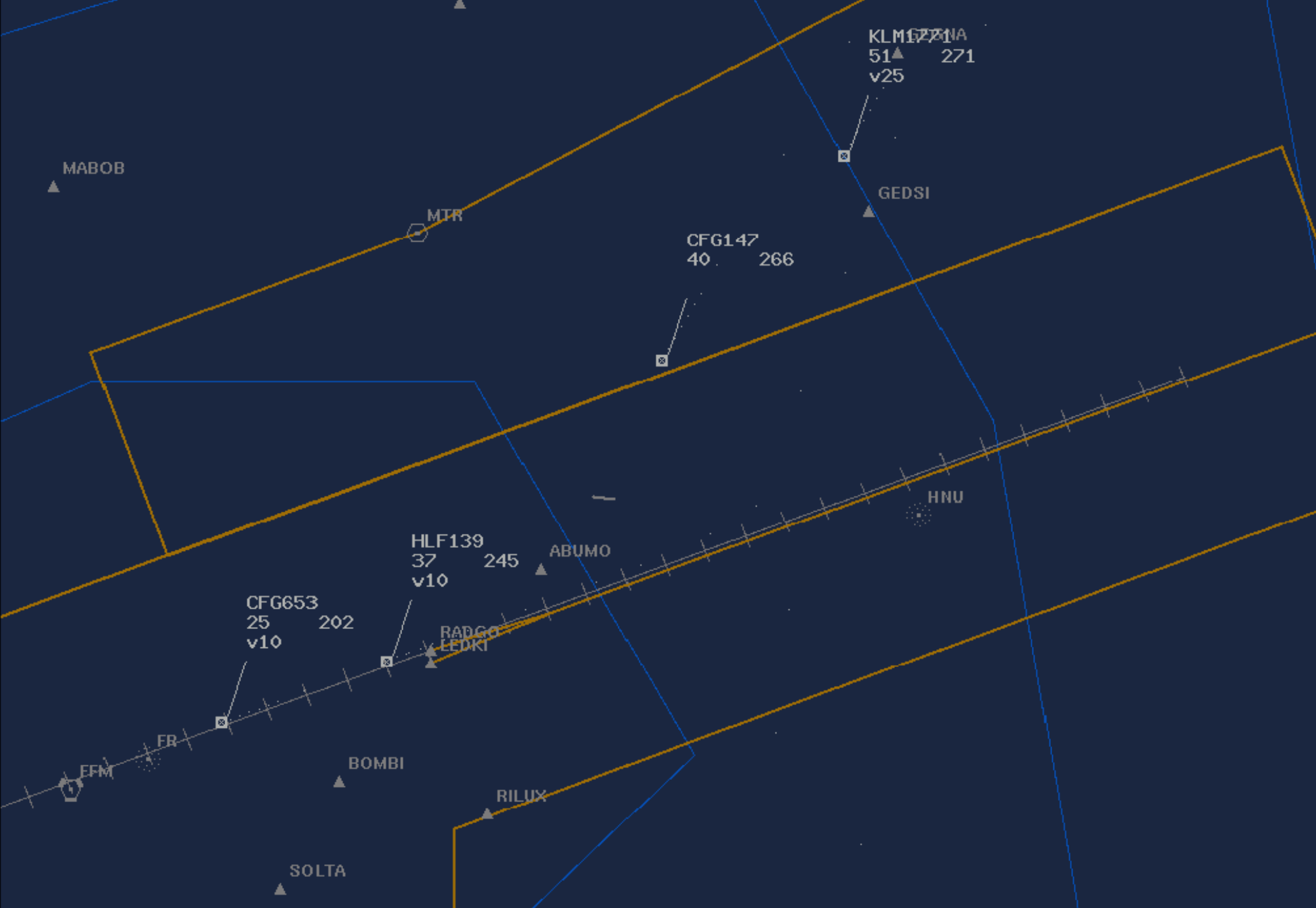
DONIS

RILUX

HNU

CHA





KLM1771A  
51▲ 271  
v25

MABOB▲

MTR

GEDSI▲

CFG147  
40 266

HNU

HLF139  
37 245  
v10

ABUMO▲

CFG653  
25 202  
v10

RADGO  
LEDKI▲

BOMBI▲

RILUX▲

SOLTA▲

EFM

FR



Seq 75\_1th\_02\_c\_noerdl\_kurz\_Logo.gif





Seq 75\_1th\_02\_c\_noerdl\_lang\_Logo.gif

## Demonstrations

Three Groups: G1, G2, G3

- ATM/ATC integration, Emergency procedures
- Collision Avoidance System
- Enhanced Vision Systems

