LUNAR LEVITATION DUST INSTRUMENT FOR A LANDER: INVESTIGATING ELECTROSTATIC DUST TRANSPORT ON THE MOON

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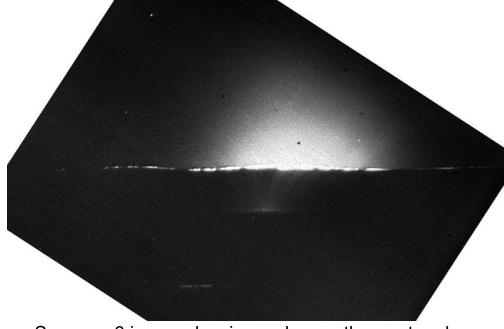


Lunar Regolith and Dust

- Lunar regolith : loose deposit of rock (Si, Fe, O₂)
- ranges from large boulders to ultrafine dust, < 1 cm in size.
- finest components < 20 micron make up Lunar dust environment
- HORIZON GLOW (HG) at the terminator by Surveyor and Apollo missions
- HG is mainly because of forward scattering of sunlight
- Dust is abrasive, sticky, health risky, technology threat
- → critical for instruments, vehicles, humans



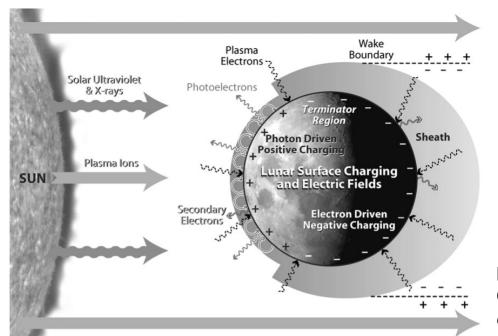
Footprint of Buzz Aldrin in Lunar Regolith (Credits: NASA Public Domain)



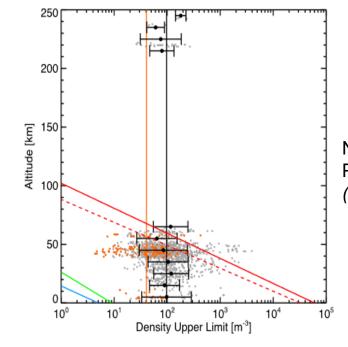
Surveyor 6 image showing a glow on the western lunar horizon after sunset (Credits: NASA Public Domain)

Lunar Dust: Charging Mechanisms

- photoemission of electrons by UV rays and light X-rays
- 2. plasma electrons and ions
- 3. secondary electrons
- 4. electrons and ions of magnetosphere plasma (variable)
- Clementine 1 / m³ # density
- LDEX (LADEE) 100 / m³ # density
- LADEE did not find dust levitation at 20-60 km
- Chang'E-3: ~ 28 cm (no dust at higher altitudes)

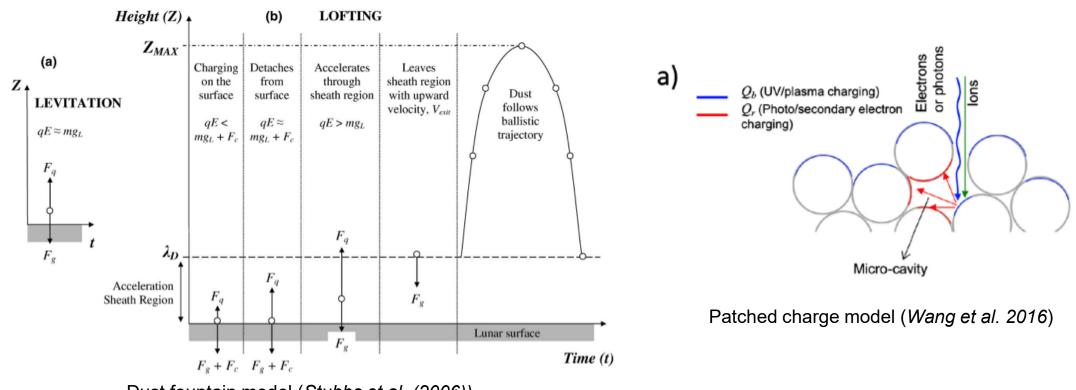


Lunar Surface Charging (Stubbs et al. (2014))



