

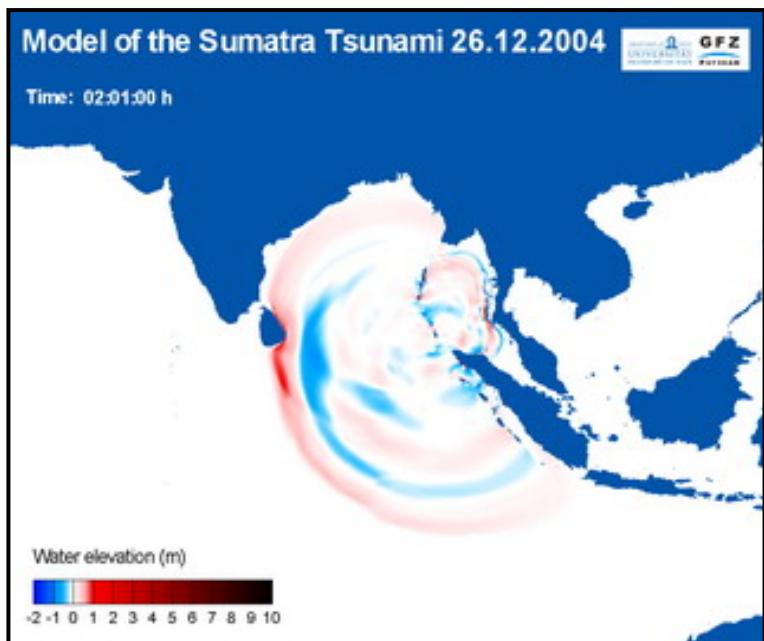
CONCEPTS FOR SPACE-BORNE AND GROUND-BASED RADAR SYSTEMS FOR TSUNAMI DETECTION



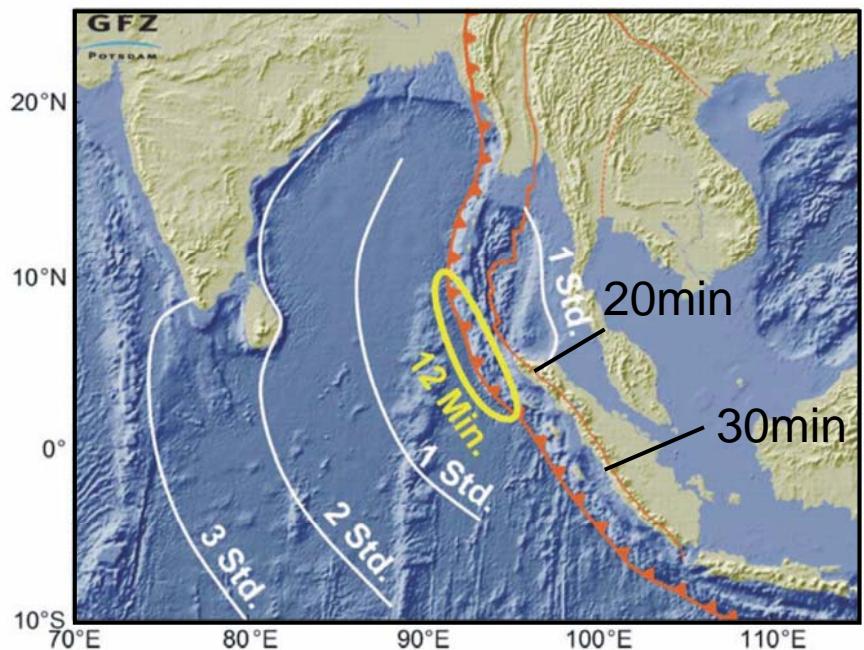
Contents

- GITEWS project
 - Motivation (Boxing Day Tsunami)
 - German-Indonesian Tsunami Early Warning System (GITEWS)
- Tsunami Geophysics
 - Measurable oceanographic observables
- Ground-Based Radars for Tsunami Detection
- Concept Design of a Spaceborne Radar for Tsunami detection

Boxing Day Tsunami (26.12.2004)



GFZ-Potsdam



German-Indonesia Tsunami Early Warning System



Konsortium Deutsche
Meeresforschung, Berlin



Alfred-Wegener-Institut für
Polar- und Meeresforschung,
Bremerhaven



Bundesanstalt für
Geowissenschaften und
Rohstoffe, Hannover

gtz

Deutsche Gesellschaft für
Technische Zusammenarbeit,
Eschborn



GeoForschungsZentrum,
Potsdam
Konsortialführer



Deutsches Zentrum für
Luft- und Raumfahrt,
Oberpfaffenhofen



IFM-GEOMAR
Leibniz-Institut für
Meereswissenschaften
an der Universität Kiel

Leibniz-Institut für
Meereswissenschaften (GEOMAR), Kiel



Universität der Vereinten Nationen,
Institut für Umwelt und Menschliche
Sicherheit Bonn

