

The CHEOPS view of HD 95338b: Refined transit parameters, and a search for exomoons[★]

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ABSTRACT

Context. Despite the ever-increasing number of known exoplanets, no uncontested detections have been made of their satellites, known as exomoons.

Aims. The quest to find exomoons is at the forefront of exoplanetary sciences. Certain space-born instruments are thought to be suitable for this purpose. We show the progress made with the CHAracterising ExOPlanets Satellite (CHEOPS) in this field using the HD 95338 planetary system. We present a novel methodology as an important step in the quest to find exomoons.

Methods. We utilised ground-based spectroscopic data in combination with Gaia observations to obtain precise stellar parameters. These were then used as input in the analysis of the planetary transits observed by CHEOPS and the Transiting Exoplanet Survey Satellite (TESS). In addition, we searched for the signs of satellites primarily in the form of additional transits in the Hill sphere of the eccentric Neptune-sized planet HD 95338b in a sequential approach based on four CHEOPS visits. We also briefly explored the transit timing variations of the planet.

Results. We present refined stellar and planetary parameters, narrowing down the uncertainty on the planet-to-star radius ratio by a factor of ten. We also pin down the ephemeris of HD 95338b. Using injection-and-retrieval tests, we show that a 5σ detection of an exomoon would be possible at $R_{\text{Moon}} = 0.8 R_{\oplus}$ with the methodology presented here.

Conclusions. We exclude the transit of an exomoon in the HD 95338 system with $R_{\text{Moon}} \approx 0.6 R_{\oplus}$ at the 1σ level. The algorithm used for finding the transit-like event can be used as a baseline for other similar targets, observed by CHEOPS or other missions.

Key words. methods: data analysis – techniques: photometric – planets and satellites: individual: HD 95338b

1. Introduction

Following the discovery of the first confirmed extrasolar planet orbiting a main sequence star (Mayor & Queloz 1995), close to 6000 exoplanets have been identified¹. One of the key points of these past decades is the fact that the Solar system is not unique in many aspects: it is simply one of the ever-growing number of known planetary systems in our Galaxy. Based on our understanding of the Solar System, we expect that there are

perhaps orders of magnitude more satellites orbiting exoplanets compared to the number of exoplanets. Yet at the time of writing, there are no confirmed exomoons, but there are a number of possible explanations for this (see Szabó et al. 2024, and references therein). With the introduction of space telescopes such as Kepler (Borucki et al. 2010) and CHAracterising ExOPlanets Satellite (CHEOPS; Benz et al. 2021), we have the theoretical capability of finding transiting exomoons below the size of Earth.

The *Kepler* space telescope was the first instrument recognised to be able to detect an exomoon (Szabó et al. 2006; Simon et al. 2007). Kipping et al. (2015) and Kipping et al. (2022) performed extensive analyses of Kepler light curves with the aim of finding transiting exomoons, yielding Kepler-1708b-i as a candidate. Another method thought to be useful for detection

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¹ On 11/06/2024, the NASA Exoplanet Archive listed 5787 confirmed planets, <https://exoplanetarchive.ipac.caltech.edu/>

of satellites is based on the transit timing variations (TTVs) of the planets (Simon et al. 2007; Kipping 2009) caused by exomoons. Fox & Wiegert (2021) identified six candidates based on their Kepler datasets, which were found to be false positives by Kipping (2020). Kipping & Yahalomi (2023) found no strong TTV signals that could be linked to satellites in a large set of suitable planets observed by Kepler. Simon et al. (2015) predicted that Earth-sized exomoons could likely be detectable with CHEOPS. For that reason, a considerable effort has been devoted within the CHEOPS Science Team to observing systems that are likely to sustain exomoons for long periods of time (see e.g. Dobos et al. 2022) in pursuit of detecting these objects. Ehrenreich et al. (2023) found that there are likely no transiting bodies above the size of Mars orbiting ν^2 Lupi d, based on 1.5 transits observed with CHEOPS.

In this paper, we present the necessary steps in the search for moons orbiting the bright ($V = 8.62$ mag) star HD 95338, including refining the stellar and planetary parameters, analysing synthetic data, and placing upper limits on the hypothesised satellite. Díaz et al. (2020) reported the discovery of a dense Neptune-sized planet ($3.89^{+0.19}_{-0.20} R_{\oplus}$, $42.44^{+2.22}_{-2.08} M_{\oplus}$, yielding a density of $3.98^{+0.62}_{-0.64} \text{ g cm}^{-3}$), HD 95338b. Based on a single transit observed by the Transiting Exoplanet Survey Satellite (TESS; Ricker et al. 2015) and a large number of radial velocity measurements, Díaz et al. (2020) found an orbital period of 55.087 ± 0.020 days. This meant that the planet could be far enough from its host star that an exomoon could survive for several gigayears (Dobos et al. 2022), yet close enough that it can be observed multiple times during the life cycle of CHEOPS, leading to tighter constraints on its parameters, as well as on those of its hypothetical companion. However, due to the Sun-synchronous, dusk-dawn low Earth orbit of the satellite, long-period planets might only be observable once a year.

This paper is structured as follows. In Sect. 2, we describe in detail the photometry of CHEOPS and TESS observations, with a special emphasis on the various detrending steps needed to account for the known instrumental effects. We also provide details of the modelling of the transit of HD 95338b. New and improved stellar parameters are provided in Sect. 3. In Sect. 4, we present the refined planetary parameters, based on five transits observed with CHEOPS and TESS. In Sect. 5, we present a novel method for chasing transits linked to exomoons. We argue for the need of a thorough noise treatment to avoid false positive exomoon detections. We exclude the presence of Mars-sized transiting exomoons at 1σ . In Sect. 5.3, we present the analyses of synthetic data, which are used to justify the algorithm utilised in the search for additional transits. We show that even from a single transit, the 3σ detection of a less than $1 R_{\oplus}$ transit would be feasible in this system.

2. Methods

2.1. CHEOPS photometry

CHEOPS observed four transits of HD 95338b (during four separate visits) in March 2021, April 2022, May 2023, and April 2025 (Table A.1). The spacecraft is on a low Earth orbit, with an ≈ 100 min period. Consequently, targets cannot be observed continuously throughout an orbit due to Earth occultations, crossing over the South Atlantic Anomaly, and too high stray-light contributions, as is often discussed with regards to CHEOPS data (e.g. Lacedelli et al. 2022; Krenn et al. 2024). This is reflected in the so-called observational efficiency (Table A.1). We extracted light curves using the CHEOPS Data Reduction Pipeline (DRP;

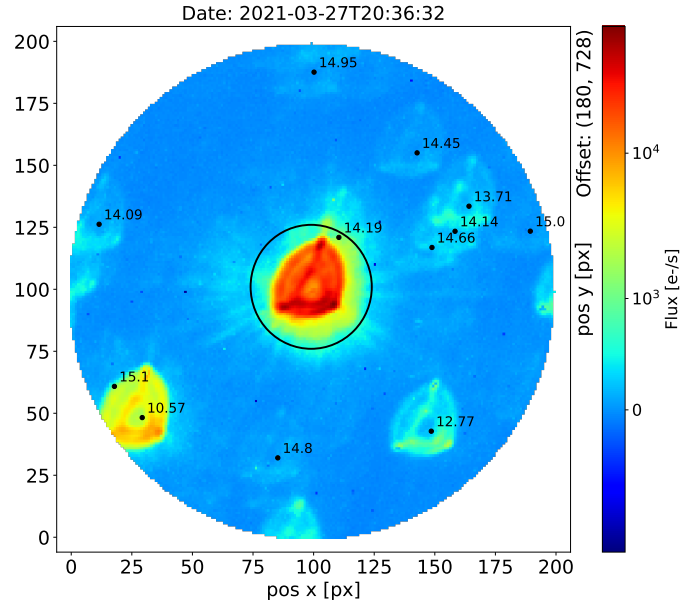


Fig. 1. The Subarray image depicts the point spread function (PSF) of HD 95338b and the neighbouring stars, with their respective magnitudes of brightness indicated. The target is centred on the coordinates (180, 178) on the CCD.

version 14.1.2; Hoyer et al. 2020). The DRP performs the bias, read-out noise, flatfield, and smearing-corrections, while also estimating the telescope jitter and background contamination. The pipeline also carries out aperture photometry using a circular apertures, with radii between 15 and 40 pixels (in 1-pixel steps). In this work, we rely on light curves extracted using the $R = 25$ px radius aperture (the so-called default mode).

Due to the spacecraft rolling around its line of sight, the well-known triangular point spread function (as discussed in e.g. Szabó et al. 2021; Kiefer et al. 2023) of any given star (Fig. 1) falls onto different pixels throughout each orbit (causing a part of the flux to fall in and out of the circular aperture as the telescope rolls). Several factors, including the inhomogeneous nature of the CCD, stray light, smearing trails, and thermal variability of the instrument result in the appearance of periodic or quasi-periodic systematic effects that are correlated with the angular orientation (and possibly the jitter) of the spacecraft. Additionally, the flux contribution of nearby stars also introduces a noise source that changes throughout each orbit and is therefore correlated in nature. The background variation thus also has to be estimated for every exposure.

We emphasise, that in the context of nominal science observations, a subset of the full frame images, known as ‘window images’, are downlinked. In order to minimise the noise caused by bad pixels, it is necessary to move the position of the window in the CCD to different regions of the CCD when required. In May 2024, the position of the window was relocated to the central location of the CCD². This resulted in the fourth visit being observed in a distinct region of the CCD compared to the initial three observations. This modification has resulted in a shift in the configuration of the star pattern within the full frame. This alteration has had an impact on the correlation between the flux and the roll angle of the telescopes (and the number of used harmonics of the roll angle in the analysis). This is due

² <https://www.cosmos.esa.int/web/cheops-guest-observers-programme/in-orbit-updates>

to the fact that the smearing trails of the background stars within the full frame intersect the window as the field rotates around the target star.

2.2. TESS photometry

In addition to the CHEOPS photometry described above, we also obtained the short-cadence SAP (Simple Aperture Photometry) light curves from sectors 10 and 63 of TESS (Transiting Exoplanet Survey Satellite; [Ricker et al. 2015](#)). These include one transit of HD 95338b each. The transit from sector 10 was also analysed by [Díaz et al. \(2020\)](#). We corrected for contamination in the aperture using the CROWDSAP keyword. We downloaded the light curves from the two sectors from MAST. Additionally, we corrected for the pointing instability of the telescope using the pipeline-estimated position of the photocenter. As a final preparatory step, we cut out a 1.5 and a 3-day window (in sectors 10 and 63, respectively) of the light curves – that are centered on the two transits – in order to minimise the computational time needed for the analysis described below.

2.3. Modelling the transit of HD 95338b from CHEOPS

There are a number of algorithms and software packages capable of modelling a transiting exoplanet and their satellites, including planetplanet ([Luger et al. 2017](#)), the phase-folding method by [Kipping \(2021\)](#), the analytical framework of [Saha & Sengupta \(2022\)](#), and Pandora ([Hippke & Heller 2022](#)). There are, however, none that incorporate the advanced noise filtering algorithms such as those based on Gaussian processes (GPs; e.g. [Rasmussen & Williams 2006](#); [Roberts et al. 2012](#); [Ebdén 2015](#)) or a wavelet-based technique (e.g. [Carter & Winn 2009](#)). These tools are used to deal with the time-correlated noise arising from both astrophysical and instrumental noise sources. Their benefits in avoiding distortions of the light curve parameters of transiting exoplanets are clearly demonstrated in [Barros et al. \(2020\)](#), [Csizmadia et al. \(2023\)](#), and [Kálmán et al. \(2023b\)](#). Regarding the detection of exomoon transits specifically, [Kálmán et al. \(2024a\)](#) and [Szabó et al. \(2024\)](#) discuss the implications of insufficient noise treatment.

The two perhaps most well-known exomoon candidates, Kepler-1625b-i ([Teachey & Kipping 2018](#)) and Kepler-1708b-i ([Kipping et al. 2022](#)), identified by a so-called photodynamical method, where the parameters of the planet and its satellite are fitted jointly, are not confirmed through independent investigations. In fact, [Heller et al. \(2019\)](#) and [Kreidberg et al. \(2019\)](#) provide alternative explanation for the exomoon signal observed in Kepler-1625b-i, involving the presence of red noise. More recently, [Heller & Hippke \(2024\)](#) presented evidence suggesting that ‘large exomoons are unlikely’ around both Kepler-1625b and Kepler-1708b, although this is again refuted ([Kipping et al. 2025](#)). It is reasonable to expect that a simultaneous fitting of the planetary and lunar signals with the time-correlated noise would be beneficial in discerning false-positives from bona fide exomoons.

Lacking such a tool, we developed a sequential scheme to search for exomoon-like signals in the CHEOPS light curves of HD 95338b. In the first step, we model the transit of HD 95338b, then in the second step, we search the residuals for signs of additional transits. The transit signal that could be attributed to an exomoon has an amplitude on the order of ≈ 100 ppm (as is discussed in Section 5). Thus a thorough detrending of the known systematic effects is essential to avoid false-positive detections.

We therefore constructed a strict framework to handle the known (quasi-periodic) systematic effects as follows:

0. Remove light curve points that are heavily affected by cosmic rays and remove four points before and after each gap (only for the fourth visit).
1. Conduct preliminary transit modelling of HD 95338b.
2. Find the best-fit model of the instrumental effects in the residuals of the previous step; find the $>3\sigma$ outliers in the residuals of this step.
3. Subtract the best-fit systematics model from the raw light curve and mask the outliers identified in the previous step.
4. Model the transit of HD 95338b in the pre-whitened light curve.
5. Check the residuals for transits of an exomoon.