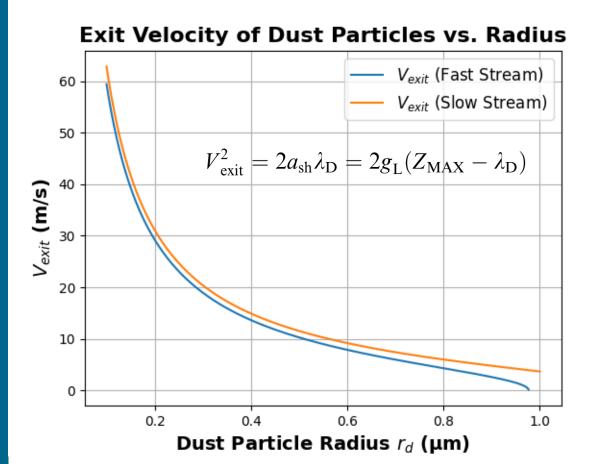
Number Density of Dust Particles measured by LDEX (Horiyani, Szalay (2015))

Dust Lofting Mechanism

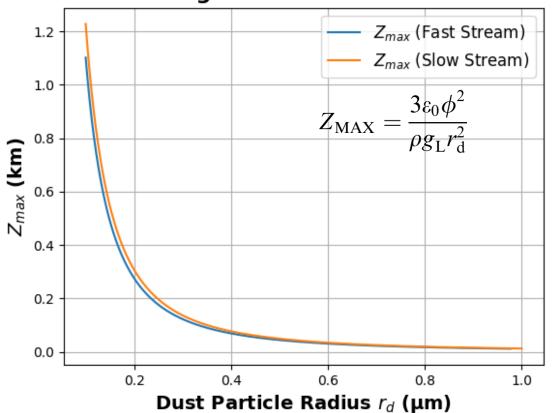


- Dust fountain model (Stubbs et al. (2006))
- dust fountain model explains the levitation simplified, but well enough for a 1st order assessment
- 'Coulomb Explosions' makes initial lift-off happen