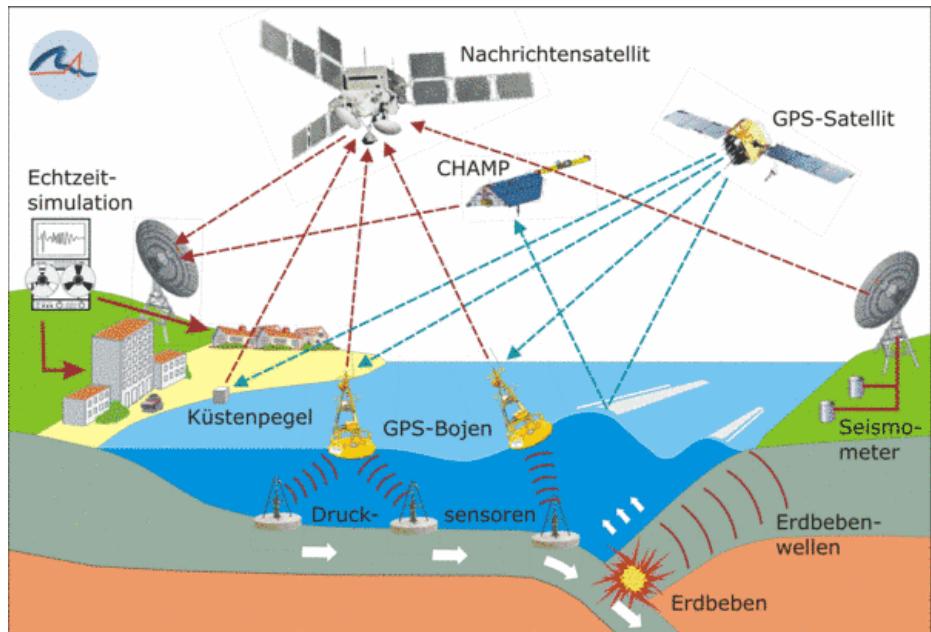


GKSS
Forschungszentrum,
Geesthacht



Deutsches Zentrum
für Luft- und Raumfahrt e.V.
in der Helmholtz-Gemeinschaft

GITEWS Workpackages



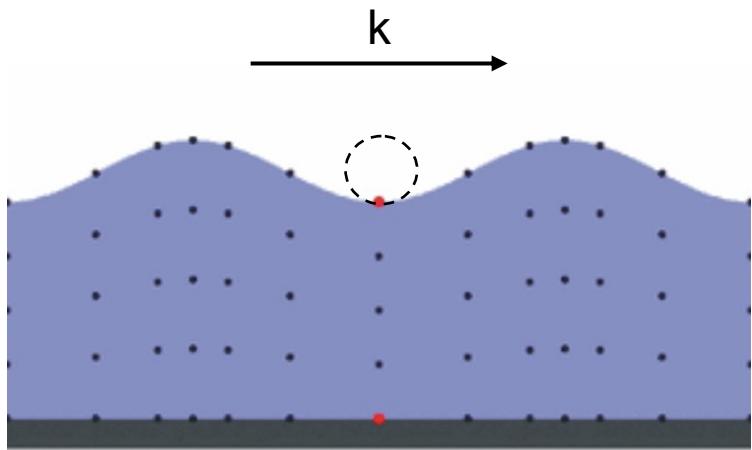
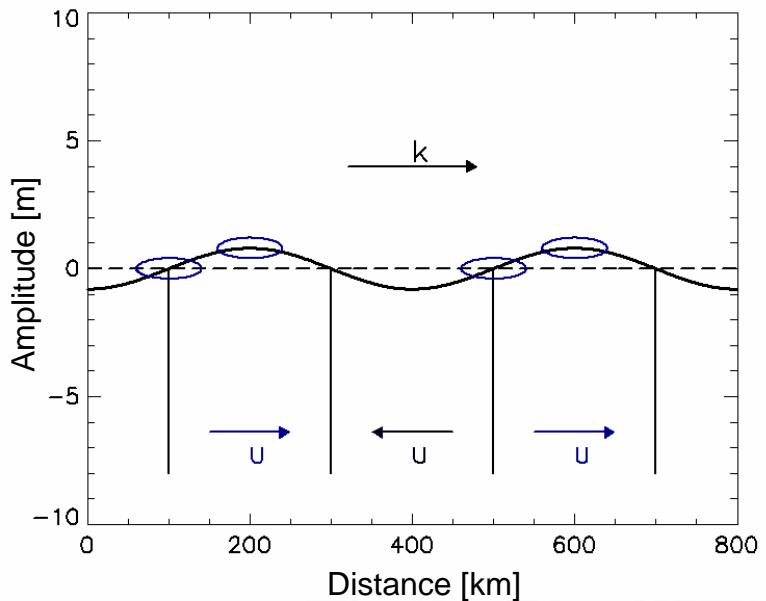
- Earthquake monitoring (WP 1000)
- Ocean Instrumentation (WP 2000)
- GPS Technology (WP 3000)
- Early Warning and Mitigation Center and Earth Observation Studies (WP 4000)
- Tsunami Modelling (WP 5000)
- Capacity Building (WP 6000)
- Project Management (WP 7000)

WP 4430
**Studies on Ground-based HF and Microwave RADAR
and new Space-borne microwave systems**

