



**The Project DemoOrt**  
„Demonstration of safety critical localization of trains“

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**DemoOrt**  
**Structure – of the presentation**

- Structure of the consortium
- Motivation
- Approach
  - Components
  - Architecture
- Results
- Perspective





## DemoOrt - Project Structure of the Consortium



**German Aerospace Center**  
Institute of Transportation Systems  
Braunschweig, Germany



**Technical University of Braunschweig**  
Institute of Traffic Safety and Automation Engineering  
Braunschweig, Germany



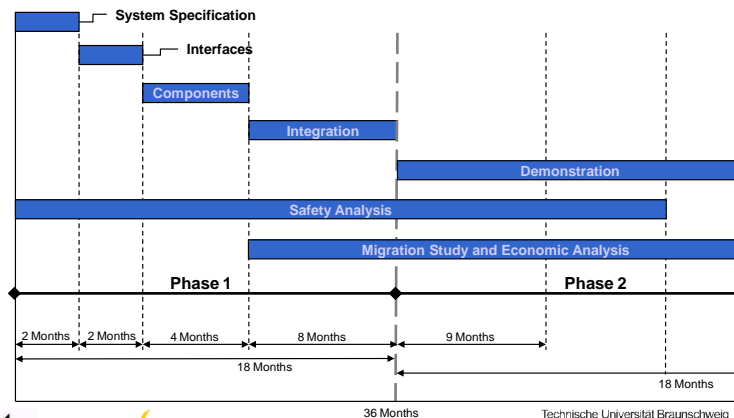
**University of Karlsruhe**  
Department of Measurement and Control  
Karlsruhe, Germany



**Bombardier Transportation**  
(Signal) Germany GmbH  
Mannheim, Germany



## DemoOrt – Project Timeplan





## DemoOrt – Motivation

- Current localization principles used by railways are basing on infrastructure-side sensors (e.g. axle counters). These lead to:
  - Significant maintenance effort
  - Difficult to adopt to modified operational requirements
- For up-to-date railway operational concepts as ERTMS/ETCS Level 3 a vehicle-autonomous localization with high accuracy, dependability and integrity is required
- Examples of advantages of autonomous localization:
  - Concentration on the vehicle
  - Reduction of trackside maintenance effort
  - Reduction of system complexity

ERTMS: European Rail Traffic Management System

ETCS: European Train Control System



## DemoOrt – Approach

### Idea and Components

#### Integration of three different Systems to one highly available and vehicle autonomous localization platform

##### 1. Global Navigation Satellite System

- No terrestrial signal required
- By using Galileo Integrity of the Signal is guaranteed

##### 2. Eddy Current Sensing System

- Precise measurement of metallic in-homogeneities of the track
- Absolutely independent from weather
- Robust

##### 3. Map Matching

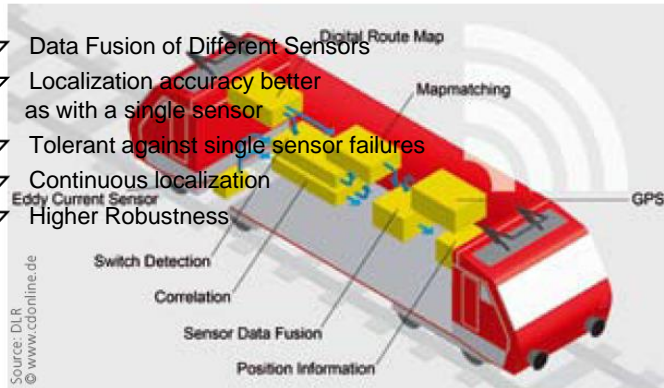
- All captured data can be used for fusion
- Visualization





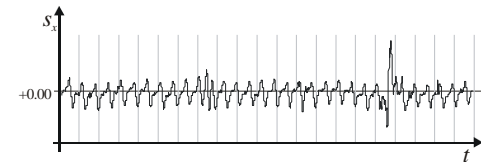
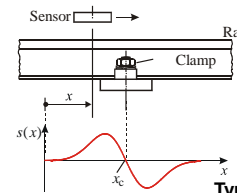
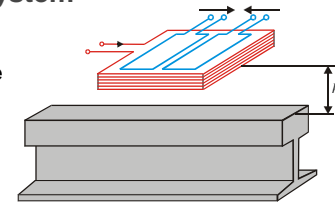
## DemoOrt – Approach System Overview

- Data Fusion of Different Sensors
- Localization accuracy better as with a single sensor
- Tolerant against single sensor failures
- Continuous localization
- Higher Robustness



## DemoOrt – Approach Eddy current sensing system

### Global Principle



Typical Sensor Signal (free Track)





### DemoOrt – Results and Perspective

- Demonstrations:
  - TeZ Poprad (SK)
  - AVG Karlsruhe (D)
- Development of a reference measurement system
- Approach for a Safety Case according to CENELEC
- Analysis of Migration strategies



Thank you for you attention!