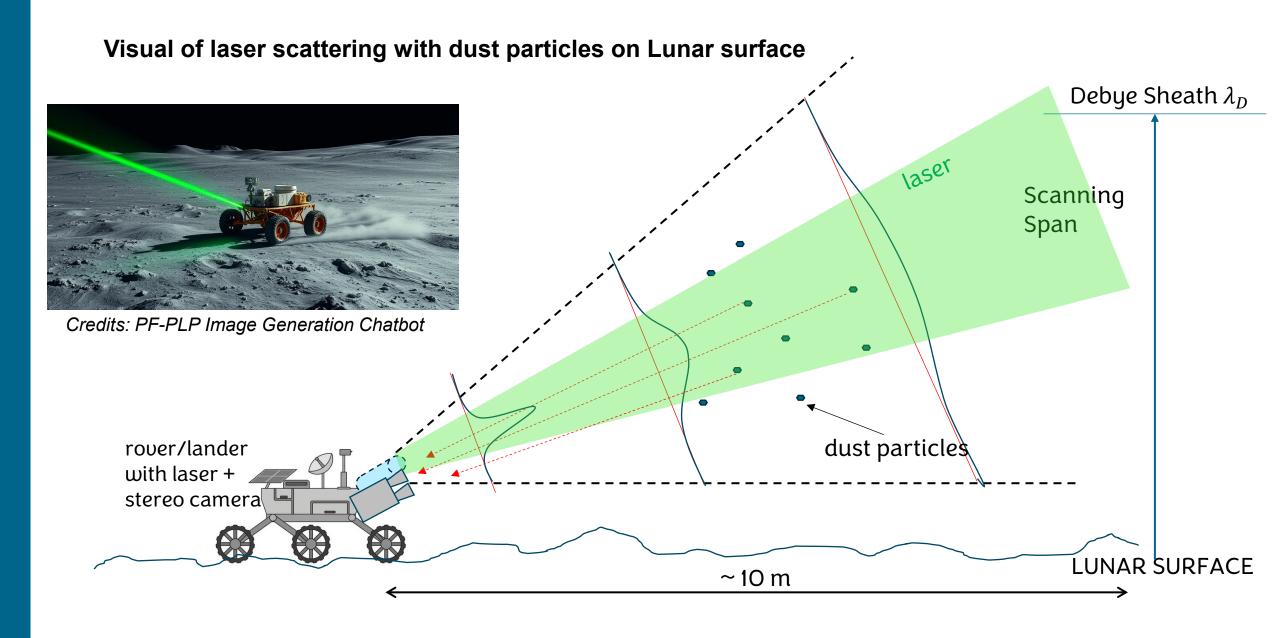
Dynamic behaviour of dust particles



Maximum Height of Dust Particles vs. Radius



- µm sized particles are accelerated in the Debye sheet to velocities of < 10 m/s
- the heights they reach are up to 50 m, and significantly lower for particles larger than some μm



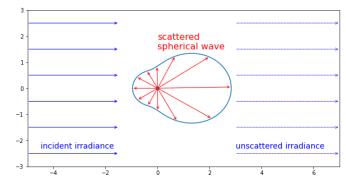
HV Power Schematic sketch of the experiment Supply (max. 5 kV) dust acceleration needle at 3 kV first tests with defined sizes chamber Lunar dust analog: Ag coated Glass ($\emptyset 10 \ \mu m$) dust samples: Cu spheres ($\emptyset 30 \mu m$) ground grid signal generator $(at \sim 100-150 \text{ Hz} = \text{FPS})$ open air accelerated particle environment beam @ 1 mm exit expander pulsed laser $(\lambda = 532 nm,$ $w_0 = 0.1 \, \mu m$ E=5 mIt = 1 nsscattering/ ~ 5 cm backscattering cloud **STEREO** $R \sim 1.4 m$ **CAMERA** pixel = $3.5 \mu m$

Signal Calculations

- SNR calculations were done for feasibility check
- Mie theory assumed for first assessment
- assuming a pulsed 5 mJ laser with full beam divergence of about 35 mrad
- SNR > 1 for particles larger 1 μm

Assumptions for Mie Calculations

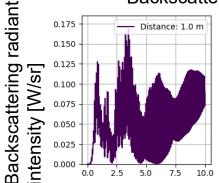
Refractive Index (lunar samples)	1.56 – 0.01j
Particle Radius	0.1 – 30 μm
Wavelength	532 nm
Scattering angle	-180 degree
Distance	1 – 8 m

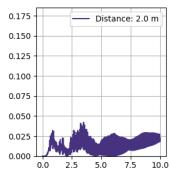


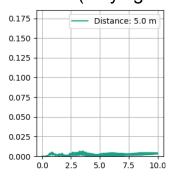
Credits: Scott Prahl/miepython

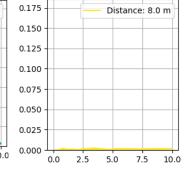
SNR vs Particle Radius for Different Distances

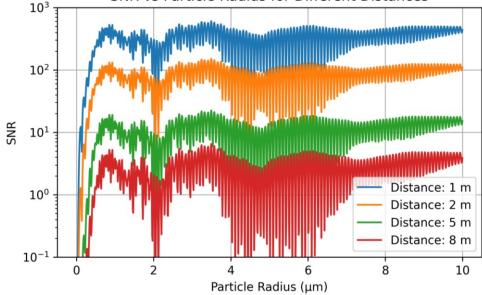
Backscattering intensity vs. particle radius (varying distance)

