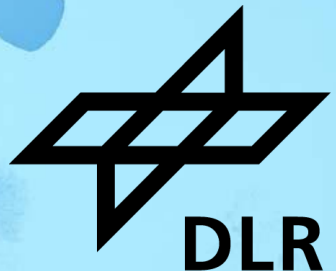


# AP1 EVALUATING POSSIBLE BENEFITS OF SPATIAL INFORMATION FROM ASCAT DATA IN BEST MEMBERS SELECTION

**Tobias Baier**, Matthias Zech, Lueder von Bremen & WEPROG

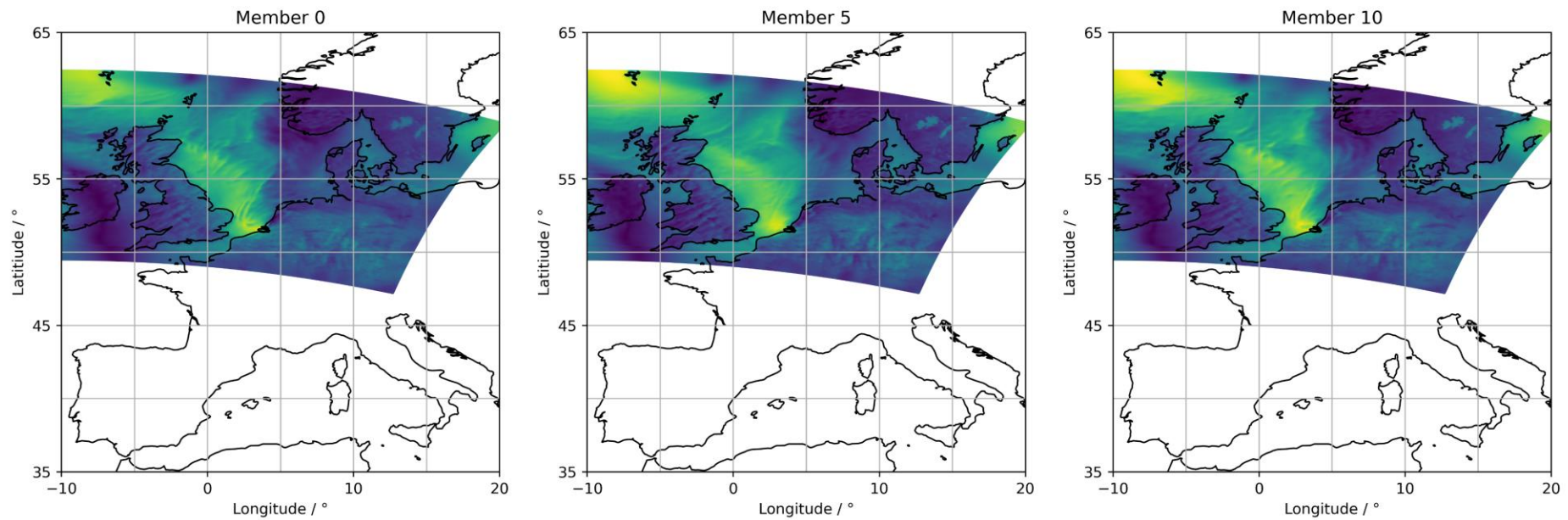
10.03.2026

German Aerospace Center (DLR), Institute of Networked Energy Systems

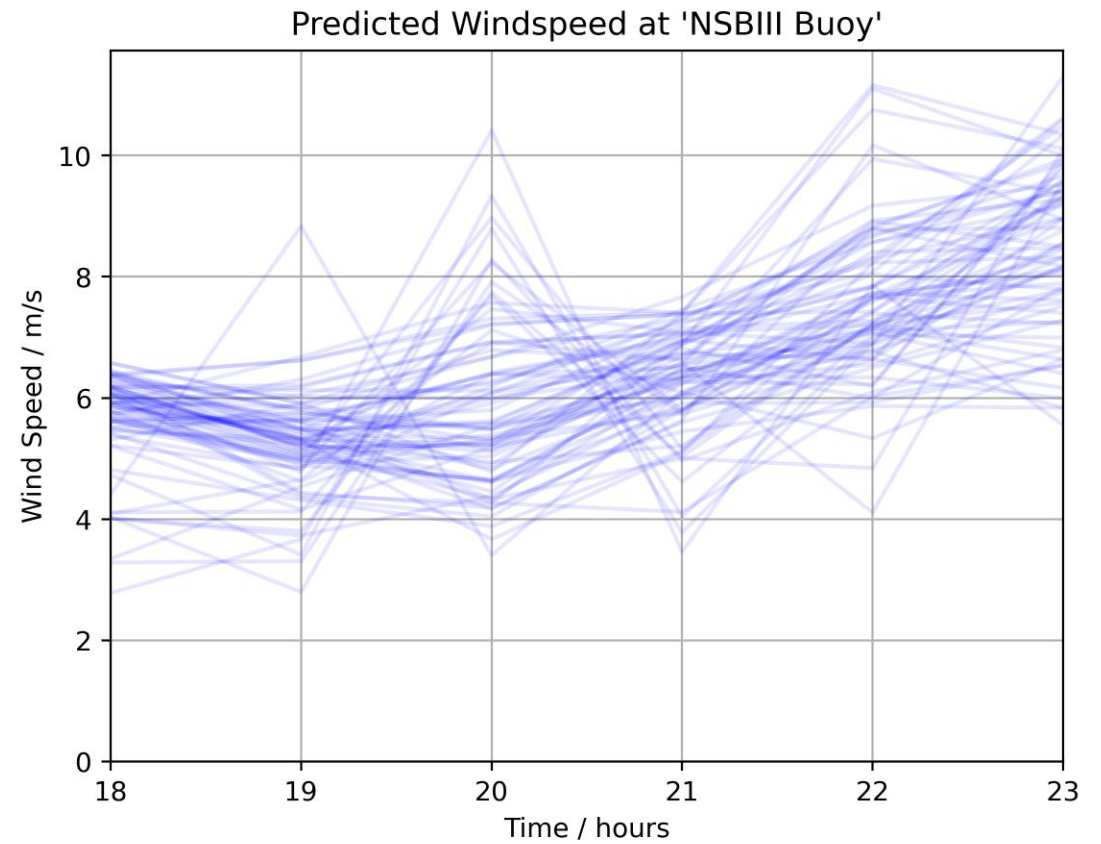
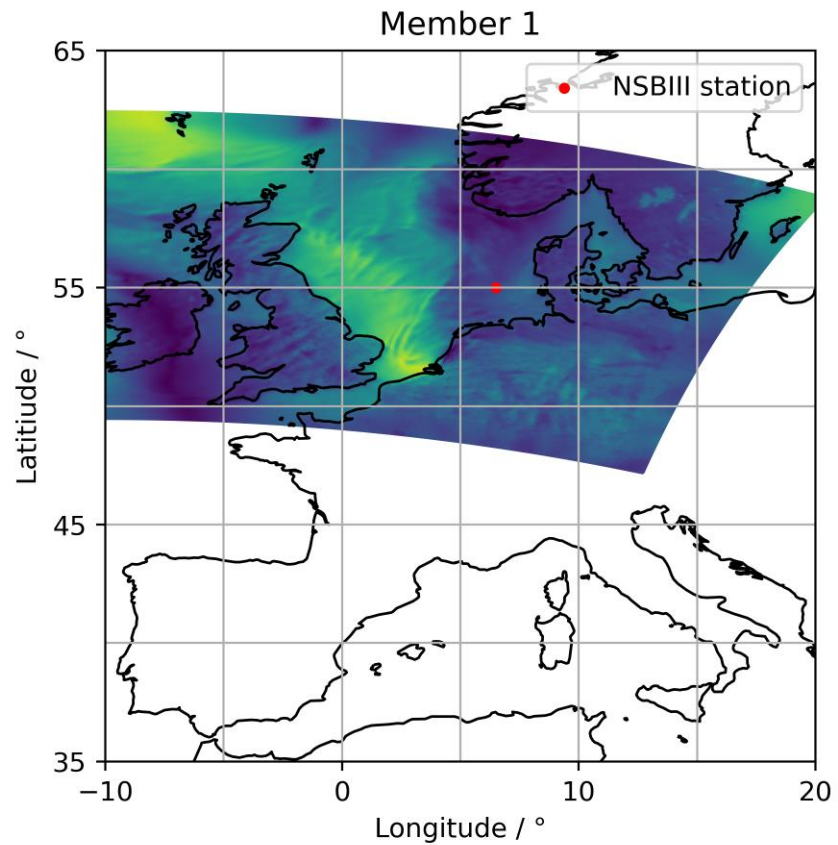