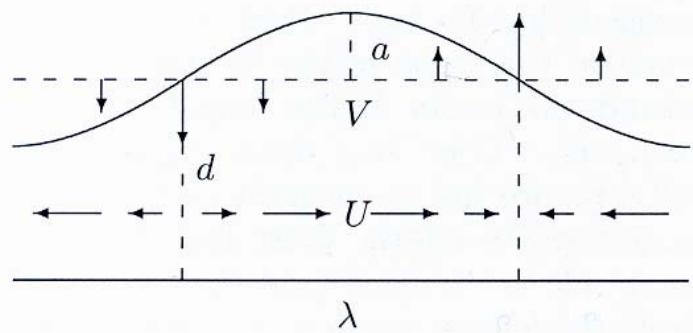


Geophysical Parameters

Tsunami parameters

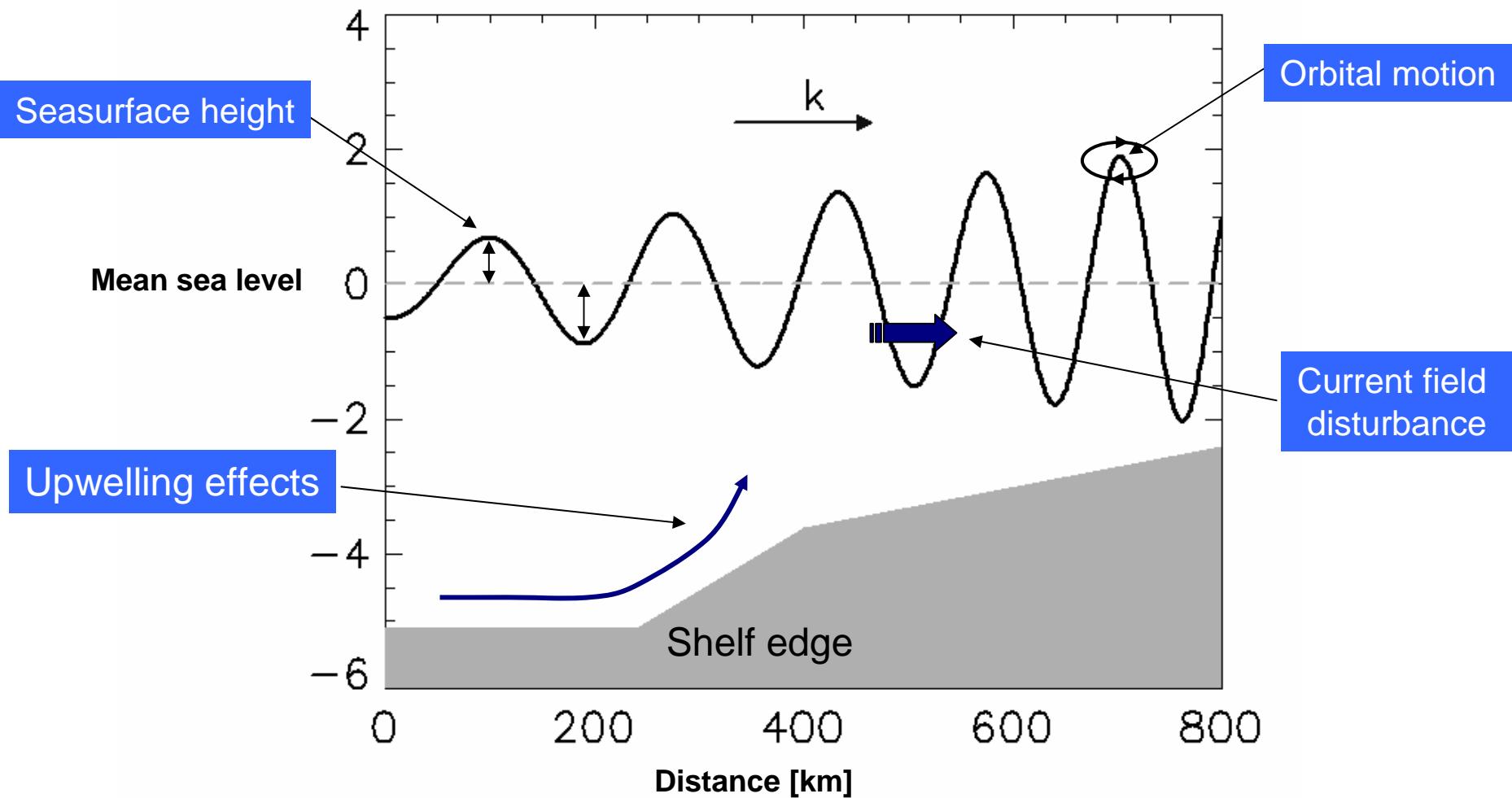


<http://de.wikipedia.org/wiki/Tsunami>



- A: amplitude
- d: water depth
- U: horizontal velocity
- V: vertical velocity
- λ : wave length

