

DISRUPTIVE APPLICATIONS ENABLED BY QUANTUM SENSORS AND CLOCKS

Heraeus Workshop

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Wilhelm Runge Straße 10
89081 Ulm



GERMAN AEROSPACE CENTER (DLR)

Research, technology and knowledge transfer for a sustainable future and to strengthen Germany as a location for science and business

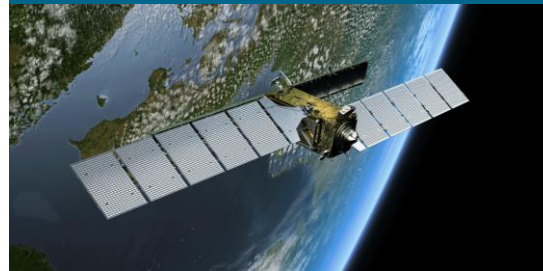


Research Center + Space Agency + Project Management

AERONAUTICS



SPACE



ENERGY



TRANSPORT



SECURITY
civil security & defence research



DIGITALISATION, QUANTUM TECHNOLOGY
AND SYSTEM MODELLING



- Europe's largest research centre for aeronautics and space
- Close cooperation with academia, research, business and industry
- BMWK is the primary funding ministry, BMVg provides institutional funding, BMI, BMU and others provide project funding

DLR sites



- **54 institutes and facilities across 30 sites**
 - 8 research stations
 - 4 international offices
- **More than 10.000 employees**
 - ~ 5.800 Scientific Staff
- **Budget: ~ 1.100 Mio. € (2021)**
 - ~ 550 Mio. Third-Party Funding

DLR Institute for Satellite Geodesy and Inertial Sensing

DLR Institute for Quantum Technologies

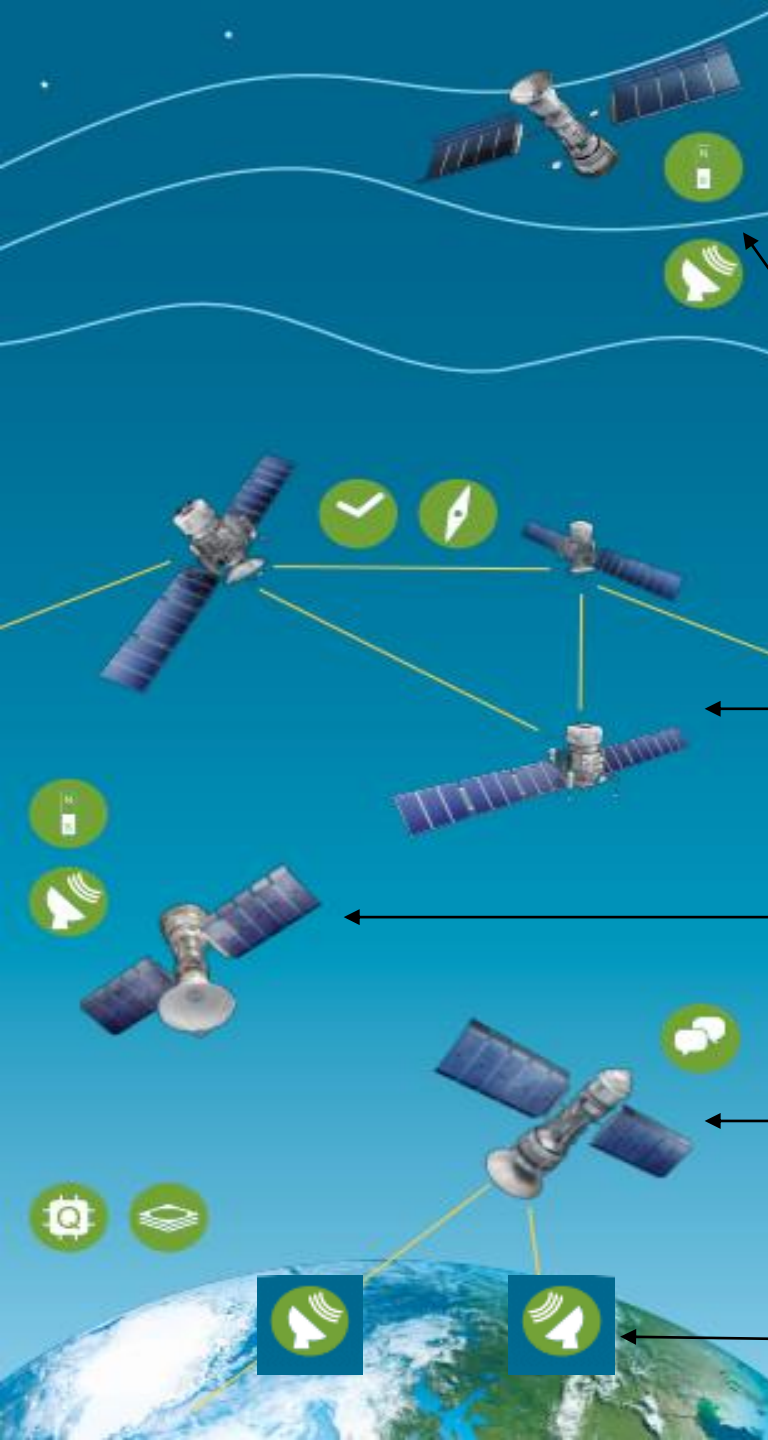
Quantum Technology Institutes
(also: DLR Quantum Computing Initiative)



DLR Institute for
Communication and
Navigation
Galileo Competence
Center

Institute for Quantum Technologies

Quantum technologies for Space



Data for ionosphere-troposphere-models
(quantum magnetometers and accelerometers)

Global Navigation Satellite Systems, resilient time
(quantum clocks)

Earth observation, resilient communication
(quantum RF receivers)

Global networks with advanced quantum functionality
(quantum communication, authentication, client computing)

Space traffic management, Space asset monitoring
(Quantum oscillators and clocks for radar)

UN proclaimed 2025 as:



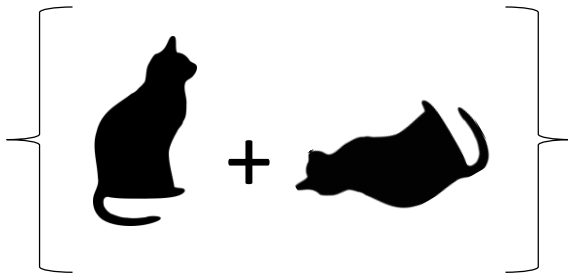
**INTERNATIONAL YEAR OF
Quantum Science
and Technology**

100 years of quantum is just the beginning...

[International Year of Quantum Science and Technology \(quantum2025.org\)](https://quantum2025.org)

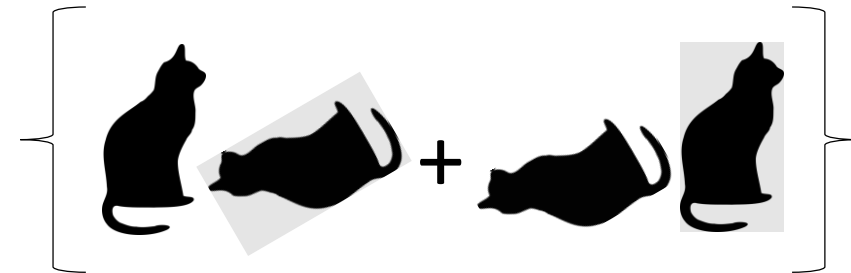
Superposition and Entanglement

Superposition



Particles simultaneously in several states
→ Schrödinger cat

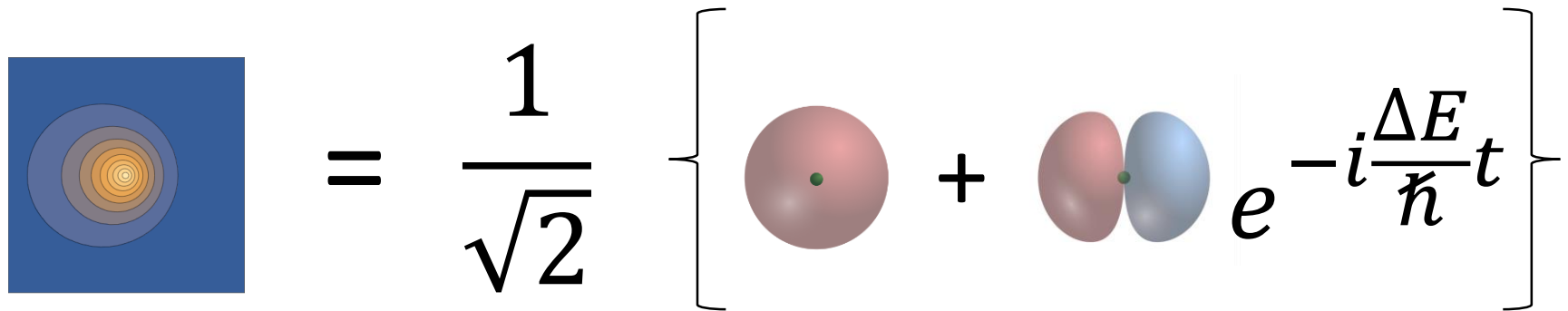
Entanglement



„Superposition involving several particles“

Example: Superposition in an Atom

Oscillating Electron Cloud


$$= \frac{1}{\sqrt{2}} \left\{ \text{red sphere} + \text{red and blue spheres} e^{-i \frac{\Delta E}{\hbar} t} \right\}$$