# Ensemble Forecasts

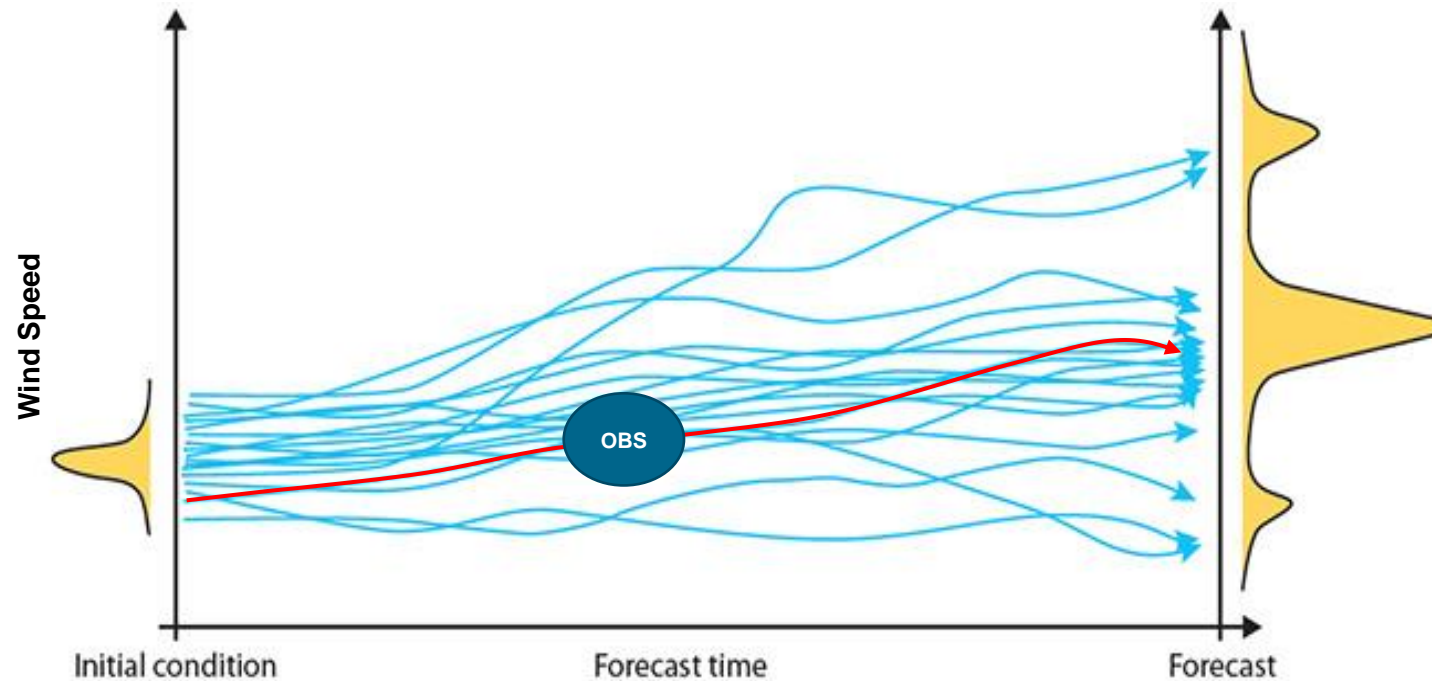
Forecasted Magnitude of Windspeed on the 20th of November



# Ensemble Forecasts

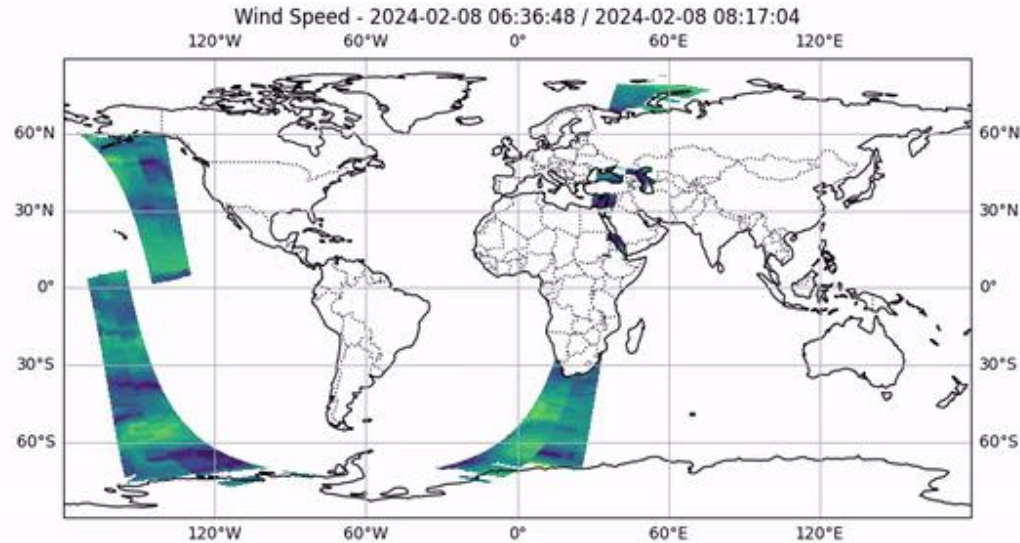


# Best Member Selection



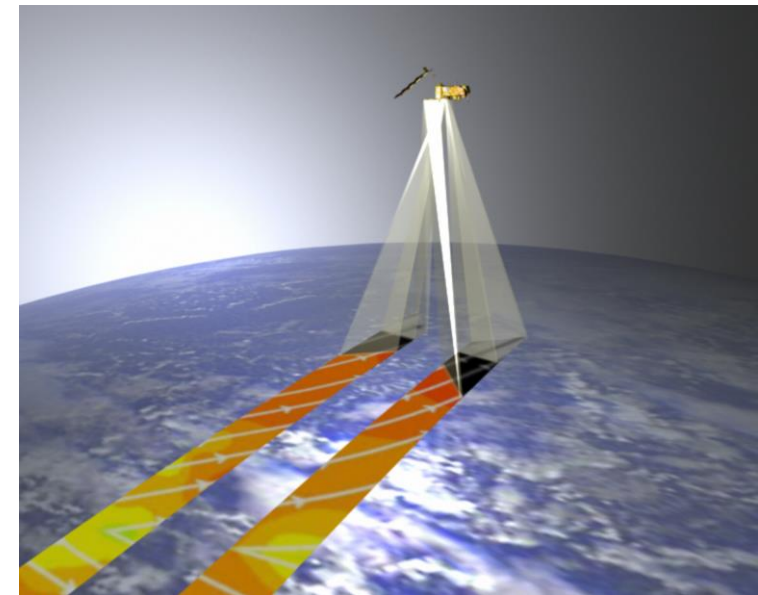
- Choose member closest to observation
- Member should provide best forecast for further future as well

# Best Member Selection using ASCAT



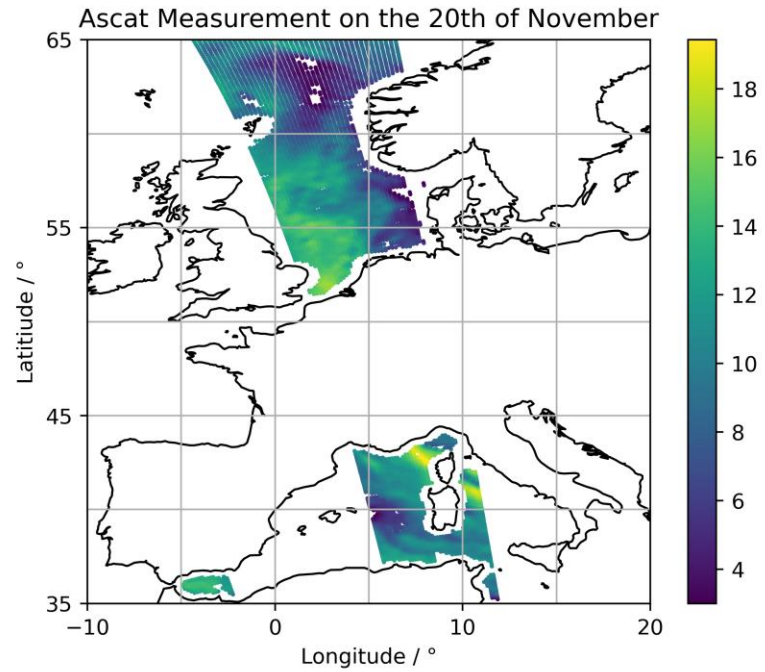
- Two satellites in polar orbits
- Pass over Europe at 8:30 a.m./p.m. (UTC)
- Surface level wind measurement over the ocean
- Uses radar scattering on waves formed by wind