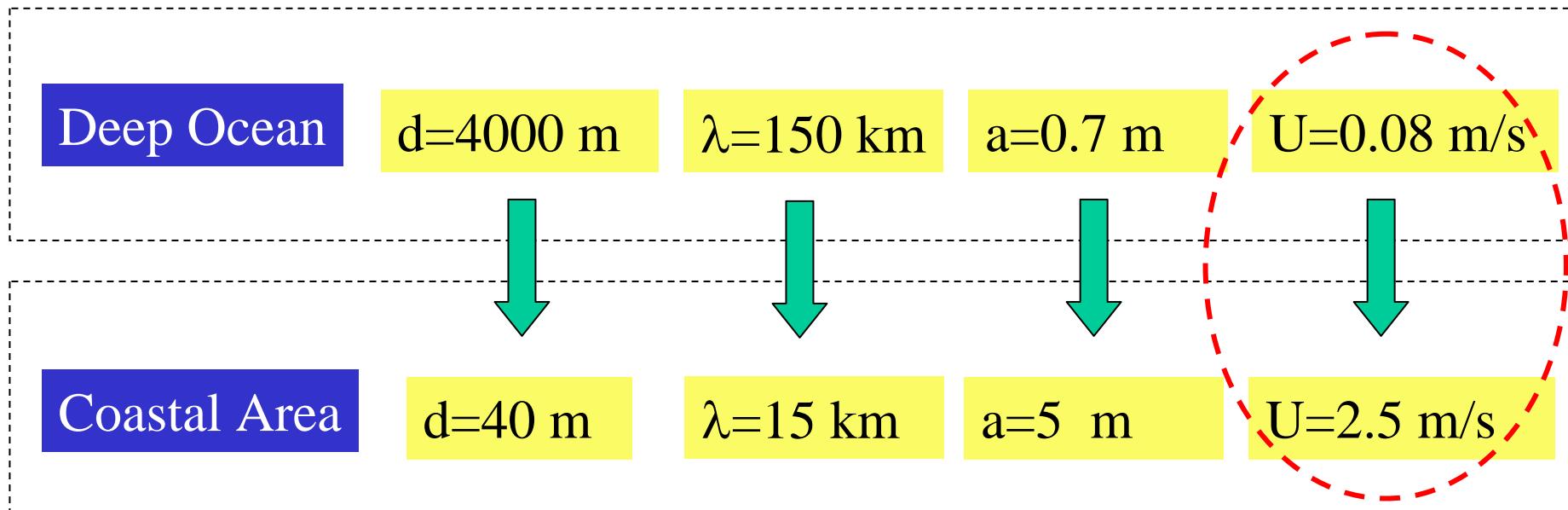
Geophysical Parameters



Tsunami Scale

Benny Lautrup, *Tsunami Physics*

Kvant, Jan 2005

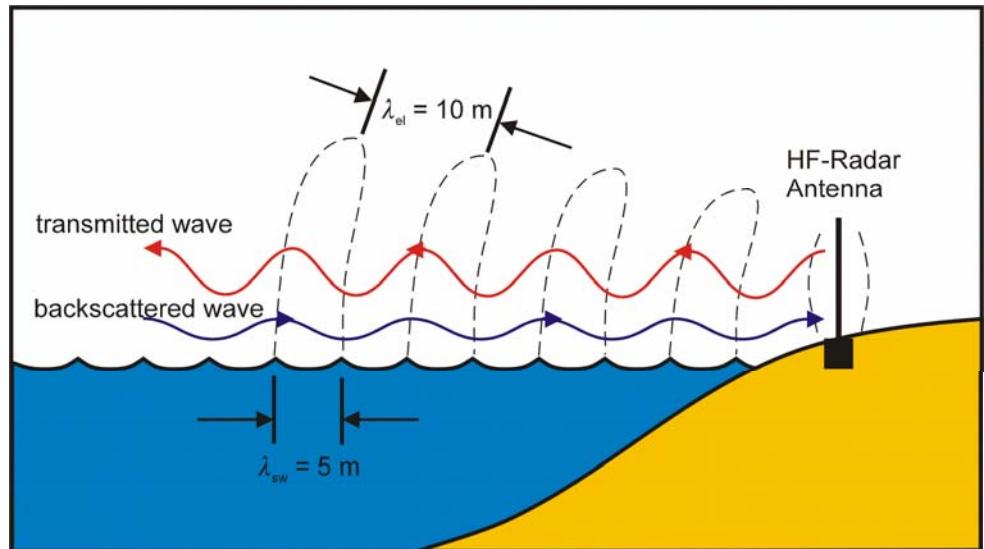


Tsunamis are more easily detectable in coastal areas



GROUND-BASED RADARS FOR TSUNAMI DETECTION: HF RADARS

HF RADAR (Helzel GmbH)



- HF ground wave
- Backscattering from wave crests
- Bragg Scattering

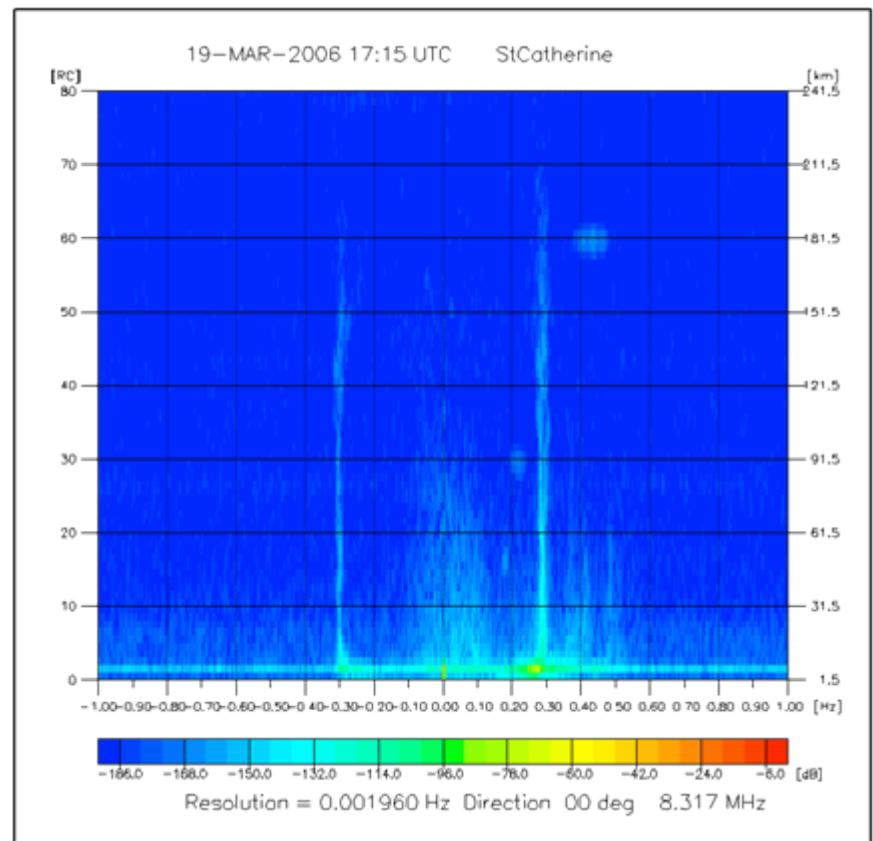
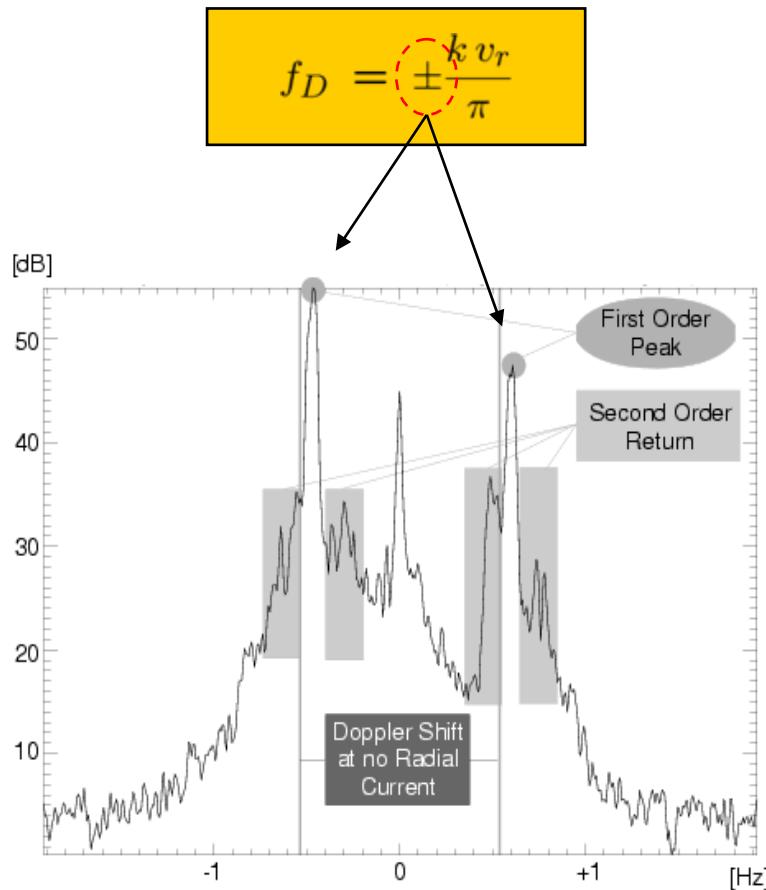
e.g. $\lambda_{sw}=25m \rightarrow f_{RADAR}= 12\text{ MHZ} \rightarrow \text{HF RADAR}$