In step 2, we constructed a basis vector (F_{BV}) for detrending (following the common recipe, e.g. [Szabó et al. 2021](#); [Smith & Csizmadia 2022](#)) in the form of

$$F_{BV,N} = \sum_{i=1}^N (a_i \sin(i\phi) + b_i \cos(i\phi)), \quad (1)$$

where ϕ is the roll angle of the spacecraft, a_i and b_i are amplitudes of the sinusoidal terms. We then used the Bayesian Information Criterion (BIC [Schwarz 1978](#)) to find the optimal number of harmonics N , where $N \in \{1 \dots 10\}$, to be included in the detrending process. Defining the optimal set of detrending vectors is also part of the optimisation problem, and besides the roll angle harmonics, all telemetry data and by-products of the photometry reduction pipeline have initially been considered. We concluded that the background contamination is among the most important detrending parameters, and therefore, we included this vector into the noise model as well.

We analysed the transits of HD 95338b using the Transit and Light Curve Modeller (TLCM; [Csizmadia 2020](#)). TLCM uses a two-dimensional Gauss-Legendre integration approach to calculate the transit curves. These are described in terms of the scaled semi-major axis of the planet, $a/R_\star$, the planet-to-star radius ratio, $R_p/R_\star$, the time of mid-transit, T_0 , and the orbital period, P . [Díaz et al. \(2020\)](#) found that the planet has an eccentric orbit, specifically, an eccentricity of $e = 0.127 \pm 0.045$ and an argument of the periastron $\omega = 39.4^\circ \pm 18.7^\circ$. In TLCM, it is possible to account for the orbital eccentricity, where the ingress and egress durations can differ. In that case, instead of the commonly used impact parameter, the so-called (inferior) conjunction parameter contains the information of the orbital inclination of the planet (i). It is given by [Csizmadia \(2020\)](#) as:

$$b' = \frac{a}{R_\star} \frac{(1 - e^2) \cos i}{(1 + e \sin \omega)}. \quad (2)$$

We fixed e and ω at their reported values during the light curve modelling.

Stellar limb darkening is taken into account via the quadratic law ([Wade & Rucinski 1985](#)), described by the linear (u_1) and quadratic (u_2) coefficients using the re-parametrisation introduced in [Kálmán et al. \(2024b\)](#) and [Harre et al. \(2024\)](#):

$$A = \frac{1}{4} \left(u_1 \left(\frac{1}{\alpha} - \frac{1}{\beta} \right) + u_2 \left(\frac{1}{\alpha} + \frac{1}{\beta} \right) \right), \quad (3)$$

$$B = \frac{1}{4} \left(u_1 \left(\frac{1}{\alpha} + \frac{1}{\beta} \right) + u_2 \left(\frac{1}{\alpha} - \frac{1}{\beta} \right) \right), \quad (4)$$

where $\alpha = \frac{1}{2} \cos(77^\circ)$, and $\beta = \frac{1}{2} \sin(77^\circ)$. In step 1 of the algorithm, the A and B parameters were fitted using the [1.06, 1.56]

Table 1. Stellar parameters of HD 95338.

Parameter	This work	Díaz et al. (2020)
T_{eff} (K)	5097 ± 77	5212^{+16}_{-11}
$\log g$ (cgs)	4.44 ± 0.04	4.54 ± 0.21
$[Fe/H]$	0.08 ± 0.05	0.04 ± 0.10
Microturbulence (km s ⁻¹)	0.60 ± 0.12	–
$v_{\star} \sin i_{\star}$ (km s ⁻¹)	1.23 ± 0.23	1.23 ± 0.28
$R_{\star}$ ($R_{\odot}$)	0.868 ± 0.006	0.87 ± 0.04
$M_{\star}$ ($M_{\odot}$)	0.848 ± 0.047	0.83 ± 0.02
$t_{\star}$ (Gyr)	$9.5^{+4.3}_{-5.7}$	5.08 ± 2.51

and [1.40, 1.80] uniform priors, respectively. These priors are set according to the theoretical limb-darkening of the star (with stellar parameters from Table 1), as calculated by LDCU³. This software uses a modified version of the routines of Espinoza & Jordán (2015) to calculate the limb darkening coefficients, based on stellar intensity profiles calculated via the ATLAS (Kurucz 1979) and PHOENIX (Husser et al. 2013) models. In step 4, when the definitive planetary parameters are computed, the A and B coefficients were treated as free parameters of the fit.

Furthermore, TLCM uses the wavelet-based formalism of Carter & Winn (2009) to handle time-correlated noise (also commonly known as ‘red noise’) that comprises of any remaining instrumental effects or astrophysical variations (Csizmadia et al. 2023). This technique introduces two additional fitting parameters, σ_w for the standard deviation of the white noise component and σ_r for characterising the red component. These are fitted simultaneously with the parameters describing the transits. To avoid overcorrecting the light curves, the red noise fit is constrained by prescribing that the standard deviation of the white noise (i.e. the residuals) has to be equal to the mean photometric uncertainty of the input light curve (Csizmadia et al. 2023). In step 1, this technique is used to handle the instrumental noise sources, as the wavelet-based noise model is fitted jointly with the transits. Theoretical limb darkening coefficients are needed at this phase to retrieve plausible transit shapes. This allows for a clear detection of the instrument-related effects in step 2. The wavelet-based noise handling is used again in step 4 to obtain the final set of planetary parameters. At this stage, it is expected that astrophysical noise sources will make up the majority of the autocorrelated effects. We emphasise that, from the perspective of the planetary transit fitting, any additional transits – including those from an exomoon – are treated as noise by the wavelet technique or other non-parametric methods, and were therefore removed. For this reason, the search for moons needs to occur on a residual light curve where the time-correlated effects (that are not clearly attributed to instrumental effects) are not removed. Therefore, the complex detrending process outlined above is warranted.

A much less computationally efficient method would be to fit the F_{BV} jointly with the (planetary) transits and the wavelet-based noise model⁴. This would, however, involve the introduction of up to 66 additional fitting parameters, since the a_i and b_i coefficients of Eq. (1), as well as the amplitudes of the background contamination are independent variables in the four

visits. In the steps outlined above, the systematic effects are fitted using a simple least squares method, which is several orders of magnitude faster than the joint F_{BV} plus red noise plus transit fit in our experience. This way, we are able to drastically narrow down the parameter space of the transit modelling itself, thus reducing the possibilities for the MCMC chains to get stuck in so-called local minima, and increasing the reliability of the solutions.

2.4. Joint TESS+CHEOPS modelling

In order to increase the precision of the recovered planetary parameters, we also performed a joint TESS+CHEOPS LC analysis. We assume that the passband-independent orbital parameters, including the eccentricity, the argument of periastron, the semi-major axis and the orbital period remain constant on the timescale relevant in these observations. We also assume that although the TESS passband is redder compared to CHEOPS (see e.g. Scandariato et al. 2024), the possible atmospheric features on HD 95338b are not detectable with the present noise levels, meaning that there is no wavelength-dependence of the transit depth. Therefore, we assumed that $R_p/R_{\star}$ is the same in the two passbands. We further assumed that the transit chord does not change between the different observations, meaning that the scaled semi-major axis, the conjunction parameter, and the orbital period are the same for all five modelled transits. The limb-darkening coefficients are passband-dependent, which necessitates the inclusion of A^{CHEOPS} , B^{CHEOPS} , A^{TESS} , and B^{TESS} into the analysis. It is understood that red noise from an astrophysical origin decreases with increasing wavelength. This manifests in an expectedly lower σ_r (see e.g. Kálmán et al. 2023a) in the TESS observations compared to the CHEOPS light curves. On the other hand, the white noise level depends primarily on the aperture size and the exposure time. We therefore include σ_r^{CHEOPS} , σ_w^{CHEOPS} , σ_r^{TESS} , and σ_w^{TESS} in the global LC modelling. The likelihood of the joint TESS+CHEOPS modelling is then the sum of the log-likelihoods of the light curve fits of the data from the two satellites.

In addition to increasing the number of transits that can be analysed, the two different passbands also allowed us to break the degeneracy between the limb-darkening coefficients and the transit parameters, yielding more precise estimates on both.

During the revision of this paper, Saha (2025) published an independent analysis based on the first three transits from CHEOPS and the two TESS transits.

2.5. Sampling the posterior distributions

In every TLCM-based light curve analysis described in this paper, we followed the same recipe. We used wide, uninformed priors on every parameter. A genetic algorithm is then able to find the (global) minimum in the likelihood space, with $N_{\text{init}} = 2000$ randomly selected values for each parameter (see Csizmadia 2020, for more details). Having found starting points that are suspected to be good, we applied a Differential Evolution Markov-chain Monte Carlo (DE-MCMC; Ter Braak 2006) to get robust estimates of the uncertainty ranges of the fitting parameters. In every case, we used ten chains (also known as walkers) each consisting of 20 000 possible steps. The convergence was monitored via the Gelman–Rubin statistic (Gelman & Rubin 1992) and the effective sample size (e.g. Ripley 1987). If convergence is not reached within these 20 000 steps, the chain length is automatically extended to $10 \cdot 20\,000$.

³ <https://github.com/delinea/LDCU>

⁴ In our experiments, with the available CPUs, the fitting the F_{BV} parameters jointly can be accomplished in ~ 1 month, instead of the several hour long runtimes needed with the pre-whitening approach that we implemented.

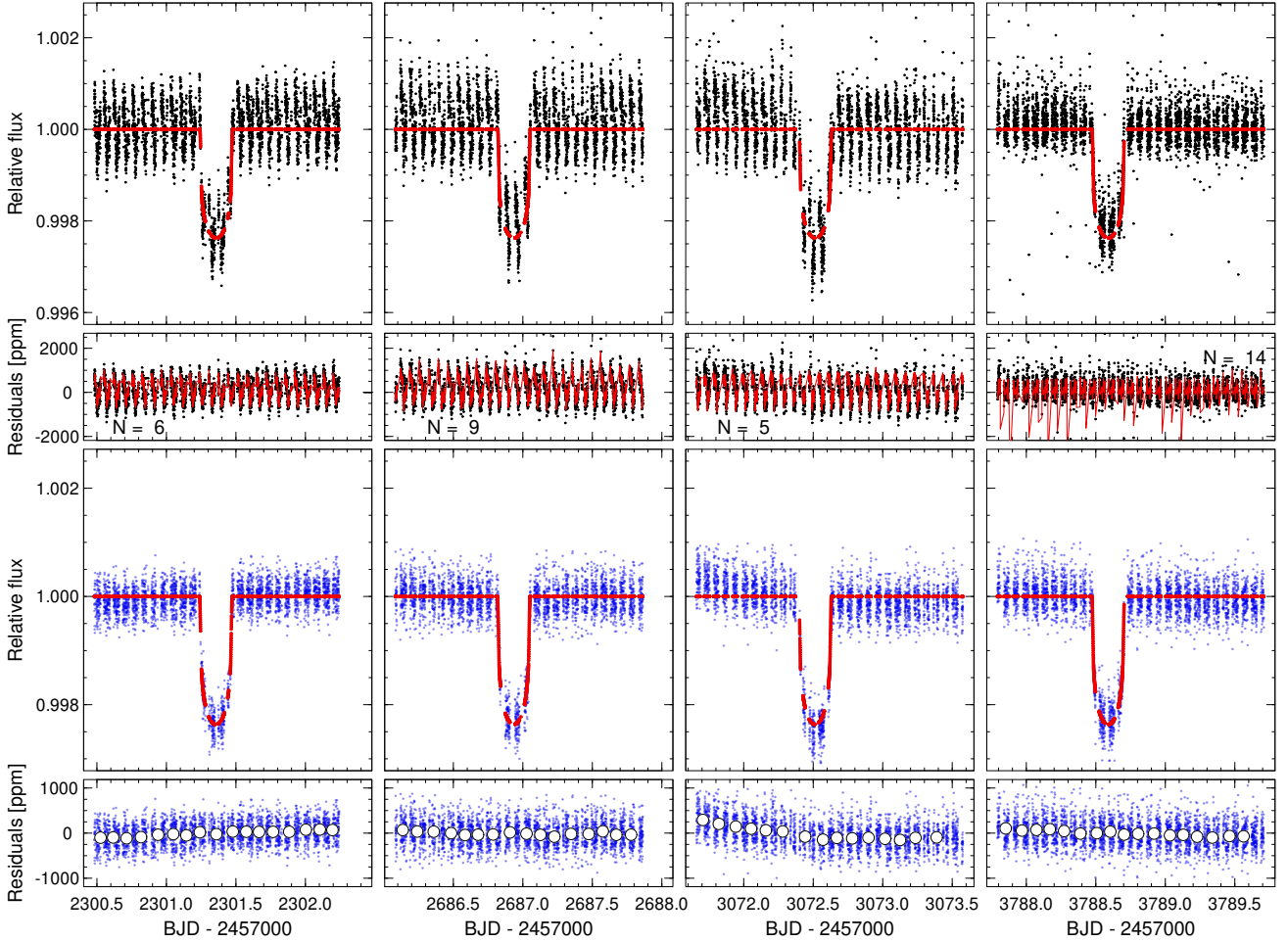


Fig. 2. Demonstration of the fitting and detrending steps. The raw CHEOPS light curves of HD 95338b are shown in the top row, along with the initially fitted transit curves (step 1). The residuals of the initial transit fit, along with the best-fit systematics model is shown in the second row, with N number of harmonics of the roll angle included. The final transit fit (step 4) and its residuals (later used in the search for additional transits) are shown in the bottom two rows, where the full white circles represent 200-point bins (with an average uncertainty of ≈ 20 ppm in each bin).