MetOP satellite with ASCAT device

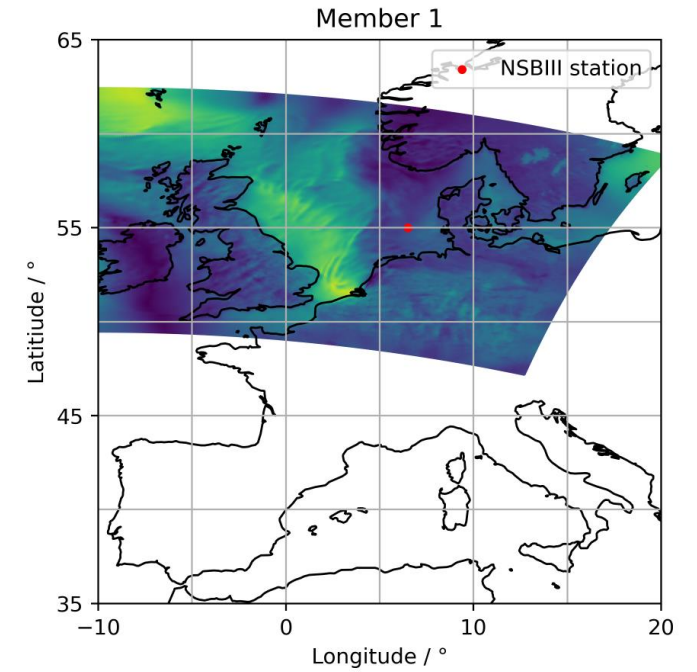


Source: ESA

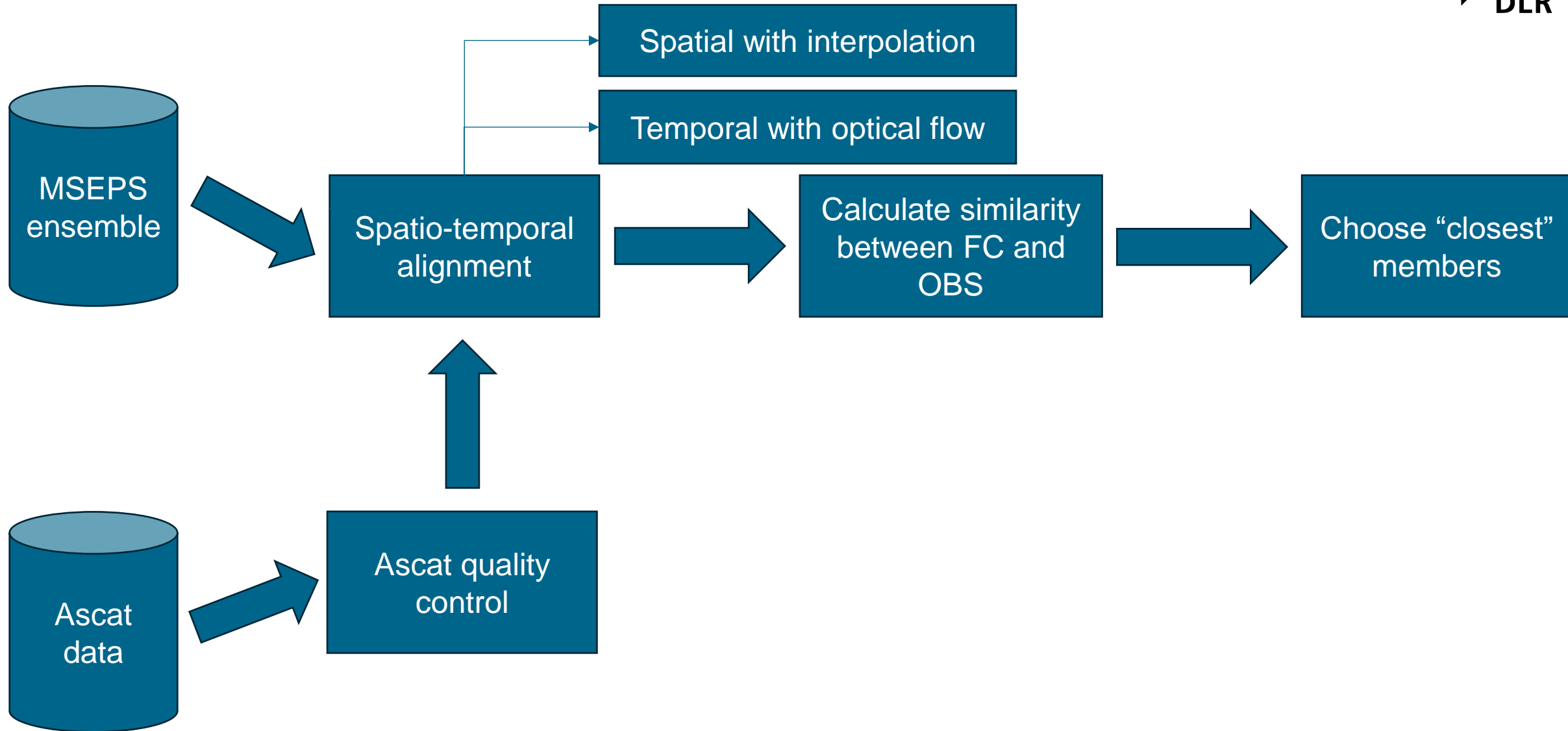
# Best Member Selection using ASCAT



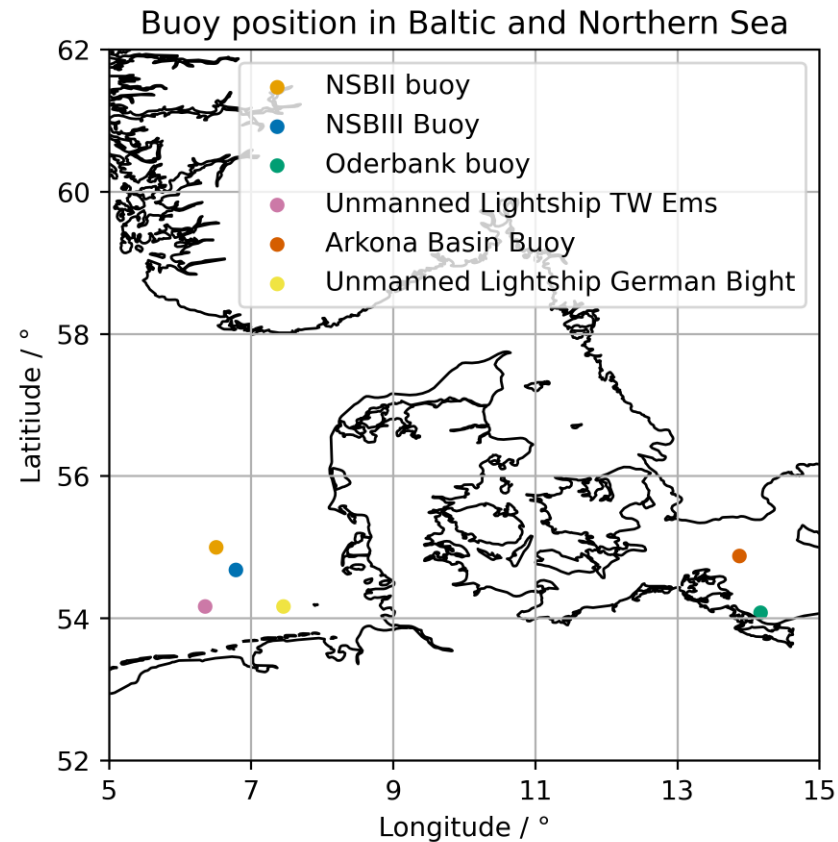
Compare and select



# Workflow for Best Member Selection



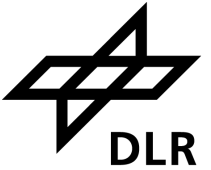
# Evaluation using buoy data



Source: BSH

- Given our supposed best member, how well does it actually perform?
- Interpolate Member onto 6 (maximum) buoy positions and compare it to their measurements
- Score is also the **Mean Absolute Error**

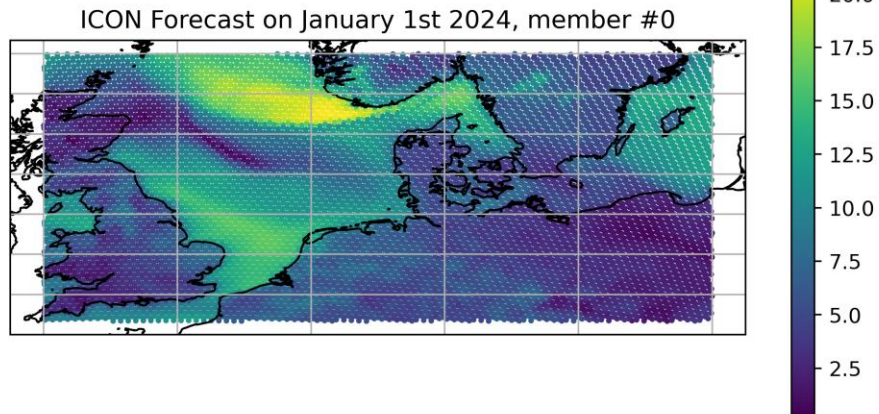
# Progress Update



- Use ICON (EU EPS) and ECMWF (EPS) forecasts with 48h lead times
- Improved optical flow algorithm for temporal alignment
- Limited area visible to ASCAT Best Member Selection
- Rewrote Workflow
- Analyzed results in the north sea to find out, what influences ASCAT driven best member selection to work well (in comparison to selection with buoy)