<http://www.helzel.com>

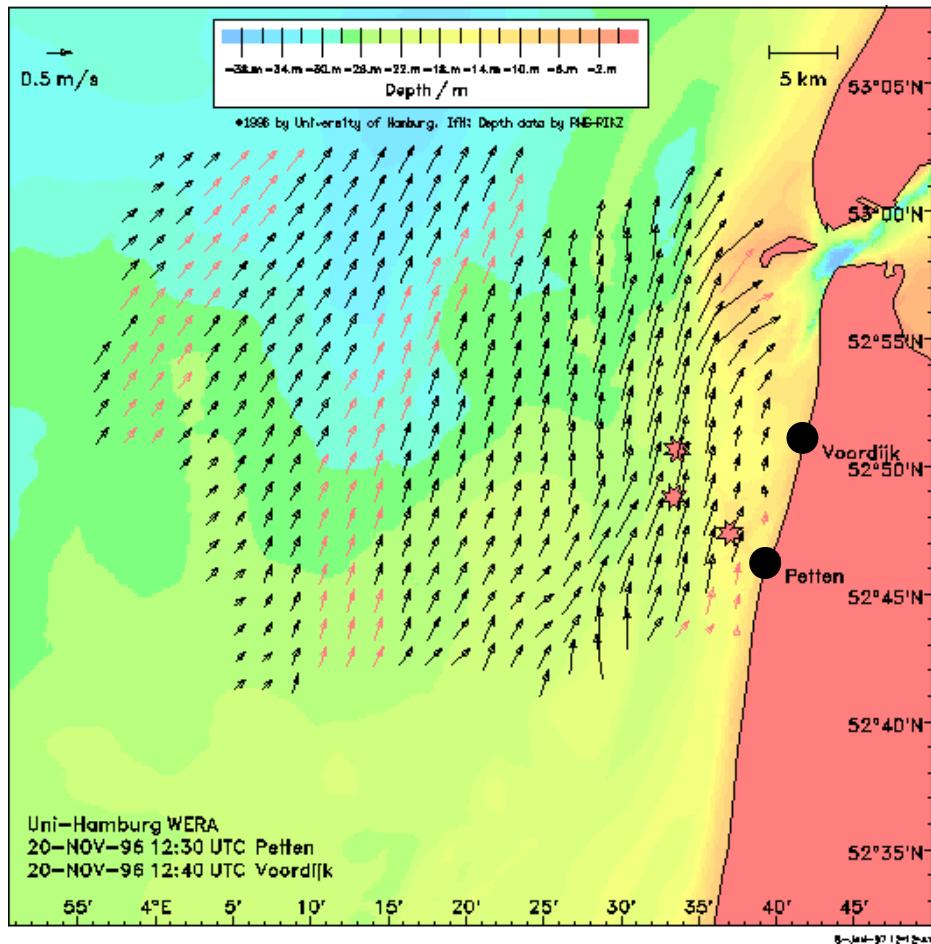
<http://www.ifm.zmaw.de>

Doppler Spectrum

1 Dim. Radial Component

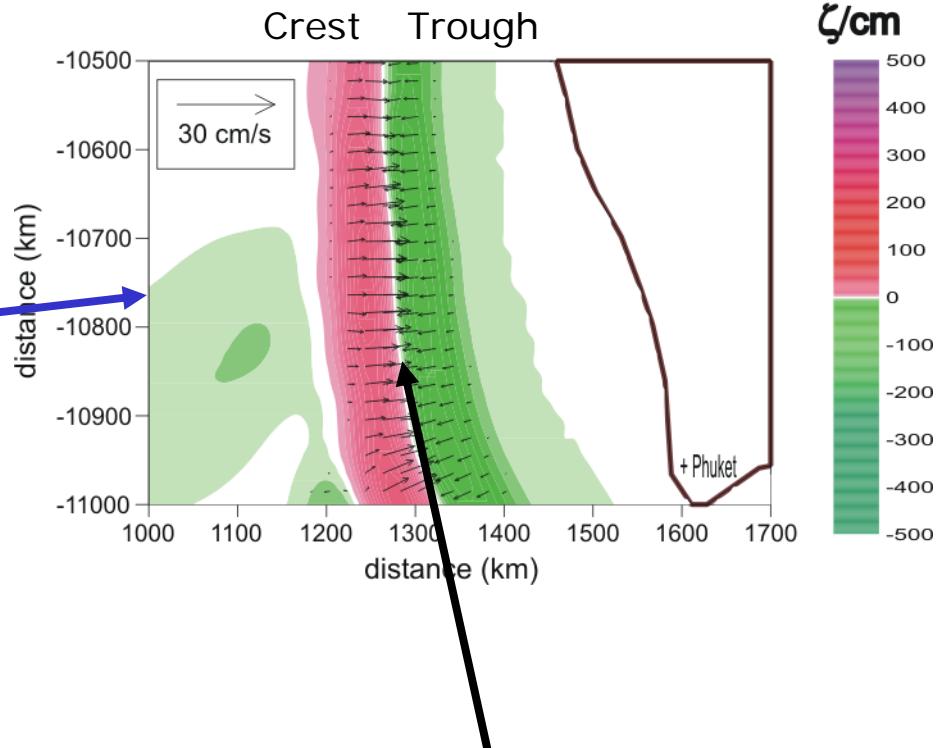
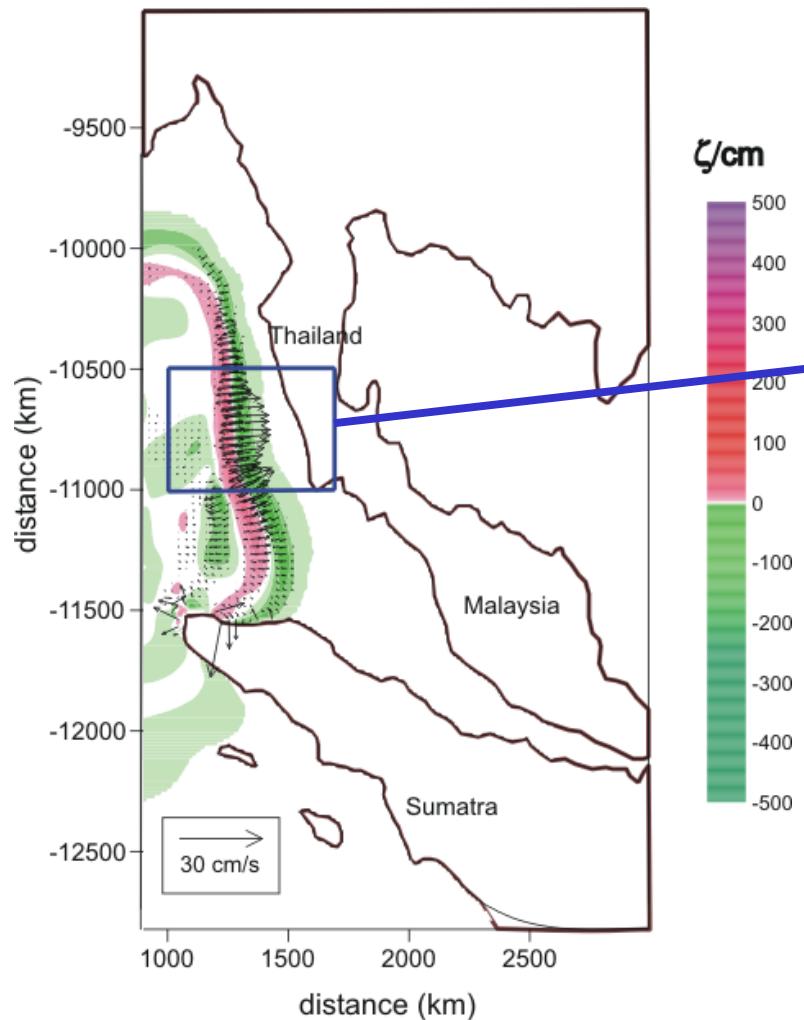


Current Field



- The operating frequency is the most important parameter for long range
- The lower the operation frequency the longer the range