3. Stellar parameters

We used the ARES+MOOG spectroscopic analysis methodology to derive the stellar spectroscopic parameters (T_{eff} , $\log g$, microturbulence, $[\text{Fe}/\text{H}]$). This methodology is described in detail in Sousa et al. (2021); Sousa (2014); Santos et al. (2013). The equivalent widths (EW) were consistently measured using the ARES code⁵ (Sousa et al. 2007, 2015). We used the list of iron lines appropriate for stars cooler than 5200 K which was presented in Tsantaki et al. (2013). For this spectral analysis we used a combined HARPS spectrum of HD 95338. To converge for the best set of spectroscopic parameters for each spectrum we use a minimisation process to find the ionisation and excitation equilibrium. This process makes use of a grid of Kurucz model atmospheres (Kurucz 1993) and the latest version of the radiative transfer code MOOG (Snedden 1973). We also derived a more accurate trigonometric surface gravity using recent Gaia data following the same procedure as described in Sousa et al. (2021) which provided a consistent value (4.44 ± 0.04 dex) when compared with the spectroscopic surface gravity.

We computed the stellar radius of HD 95338 utilising a MCMC modified infrared flux method (IRFM – Blackwell &

Shallis 1977; Schanche et al. 2020) that allows us to produce synthetic photometry from a constructed spectral energy distribution (SED) using stellar atmospheric models (Castelli & Kurucz 2003) and our stellar spectroscopic parameters as priors. These simulated data are compared to broadband fluxes in the following bandpasses: *Gaia* G , G_{BP} , and G_{RP} , 2MASS J , H , and K , and WISE W1 and W2 (Skrutskie et al. 2006; Wright et al. 2010; WISE Collaboration 2023) that are listed in Table 4 of Díaz et al. (2020) to derive the stellar bolometric flux. The last step in the MCMC is to convert this flux to the stellar effective temperature and angular diameter, that is combined with the offset-corrected *Gaia* parallax (Lindgren et al. 2021) to produce the stellar radius.

To accurately characterise the stellar properties of HD 95338 and account for some modelling systematics, we derived two pairs of $\{M_{\star}, t_{\star}\}$ from two different approaches. The first mass and age pair were estimated by applying the isochrone placement algorithm (Bonfanti et al. 2015, 2016) that interpolates the input stellar parameters within pre-computed grids of isochrones and tracks of PARSEC⁶ v1.2S (Marigo et al. 2017). The second pair of mass and age estimates were derived from

⁵ The last version, ARES v2, can be downloaded at <https://github.com/sousasag/ARES>

⁶ PAdova and TRieste Stellar Evolutionary Code: <http://stev.oapd.inaf.it/cgi-bin/cmd>

Table 2. Parameters obtained from the transit modelling of HD 95338b.

Parameter	Prior	CHEOPS	CHEOPS + TESS (global)	Díaz et al. (2020)	Saha (2025)
$a/R_\star$	[1.0, 133.0]	67.19 ± 0.40	67.34 ± 0.40	$64.676^{+0.381}_{-0.384}$	$69.1^{+1.8}_{-2.3}$
$R_p/R_\star$	[0, 0.2]	0.04423 ± 0.00027	0.04413 ± 0.00026	0.0409 ± 0.0028	$0.04369^{+0.00049}_{-0.00041}$
b'	[0, 1.0]	0.373 ± 0.018	0.370 ± 0.016	$0.430^{+0.070}_{-0.113}$	$0.25^{+0.11}_{-0.15}$
T_0 (BJD – 245 700)	[2300.35, 2302.35]	2301.35590 ± 0.00033	1585.28087 ± 0.00050^a	1585.2795 ± 0.0006	$1585.28072^{+0.00055}_{-0.00054}$
P (days)	[54.056, 56.056]	55.082697 ± 0.000020	55.082694 ± 0.000018	55.087 ± 0.020	55.082695 ± 0.000027
σ_r^{CHEOPS}	[0, 0.1]	0.00552 ± 0.00019	0.00553 ± 0.00019	–	–
σ_w^{CHEOPS}	[0, 0.1]	0.0002265 ± 0.0000015	0.000226 ± 0.0000015	–	–
σ_r^{TESS}	[0, 0.1]	–	0.0068 ± 0.00028	–	–
σ_w^{TESS}	[0, 0.1]	–	0.0003727 ± 0.0000050	–	–
A^{CHEOPS}	[–1.5, 2.5]	1.51 ± 0.24	1.47 ± 0.22	–	1.2 ± 2.1
B^{CHEOPS}	[–2.0, 2.0]	1.747 ± 0.062	1.747 ± 0.061	–	1.1 ± 2.0
A^{TESS}	[–1.5, 2.5]	–	0.53 ± 0.18	0.73 ± 0.59	1.2 ± 2.3
B^{TESS}	[–2.0, 2.0]	–	1.44 ± 0.15	1.467 ± 0.25	1.1 ± 2.3

Notes. ^(a) Uniform prior applied: [1585.2790, 1585.2800].

a Levenberg-Marquardt minimisation scheme (as detailed in Salmon et al. 2021) computing stellar models on the fly with the CLÉS code (Code Liégeois d’Évolution Stellaire – Scuflaire et al. 2008). This minimisation scheme optimises over the age and mass to produce the best agreement between model and observed radii and effective temperatures. As detailed in Bonfanti et al. (2021), we checked the mutual consistency between the two respective pairs of outcomes via a χ^2 -based criterion and then merged the results obtaining $M_\star = 0.848 \pm 0.043 M_\odot$ and $t_\star = 9.5^{+4.3}_{-5.7}$ Gyr.

The derived stellar parameters are listed in Table 1. In general, they are in good agreements with the values reported by Díaz et al. (2020), although we present more precise estimates on $R_\star$ and $\log g$, which are used in the transit modelling.

In order to increase the precision and accuracy of the planetary model, we incorporated the stellar parameters of Table 1 as inputs to the light curve analysis. By a rearrangement of Kepler’s third law of planetary motion, the scaled semi-major axis is connected to the stellar density as well, since (under the assumption of a spherical star)

$$\left(\frac{a}{R_\star}\right)^3 = P^2 G (1 + q) \frac{\rho_{\star, \text{transit}}}{3\pi}, \quad (5)$$

where $q = M_p/M_\star$, and $\rho_{\star, \text{transit}}$ is a geometrically constrained density, since $a/R_\star$ is determined from the transit duration. Using the estimated T_{eff} , [Fe/H] and $\rho_{\star, \text{transit}}$, we are able to provide estimate $M_{\star, \text{transit}}$ and $R_{\star, \text{transit}}$ using the empirical formulae⁷ of Southworth (2011). Then, according to Csizmadia (2020), the goodness-of-fit metric (in this case, the logarithmic likelihood) can be modified as

$$-\log \mathcal{L}_{\text{mod}} = -\log \mathcal{L} + \frac{1}{2} \left(\frac{R_\star - R_{\star, \text{transit}}}{\sqrt{(\Delta R_\star)^2 + (\Delta R_{\star, \text{transit}})^2}} \right)^2 + \frac{1}{2} \left(\frac{\log g - \log g|_{\text{transit}}}{\sqrt{(\Delta \log g)^2 + (\Delta \log g|_{\text{transit}})^2}} \right)^2, \quad (6)$$

⁷ We assumed that [Fe/H] = [M/H].

where $\log g|_{\text{transit}} = 4.43 - 2 \log R_{\star, \text{transit}} + \log M_{\star, \text{transit}}$, where $\log g_\odot = 4.43$. Given that both the second and third terms contain information about ρ_{transit} , $a/R_\star$ is constrained via the input stellar parameters as well.

4. Results

4.1. Planetary parameters

The best-fit CHEOPS and TESS light curves (from the joint fit) are shown in Figs. 3 and 4. The corresponding parameters are shown in Table 2. The parameters describing the planetary transit agree well with each other between the CHEOPS only and the joint TESS plus CHEOPS modelling. We note that the uncertainty ranges do not decrease with the inclusion of the two additional TESS transits, which implies that they are dominated by the uncertainty in the input stellar parameters. The best-fit conjunction parameter is in a $<1\sigma$ agreement with the impact parameter presented by Díaz et al. (2020), and the relative planetary radius shows a discrepancy of only $\approx 1.2\sigma$. There is a 4.8σ disagreement between the estimated $a/R_\star$ values, and a 2.8σ difference between the T_0 from our joint TESS+CHEOPS analysis and the respective values shown by Díaz et al. (2020). Using the S/N criteria established by Csizmadia et al. (2023) for $a/R_\star$, we know that from the CHEOPS analysis alone, we are able to constrain the scaled semi-major axis well within 2% of the truth (since for a 2% accuracy, a S/N = 3 is needed, and in our case, S/N = 22). Consequently, we argue that the uncertainty range presented in Díaz et al. (2020) is likely underestimated. Díaz et al. (2020) find that the first TESS transits occurs 166 ± 52 seconds earlier than our estimates, which is likely a combination of inadequate noise treatment (Kiefer et al. 2023) and the fact that we analyse five transits together. However, the discrepancy in T_0 is $<3\sigma$. A brief TTV (transit timing variation) analysis is shown in Sect. 4.2.

The smaller aperture of the TESS cameras implies that the TESS observations are more noisy – this is confirmed by the higher σ_w^{TESS} compared to σ_w^{CHEOPS} . The red noise parameters are not directly comparable between the two instruments, although we expect the this noise type to decrease at longer wavelengths (e.g. Kálmán et al. 2023a). The retrieved A^{CHEOPS} and B^{CHEOPS} are within 3σ of the theoretical values. Both limb darkening coefficients in the TESS passband are in agreement with those presented by Díaz et al. (2020) (after conversion to the formalism used in this paper).

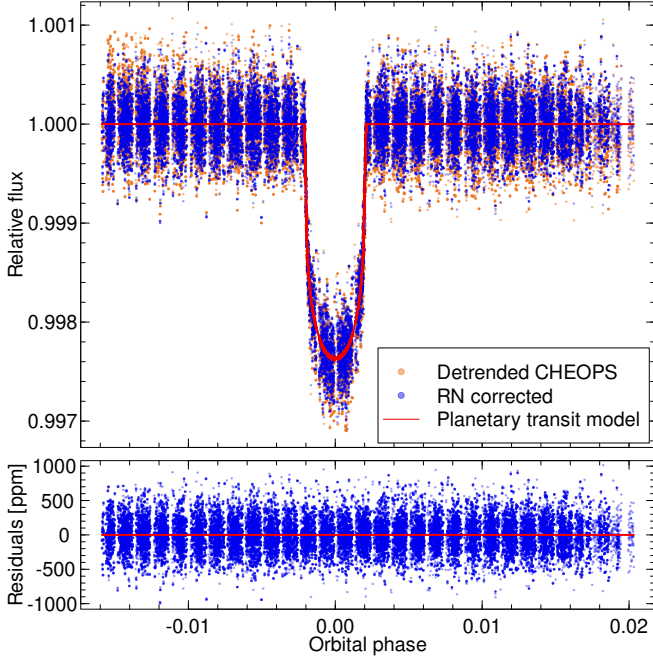


Fig. 3. Phase-folded detrended CHEOPS light curve of HD 95338 (top panel, orange; same data as the third row of Fig. 2.) The rednoise-corrected light curve is shown with blue, while the best-fit transit light curves of HD 95338b is represented by the solid red curve.

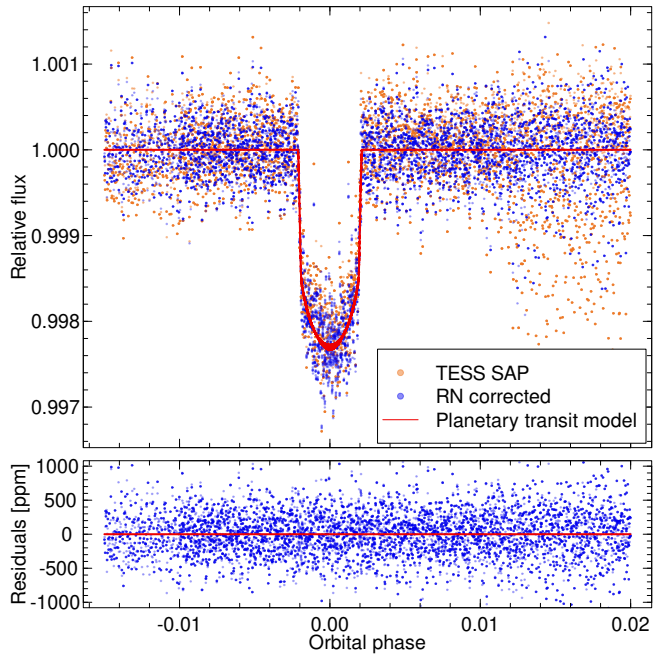


Fig. 4. Phase-folded detrended TESS light curve of HD 95338 (top panel, orange, the same data as the third row of Fig. 2.) The rednoise-corrected light curve is shown with blue, while the best-fit transit light curves of HD 95338b is represented by the solid red curve.