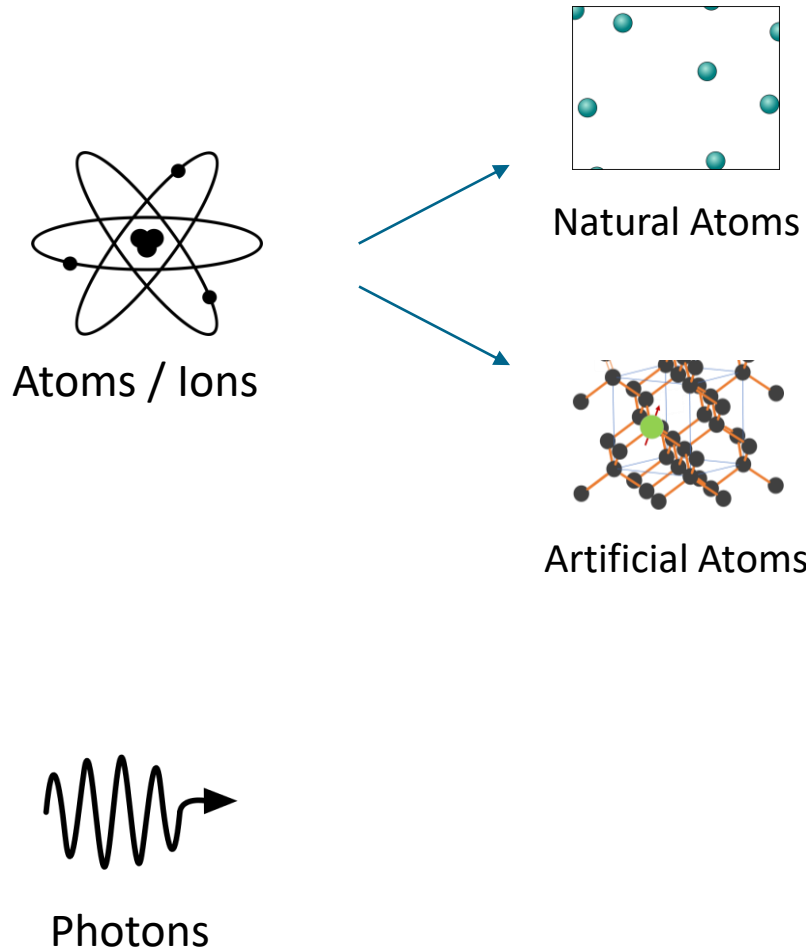
Adapted from:

By This file was made by User:Sven

(<http://creativecommons.org/licenses/by-sa/3.0/>), CC BY-SA 2.5-2.0-1.0

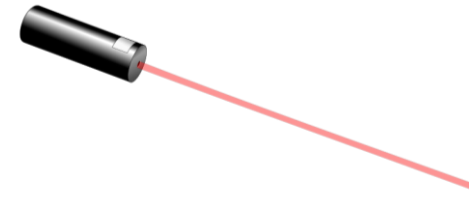
Ingredients for Quantum Technologies

Quantum Particles

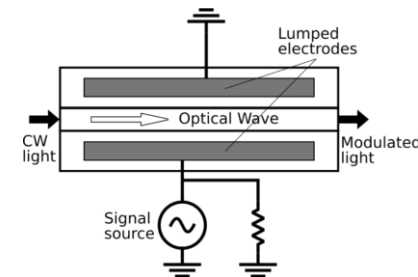


+

Control



Laser- or RF Pulses



Nonlinear crystals
Photonics

Electronics
Software
Shielding
Packaging
User interface

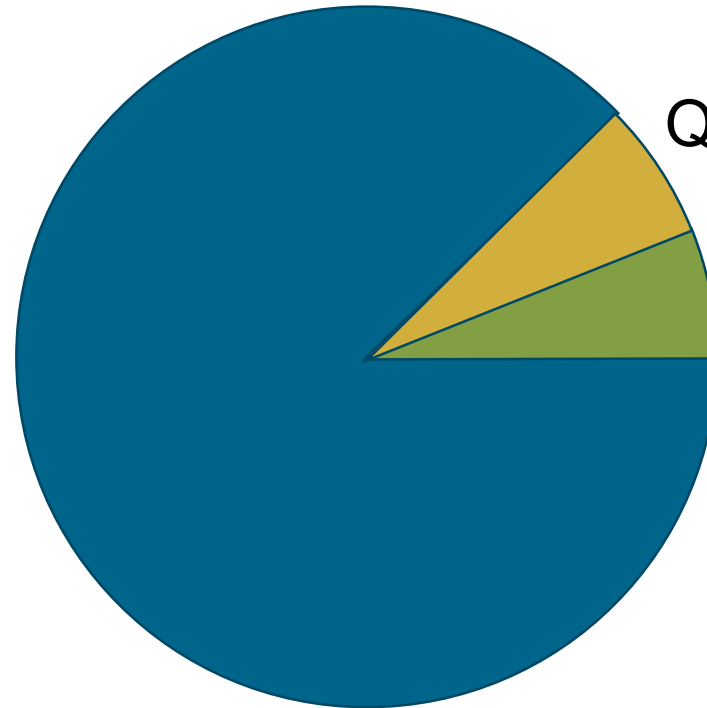
...

Quantum Technology Applications and Markets



Market estimates in 2024 (source: McKinsey Quantum Technology Monitor, 2023)

Quantum Computing (\$9-\$93B)



Quantum Communications (\$1-\$7B)

Quantum Sensing (\$1-\$6B)

Overall economic impact much larger (e.g. estimate for QC in 2035: \$620B-\$1270B)

Quantum Sensor Applications and their Impact



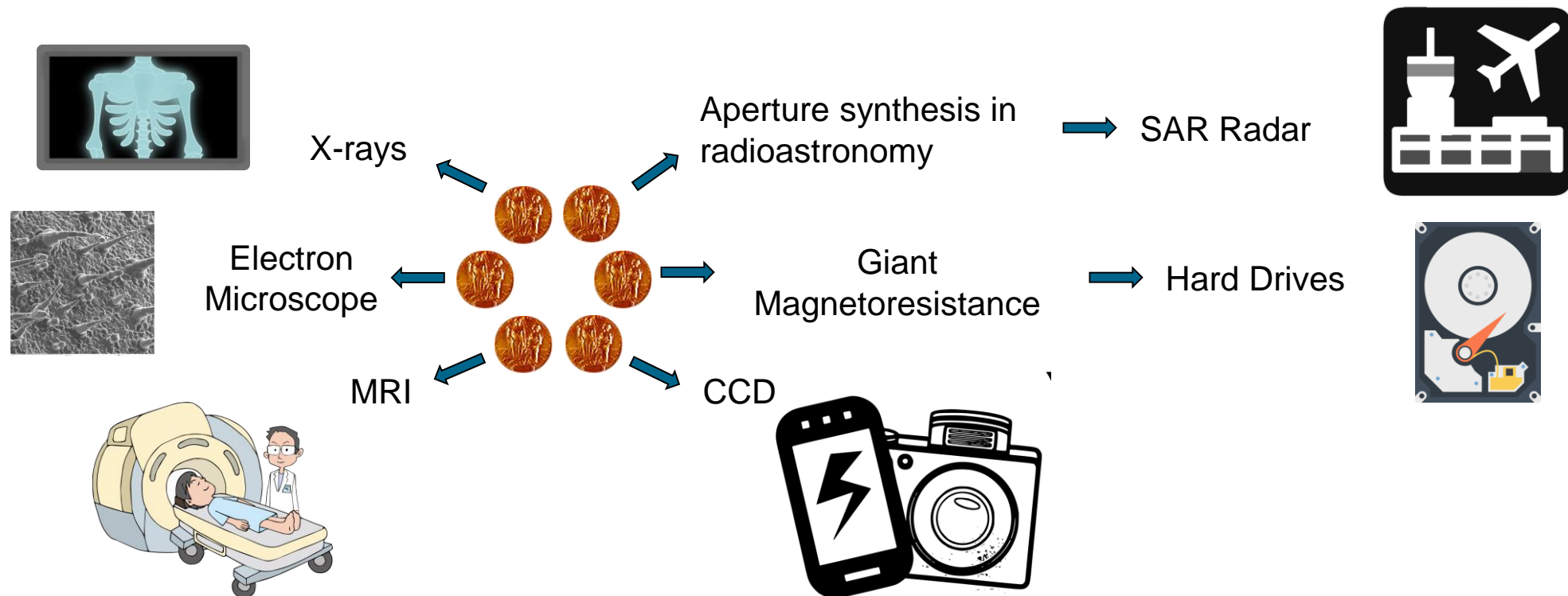
How important are sensors?

- What sensors did you use today?