- A center frequency of 10MHz results in a Bragg wave length of about 15m
- f [5-15MHz] → Range [100-200km]

Current Field Simulation



Strong ocean current signature
along the Tsunami front !

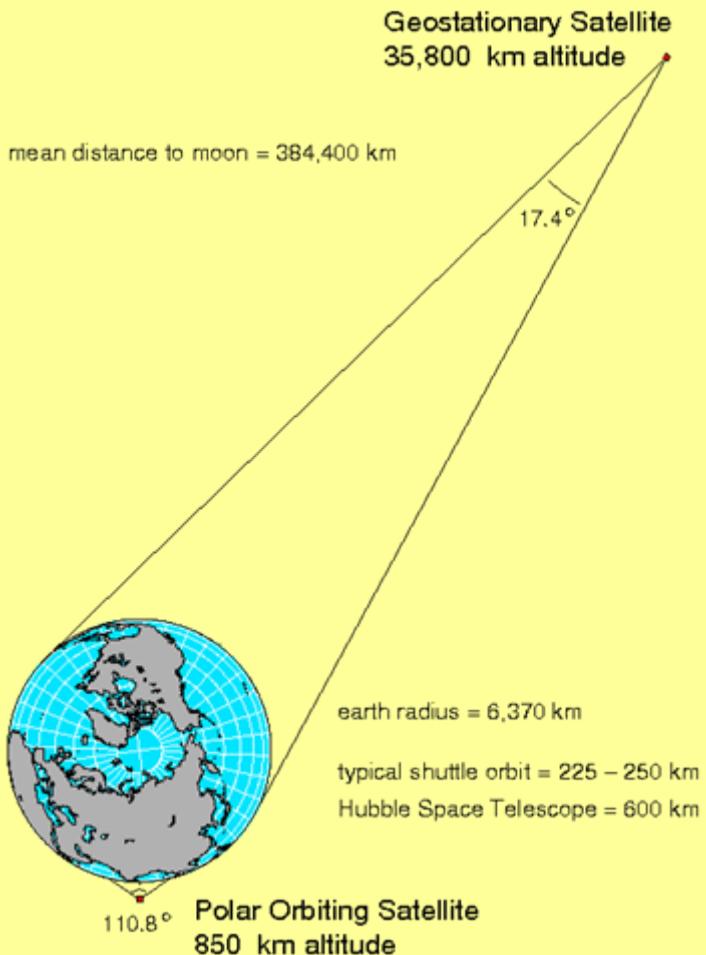
Institute of Oceanography (IfM) Hamburg



DLR CONCEPT FOR TSUNAMI DETECTION:

GEOSTATIONARY INTERFEROMETER

Why a geostationary orbit ?