Our results are also in agreement with the parameters presented by Saha (2025). Due to the additional transit included in this work and the refined stellar parameters, we estimate slightly lower uncertainties in R_p/R_* , b' , P , and T_0 . A direct comparison of the confidence intervals of a/R_* and the limb-darkening coefficients is not applicable, since Saha (2025) did not use these as fitting parameters.

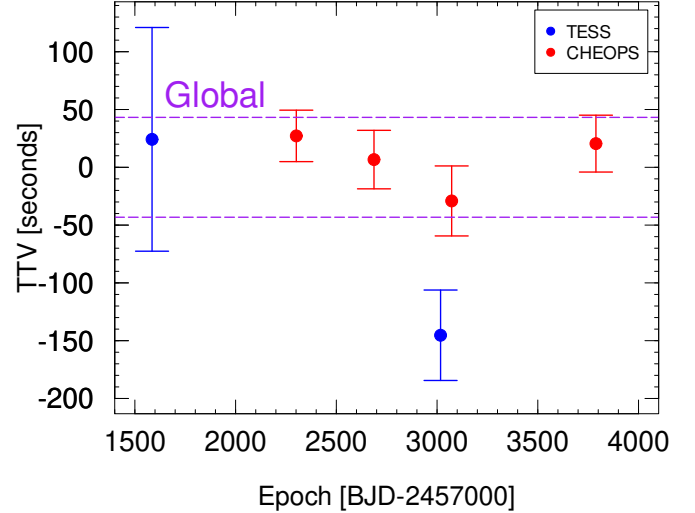


Fig. 5. Transit timing data of HD 95338b. The dashed purple lines represent the uncertainty range from the global fit.

We find that the planetary orbit has an inclination of $89.654^\circ \pm 0.0155^\circ$, the planet has a radius of $R_p = 0.3811 \pm 0.0035 R_{\text{Jup}}$, with a transit duration of $5.587^{+0.018}_{-0.016}$ hours.

4.2. Transit timing

We extracted the timing of each individual transit (two from TESS, four from CHEOPS) by fixing all parameters to the best-fit values from Table 2 with the exception of σ_w , σ_r and T_0 , assuming a constant orbital period. We also included a possible quadratic trend in the modellings. The resultant transit timing data are shown in Fig. 5 and are compiled in Table 3. There is no apparent TTV, meaning that the transit timings are explained well by a constant period. The T_0 value from sector 63 is in a 2.5σ disagreement with the global modelling, which is not statistically significant. A deeper exploration of the TTV signals is beyond the scope of this paper.

5. The search for moons

We chose to restrict the search for exomoons on the CHEOPS dataset alone. This is done because the smaller (mirror) aperture of TESS in comparison to CHEOPS manifests as higher white noise levels, which are detrimental to the quest for moons with the methodology presented here (191 ppm for CHEOPS compared to 289 ppm in TESS despite the exposure time that is more than 4 times shorter, Table 2). For that reason, and to keep the analysis self-consistent, we use the planetary orbital parameters (P , b and a/R_*) that are derived from the CHEOPS photometry alone in the processes described below.

5.1. Sensitivity maps

We examined the CHEOPS residual light curves for shallow transit signals (that could be linked to an exomoon) following the approach detailed in Ehrenreich et al. (2023). This method explores a grid of moon transit epochs and durations $\{T_{0,\text{Moon}}, W\}$. For each point of the grid, we fit for a box-shaped transit depth (allowed to be negative) together with a trend (linear or quadratic) and a multiplicative noise term (factor applied to the data error bars). The fit is done using the Markov chain

Table 3. Transit timing data (and other selected parameters from the transit modelling) of HD 95338b.

Instrument	t_c	p_0 (ppm)	p_1 (ppm)	p_2 (ppm)	σ_r (ppm)	σ_w (ppm)
CHEOPS	2301.35620 ± 0.00026	-4.5 ± 11.7	117.9 ± 12.2	-13.3 ± 24.7	611.5 ± 259.5	211.8 ± 2.5
CHEOPS	2686.93482 ± 0.00029	-32.0 ± 22.5	-51.2 ± 20.2	83.6 ± 41.0	1252.2 ± 257.4	236.4 ± 2.9
CHEOPS	3072.51326 ± 0.00035	-44.9 ± 38.1	-278.4 ± 29.5	172.7 ± 57.0	2218.3 ± 290.7	230.5 ± 3.3
CHEOPS	3788.58886 ± 0.00028	-4.4 ± 13.9	-112.5 ± 15.3	43.8 ± 25.8	742.8 ± 435.3	259.1 ± 3.2
TESS	1585.28114 ± 0.00112	-301.9 ± 98.2	-742.0 ± 141.4	517.8 ± 114.9	4439.6 ± 342.6	418.0 ± 8.0
TESS	3017.42922 ± 0.00045	57.2 ± 15.4	231.1 ± 10.1	-36.2 ± 12.0	690.5 ± 397.9	257.4 ± 3.0

Monte Carlo algorithm (MCMC) implemented in the Python package *emcee* (Foreman-Mackey et al. 2013). From the posterior distribution on the transit depth, we derive the best-fit value of the moon radius and its $3\text{-}\sigma$ lower limit. We also compute the Bayesian Information Criterion and the Akaike Information Criteria (AIC; Akaike 1998) defined as:

$$\text{BIC} = k \ln(n) - 2 \ln(\mathcal{L}) \quad (7)$$

$$\text{AIC} = 2k - 2 \ln(\mathcal{L}), \quad (8)$$

where n is the number of data points, k is the number of parameters included in the fit, $\mathcal{L}$ is the best-fit (maximum) likelihood value. The BIC and AIC values are compared to their respective values in the case where the moon transit depth is fixed to 0, i.e. a ‘no-moon’ reference fit.

The parameter space scanned by the $\{T_{0,\text{Moon}}, W\}$ grid must cover mid-transit times across the full Hill-sphere of HD 95338b⁸ while allowing for either shorter or longer transit duration (e.g. if the moon impact parameter is larger or smaller) than that of its planet. With a transit duration of the Hill sphere of 17.6 ± 0.9 hours (i.e. <20.3 h at 3σ), we considered $T_{0,\text{Moon}}$ values that satisfy $-10.5 \text{ h} \leq \Delta T_0 \leq +10.5 \text{ h}$, where $\Delta T_0 = T_{0,\text{Moon}} - T_{0,\text{Planet}}$. The range of moon transit durations W covers values from 30 min (grazing moon) to 7 h, with a planetary transit duration of ~ 5.6 h. The grid resolution (increment) is set to 15 min in both dimensions.

In order to provide conservative estimates of a possible exomoon signal in the T_0 – W parameter space, we propagate the uncertainties from the planetary transit fit. To that end, we calculate the standard deviation of 100 red noise plus planetary transit (see Sect. 4.1) models (with parameters selected randomly from the posterior distribution of the fit) at every time stamp of the observations, and add this to the flux uncertainties estimated by DRP in quadrature. In order to increase computational efficiency, we fit F_{BV} via a least-squares algorithm. Consequently, we do not propagate the uncertainties of F_{BV} into the residuals.

5.2. Box-shift method

We performed a more detailed transit modelling after the planetary transit in the third visit to try to explore the possibility of an additional transit being there. To do that, we used narrow box priors on $T_{0,\text{Moon}}$, which allowed us to perform an in-depth scan of the selected areas, by shifting them through the light curve. The priors are chosen to be 3 hours wide ($\approx 1/2$ transit duration), and at each new step, their borders are increased by 1.5 hours

⁸ The Hill sphere defines the gravitational sphere of influence of a body and is therefore where moons are expected to exist. Domingos et al. (2006) shows that beyond half the Hill sphere radius, only retrograde orbits are stable, and we cover the full radius not to exclude these potential objects.

($\approx 1/4$ transit duration), yielding an overlapping configuration for the transit modelling. In total, we performed 8 different transit modellings in every light curve.

We assumed that the inclination of the orbit of the moon is such that the impact parameter is the same as for HD 95338b. We further assume that the separation of the planet and its companion is so small that the star–moon distance can be described sufficiently well with the semi-major axis of the planetary orbit, and that the relative velocity of the moon is negligible compared to the orbital velocity of the system. The difference in the transit duration, although difficult to estimate as it depends on the mass of the moon and its semi-major axis in the orbit around the planet. Based on the specific configuration, it is possible that a moon within the Hill sphere would not be transiting or would show a grazing transit (Ehrenreich et al. 2023), or that the duration of the lunar transit would exceed that of the planet (Kálmán et al. 2024a). It is also established that the limb-darkening coefficients can more reliably be measured in case of deeper transits (e.g. Eq. (34) of Csizmadia et al. 2023). For these reasons, we only fit the depth and epoch of the lunar transit, while we adopt all other transit parameters from the analysis of the planetary transits (Table 2).

5.3. Injection-and-retrieval tests

In order to verify the performance of the sequential exomoon-detecting algorithm presented above, we performed a number of injection-and-retrieval tests. We injected transits with the $a/R_\star$ and b values of Díaz et al. (2020). We tested a wide range of moon radii, with a grid consisting of $R_{\text{Moon, injected}} \in \{0.8, 0.9, 1.05, 1.2, 1.35\} R_\oplus$. The transits were injected at two epochs (BJD 2459301.25 in the first visit and BJD 2459687.05 in the second visit) so that they overlap with the transit of HD 95338b. We followed the same steps as described in Sect. 2.1, then proceeded to generate the sensitivity maps, and, having identified the transits on these we also performed the box-shifting approach as well. There is an infinite number of possible $T_{0,\text{Moon}} - R_{\text{Moon}}$ combinations that could be used in such tests. These specific cases are useful to demonstrate that the technique described above works well for finding lunar transits. We only use data from the first three CHEOPS visits for the injection-and-retrieval tests.

In Figs. B.2 and B.3, we show the sensitivity maps for the $R_{\text{Moon, injected}} = 0.8 R_\oplus$ and $R_{\text{Moon, injected}} = 1.35 R_\oplus$ cases. The second rows, showing the 3σ lower limit on the moon radii show on clear strip for about 4 hours before and 5 hours after the conjunction of HD 95338b in the first and second visits, respectively. The presence of the signal is also confirmed by the ΔBIC and ΔAIC values (third and fourth rows of Figs. B.2 and B.3, respectively). The ΔBIC and ΔAIC metrics also show that at certain times (≈ 2 hours after and ≈ 1 hour before the midtransit of the

Table 4. Retrieved planetary parameters for the different injected exomoon sizes.

Size of injected moon ($R_{\oplus}$)	T_0	$R_p/R_{\star}$	$a/R_{\star}$	b'
$R_{\text{Moon}} = 0.80$	2301.35602 ± 0.00031	0.04435 ± 0.00026	67.74 ± 0.40	0.344 ± 0.019
$R_{\text{Moon}} = 0.90$	2301.35600 ± 0.00032	0.04437 ± 0.00026	67.76 ± 0.41	0.345 ± 0.019
$R_{\text{Moon}} = 1.05$	2301.35594 ± 0.00032	0.04444 ± 0.00027	67.73 ± 0.41	0.344 ± 0.019
$R_{\text{Moon}} = 1.20$	2301.35589 ± 0.00032	0.04453 ± 0.00027	67.73 ± 0.40	0.345 ± 0.019
$R_{\text{Moon}} = 1.35$	2301.35585 ± 0.00032	0.04462 ± 0.00027	67.71 ± 0.40	0.345 ± 0.018

Table 5. Temporal coordinates of the eight searchboxes used in the box-shifting analysis of the exomoon signal seen in the third visit, and the best-fit parameters describing the correlated noise, the transit, and the long-term trend.

Searchbox number	Searchbox left	Searchbox right	$T_{0,\text{Moon}}$	$R_{\text{Moon}}/R_{\star}$	σ_r (100 ppm)	σ_w (100 ppm)	p_0 (ppm)	p_1 (ppm)	p_2 (ppm)
1	3072.4265	3072.5515	3072.482 ± 0.040	0.0041 ± 0.0055	30.9 ± 2.0	2.234 ± 0.030	-27 ± 54	-284 ± 42	145 ± 75
2	3072.4578	3072.5828	3072.513 ± 0.045	0.0040 ± 0.0052	30.9 ± 2.0	2.234 ± 0.030	-27 ± 54	-284 ± 42	145 ± 75
3	3072.4890	3072.6140	3072.563 ± 0.043	0.0052 ± 0.0056	30.9 ± 2.0	2.233 ± 0.030	-27 ± 54	-284 ± 42	145 ± 75
4	3072.5203	3072.6453	3072.591 ± 0.035	0.0042 ± 0.0061	30.9 ± 2.0	2.235 ± 0.030	-27 ± 54	-284 ± 42	145 ± 75
5	3072.5515	3072.6765	3072.599 ± 0.036	0.0040 ± 0.0061	30.9 ± 2.0	2.235 ± 0.030	-27 ± 54	-284 ± 42	145 ± 75
6	3072.5828	3072.7078	3072.623 ± 0.044	0.0031 ± 0.0067	30.9 ± 1.9	2.234 ± 0.030	-27 ± 54	-284 ± 42	145 ± 75
7	3072.6140	3072.7390	3072.676 ± 0.041	-0.0008 ± 0.0052	30.9 ± 2.0	2.234 ± 0.030	-27 ± 54	-284 ± 42	145 ± 75
8	3072.6453	3072.7703	3072.705 ± 0.043	-0.0006 ± 0.0052	31.0 ± 2.0	2.235 ± 0.030	-27 ± 54	-284 ± 42	145 ± 75

planet) positive bumps (i.e. negative moon radii) are preferred to the combination of GPs and the quadratic trend. Such signals do not correspond to the transit of hypothetical exomoon. Comparing with Fig. B.1, we may conclude that they appear as a consequence of the injected lunar transits. It is likely that these two additional signals act as weights on the planetary transit, causing minor distortions that are then detected during the sensitivity mapping.