Disruptive consequences of new sensors

Sensors and clocks are enabling system capabilities with large economic impact

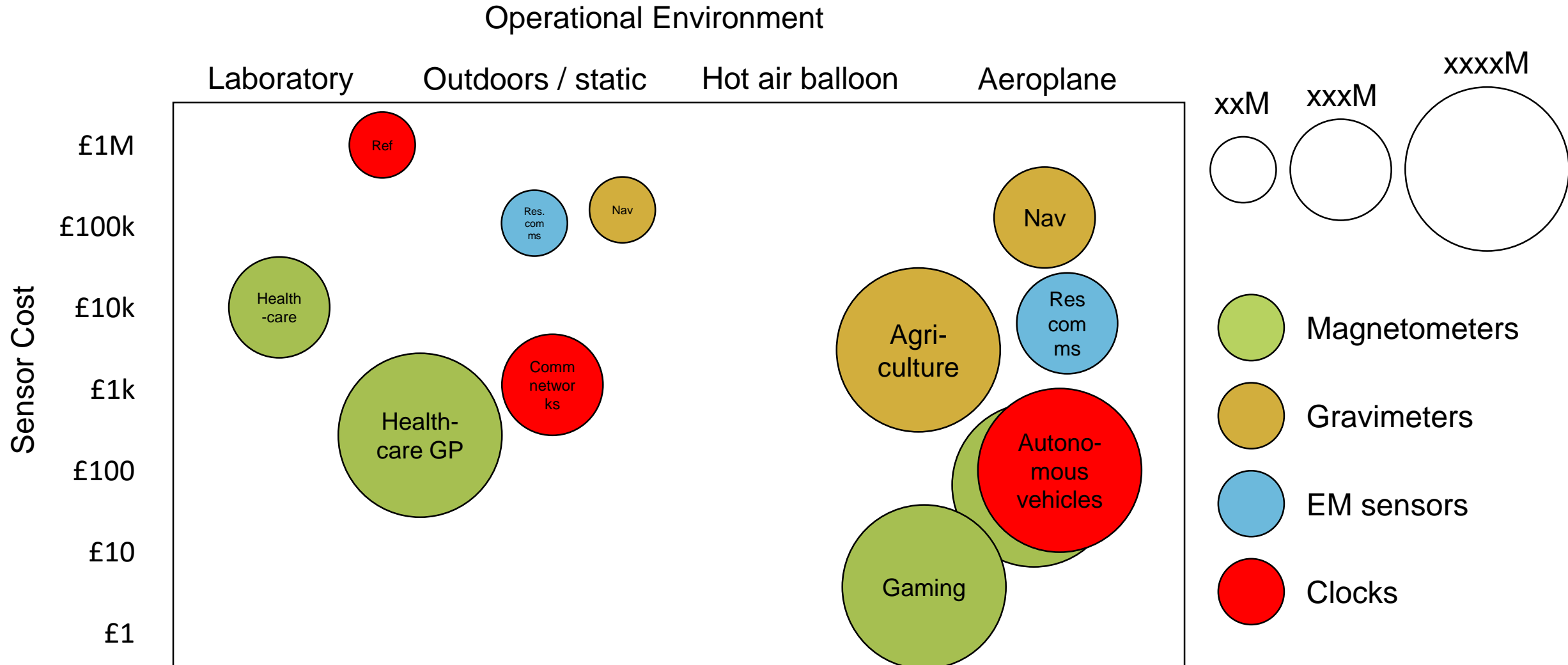
- Historic examples based on sensor-related Nobel Prizes



Potentially Accessible Quantum Sensor Markets



Key Drivers: Robustness and Cost



Magnetometers for Healthcare



Epilepsy: 60M people worldwide

Dementia: 1% GDP

Schizophrenia: 1% of population

Trauma: 100.000 / year in UK

What is “good enough”?

What are the barriers QT could overcome?

- Adaptation to head size
- Movement while measurement
- System cost

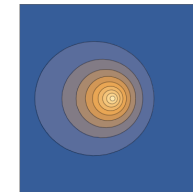
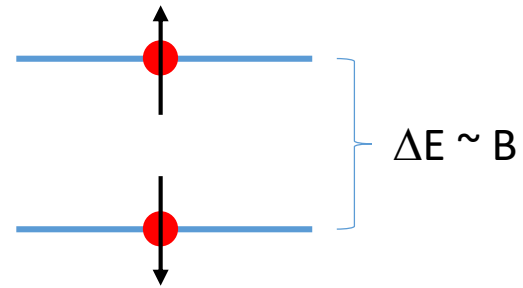
Several commercial sensors available:

e.g. QuSpin with $<15 \text{ fT/Hz}^{-1/2}$, 3-100Hz bandwidth

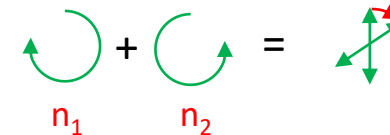
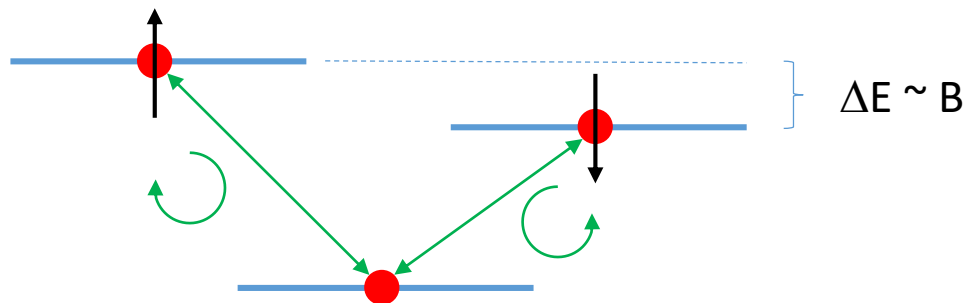
- This allows 5-10 times SNR enhancement over SQUID-MEG
- Good enough

Quantum Magnetometers

Superposition of energy levels depending on external magnetic field

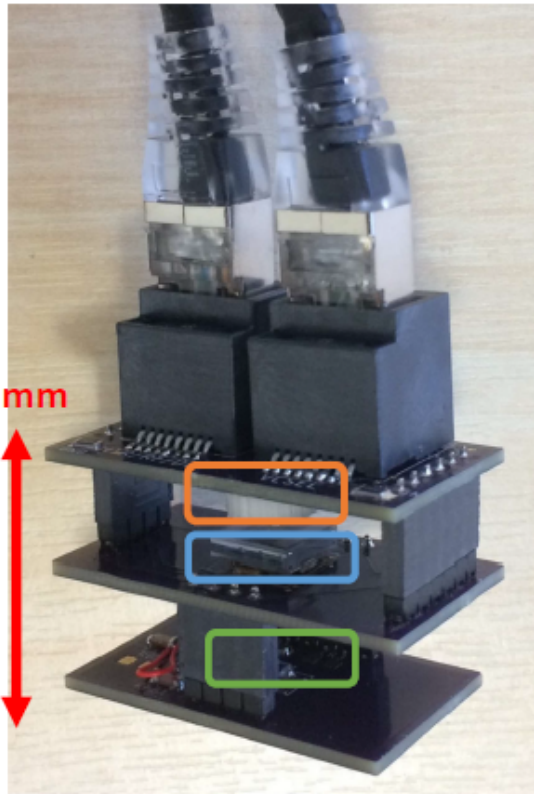


Oscillation frequency depends on magnetic field



Rotation of polarization

Miniaturisation of atomic magnetometers

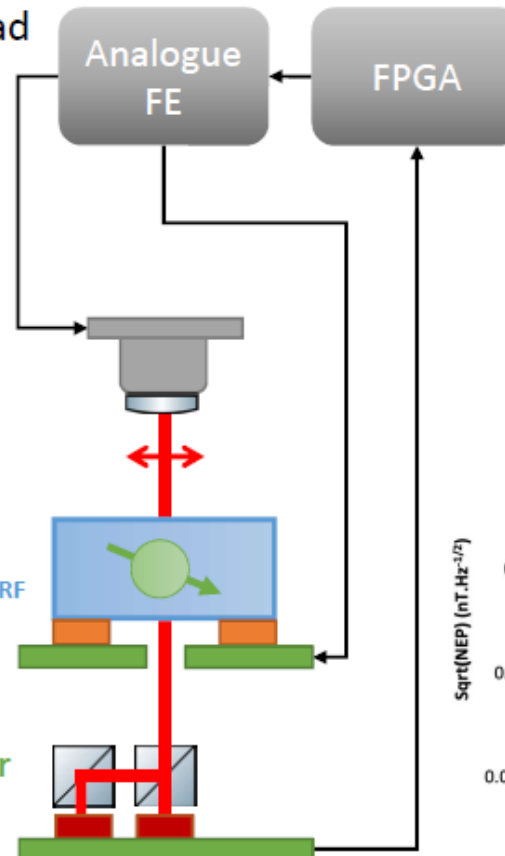


- 75 cm³ sensor head
- 60 g weight
- 5 W power

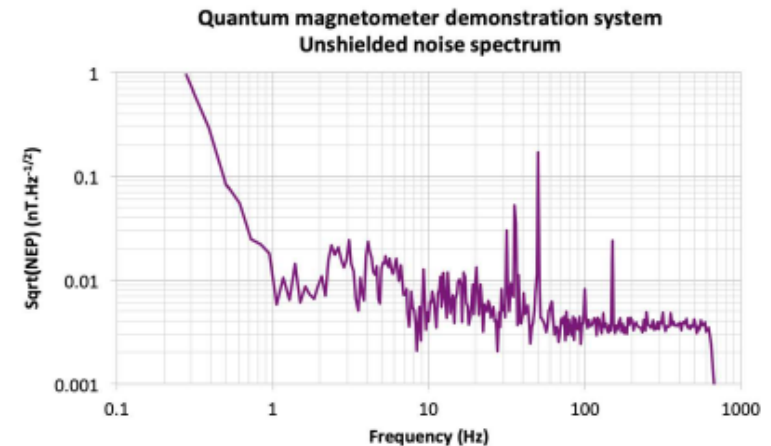
895 nm VCSEL with thermal feedback

¹³³Cs vapour cell & B_{RF} coils

Balanced polarimeter

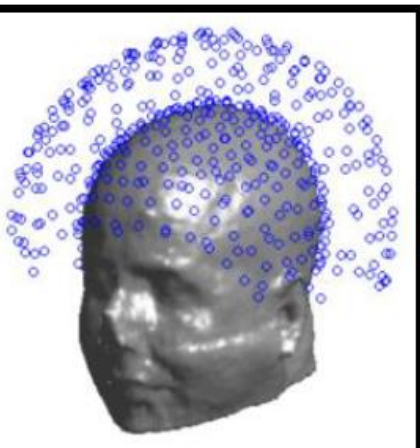


- High sensitivity
 - $\sim \text{pT}\cdot\text{Hz}^{-1/2}$
 - 0.1 ppm in Earth's field





Conventional MEG



On scalp MEG simulations 2016



Single channel recording 2017



First wearable OPM array 2018



First paediatric helmet 2019

A new generation of quantum sensors have enabled 'wearable' brain imaging technology