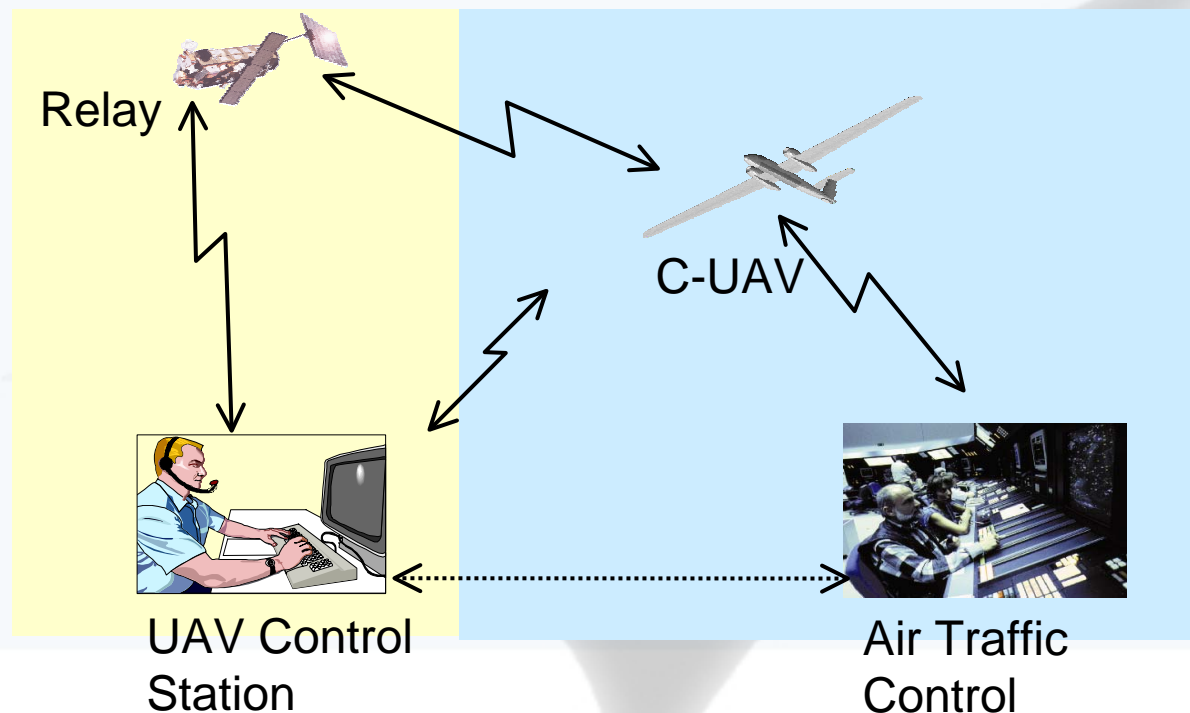
**All groups will see everything**

*Now: Lunch*



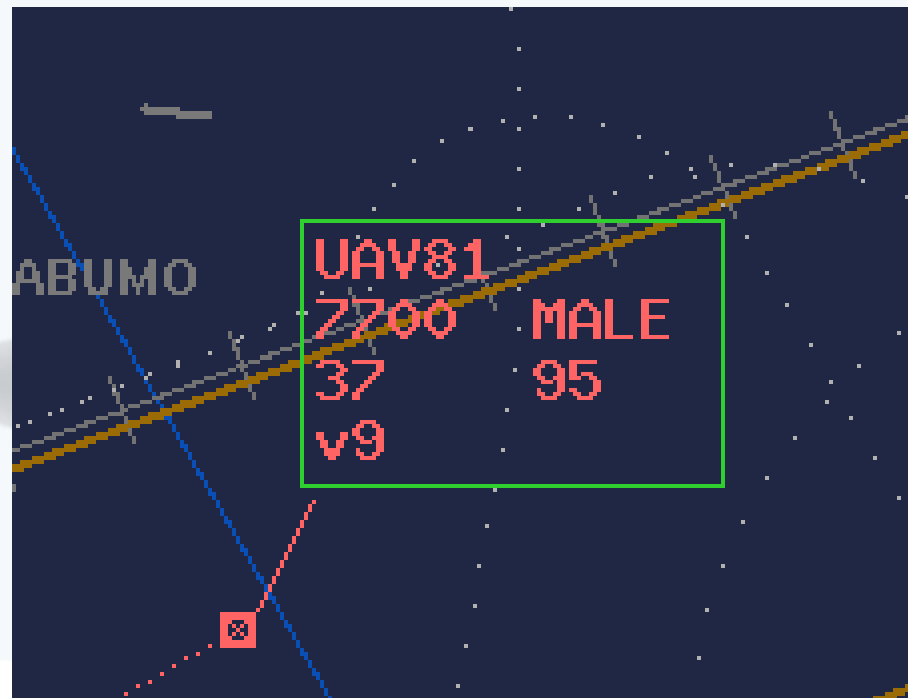
## First Results based on controllers' comments