After identifying these regions of interest (between ≈ 2301.04 and ≈ 2301.26 for the first visit, ≈ 2686.93 and ≈ 2697.15 for the second visit), we also conducted the box-shifting parameter extraction similarly to the study of the real dataset (Sec. 5.2). We include a quadratic trend (Eq. (6)) in the analyses. For the cases of $R_{\text{Moon, injected}} = 0.8 R_{\oplus}$ and $R_{\text{Moon, injected}} = 1.35 R_{\oplus}$, the light curves from this method are shown on Figs. B.4 and B.5. We can observe the transit appearing and then disappearing again as the searchbox for $T_{0,\text{Moon}}$ is shifted through the light curves.

The extracted $T_{0,\text{Moon}}$ and R_{Moon} values are listed in Tables B.1 and B.2 for all tested moon sizes, along with the respective deviations from the nominal values. The transit depths are recovered even for $R_{\text{Moon, injected}} = 0.8 R_{\oplus}$ case in both visits. We find that the significance of this parameter (and consequently the transit itself) is $\approx 5.5 R_{\oplus}$ in the first visit and ≈ 4.2 in the second visit for $R_{\text{Moon, injected}} = 0.8 R_{\oplus}$. The significances of the detected transits naturally increase with $R_{\text{Moon, injected}}$. Table 3 suggests that in the second visit, the time-correlated noise level is higher at $\sigma_r = 1356.0 \pm 259.8$ ppm compared to just $\sigma_r = 589.8 \pm 255.2$ ppm. We emphasise that anything not explicitly included in the modelling (via a fitting parameter) is described by the wavelets. For this reason, σ_r depends heavily on the underlying light curve (whether it contains injected transits or not) and the actual fitted quantities. Consequently, comparison of the red noise levels between the various $R_{\text{Moon, injected}}$ cases is not possible. The ≈ 900 ppm difference in the red noise levels may explain the larger uncertainties on R_{Moon} seen in the second visit. Similarly, the in the third visit, we find $\sigma_r = 2443.8 \pm 282.3$ ppm (Table 3), which may shroud any evidence for an exomoon. A comprehensive analysis of the underlying causes of these discrepancies is beyond the scope of this paper, but it should be noted that the instrument displays a certain degree of sensitivity loss in relation to its ageing process (Fortier et al. 2024, Sect. 4).

We note that the new window on the CCD yielded considerably lower red noise (Table 3).

Although one of the injected moon transits is on the ingress of the planetary transit and the other one is on the egress, they are not symmetric with respect to T_0 . Consequently, the shape of the modelled planetary transit gets distorted in comparison with the original dataset, and this discrepancy is more evident the larger the injected exomoon radius is. In this sequential approach of the chase for moons, we are in fact fitting the photocenter (Simon et al. 2007) as the ‘planet’. The retrieved ‘planetary’ parameters are therefore more distorted if we increase $R_{\text{Moon, injected}}$. This is shown in Table 4. We observe a shift in T_0 to earlier epochs, and increase in $R_p/R_{\star}$, and a decrease in $a/R_{\star}$. Although the recovered parameters agree in a 1σ with each other and even the original dataset (Table 5), these minor inconsistencies may lead to differences in the residuals that are then converted into the parameter biases seen in Tables B.1 and B.2. Furthermore, the additional signals (i.e. transits) can also cause and increased variance in the 100 models chosen from the posteriors for the uncertainty propagation. As a result, the hint of an exomoon seen on the left column Fig. B.1 disappears (left columns of Figs. B.2, B.3). A more detailed investigation of the distortion of the planetary parameters is beyond the scope of this paper.

Given that the distortion of the transit parameters and the flux uncertainties increases with $R_{\text{Moon, injected}}$, the recovered R_{Moon} and $T_{0,\text{Moon}}$ are also further from their input values at the higher moon radii (Tables B.1, B.2). At the same time, the lower moon sizes yield $\{T_{0,\text{Moon}}, R_{\text{Moon}}\}$ combinations that are within 1σ of the injections.

6. The search for moons orbiting HD 95338b

Having verified that we are able to achieve $>3\sigma$ detections of additional transiting bodies with $0.8 R_{\oplus}$ based on single transits (Sect. 5.3), we explored the residual light curves of HD 95338 from the four CHEOPS visits. The sensitivity map for each visit of HD 95338 is shown in Fig. 6 (with an underlying linear trend), which hints and the presence of a signal that occurs slightly later than the planetary transit during the second visit (middle column), and a strong signal in the third visit (right column). The signals in these two visits can be described by a box with

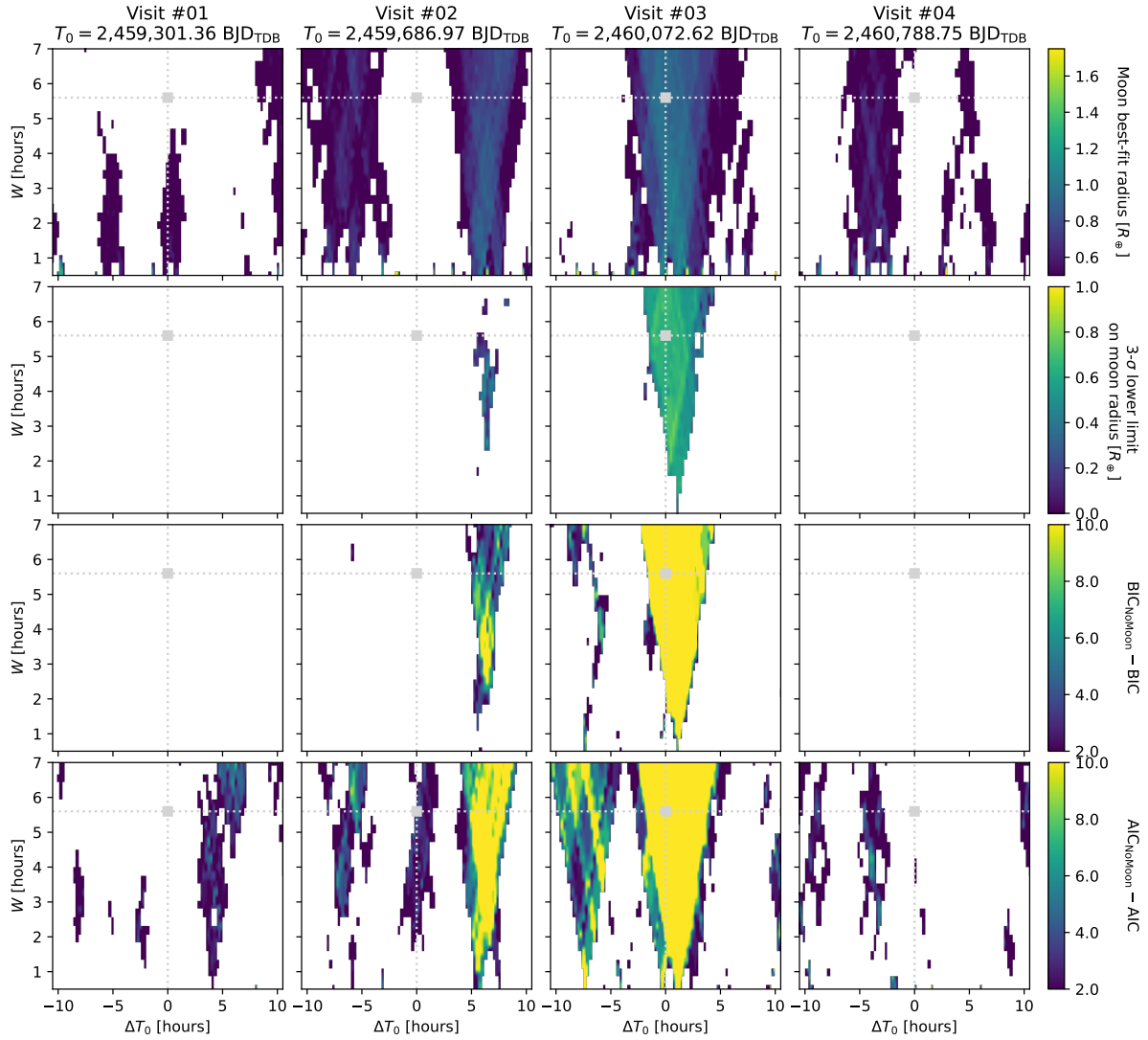


Fig. 6. Sensitivity maps for the four CHEOPS visits of HD 95338. The first row represents the best-fit box depth (i.e. moon radius) in the ΔT_0 – W space. The 3σ lower limit of the moon radius is shown in the second row, while the third and fourth rows represent the ΔBIC and ΔAIC values between a solution with and without a moon. The empty (blank) areas are values that are below a threshold of $0 R_\oplus$ for the moon radius (first 2 rows) and a threshold of 2 for the ΔBIC and ΔAIC (last 2 rows). The grey squares (and corresponding dotted lines) show the position of the transit of HD 95338b in this parameter space for each visit. An underlying linear trend is assumed for each of the four visits.

a depth corresponding to $0.8 R_\oplus$ and $\approx 1.2 R_\oplus$, respectively. We also estimate 3σ lower limits at $\approx 0.6 R_\oplus$ (in the second visit) and $\approx 0.8 R_\oplus$ (in the third visit). We find that the cases where a box-shaped signal is included in the fit is favoured by $\Delta BIC \geq 10$ and $\Delta AIC \geq 10$. In the first visit (Fig. 6, left column), the lower limit on the hypothetical transit depth is negative at every $(\Delta T_0, W)$ grid point. In the case of the second transit, the detection statistics are more sporadically distributed in the parameter space and not in a manner that we expect for a transit based on the injection–and–retrieval tests (see Sect. 5.3).

The spread-out detections (non-zero 3σ lower limits) before the transit in the second visit are likely noise. In the first and fourth visits, the best-fit box does not have a 3σ detection significance (i.e. the 3σ lower limit on the radius is negative), and the inclusion of the box is disfavoured by the BIC. For these reasons, we conclude that a moon signal is not detectable in the first two visits or the last visit, while the signal seen in the third visit warrants further investigations. We note that at the bottom edge of the maps (Fig. 6) the width of the boxes (i.e. the duration of

the supposed lunar transit) is commensurable with the duration of the gaps in observations, as discussed in Sect. 2.1. For this reason, any signal seen there can also safely be disregarded.

We also constructed the sensitivity maps by using a quadratic trend (Fig. B.1). Firstly, we note that no signals appear in the first or fourth visits. Secondly, we observe that the features seen in the second and third visits (Fig. 6) disappear, as the 3σ lower limit (second row of Fig. B.1) no longer implies a clear detection. The BIC and AIC values still suggest that the inclusion of a dip is preferred, although lower with probabilities ($\Delta BIC \approx 8$ instead of ≥ 10 as seen in the case when a linear trend is included).

After narrowing down the possible locations of the exomoon transit via the sensitivity maps (Fig. 6), we pinned down the exact position and duration of the signal. We identified the relevant light curve section to be between ≈ 246072.427 BJD and ≈ 246072.777 BJD. We constructed eight overlapping segments (each spanning 3 hours, or roughly half of the transit duration of HD 95338b). These segments are used as uniform priors (or searchboxes) for mid-time of the lunar transit. To scan the

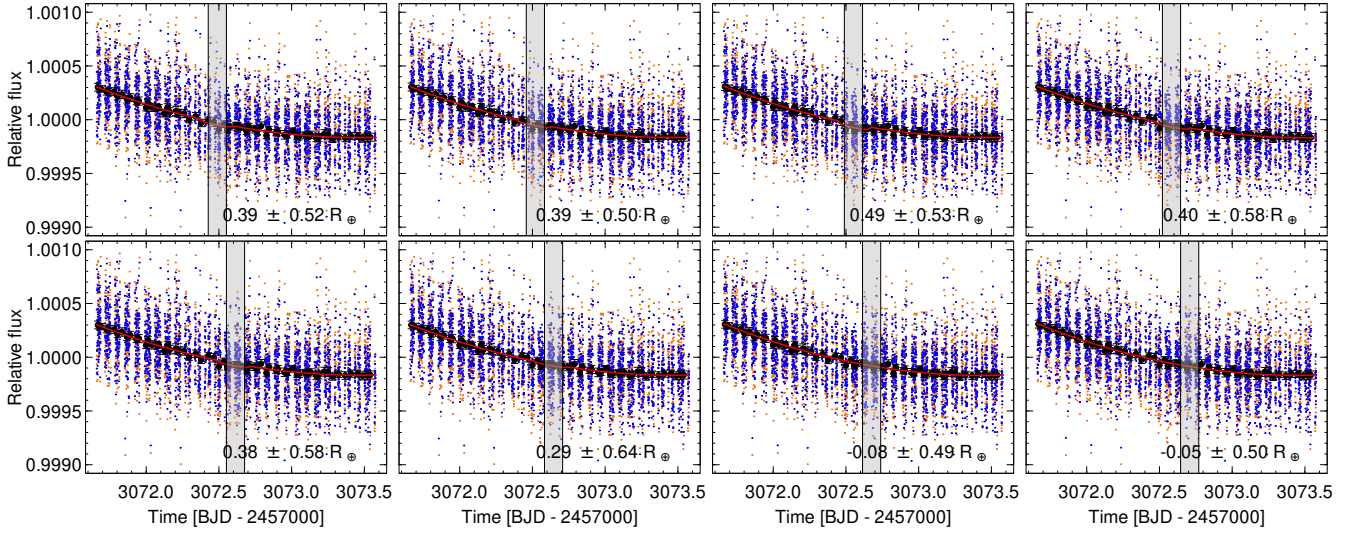


Fig. 7. Results of the box-shifting method. The shaded gray areas represent the searchboxes within which the mid-time of the lunar transit is constrained. The best-fit moon radius and its 1σ uncertainty is shown on the bottom of each plot.

above-mentioned portion of the light curve, we shift these searchboxes by 45 minutes (or one-eighth of the planetary transit duration) for each individual fit. We thus performed eight individual fits in search of the lunar transit, as seen on Fig. 7. We also included a quadratic trend (for the flux–time detrending) in the form of

$$F_{\text{trend}} = p_0 + p_1 \cdot (t - T_{\text{ref}}) + p_2 \cdot (t - T_{\text{ref}})^2, \quad (9)$$

where p_0 , p_1 , and p_2 are the constant, linear, and quadratic coefficients respectively, and $t_{\text{ref}} = T_{0,\text{Moon}}$ is the reference time of the trend. We also allow for the two parameters of the wavelet-based noise filtering to vary in an unconstrained manner. The results of the box-shifting method are shown on Fig. 7, and the best-fit parameters are listed in Table 5. The noise-related parameters (σ_r , σ_w , p_0 , p_1 and p_2) are consistent with each other in all eight cases, while $R_{\text{Moon}}/R_\star$ is consistent with 0 within 1σ . We therefore do not see a significant detection of a transit-like dip.