50 channel whole head system 2020



First simultaneous OPM/EEG 2019

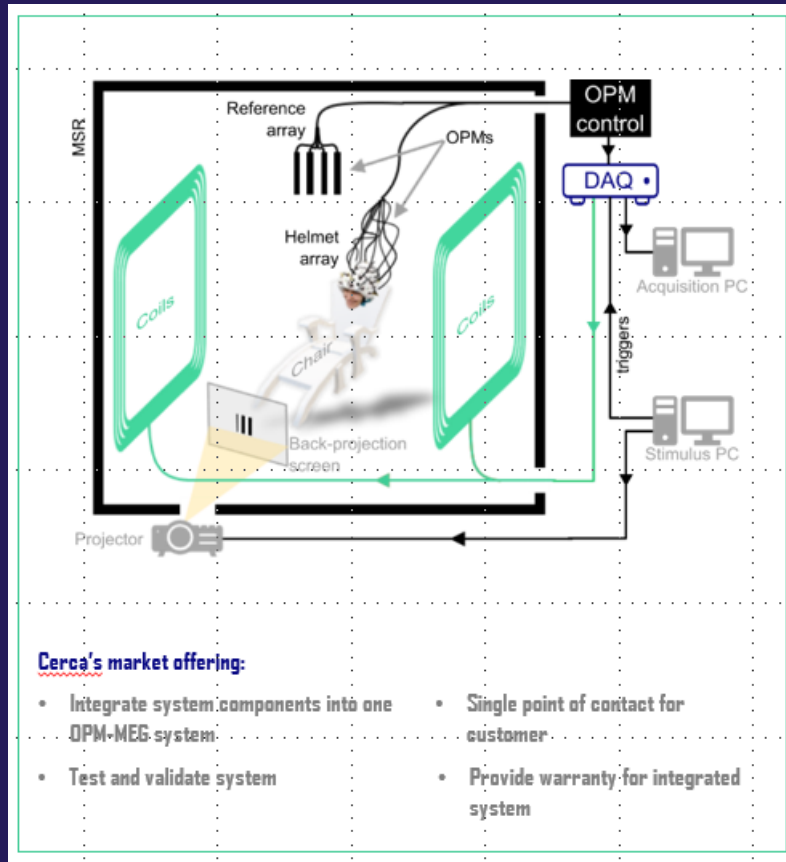


First Gen II OPM recordings 2019

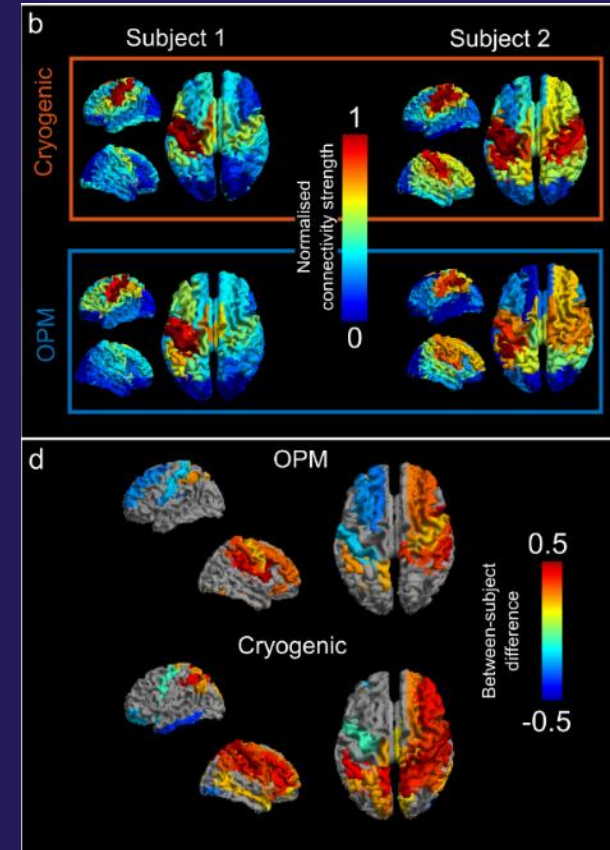


First VR-MEG recording 2019

Its here NOW: Commercial Offering



Joint venture between University of Nottingham and Magnetic Shields Ltd.



Gravity Gradients for Construction



Underground risk in infrastructure projects
→ **0.5% GDP**



Drainage



Voids leading to sinkholes



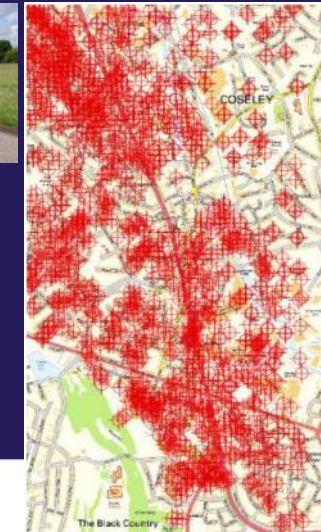
Badger setts



Leakage from canals and reservoirs



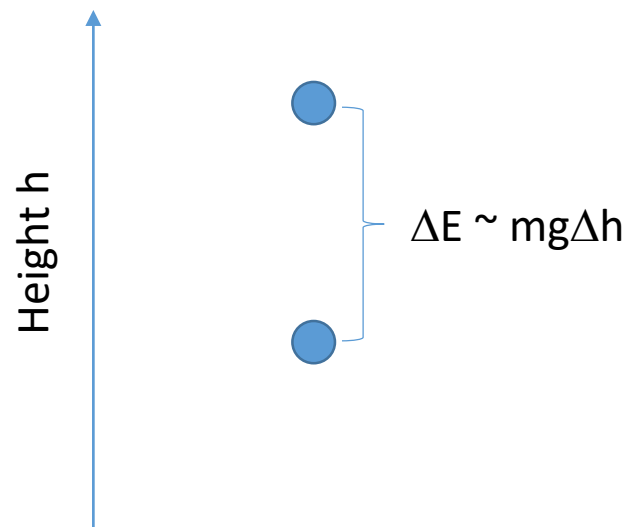
Mineshafts



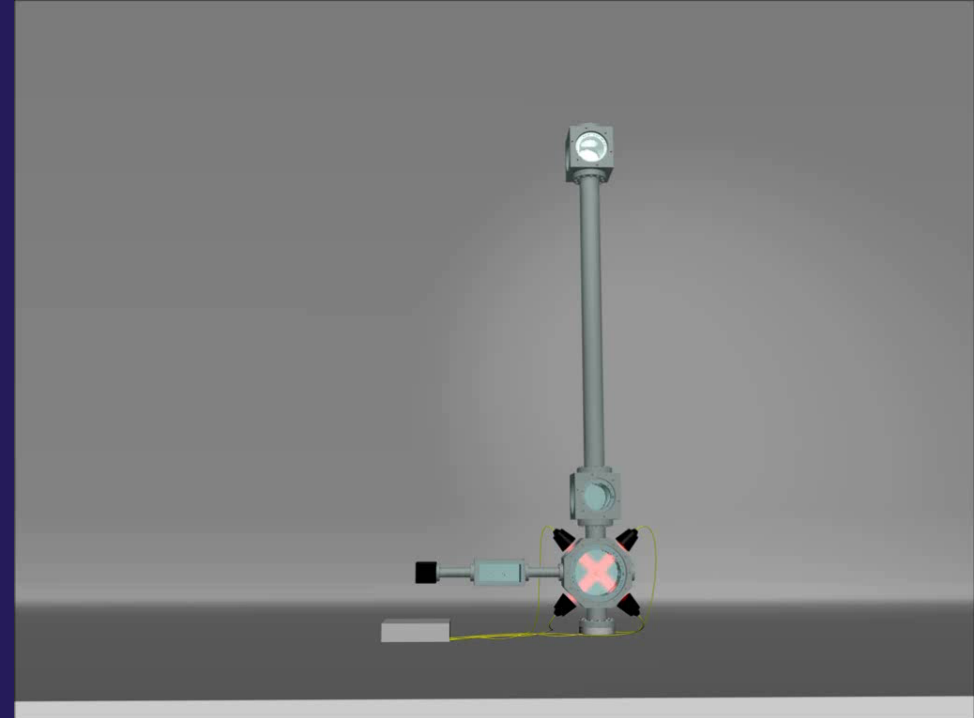
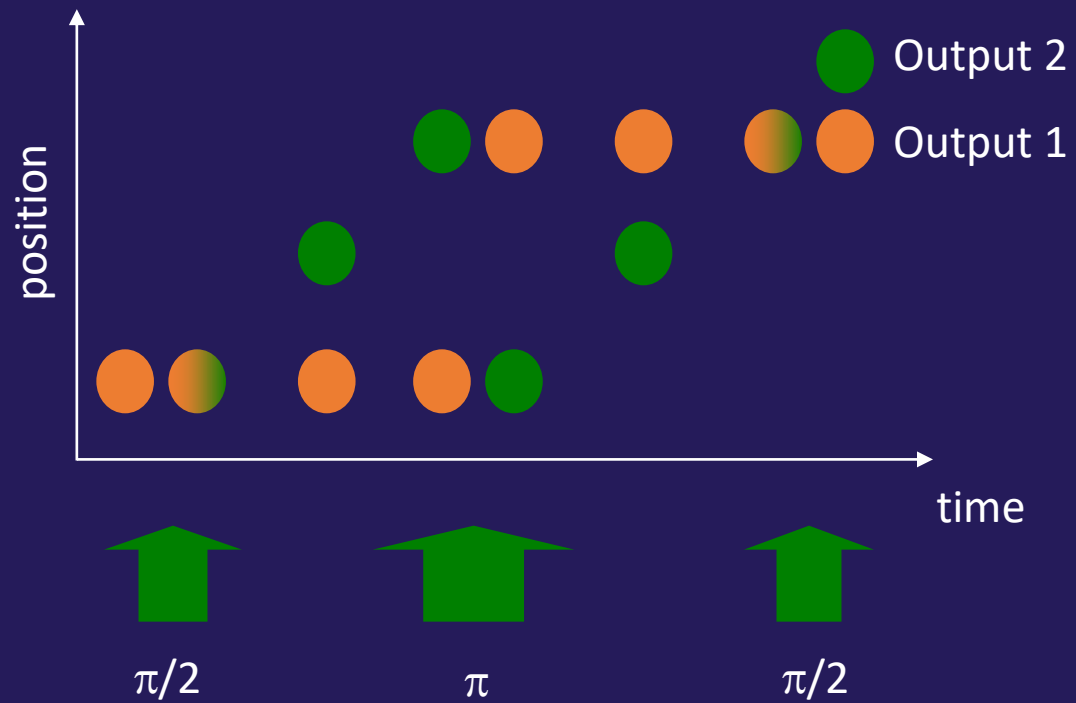
Collaboration: physics, civil engineering, geophysics, industry