- Huge Field of View:
Covers virtually every oceanic trench up to 50° latitude
- Continuous Monitoring for early warning
- While waiting for the next tsunami, other applications are possible:
 - ✓ Ocean Current measurements
 - ✓ Wave measurements
 - ✓ Global Ocean Circulation
 - ✓ Wind measurements

Principle of along track interferometry

$$\Delta\varphi_{\text{meas.}} = \varphi_1 - \varphi_2$$

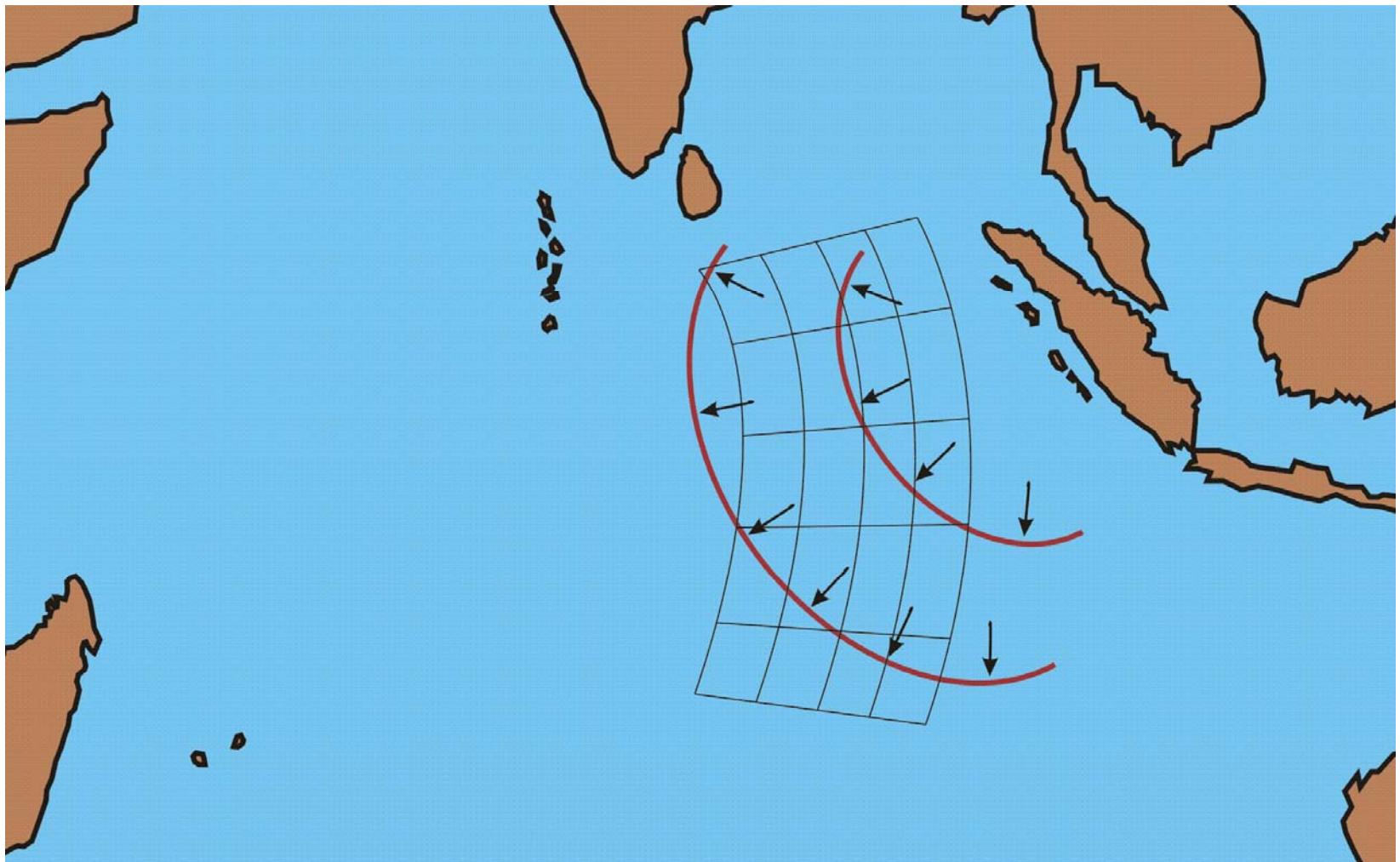


Wide Swath Pattern Mearurements

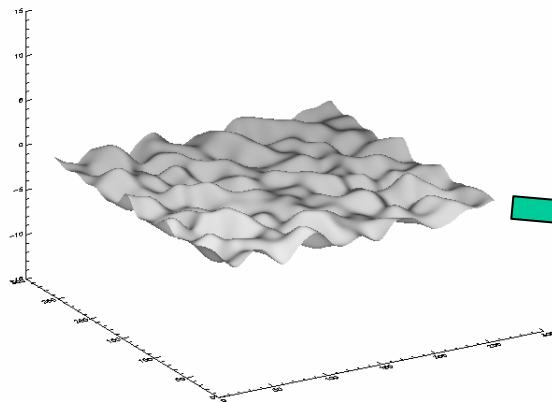


- Current field
- Tsunami
- Resulting motion

Tsunami Wavefront



Modeling the Problem



Coherent target

$$\Delta\varphi_{measured} = 2\pi\tau\nu$$

[Goldstein and Zebker 87]

Incoherent target

$$\Delta\varphi_{measured} = \arg\left(\frac{1}{\sigma} \int_{-\infty}^{+\infty} e^{i2\pi\nu} S(\nu) d\nu\right)$$

[Thompson and Jensen 93]

The resolution cell is occupied by a moving surface with scatterers moving on it.