7. Discussion and concluding remarks

In this work, we have carried out a search for possible satellites orbiting the eccentric Neptune-sized planet HD 95338b in a sequential approach. Using four transits from CHEOPS and two from TESS, we present a detailed transit modelling, followed by a novel approach in the quest for exomoons. We re-derived the stellar parameters of the host star HD 95338, and present considerable improvements on some of them in comparison with the discovery paper (Díaz et al. 2020). We present improvements on the basic transit parameters of HD 95338b. Most notably, we reduce the uncertainty on the planetary radius by a factor of 10 compared to the results presented by Díaz et al. (2020). Given that the precision of these parameters does not change with the inclusion/exclusion of the two TESS transits, we argue that the stellar parameters and their uncertainties are properly taken into account in TLCDM (as described in Csizmadia 2020) and that the uncertainties of the modelling parameters are limited by our knowledge of the star. The most remarkable improvement is achieved regarding the orbital period, which we estimate with a precision of ≈ 0.3 s compared to ≈ 1700 s in the discovery paper.

The quest for exomoons is difficult as we are trying to find transits whose timing and duration are not known, and that

are shallow (especially in comparison with the instrumental noise effects of CHEOPS). A thorough detrending, incorporating all known noise sources is therefore a pre-requisite for such a project, as outlined in Sect. 2. We scanned the residual light curves after subtracting the planetary signal for signs of additional transit-like features that could be attributed to an exomoon orbiting HD 95338b. For a thorough characterisation of an exomoon which would incorporate the combination of two Keplerian orbits (Hippke & Heller 2022), at least three transit detections would be needed. We are able to rule out the presence of additional signals below $\approx 0.6 R_\oplus$ at 1σ , thus placing an upper limit on the size of a hypothetical satellite in the system.

There are obvious long-term trends in the residuals seen in Fig. 2. With the assumption that these are linear (and letting the complex noise handling tools, either GP-based or wavelet-based, handle all other possible non-white noise realisations), we observed the detection of a transit-like feature (Fig. 6). However, with the addition of a quadratic trend (Figs. B.1 and 7), the transit detection is no longer significant. The deviation between the fitted linear and quadratic trends is the greatest around the position of the detected transit. The fact that the significance of the detection decreases after including a higher-order time-dependent term – which is commonly associated with astrophysical noise sources, such as spots – implies that the transit-like feature is likely not originated by a transit of an exomoon. Increasing the order of polynomials included in the modelling introduces the risk that the shorter timescale noise components are enhanced in a way that may introduce additional transit-like features. Thus we do not test for these possibilities, relying instead on the noise handling algorithms that are thought to be more efficient at higher frequencies. In any case, the retrieved moon size is consistent with a no-moon case at 3σ . Additionally, the lack of obvious TTVs (Fig. 5) also serves as counterargument against the presence of a satellite (Simon et al. 2007; Kipping 2009).

Based on the analysis of the synthetic LCs, we conclude that the method presented in Sect. 5 is viable for searching for exomoon transits in a non-photodynamical way. The injection-and-retrieval tests suggest that the combination of the sensitivity maps and the box-shifting method does not induce false positive detections, however, it does recover the size and position of the injected exomoon transits (within 2σ of their respective input

values), and leads to $>3\sigma$ detections even for the smallest tested moon sizes.

HD 95338b is an interesting target and an important milestone in the quest for exomoons. Future observations with CHEOPS, PLATO (PLANetary Transits and Oscillations of stars Rauer et al. 2014, 2025), Ariel (Atmospheric Remote-sensing Infrared Exoplanet Large-survey Tinetti et al. 2018, 2022), or JWST (James Webb Space Telescope Gardner et al. 2006) may further reduce the current upper limit of $0.6 R_{\oplus}$ on the radius of a possible moon in the system. The methodology presented in Sections 2 and 5 can also be regarded a stepping stone in the hunt for exomoons using the telescopes of the future. In the event of detections of additional signals that are similar to the one seen on Fig. 7, a fully photodynamic characterisation may be able to provide deeper insights into the nature of this system.

The discovery of the first confirmed exomoon will open a new chapter in exoplanet research. The above-told tale about the exomoon hunt around HD 95338b, together with the earlier examples mentioned in Section 1, sends a strong message to the research community regarding this subject. Detecting exomoons is currently situated at the frontiers of contemporary research, and success in confirming such discoveries can only be achieved through a comprehensive understanding and in-depth exploration of the intricacies involved in signal design, measurement techniques, and data analysis. Our discussion also outlines potential pathways to be explored during this investigation, and we are convinced that our considerations in the above analysis will provide significant methodological tools to this demanding task.

Data availability

The raw and detrended photometric time series data are available at the CDS via <https://cdsarc.cds.unistra.fr/viz-bin/cat/J/A+A/701/A240>

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Appendix A: Information about the CHEOPS observations

The metadata of the four CHEOPS observations are shown in Table A.1. The list of nearby stars, that may interfere with the aperture photometry, is shown in Table A.2.

Table A.1. File keys and the respective observation dates for the four CHEOPS visits of HD 95338.

File key	Observation start	Observation end	Number of orbits	Efficiency [%]
CH_PR100009_TG001101	2021-03-26T23:27:04	2021-03-28T17:43:29	26	59.5
CH_PR100009_TG001102	2022-04-16T13:53:05	2022-04-18T08:37:02	26	57.6
CH_PR140072_TG000901	2023-05-07T03:44:19	2023-05-09T01:44:46	28	58.2
CH_PR140072_TG000902	2025-04-22T06:55:00	2025-04-24T04:53:43	29	64.1

Table A.2. List of stars that are (i) within 100'' of HD 95338 and (ii) brighter than $G = 15.2$ magnitudes.

Gaia ID	α_{J2000} [°]	δ_{J2000} [°]	Separation from target [']	G [mag]
Gaia DR2 5340648488081462528 ^a	164.854663528690	-56.6238174607725	0	8.38
Gaia DR2 5340648110124332288	164.849734257485	-56.6295150776728	25.1166801452637	14.19
Gaia DR2 5340648110124331008	164.863838643089	-56.6369880728433	50.5965957641602	14.66
Gaia DR2 5340648110124328448	164.864406506541	-56.6401925897662	61.9967308044434	14.14
Gaia DR2 5340648621192205696	164.876026962042	-56.6081809926106	67.7202606201172	14.80
Gaia DR2 5340648075764581888	164.847011556551	-56.6425190710745	70.7192840576172	14.45
Gaia DR2 5340647766526968704	164.892506952765	-56.6236315284767	71.6561660766602	12.77
Gaia DR2 5340648110124325248	164.862354443584	-56.643234452212	71.8457717895508	13.71
Gaia DR2 5340648591142853888	164.851492797189	-56.5991502768792	88.3759384155273	10.57
Gaia DR2 5340648140155761536	164.820502759141	-56.639273910009	90.7409591674805	14.95
Gaia DR2 5340647354210316288	164.874514445752	-56.6468253286776	91.1862640380859	15.00
Gaia DR2 5340648591160693376	164.842872932682	-56.5989572030799	92.4748764038086	15.10
Gaia DR2 5340648762959367168	164.815444234184	-56.6093308787378	95.8126449584961	14.09

Notes. ^(a)Target star, HD 95338.

Appendix B: Sensitivity maps

B.1. Quadratic trend

The sensitivity maps in case of a quadratic trend (for the real observations) are shown on Fig. B.1.

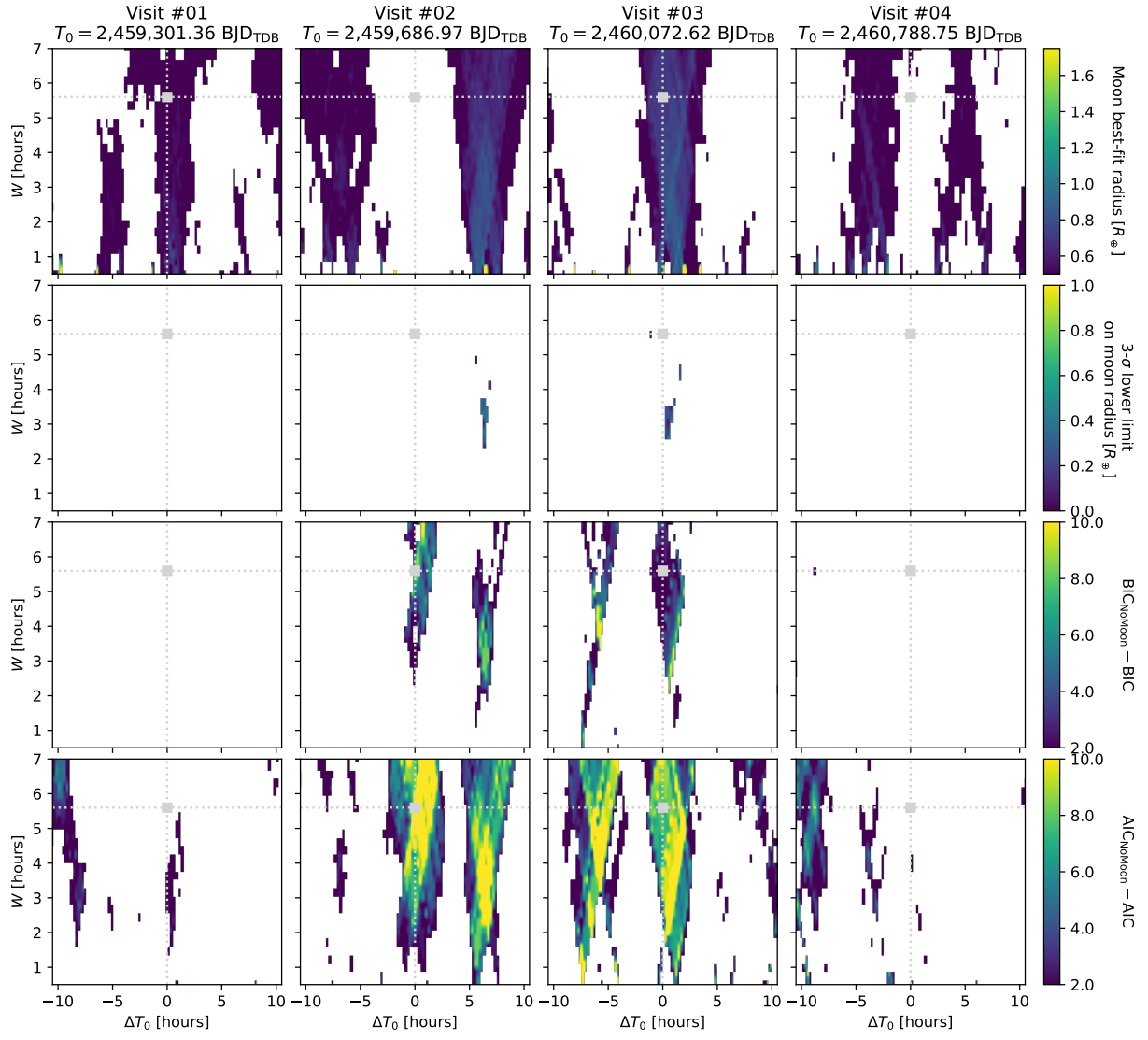


Fig. B.1. Same as Fig. 6 but with a quadratic trend instead of a linear trend.

B.2. Synthetic transits

The results of injection-and-retrieval tests are shown in Figs. B.2 – B.5, and Tables B.1 – B.1.