Quantum Gravimeters / Inertial Sensors

Potential difference leads to different phase evolution

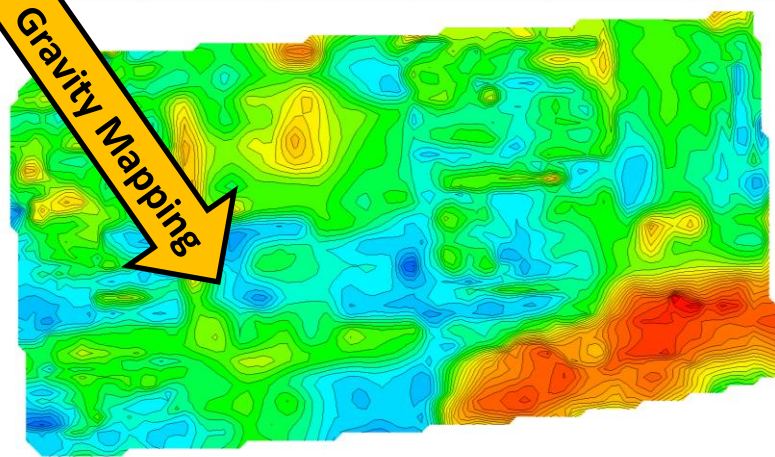


Atom Interferometer



Microgravity Surveys and their Limitations

Example: Brown Field Site Survey



RSK

UNIVERSITY OF
BIRMINGHAM

Classical microgravity sensors are sufficiently sensitive to deliver useful information!

BUT:

They take 5-10 min/measurement point

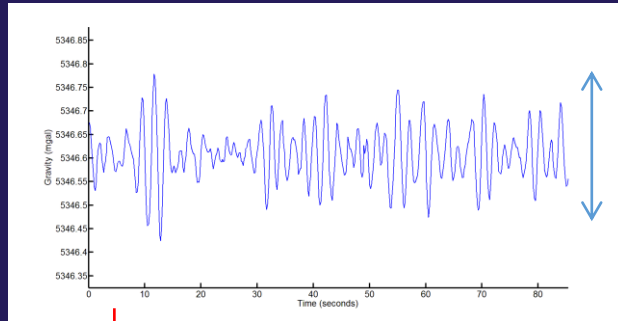
Sensor drift needs to be corrected by periodically returning to a calibration point

In this example: 1 month for 1 ha with 3 sensors and 4 persons

→ Commercial uptake hindered by cost of operation, not the sensitivity of the instrument

Why do Gravity Measurements take so much Time?

- Acceleration vs gravity



30-100 ng

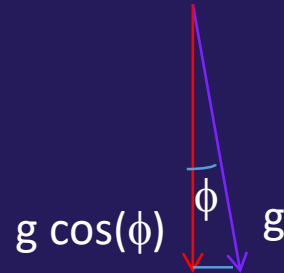


Minutes / point

Requirement to
achieve 1 ng



- Tilt

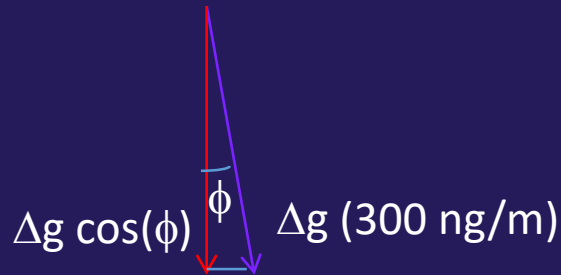


0.001° alignment

Better gravity sensors only provide calibration benefits, not lower measurement time/point !!!

Solution: Gravity Gradiometry

- Suppression of Accelerations
- Reduced Tilt Sensitivity

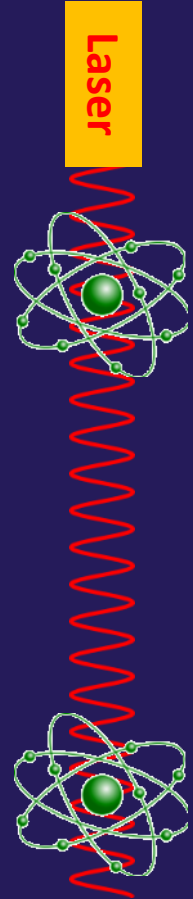


Requirement to achieve 1 ng/m

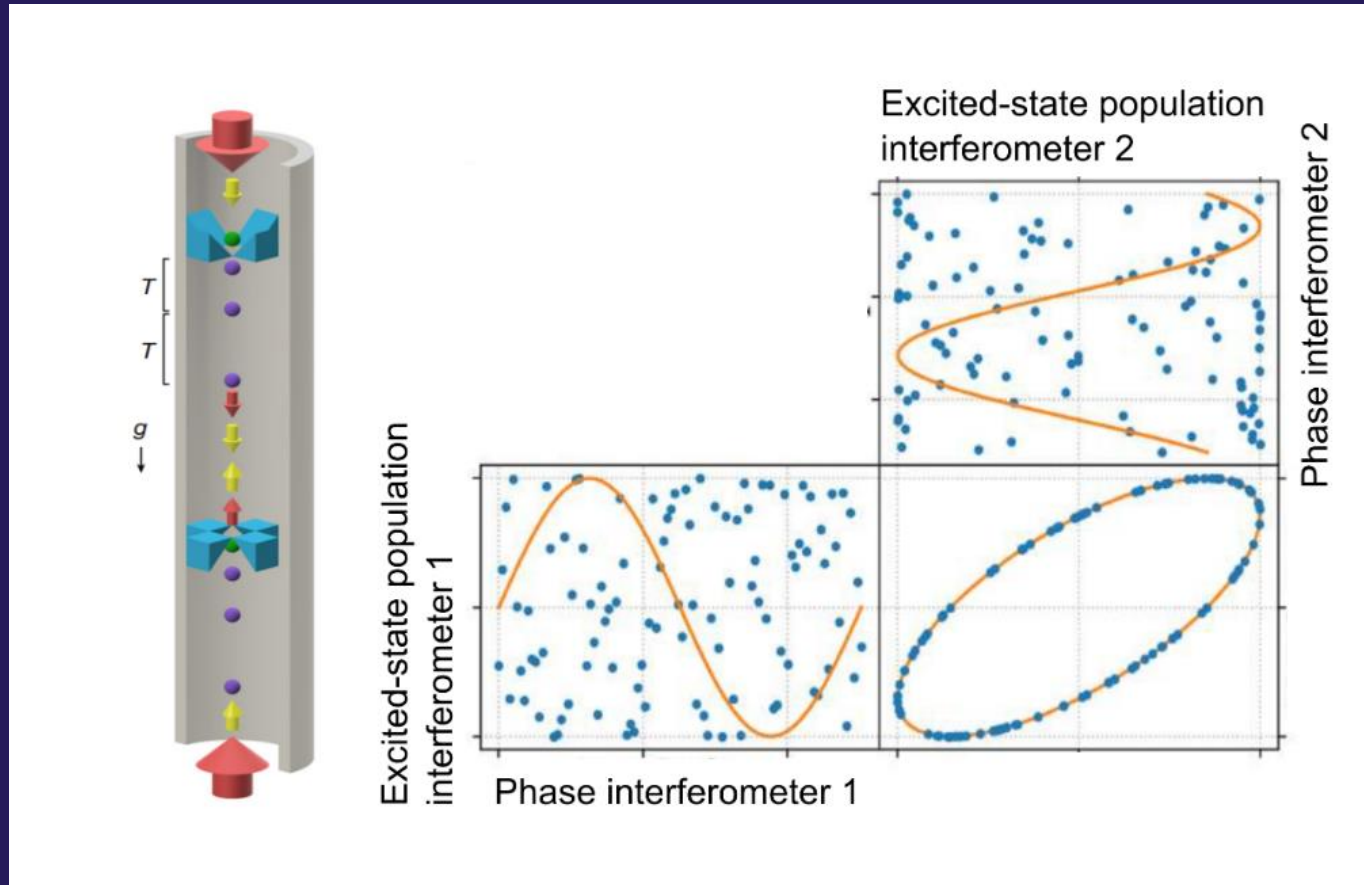
As fast as your instrument
→ 1 s / point

3° alignment

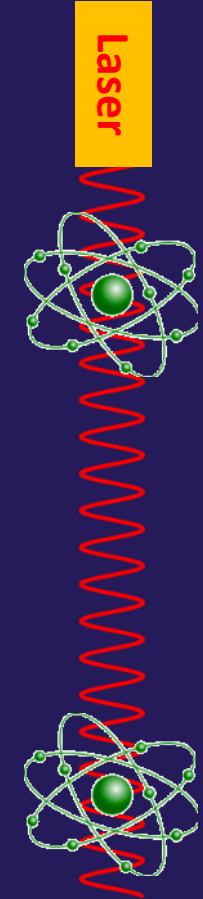
Common laser beam
Near-Perfect acceleration suppression and alignment in Atom Interferometry