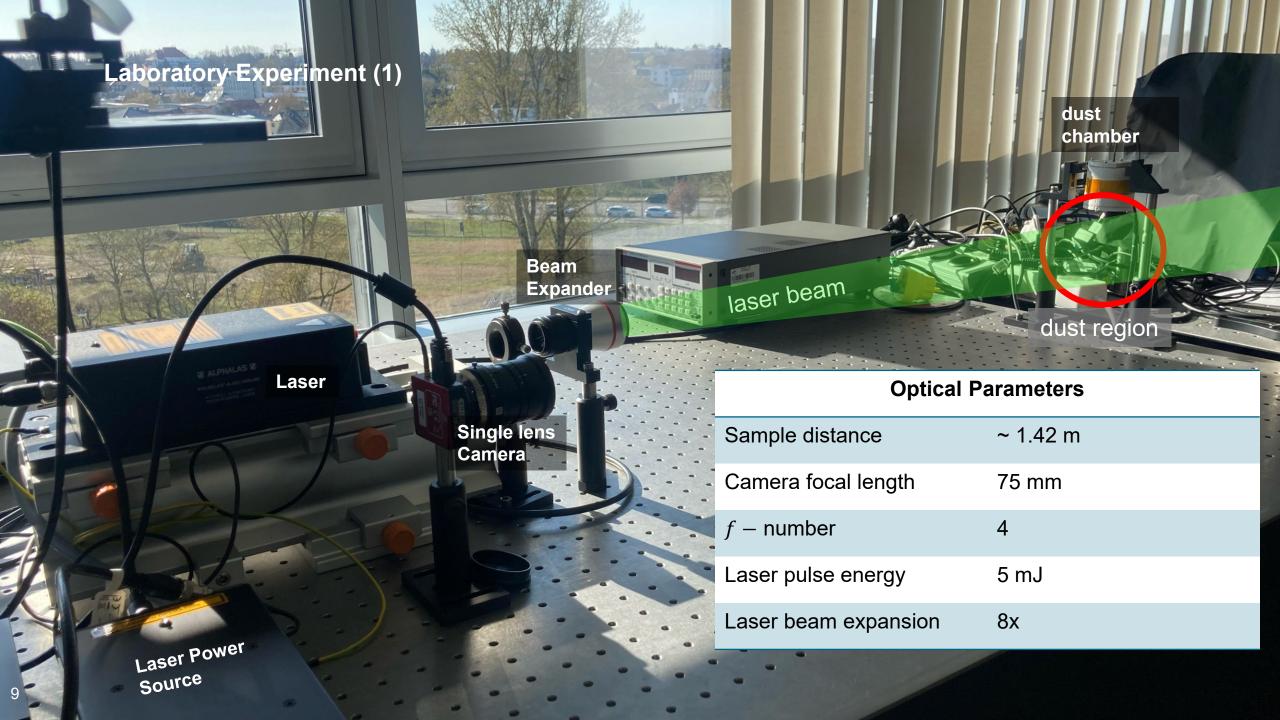




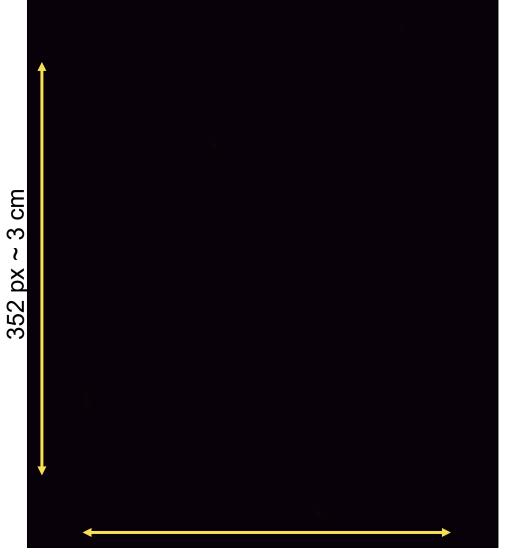






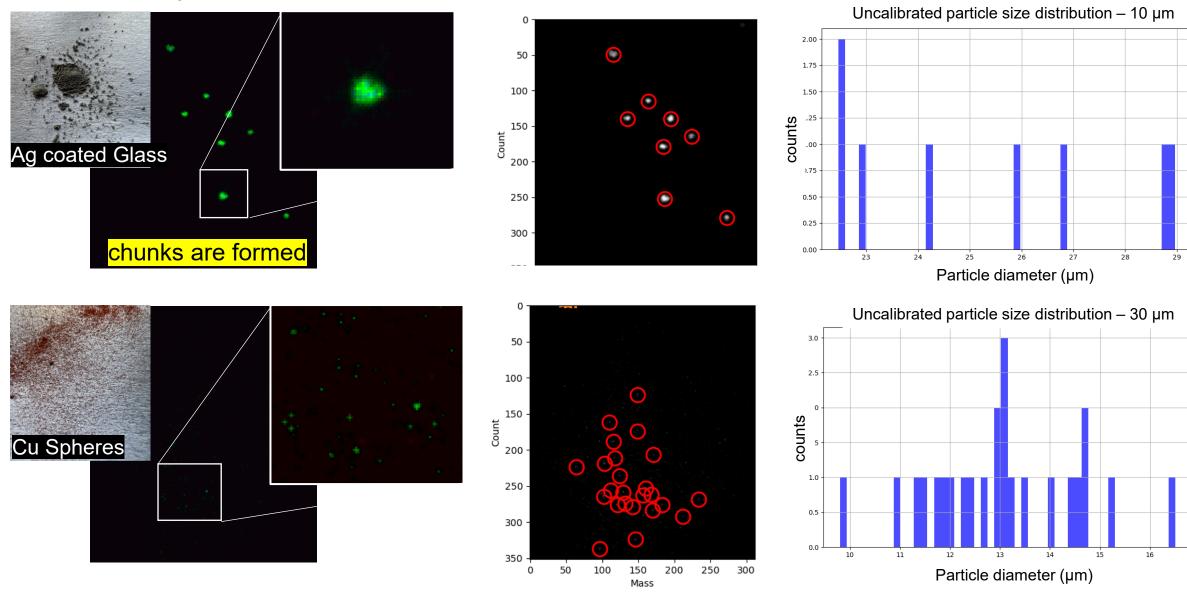


Laboratory Experiment (2)



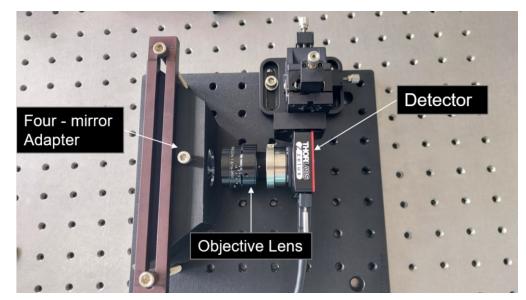
Camera settings	
Detector Resolution	1080 x 1440
ROI	312 x 352
Frames per second	100
Exposure time	1.6 ms
Gain	0
Triggering	Hardware
Pixel pitch	3.5 µm
Magnification	0.06

Laboratory Experiment (3)

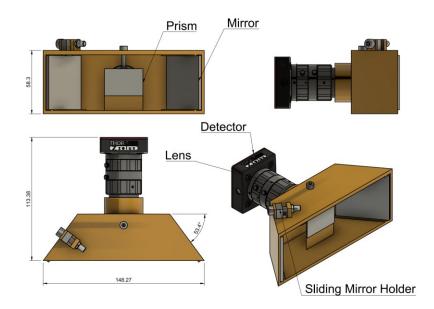


Later implementation of Stereo Camera

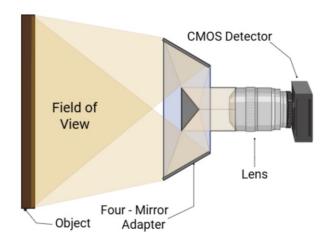
- implementation of stereo imaging planned
- knowledge of position of the particle in space (x, y, z)
- for deriving number densities
- for estimating particle sizes through signal strength
- for calculation of **velocity** components v_x , v_y , v_z



Credits: S. Chauhan



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Conclusions & Outlook

- Understanding lunar dust under various charging mechanisms is essential.
- Literature and missions **show µm/sub-µm dust particles levitate to meter scales** and contribute to Horizon Glow.
- Laser scattering successfully demonstrated dust detection.
- Algorithm identified particle sizes, distributions, and densities.
- Dust chamber testing requires a more controlled approach.
- "Salt-pinching" used as an alternative test method.
- Algorithm needs development for backscattered intensity and detector irradiance.
- A higher FPS camera (>150 FPS) is needed to track faster particles (~4 m/s).
- More accurate particle refractive index data needed for model validation.
- Correlation signal strength with particle size.
- Conduct tests in controlled environments with finer dust.