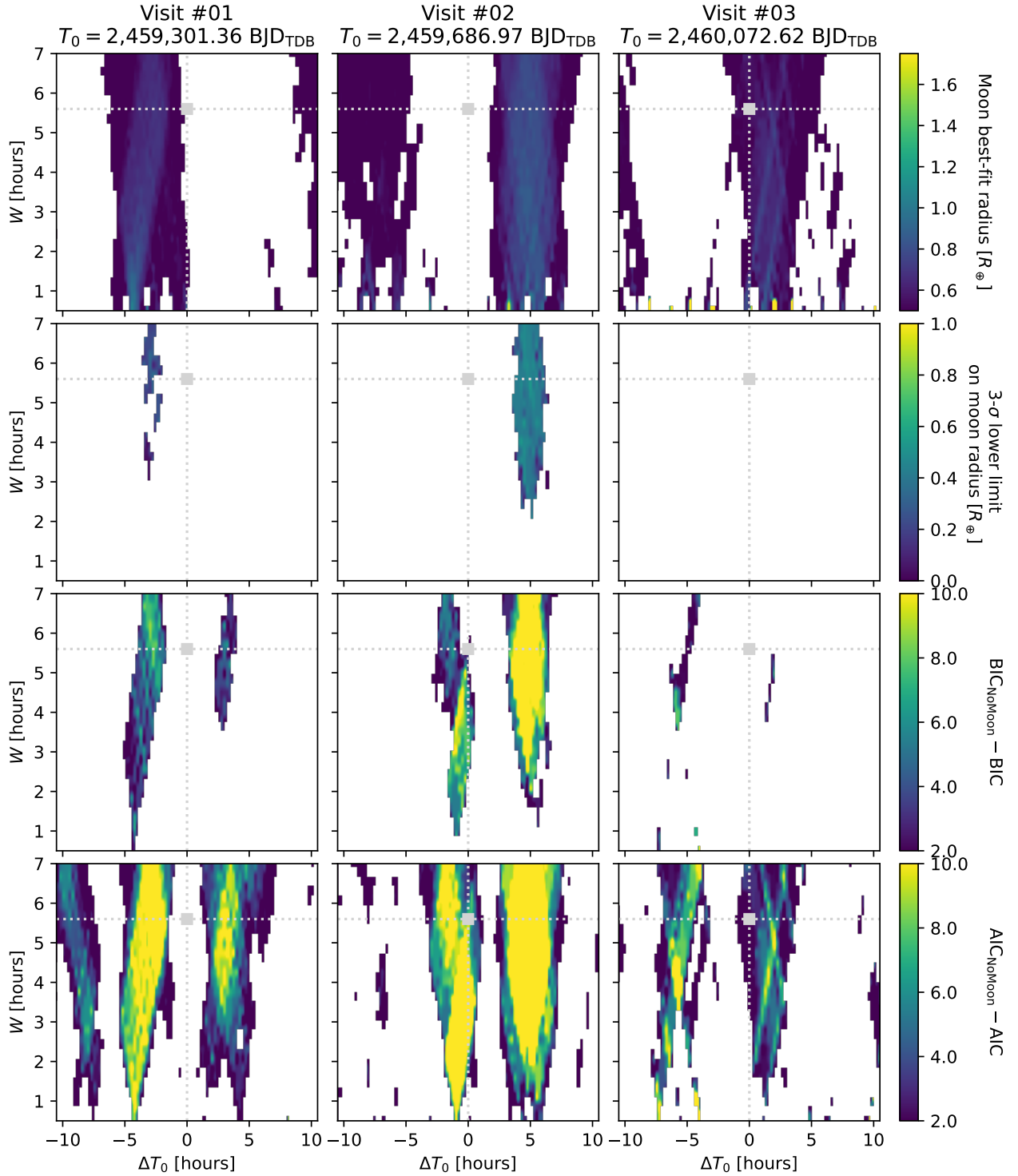


Fig. B.2. Same as Fig. 6 but with a quadratic trend instead of a linear trend and with an $R_{\text{Moon}} = 0.8 R_{\oplus}$ moon injected into the first two visits. The injection-and retrieval tests were carried out only on the first three CHEOPS visits.

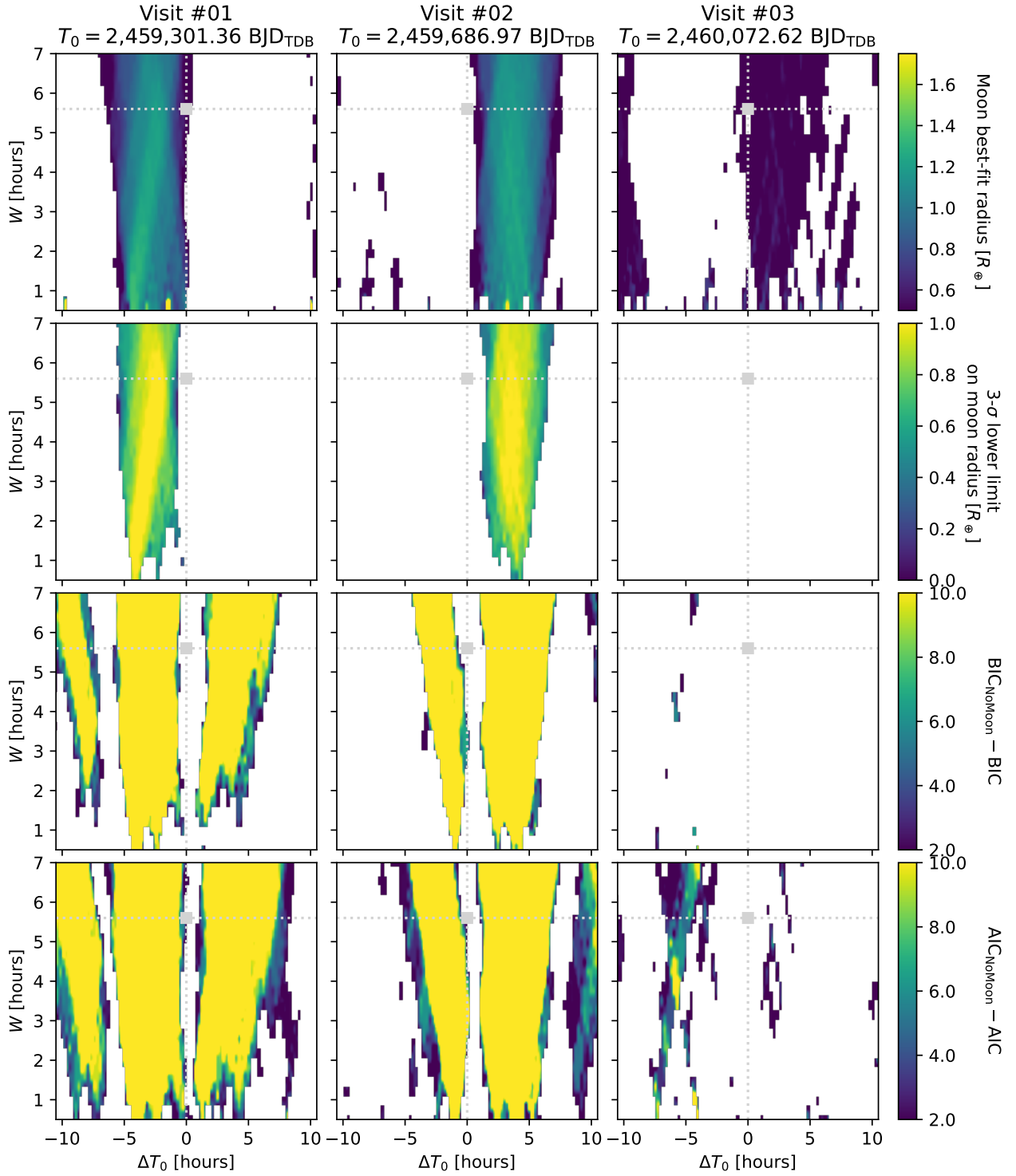


Fig. B.3. Same as Fig. B.2 but with a quadratic trend instead of a linear trend and with an $R_{\text{Moon}} = 1.35 R_{\oplus}$ moon injected into the first two visits.

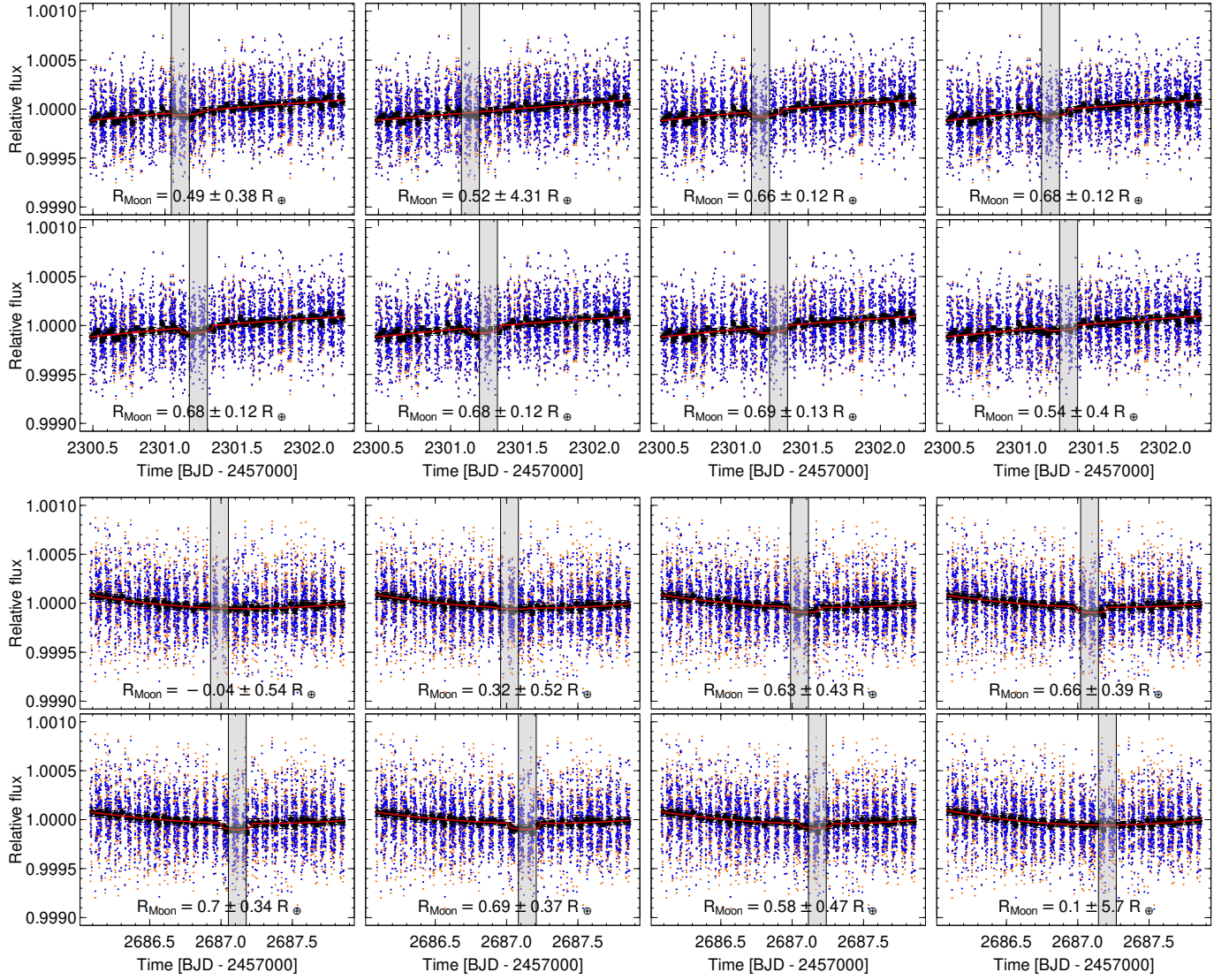


Fig. B.4. Performance of the box-shifting approach on the injected exomoon transits. **Top rows:** Recovery of an $R_{\text{Moon}} = 0.8 R_{\oplus}$ in the first visit. **Bottom row:** Recovery of an $R_{\text{Moon}} = 0.8 R_{\oplus}$ in the second visit.