Solution: Gravity Gradiometry



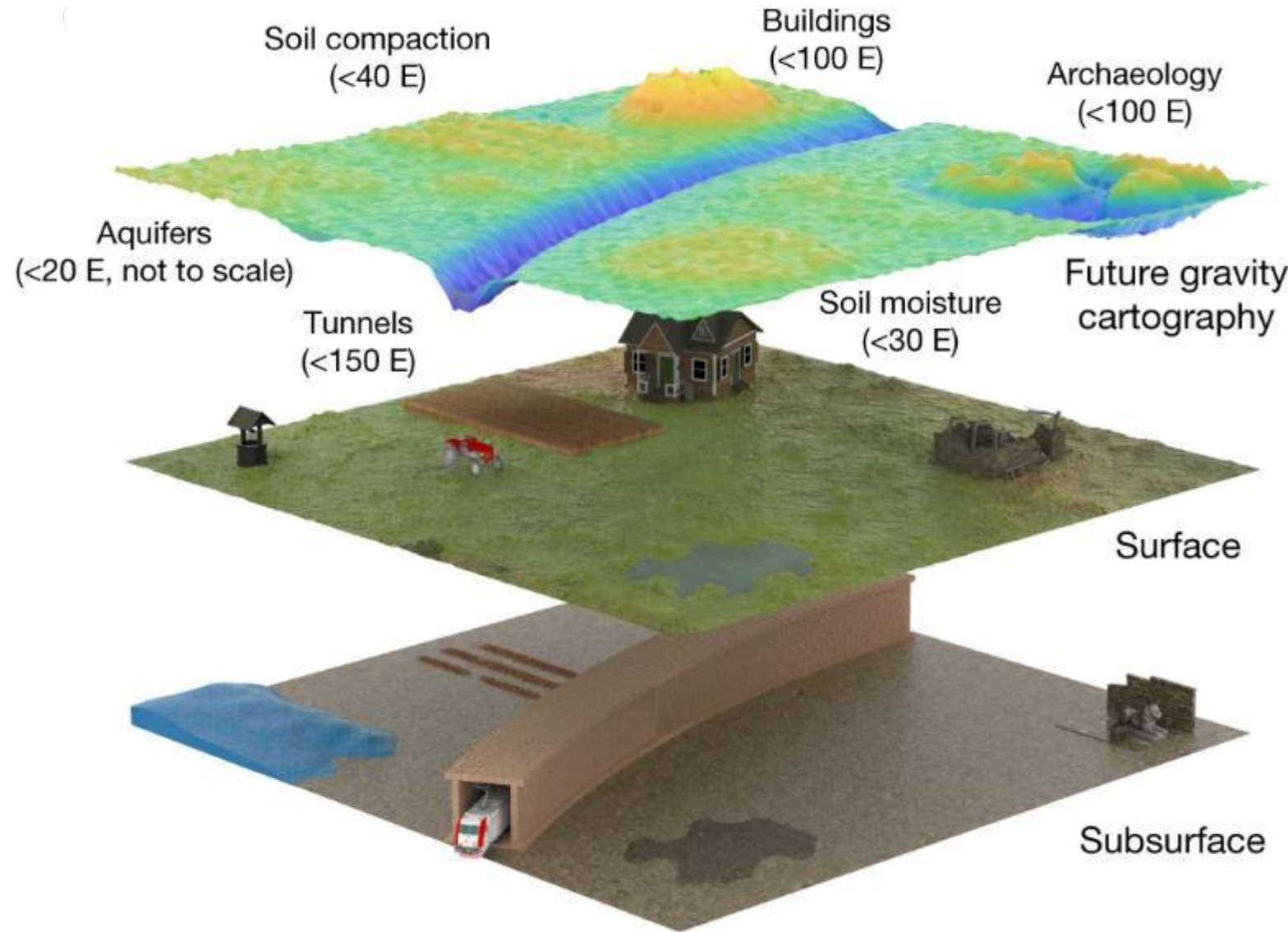
Common laser beam
↓
Near-Perfect acceleration suppression and alignment in Atom Interferometry



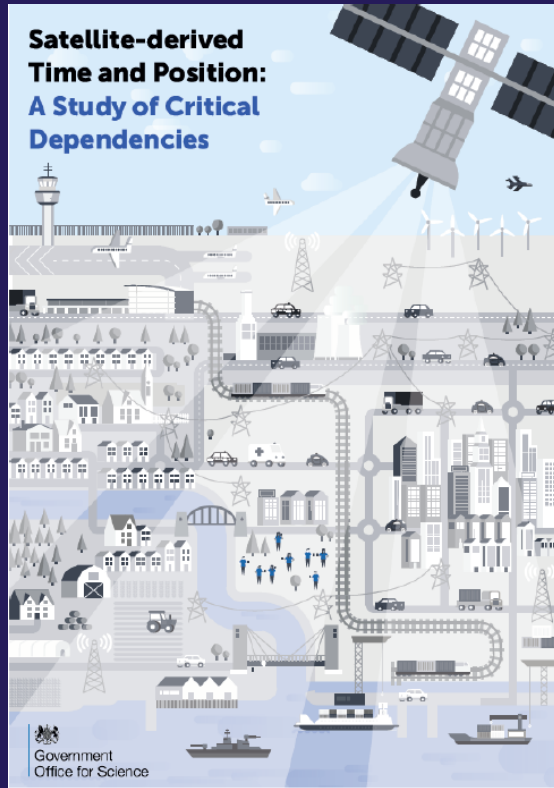
[Nature](#) volume 602, pages590–594 (2022)

Enabling Gravity Cartography

- Relevant to a range of applications, including:
 - Water monitoring
 - Infrastructure
 - Archaeology
 - Agriculture
 - Navigation



Gravity Sensors for Navigation



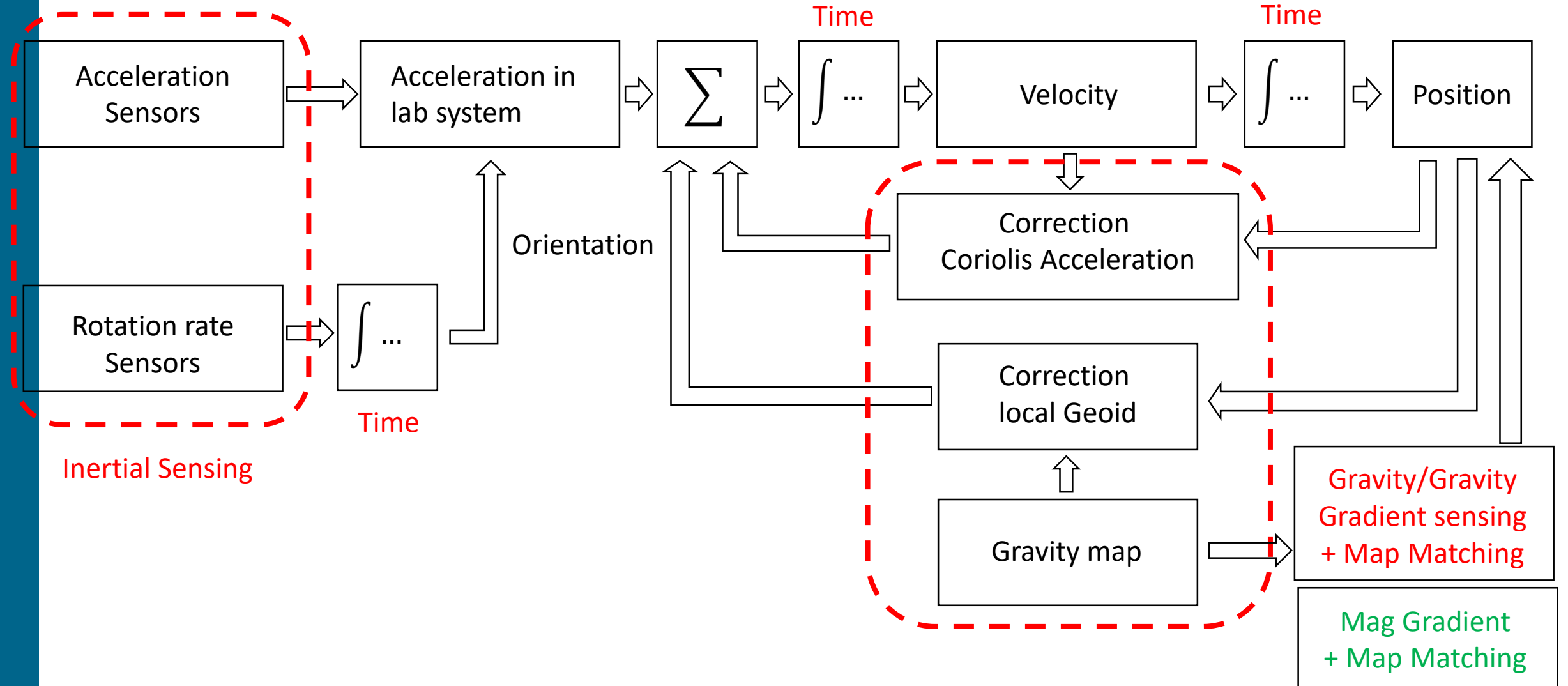
~7% GDP

Motivation: GNSS Vulnerabilities

- Reduced precision in cluttered spaces
- Does not work indoors, underwater, or underground
- Can be easily jammed or spoofed

Collaboration: physics, materials science, electrical engineering, industry

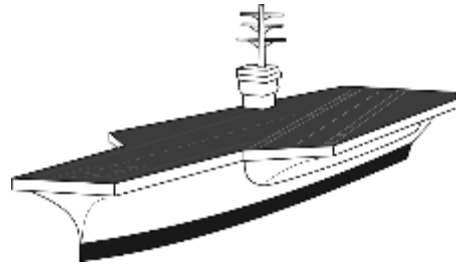
Schematic Setup of a Quantum Navigation System