- General  
No special problems with UAV in airspace  
Integration concept allows treatment of UAV like normal aircraft



## First Results based on controllers's comments (cont 1)

- Emergency Codes  
7600 for data link loss and comm loss appropriate  
7700 for unpredictable emergency behaviour only



## First Results based on controllers' comments (cont 2)

- Telephone comm between controller and UAVpilot is a benefit compared to manned aircraft



UAV Control Station



Air Traffic Control





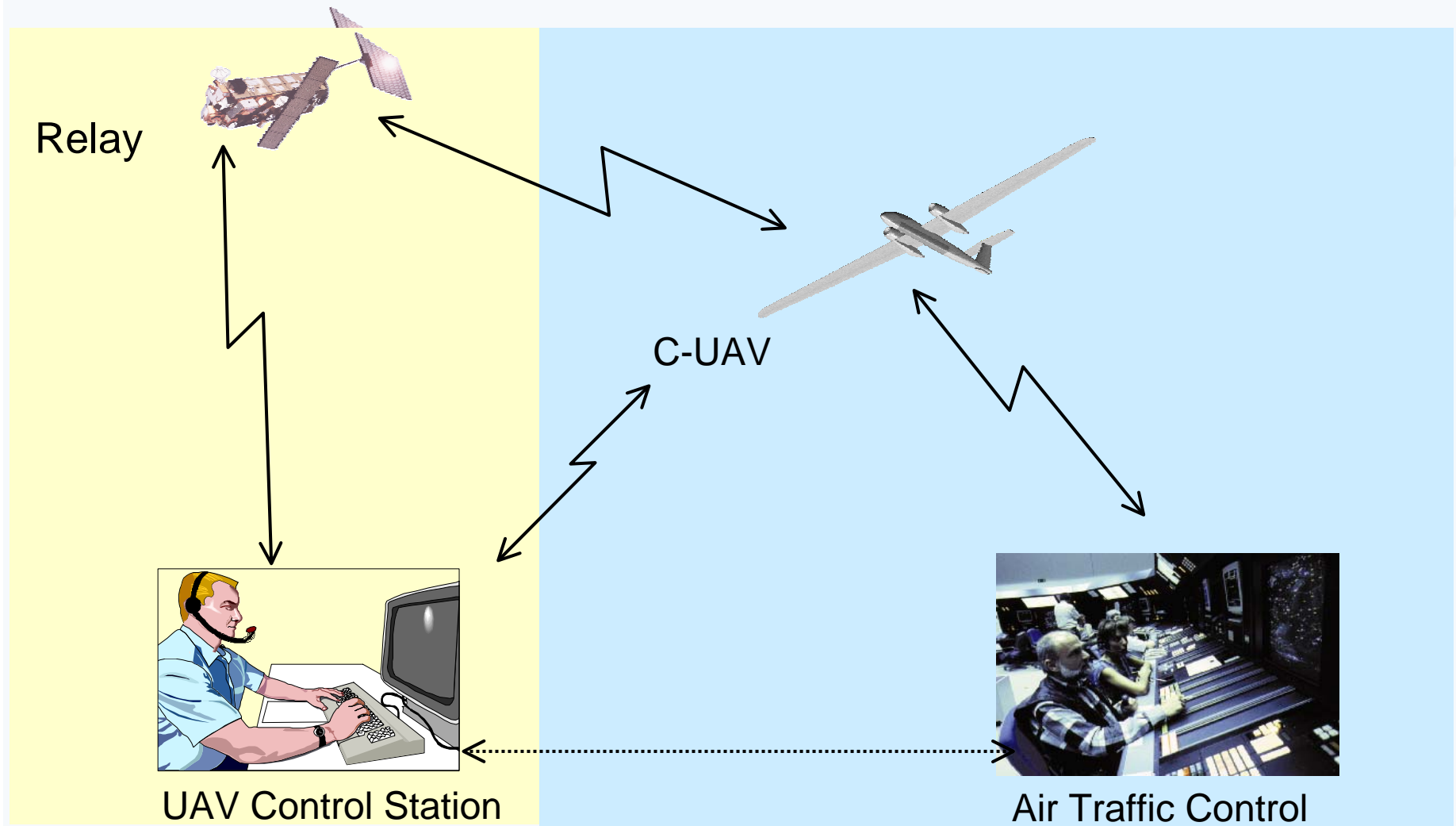
## Simulated Airspace

- FIR Frankfurt:
  - Sector West (modified)
  - TMA Frankfurt

## Simulated Airports

USICO will simulate the approach traffic of Frankfurt (and Hahn or another potential UAV airfield )

## Simulation Concept for UAV Integration



## Simulation Concept for UAV Integration



UAV Control Station



Air Traffic Control