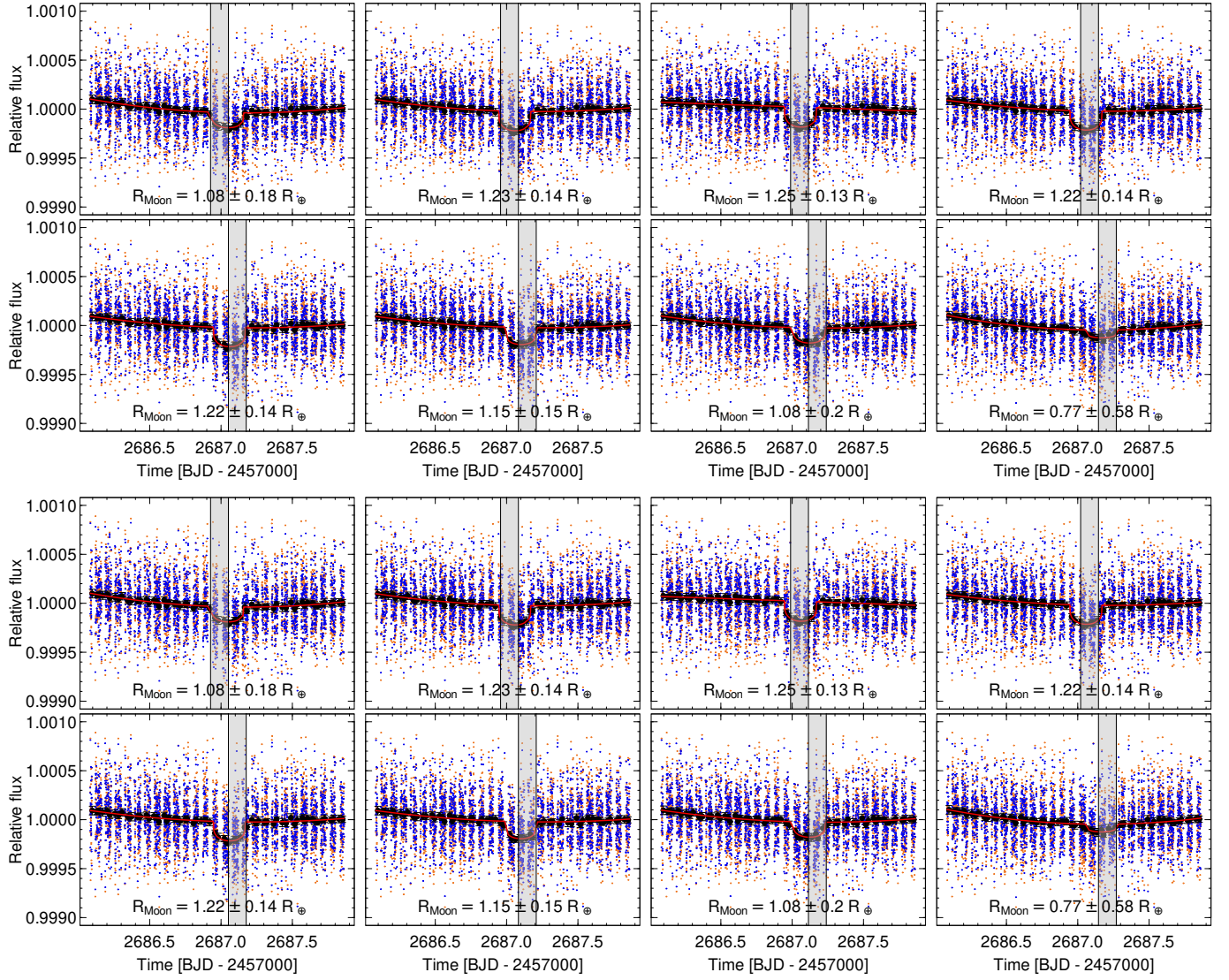


Fig. B.5. Performance of the box-shifting approach on the injected exomoon transits. **Top row:** Recovery of an $R_{\text{Moon}} = 1.35 R_{\oplus}$ in the first visit. **Bottom row:** Recovery of an $R_{\text{Moon}} = 1.35 R_{\oplus}$ in the second visit.

Table B.1. Times of midtransit and recovered radii by the box-shifting method, of the injection-and-retrieval tests ($T_{0,\text{Moon, injected}} = 2301.25$) from the first visit.

Searchbox number	Searchbox left edge	Searchbox right edge	$T_{0,\text{Moon}}$	$R_{\text{Moon}} [R_{\oplus}]$	$\frac{T_{0,\text{Moon, injected}} - T_{0,\text{Moon}}}{\Delta T_{0,\text{Moon}}}$	$\frac{R_{\text{Moon, injected}} - R_{\text{Moon}}}{\Delta R_{\text{Moon}}}$
$R_{\text{Moon, injected}} = 0.8 R_{\oplus}$						
1	2301.0438	2301.1688	2301.152 ± 0.039	0.47 ± 0.36	2.5	0.9
2	2301.0750	2301.2000	2301.179 ± 0.019	0.60 ± 0.15	3.8	1.3
3	2301.1063	2301.2313	2301.202 ± 0.023	0.63 ± 0.13	2.1	1.4
4	2301.1375	2301.2625	2301.216 ± 0.032	0.64 ± 0.12	1.1	1.2
5	2301.1688	2301.2938	2301.225 ± 0.030	0.65 ± 0.12	0.8	1.3
6	2301.2000	2301.3250	2301.238 ± 0.024	0.66 ± 0.12	0.5	1.2
7	2301.2313	2301.3563	2301.246 ± 0.014	0.66 ± 0.13	0.3	1.0
8	2301.2625	2301.3875	2301.276 ± 0.038	0.52 ± 0.42	-0.7	0.7
$R_{\text{Moon, injected}} = 0.9 R_{\oplus}$						
1	2301.0438	2301.1688	2301.154 ± 0.034	0.55 ± 0.34	2.8	1.0
2	2301.0750	2301.2000	2301.181 ± 0.017	0.66 ± 0.13	4.2	1.9
3	2301.1063	2301.2313	2301.209 ± 0.022	0.71 ± 0.11	1.9	1.7
4	2301.1375	2301.2625	2301.238 ± 0.021	0.75 ± 0.11	0.6	1.3
5	2301.1688	2301.2938	2301.239 ± 0.022	0.75 ± 0.11	0.5	1.4
6	2301.2000	2301.3250	2301.240 ± 0.019	0.75 ± 0.11	0.5	1.3
7	2301.2313	2301.3563	2301.243 ± 0.010	0.77 ± 0.10	0.7	1.2
8	2301.2625	2301.3875	2301.269 ± 0.008	0.71 ± 0.16	-2.4	1.2
$R_{\text{Moon, injected}} = 1.05 R_{\oplus}$						
1	2301.0438	2301.1688	2301.158 ± 0.019	0.68 ± 0.22	4.8	1.7
2	2301.0750	2301.2000	2301.183 ± 0.014	0.77 ± 0.12	4.8	2.4
3	2301.1063	2301.2313	2301.222 ± 0.013	0.85 ± 0.10	2.2	1.9
4	2301.1375	2301.2625	2301.241 ± 0.006	0.93 ± 0.09	1.6	1.4
5	2301.1688	2301.2938	2301.241 ± 0.006	0.93 ± 0.09	1.5	1.4
6	2301.2000	2301.3250	2301.241 ± 0.006	0.93 ± 0.09	1.5	1.3
7	2301.2313	2301.3563	2301.242 ± 0.006	0.93 ± 0.09	1.4	1.3
8	2301.2625	2301.3875	2301.267 ± 0.004	0.88 ± 0.10	-3.8	1.6
$R_{\text{Moon, injected}} = 1.20 R_{\oplus}$						
1	2301.0438	2301.1688	2301.160 ± 0.010	0.77 ± 0.18	9.0	2.4
2	2301.0750	2301.2000	2301.189 ± 0.011	0.87 ± 0.11	5.5	3.1
3	2301.1063	2301.2313	2301.229 ± 0.004	1.02 ± 0.09	5.4	2.1
4	2301.1375	2301.2625	2301.241 ± 0.003	1.09 ± 0.08	2.8	1.4
5	2301.1688	2301.2938	2301.241 ± 0.003	1.09 ± 0.08	2.8	1.4
6	2301.2000	2301.3250	2301.241 ± 0.003	1.09 ± 0.08	2.8	1.4
7	2301.2313	2301.3563	2301.241 ± 0.003	1.09 ± 0.07	2.8	1.5
8	2301.2625	2301.3875	2301.265 ± 0.003	1.04 ± 0.09	-5.1	1.8
$R_{\text{Moon, injected}} = 1.35 R_{\oplus}$						
1	2301.0438	2301.1688	2301.163 ± 0.007	0.87 ± 0.14	12.9	3.5
2	2301.0750	2301.2000	2301.195 ± 0.010	0.97 ± 0.10	5.5	3.7
3	2301.1063	2301.2313	2301.230 ± 0.002	1.15 ± 0.08	10.9	2.5
4	2301.1375	2301.2625	2301.241 ± 0.002	1.23 ± 0.07	3.9	1.8
5	2301.1688	2301.2938	2301.241 ± 0.002	1.23 ± 0.07	3.8	1.8
6	2301.2000	2301.3250	2301.241 ± 0.002	1.23 ± 0.07	3.8	1.7
7	2301.2313	2301.3563	2301.241 ± 0.002	1.23 ± 0.07	3.8	1.7
8	2301.2625	2301.3875	2301.264 ± 0.002	1.17 ± 0.08	-6.7	2.1

Table B.2. Times of midtransit and recovered radii by the box-shifting method, of the injection-and-retrieval tests ($T_{0,\text{Moon, injected}} = 2687.05$ from the first visit).

Searchbox number	Searchbox left edge	Searchbox right edge	$T_{0,\text{Moon}}$	$R_{\text{Moon}} [R_{\oplus}]$	$\frac{T_{0,\text{Moon, injected}} - T_{0,\text{Moon}}}{\Delta T_{0,\text{Moon}}}$	$\frac{R_{\text{Moon, injected}} - R_{\text{Moon}}}{\Delta R_{\text{Moon}}}$
$R_{\text{Moon, injected}} = 0.8 R_{\oplus}$						
1	2686.9265	2687.0515	2686.962 ± 0.048	-0.28 ± 0.55	1.8	2.0
2	2686.9578	2687.0828	2687.068 ± 0.033	0.60 ± 0.39	-0.5	0.5
3	2686.9890	2687.1140	2687.089 ± 0.020	0.70 ± 0.20	-2.0	0.5
4	2687.0203	2687.1453	2687.100 ± 0.024	0.70 ± 0.18	-2.0	0.5
5	2687.0515	2687.1765	2687.106 ± 0.036	0.72 ± 0.17	-1.6	0.4
6	2687.0828	2687.2078	2687.118 ± 0.034	0.71 ± 0.18	-2.0	0.5
7	2687.1140	2687.2390	2687.152 ± 0.028	0.69 ± 0.22	-3.6	0.5
8	2687.1453	2687.2703	2687.170 ± 0.028	0.62 ± 0.35	-4.3	0.5
$R_{\text{Moon, injected}} = 0.9 R_{\oplus}$						
1	2686.9265	2687.0515	2687.002 ± 0.054	0.14 ± 0.64	0.9	1.2
2	2686.9578	2687.0828	2687.075 ± 0.013	0.77 ± 0.18	-1.8	0.7
3	2686.9890	2687.1140	2687.090 ± 0.015	0.80 ± 0.14	-2.7	0.7
4	2687.0203	2687.1453	2687.096 ± 0.019	0.80 ± 0.14	-2.4	0.7
5	2687.0515	2687.1765	2687.099 ± 0.024	0.80 ± 0.14	-2.0	0.7
6	2687.0828	2687.2078	2687.104 ± 0.026	0.80 ± 0.15	-2.1	0.7
7	2687.1140	2687.2390	2687.141 ± 0.026	0.75 ± 0.18	-3.5	0.8
8	2687.1453	2687.2703	2687.168 ± 0.027	0.67 ± 0.37	-4.4	0.6
$R_{\text{Moon, injected}} = 1.05 R_{\oplus}$						
1	2686.9265	2687.0515	2687.038 ± 0.024	0.72 ± 0.36	0.5	0.9
2	2686.9578	2687.0828	2687.075 ± 0.012	0.91 ± 0.13	-2.1	1.1
3	2686.9890	2687.1140	2687.084 ± 0.017	0.90 ± 0.12	-2.0	1.2
4	2687.0203	2687.1453	2687.085 ± 0.017	0.90 ± 0.12	-2.1	1.2
5	2687.0515	2687.1765	2687.086 ± 0.017	0.90 ± 0.12	-2.1	1.2
6	2687.0828	2687.2078	2687.101 ± 0.015	0.90 ± 0.13	-3.5	1.2
7	2687.1140	2687.2390	2687.125 ± 0.020	0.86 ± 0.16	-3.7	1.2
8	2687.1453	2687.2703	2687.164 ± 0.019	0.74 ± 0.29	-6.0	1.0
$R_{\text{Moon, injected}} = 1.20 R_{\oplus}$						
1	2686.9265	2687.0515	2687.048 ± 0.010	0.95 ± 0.13	0.2	1.8
2	2686.9578	2687.0828	2687.069 ± 0.012	1.05 ± 0.11	-1.7	1.3
3	2686.9890	2687.1140	2687.076 ± 0.018	1.05 ± 0.11	-1.5	1.4
4	2687.0203	2687.1453	2687.075 ± 0.020	1.04 ± 0.11	-1.3	1.5
5	2687.0515	2687.1765	2687.077 ± 0.020	1.04 ± 0.11	-1.3	1.4
6	2687.0828	2687.2078	2687.098 ± 0.010	1.02 ± 0.11	-4.7	1.6
7	2687.1140	2687.2390	2687.119 ± 0.010	0.97 ± 0.14	-6.9	1.7
8	2687.1453	2687.2703	2687.162 ± 0.021	0.79 ± 0.36	-5.3	1.1
$R_{\text{Moon, injected}} = 1.35 R_{\oplus}$						
1	2686.9265	2687.0515	2687.049 ± 0.002	1.14 ± 0.11	0.3	1.9
2	2686.9578	2687.0828	2687.057 ± 0.006	1.20 ± 0.10	-1.2	1.5
3	2686.9890	2687.1140	2687.057 ± 0.010	1.20 ± 0.10	-0.7	1.5
4	2687.0203	2687.1453	2687.057 ± 0.009	1.20 ± 0.10	-0.8	1.5
5	2687.0515	2687.1765	2687.057 ± 0.009	1.20 ± 0.10	-0.8	1.5
6	2687.0828	2687.2078	2687.092 ± 0.009	1.13 ± 0.11	-4.5	1.9
7	2687.1140	2687.2390	2687.117 ± 0.004	1.09 ± 0.13	-19.0	2.0
8	2687.1453	2687.2703	2687.161 ± 0.023	0.82 ± 0.41	-4.9	1.3