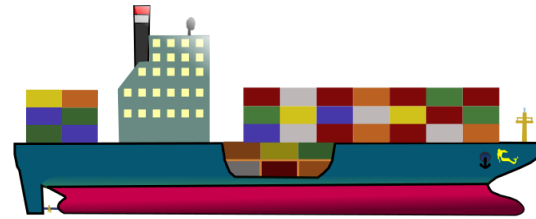
Market Roadmap for Quantum Navigation Systems



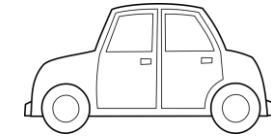
Cost and regulatory requirements as key drivers



Strategic platforms



Autonomous ships and underwater vehicles



Autonomous vehicles

2030

2040

2050

Unit cost

xM€

xxxk€

xxx€

Market volume

xxM€

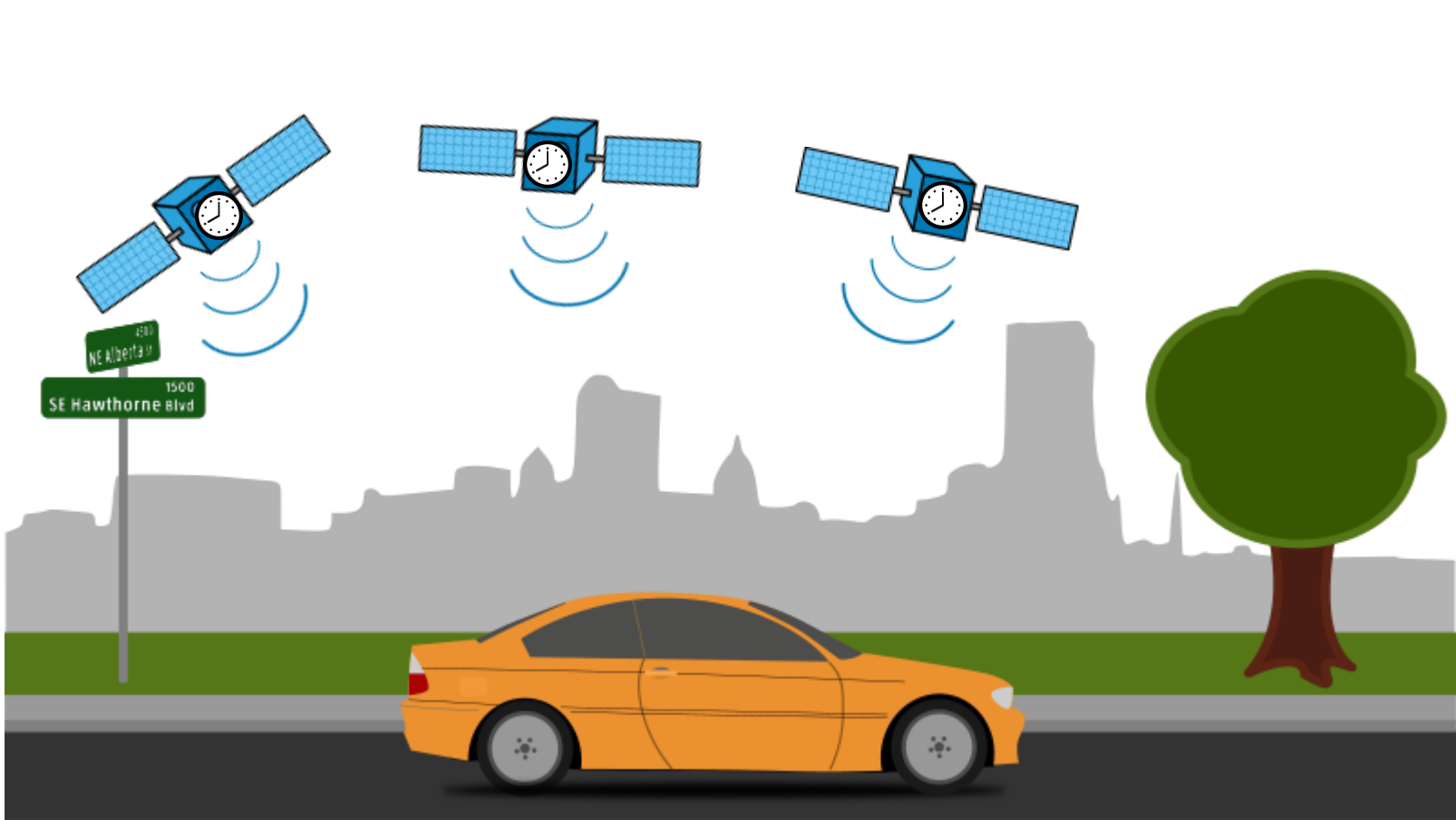
xxxM€

xxxxxM€

Quantum 2.0 for Navigation and Time



Quantum clocks are powering current global satellite navigation systems



Navigation

Impact: 5-10% of GDP



Synchronisation

GNSS critical dependencies

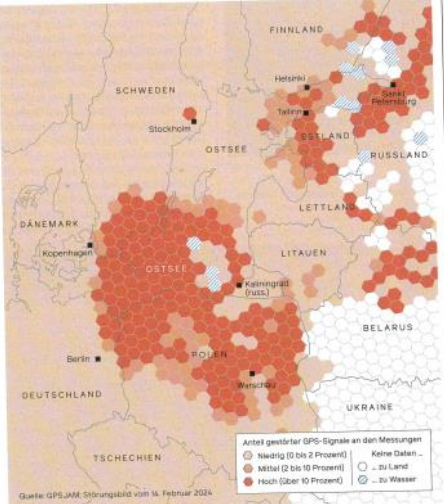
Need for independent alternatives

64 UNTERNEHMEN & TECHNOLOGIE
Satelliten

Wo bin ich?

Satellitensysteme wie GPS steuern Wirtschaft und Verkehr. Nun werden sie großflächig gestört – und der Westen arbeitet an einer Alternative

TEXT
Thomas Kuhn



Quelle: GPS-JAM Störungsbild vom 14. Februar 2024



FEDERAL REGISTER
The Daily Journal of the United States Government



PD Presidential Document

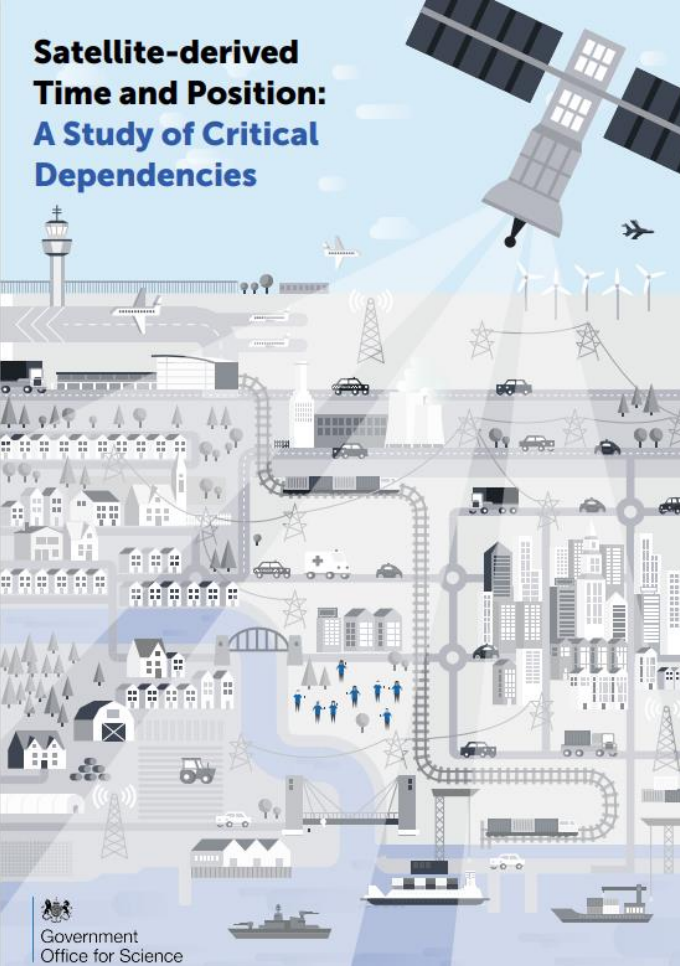
Strengthening National Resilience Through Responsible Use of Positioning, Navigation, and Timing Services

A Presidential Document by the Executive Office of the President on 02/18/2020

Wirtschaftswoche 10, 2024

UK Blackett Report 2018

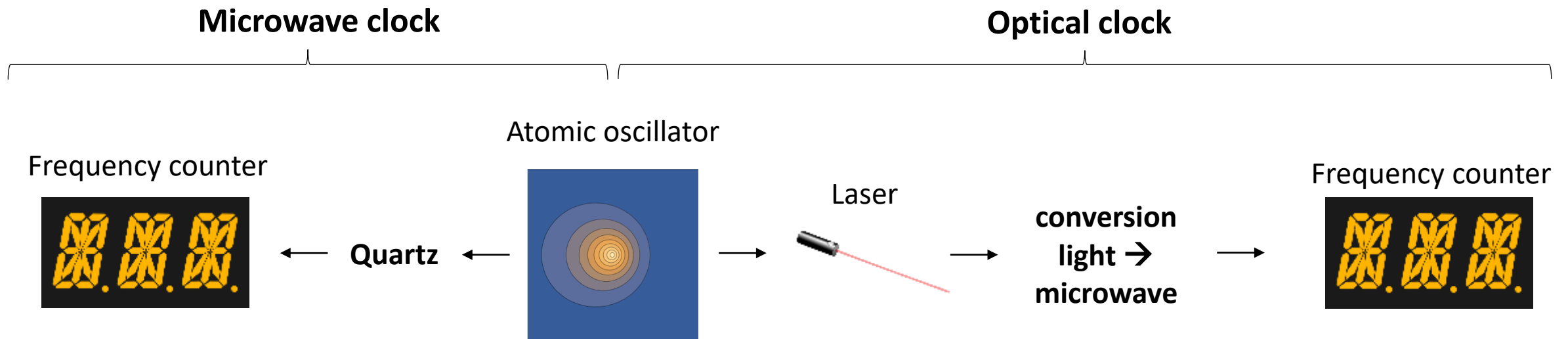
Satellite-derived Time and Position: A Study of Critical Dependencies