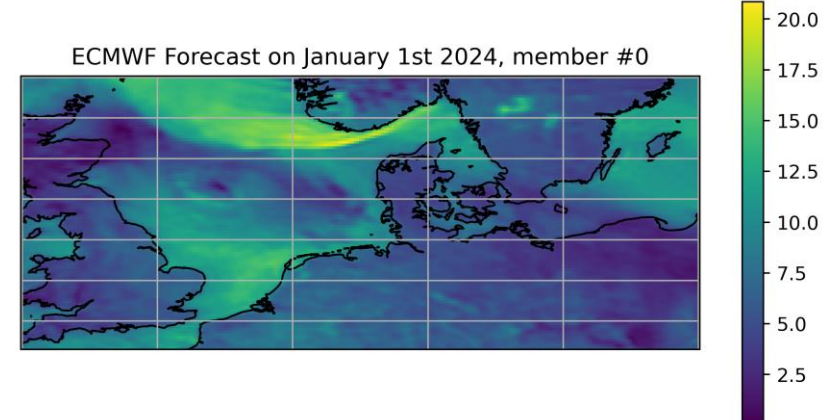
# ICON and ECMWF forecasts

## ICON



40 members  
48h maximum lead time

## ECWMF

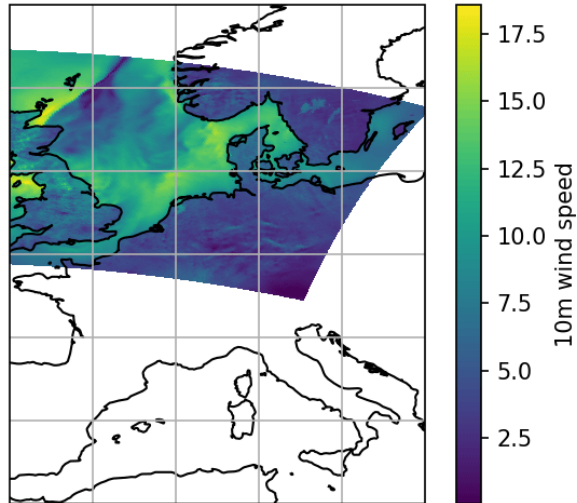


50 members  
48h maximum lead time

# Improved optical flow

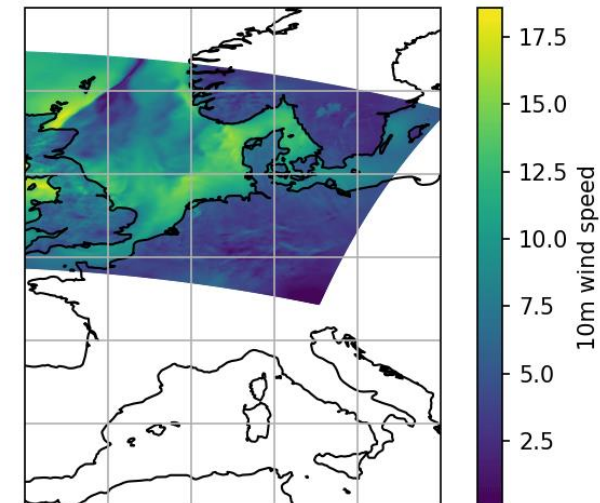
Before

Forecast member 1, t=2024-10-12T18:00:00.000000000



After

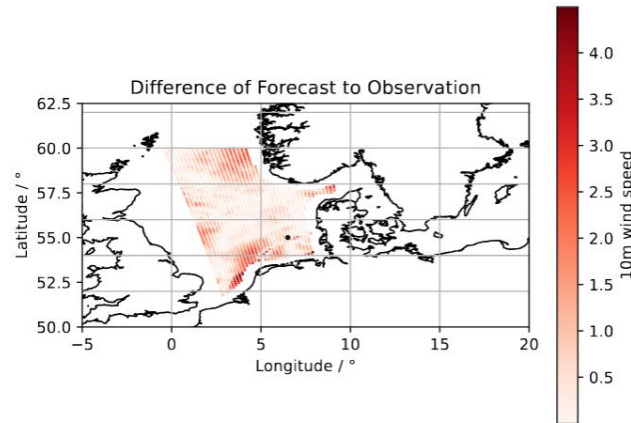
Forecast member 1, t=2024-10-12T18:00:00.000000000



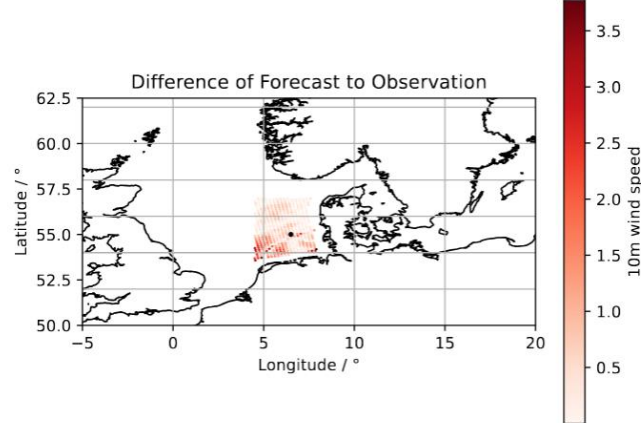
- Old algorithm calculated very small movement vectors
- Changed from polynomial based algorithm to variational algorithm that optimizes a cost function (DualTVL)
- Reduced artifacts, but slightly longer calculation time (~60s for 50 members)

# Impact of high gradient features on overall score

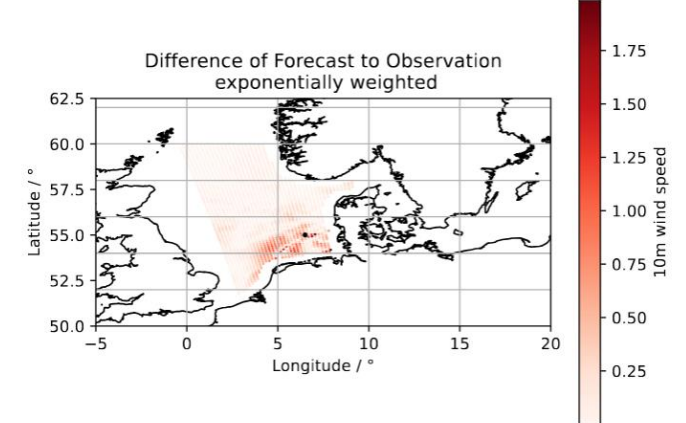
**Full ASCAT  
measurement**



**ASCAT limited to  
4°x4° window**

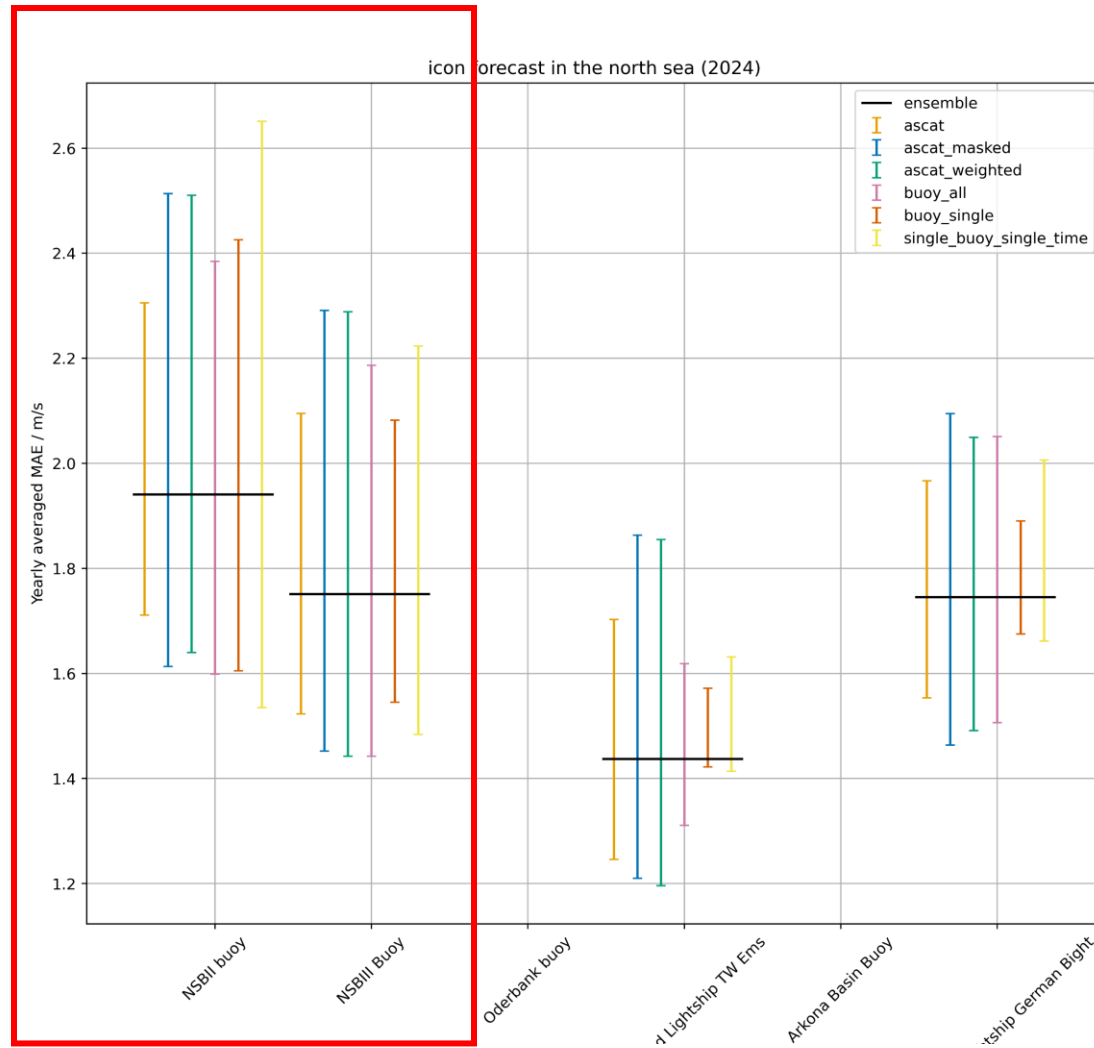


**Differences weighed**



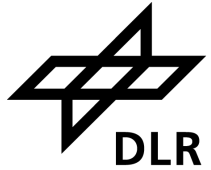
- Limited the spatial information to a smaller area
  - By using a smaller window
  - By exponentially weighing the absolute differences ( $\sim e^{-\frac{x}{\lambda}}$ ), where  $x$  is distance from buoy and  $\lambda$  a constant (150 km)
- Reduces impact of further away areas while keeping spatial information of direct surroundings of point of interest