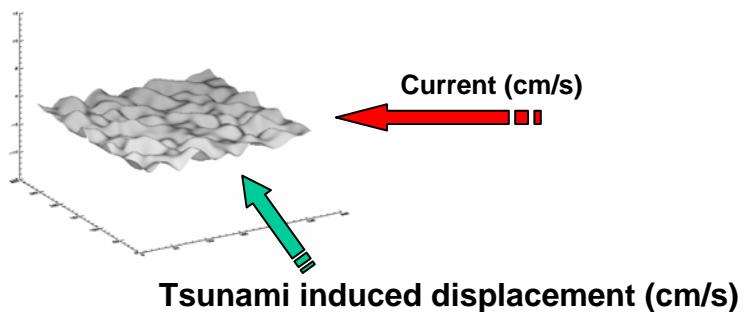
Local currents and a tsunami displace the surface. (first order contributions)

Wind driven waves act as scatterers on the surface. (second order contribution)

Detection is achieved by comparing different measurements →

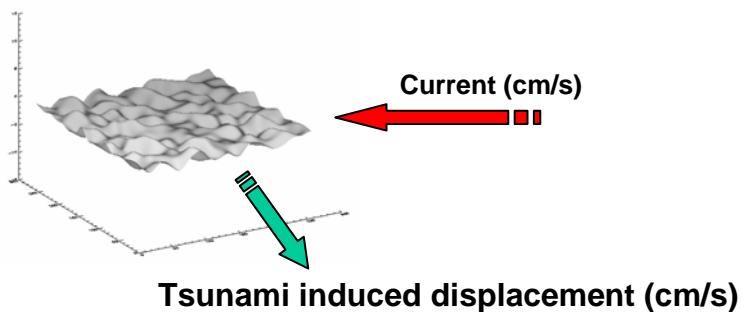
Tsunami Orbital Motion Detection

First semiperiod



$$\Delta\varphi_{measured} = \Delta\varphi_{current} + \Delta\varphi_{tsunami} + \Delta\varphi_{speckle} + \Delta\varphi_{noise}$$

Second semiperiod



$$\Delta\varphi_{measured} = \Delta\varphi_{current} - \Delta\varphi_{tsunami} + \Delta\varphi_{speckle} + \Delta\varphi_{noise}$$

Current velocities:

~ cm/s (typical)

Tsunami induced displacements:

1-2 m/s (maximum)

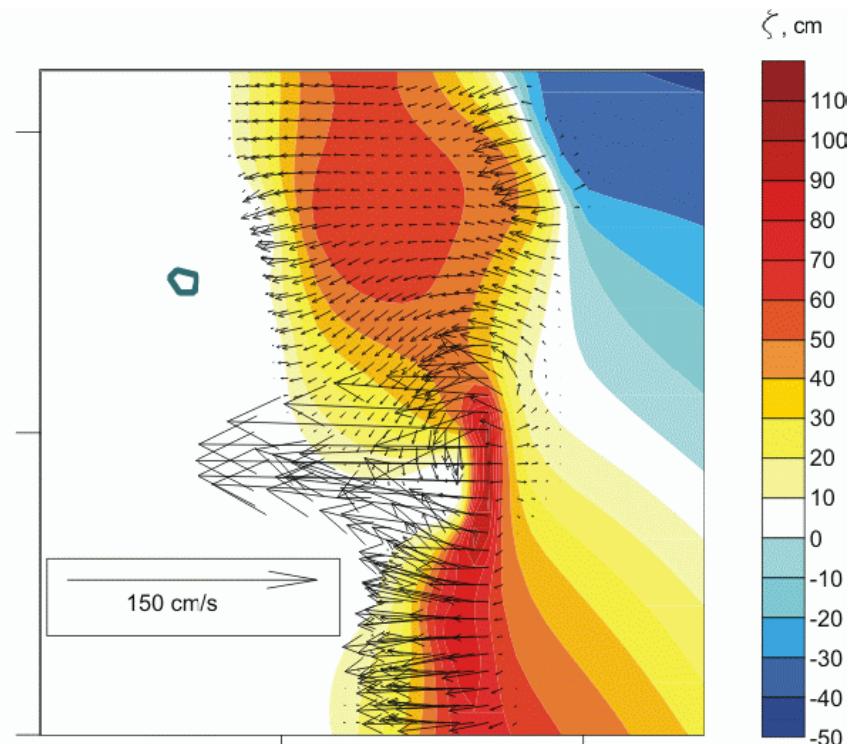
~ cm/s

- The line of sight velocity difference should be in the order of cm/s.

Detection Strategy in the Continental Shelf

Even easier !

- Tsunamis induce anomalous current patterns when they impact the continental shelf



Simulation results
(courtesy UniHamburg)



Outlook

- We can draw on knowledge from many interferometric missions
AIRSAR, ESAR, SRTM, TanDEM-X
Mature technology for operational purposes
Technology evolution, not revolution
- The Geostationary Interferometer makes available:
Long time series
Averaging over thousands of samples should improve the accuracy from 10 cm/s (standard ATI doppler accuracy) to 1cm/s (for tsunami detection)
- Digital Beamforming and Subspace Methods for azimuthal superresolution are being studied to limit antenna size
- Experimental validation of Doppler Accuracy Improvement upon averaging



**Thanks for your
Attention !**