# Performance of different BMS methods for ICON forecast

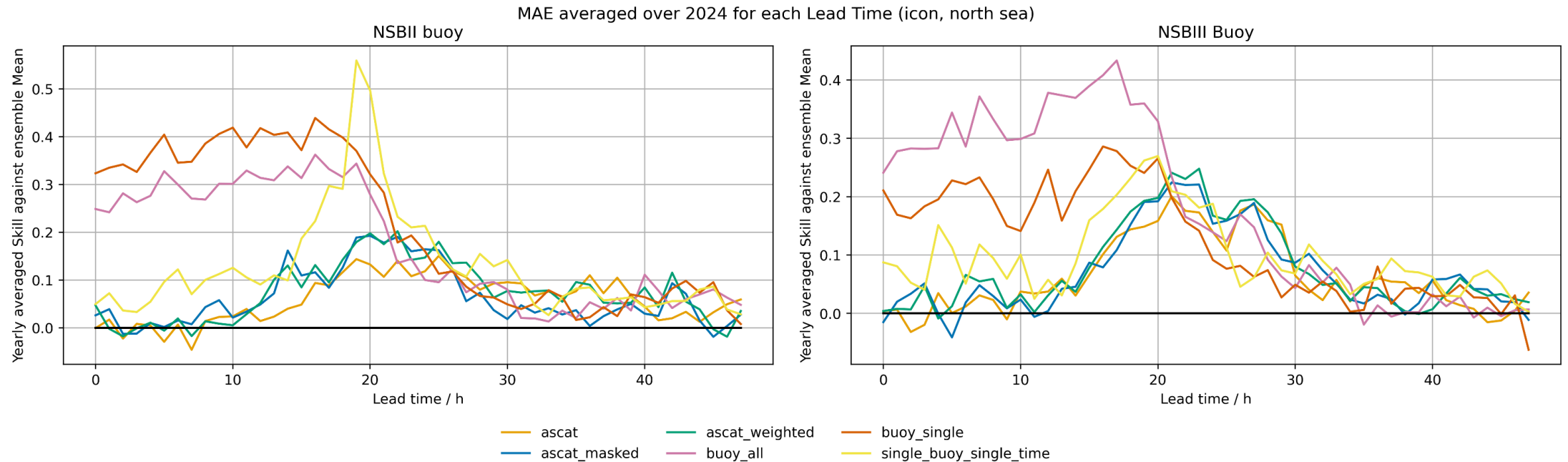


- These are not errors!
- **Black line is Ensemble Mean MAE**
- **Lower marker is Best Member MAE**
- **Upper marker is Worst Member MAE**
- with masking (cutout or weighing), ASCAT BMS performs as well as Buoy BMS

# Performance of different BMS methods for ICON forecast

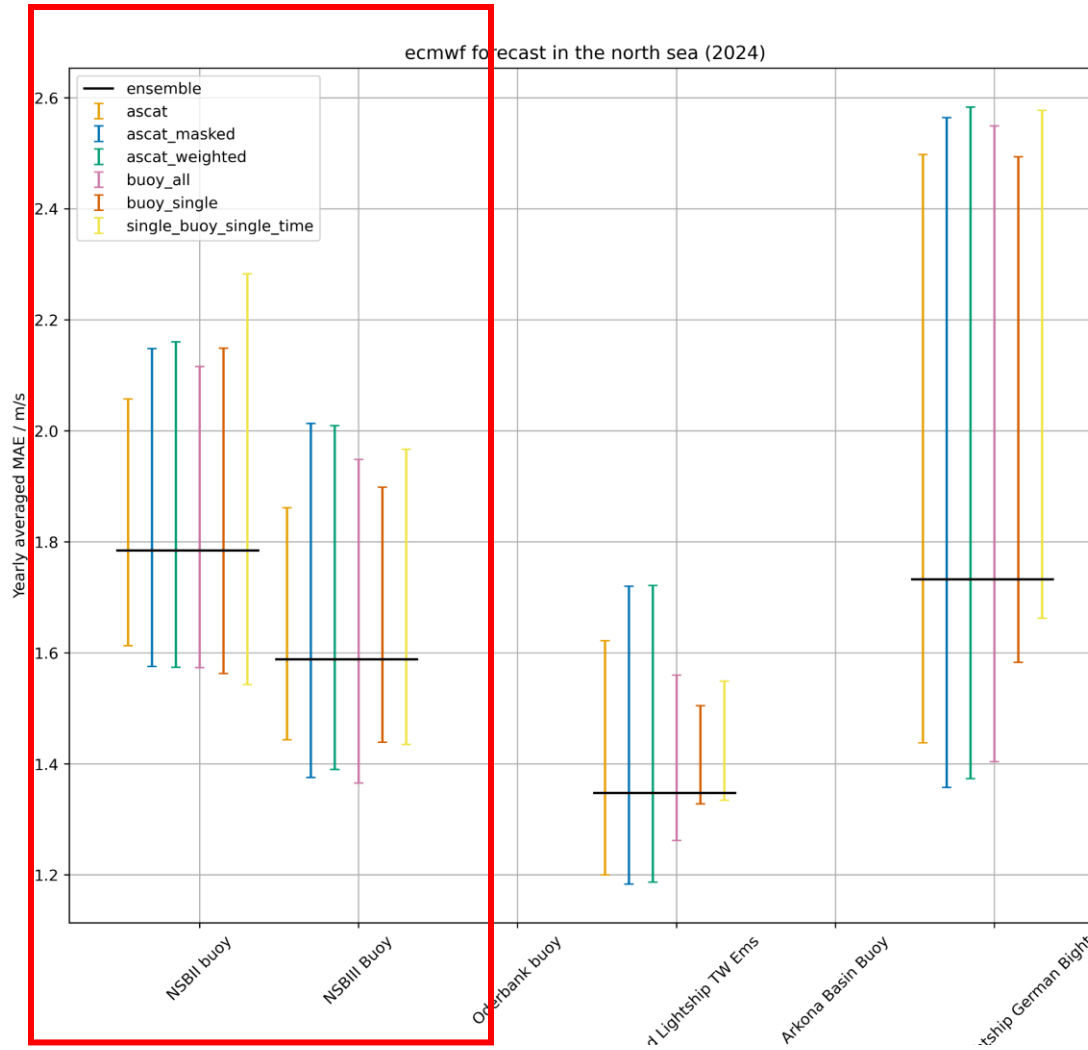


$$\text{Skill Score: } (1 - (MAE_{ASCAT\ BMS} / MAE_{Ensemble\ Mean}))$$



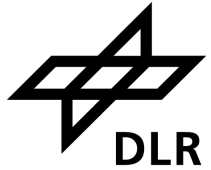
- Each time step is averaged for that time over the year of 2024
- ASCAT observation happens at 20h lead time
- Afterwards, there is a 5-7h period where Best Members perform better than ensemble mean (on average)
- Buoy BMS (that sees history) also performs well before ASCAT observation (orange and pink line)

# Performance of different BMS methods for ECMWF forecast

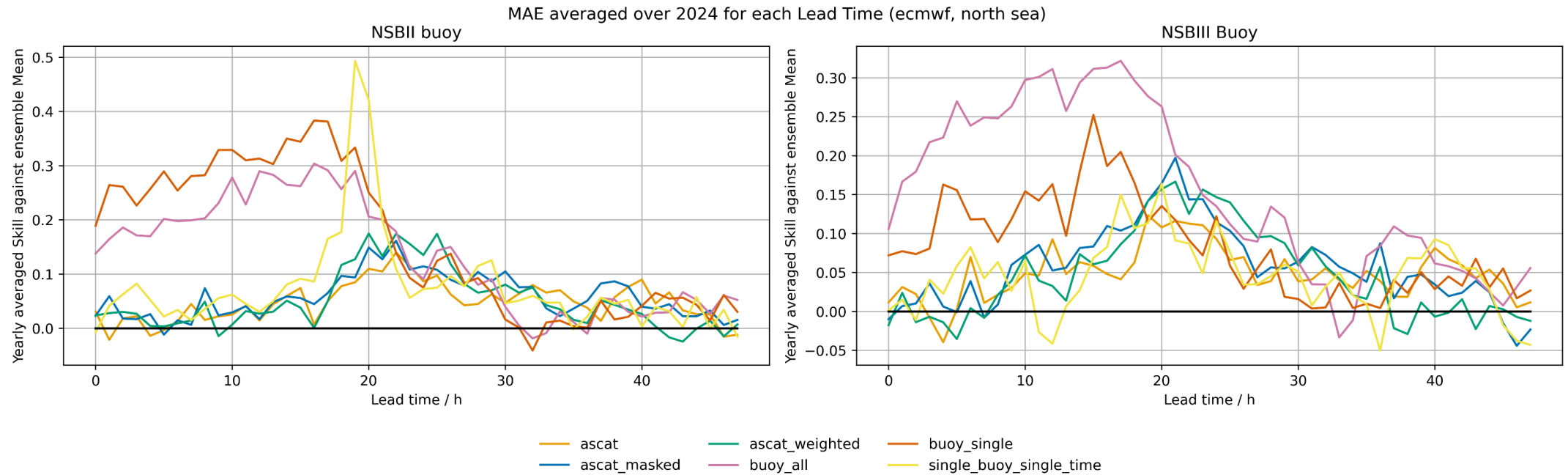


- Similar to ICON
- Ensemble MAE is slightly lower (0.2 m/s)

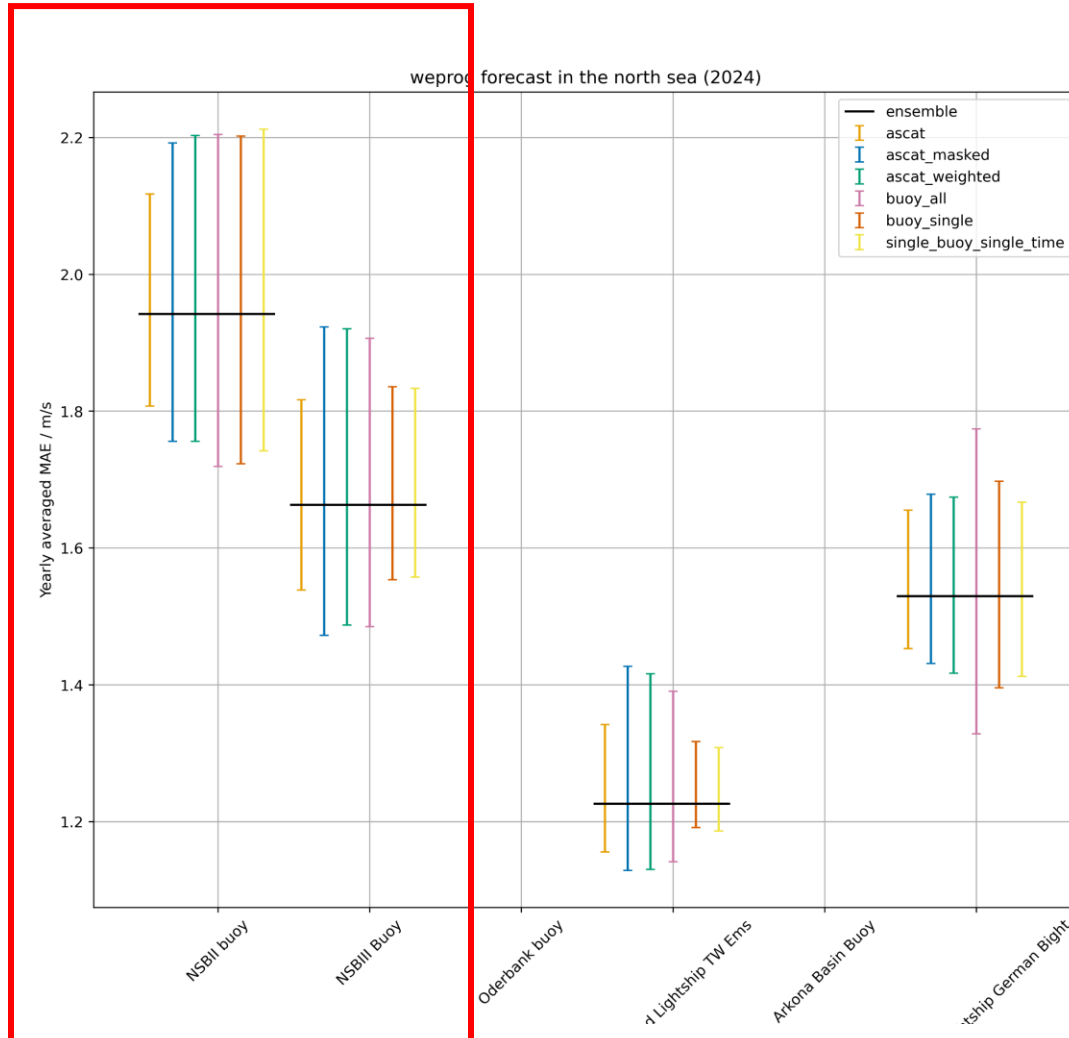
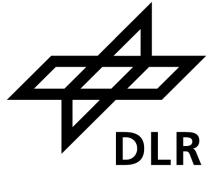
# Performance of different BMS methods for ECMWF forecast



Skill Score:  $(1 - (MAE_{ASCAT\ BMS} / MAE_{Ensemble\ Mean}))$



# Performance of different BMS methods for WEPROG forecast



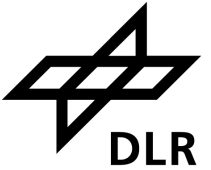
- Slightly better ensemble MAE than ICON
- Lower spread of (best and worst) members

# Finding a score to determine when to use ASCAT over buoy



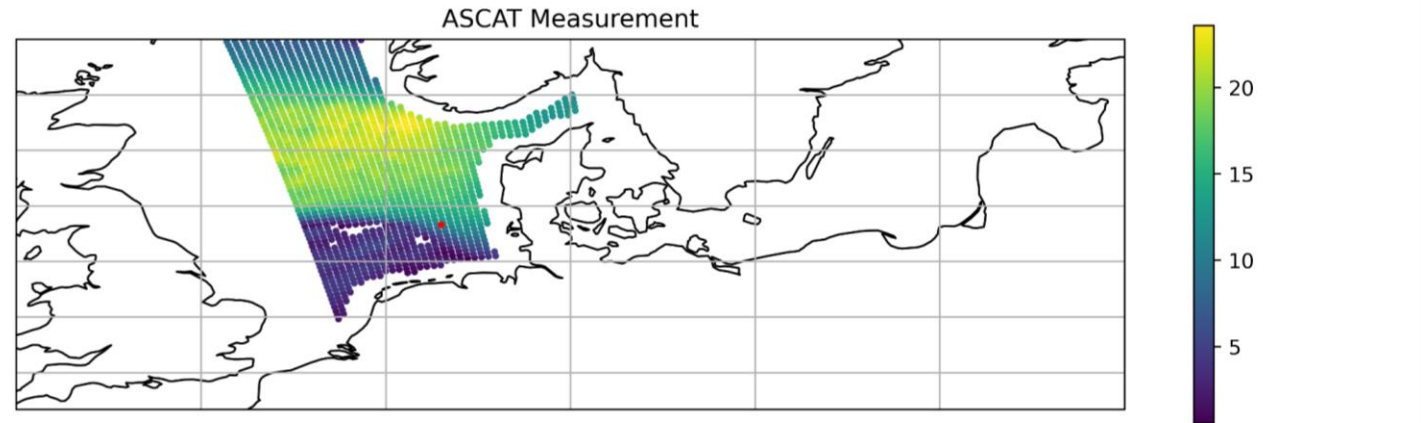
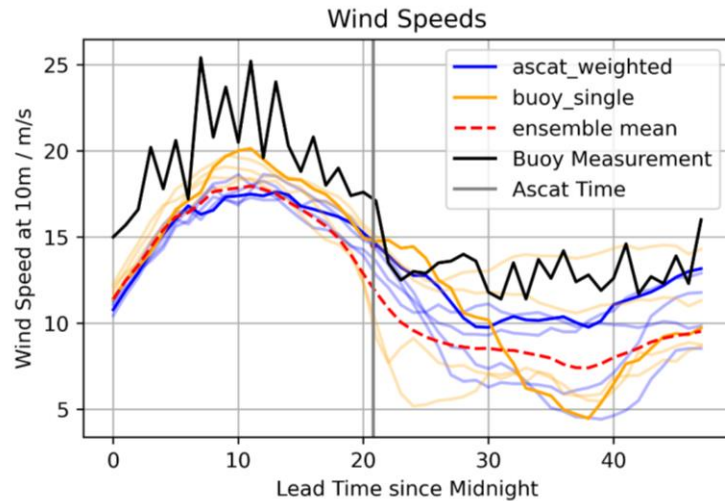
- After forecast period has passed, we can evaluate performance with buoy data
- Use a combined score
  - $(MAE_{Buoy\ BMS} - MAE_{ASCAT\ BMS})$ : difference of MAEs of members selected by buoys and ASCAT; **is large if ASCAT performs better than buoys** (evaluated for 5 hours after the ASCAT measurement)
  - $(1 - (MAE_{ASCAT\ BMS}/MAE_{Ensemble\ Mean}))$ : Skill score of best ASCAT selected member compared to Ensemble Mean; **is large if ASCAT performs better than ensemble mean**
  - Look at events where BMS leads to improvement and ASCAT works better than buoy
- Cannot calculate this score “at runtime”
- Find a different score that correlates with this one

# Investigating events, where ASCAT performs better than selection with buoy

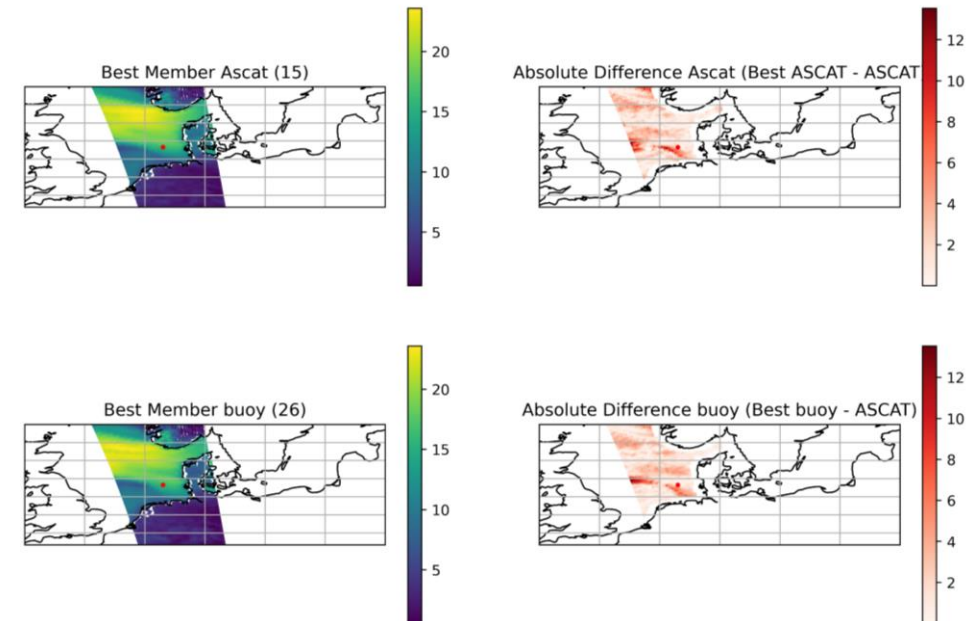


- Usual involvement of spatial features in the wind field
- Also works on days with more homogenous wind
- “historic information” for buoy selection does not seem to matter
  - May actually be a disadvantage, as prior good performance does not guarantee good performance in the future

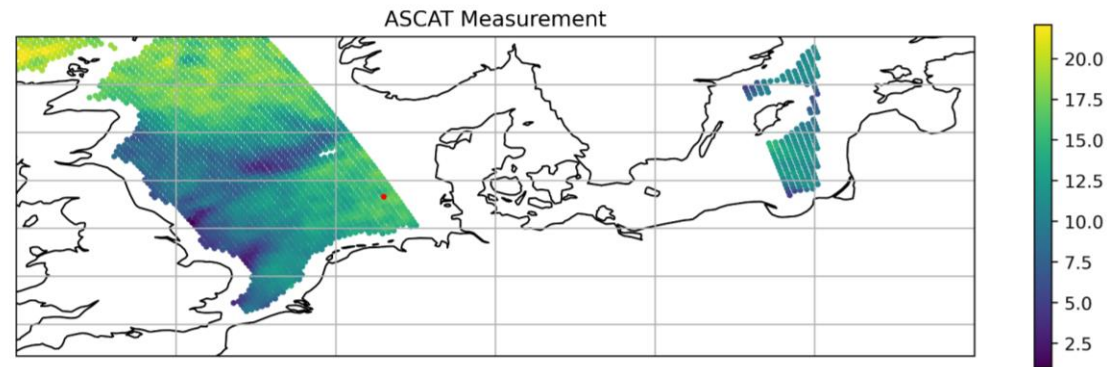
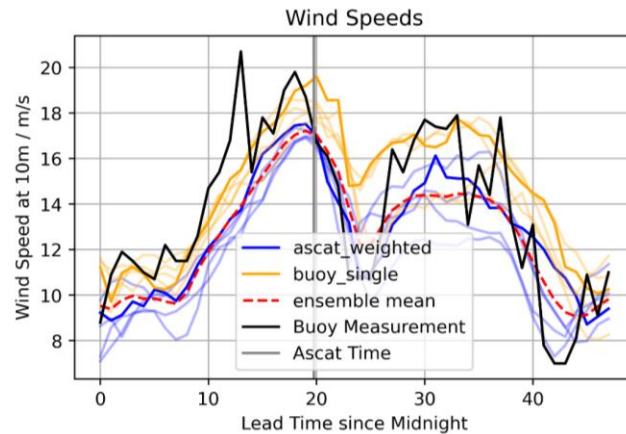
# Investigating events, where ASCAT performs better than selection with buoy



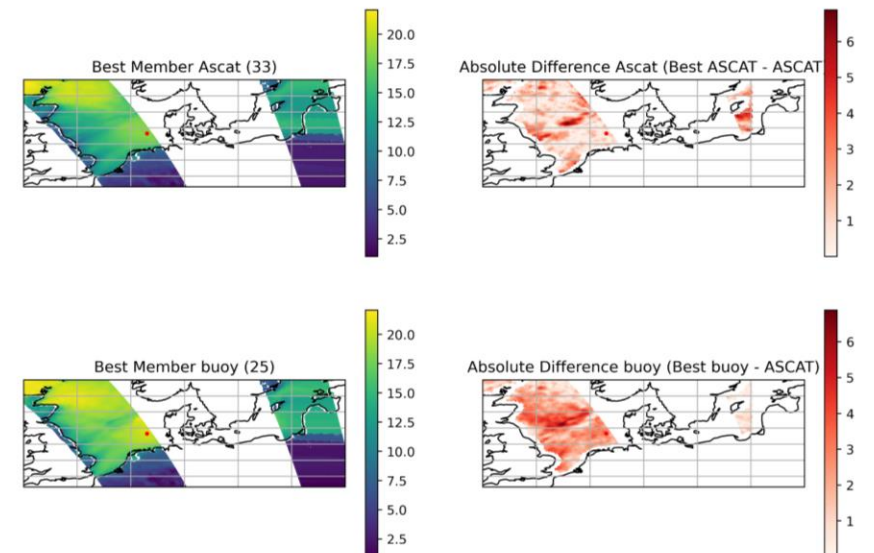
- Timing of windfront predicted
- Also predicted windspeed better than mean
- MAE map again shows influence of spatial feature



# Investigating events, where ASCAT performs better than selection with buoy

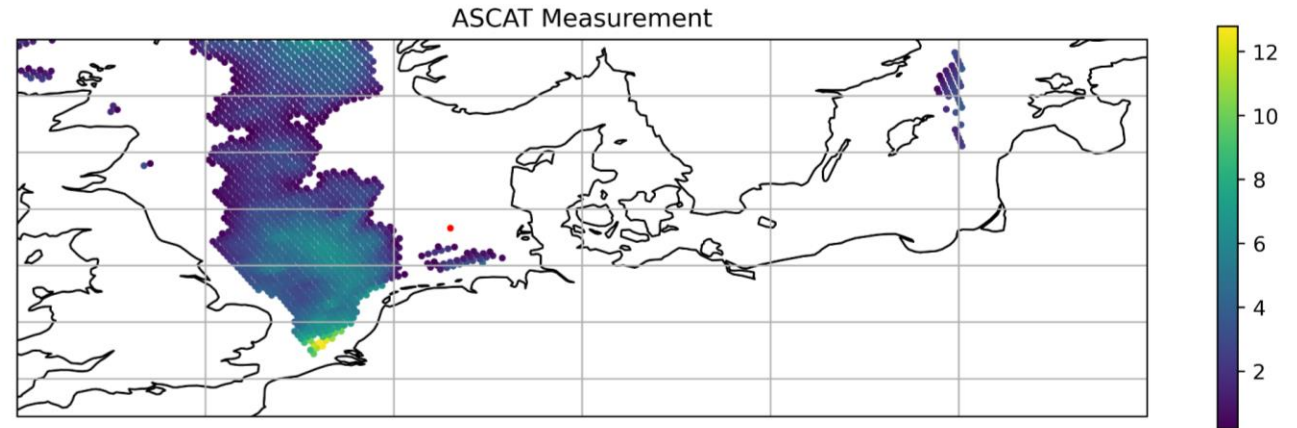
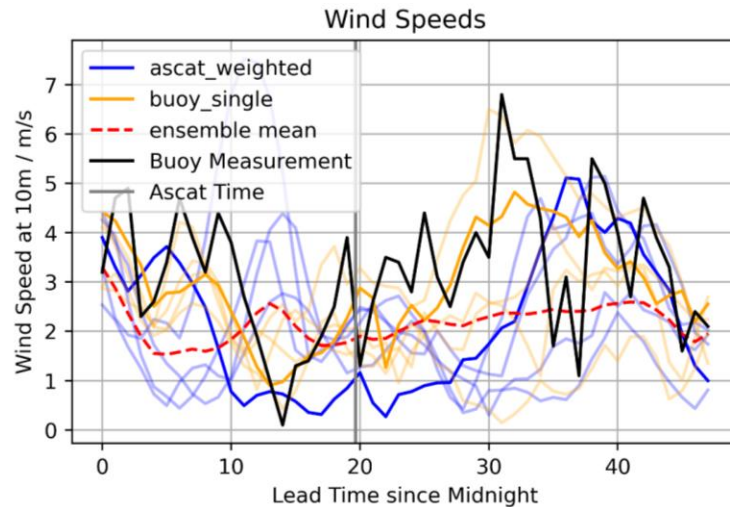


- Also works without obvious spatial features
- ASCAT selects event, where windspeed is correct in the surrounding area, ensuring good forecast over next few hours
- Buoy only selects member, that fits at observation time, no guarantee for future performance

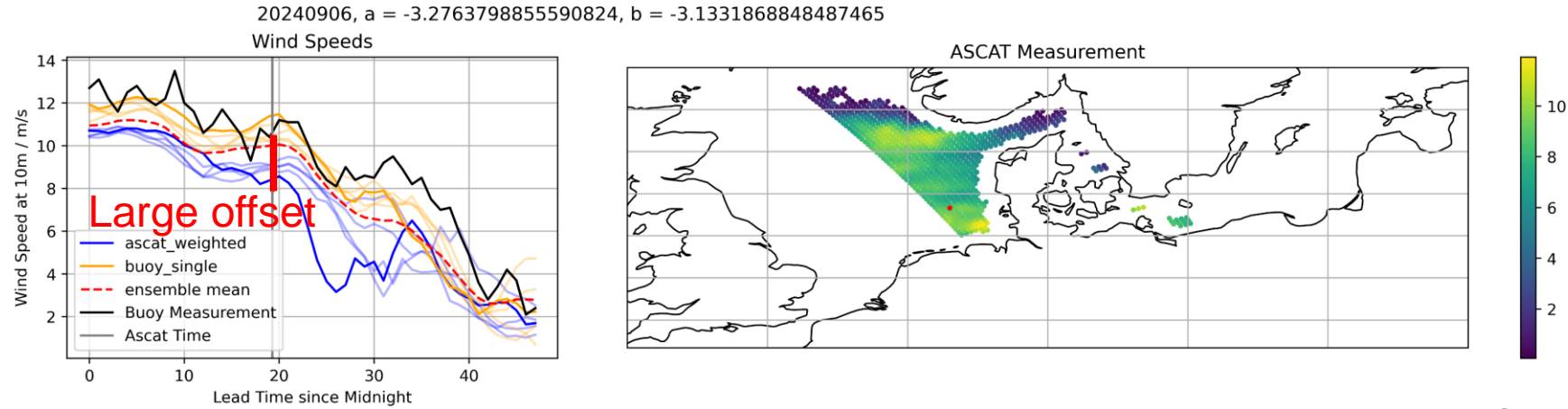


# Investigating events, where ASCAT performs worse than selection with buoy

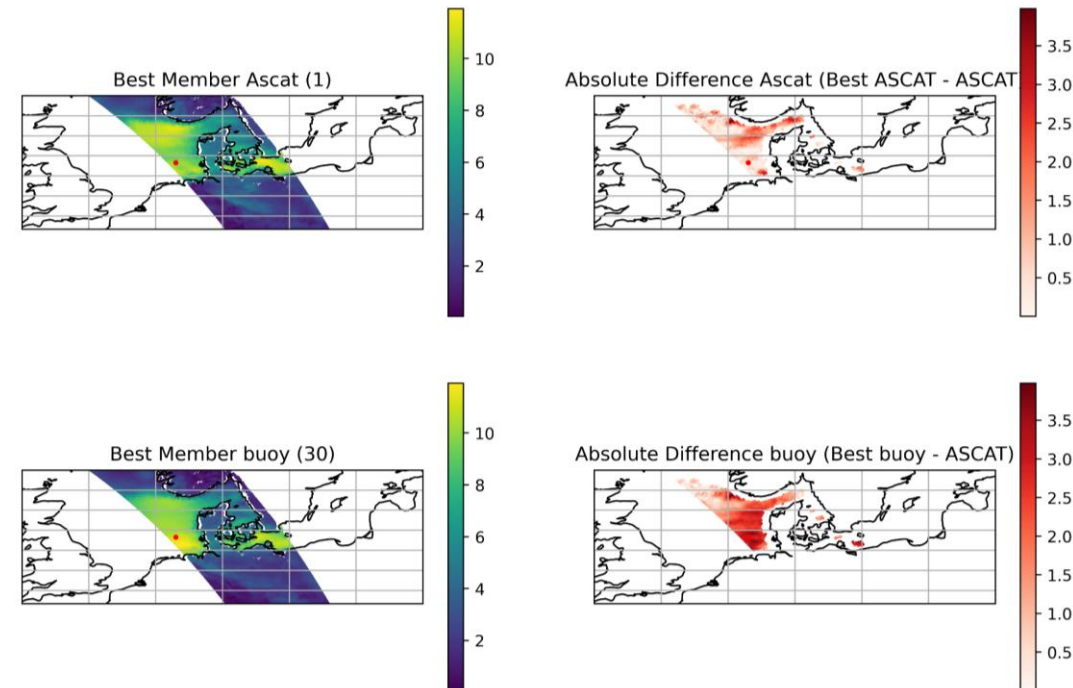
- For a lot of events, the buoy was not actually in the ASCAT scan
- Quality control flags large regions due to low wind speed and/or e.g. storms



# Investigating events, where ASCAT performs worse than selection with buoy

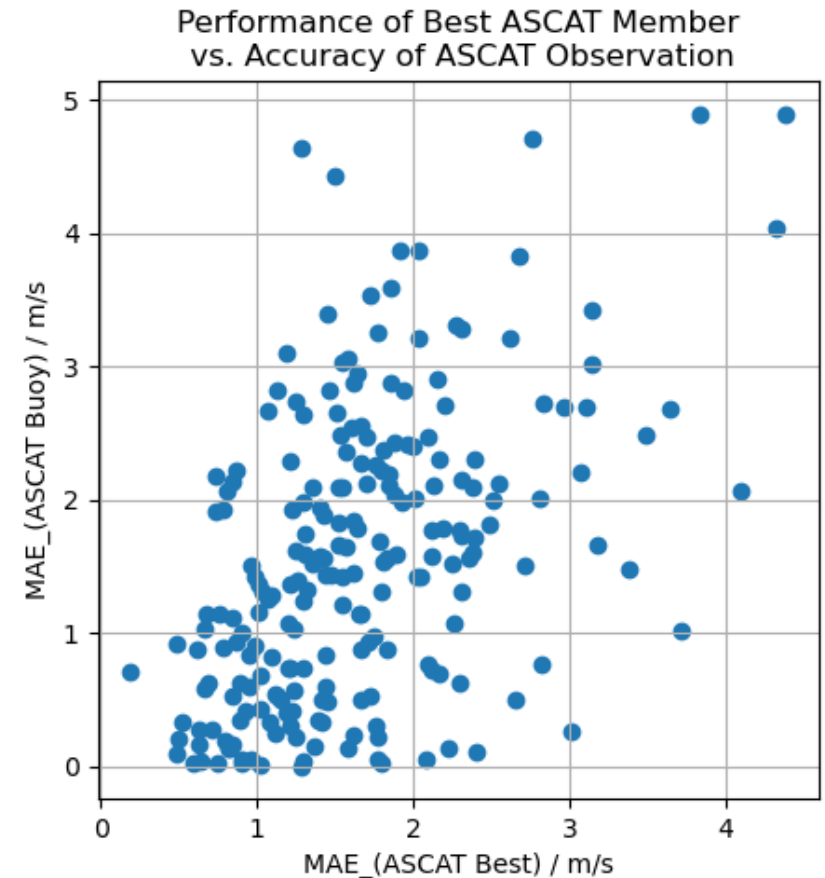


- ASCAT sometimes measures windspeed wrong
  - ASCAT map is offset by a few m/s compared to forecast
  - Especially bad if buoy is currently experiencing rising/falling windspeed



# Finding a score that predicts if ASCAT will work better than selection with buoy

- Use gradient (its magnitude) of the windfield as score
  - Magnitude is related to average windspeed
  - Difficult to find a threshold, as spatial features are not only in high wind speed regions
- Difference of **ASCAT Windspeed and Buoy Windspeed** (during scan) to judge if ASCAT measured wrong
  - Correlation between **Best Member MAE** (over five hours after ASCAT observation) and this difference
  - Correlation coefficient of 0.48



# Summary



- Using optimized optical flow and better ASCAT scan selection, ASCAT BMS performs about as good as BMS with buoys on buoys in the north sea
- ASCAT BMS works across different Forecasts (WEPROG, ECMWF ICON)
  - Improvement for about 5 hours after Scan
- ASCAT BMS suffers from relatively high measurement errors of wind speed (~2 m/s)
  - The measurement error correlates with ASCAT performance

- Use a neural network to select the members
  - Replaces MAE as metric
  - Generate probabilistic forecasts
- Also possibly judge when to use/trust a Scan and when not
- Make use of Chinese and Indian Satellites (Oceansat3, HY-2B, HY-2C)
  - More scans spread over the entire day
- We are also placing a lot of trust in (two!) buoys for verification
  - Not sufficient
  - Try to get more data for verification
  - Possibly do verification in Ireland using data from wind parks