Government Office for Science

Microwave clocks (old) and optical clocks (new)

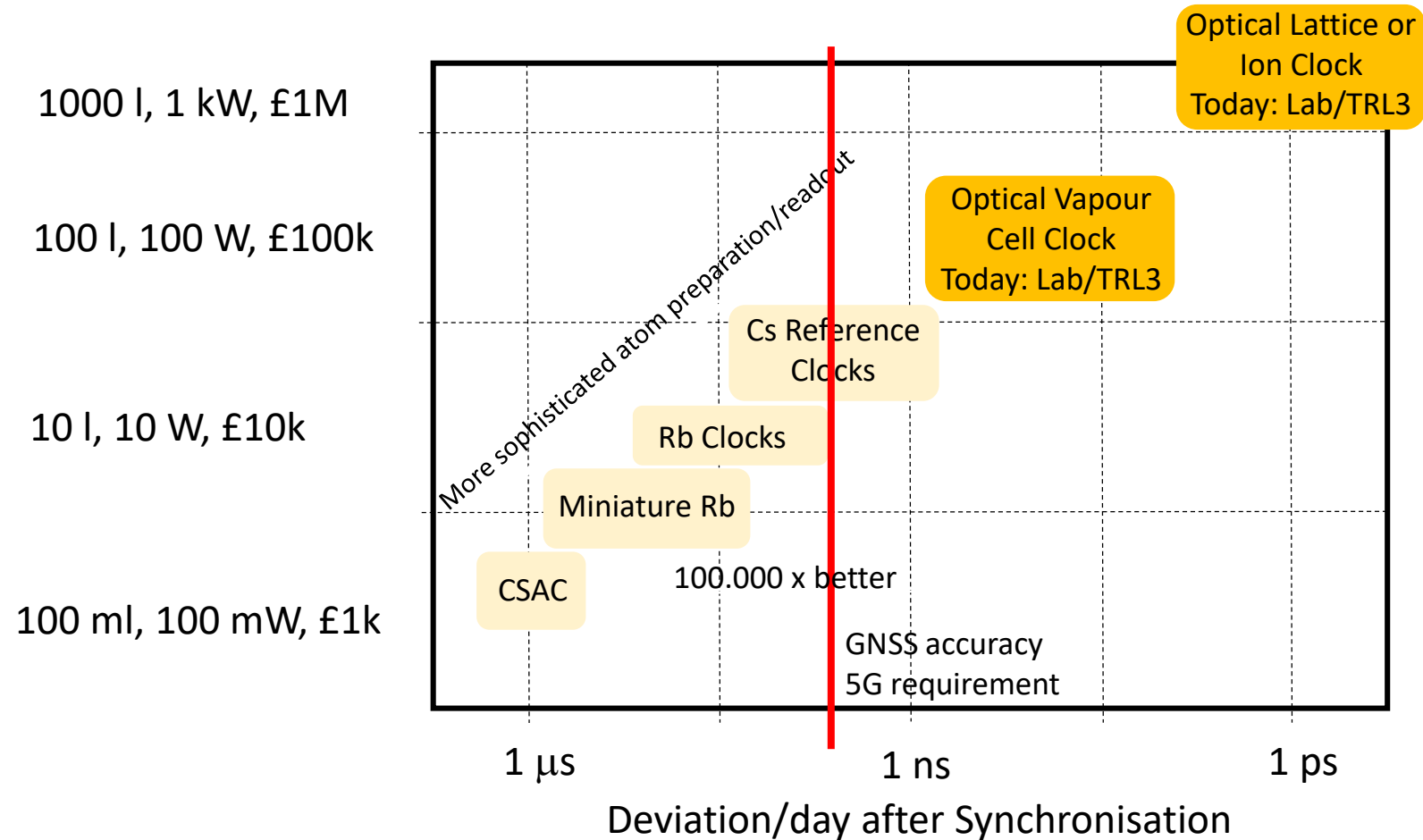
Optical clocks allow higher precision and faster synchronization



Disruptive: 100x better synchronisation as compared to GNSS
Lower phase noise than Quartz-oscillators

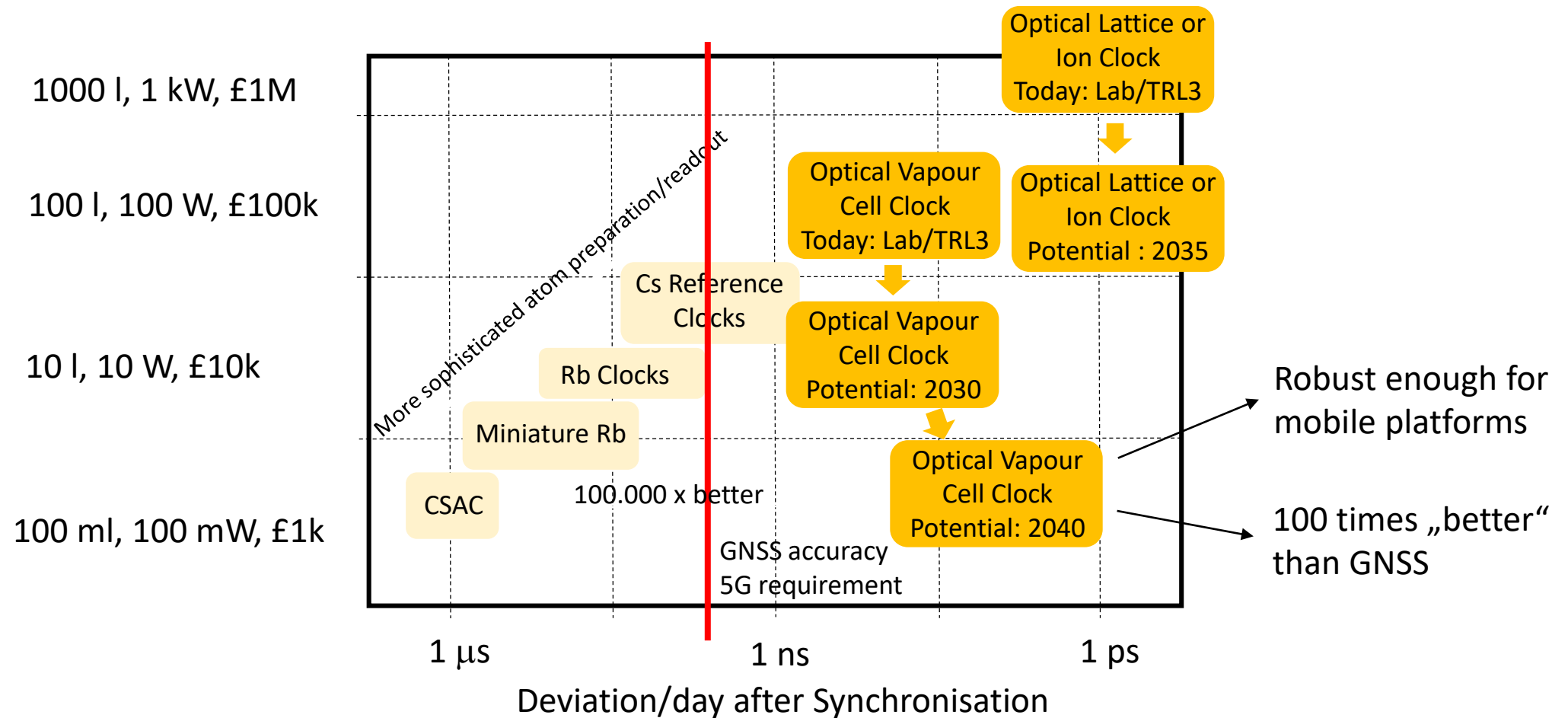
Why are Optical Clocks Disruptive?

So far: "linear" relationship between SWAP-C and stability



Why are Optical Clocks Disruptive?

So far: "linear" relationship between SWAP-C and stability



DLR-QT Optical Clock Technology

Iodine optical vapour cell clock

GPS Solutions (2021) 25:83
<https://doi.org/10.1007/s10291-021-01113-2>

Table 1 Summary of the key figures of the different optical clock technologies, together with the corresponding figures of the Galileo RAFS and PHM

References	Galileo RAFS Oroliia datasheet (2016)	Galileo PHM Leonardo data- sheet (2017)	Ca beam Shang et al. (2017)	I ₂ MTS Schuldt et al. (2017); Döring- shoff et al. (2019)	Rb MTS Zhang et al. (2017)	Rb TPT Martin et al. (2018)	Sr Lattice clock Bongs et al. (2015); Origlia et al. (2018)	Ca single ion clock (Delehay and Lac- route 2018; Cao et al. 2017)
Frequency stability (in RAV @ integration time τ)								
1 s	3×10^{-12}	2×10^{-12}	5×10^{-14}	6×10^{-15}	1×10^{-14a}	4×10^{-13}	n/s	n/s
10 s	1×10^{-12}	3×10^{-13}	2×10^{-14}	3×10^{-15}	4×10^{-15a}	1×10^{-13}	1×10^{-16}	6×10^{-15}
10^2 s	3×10^{-13}	7×10^{-14}	5×10^{-15}	2×10^{-15}	3×10^{-15a}	4×10^{-14}	4×10^{-17}	2×10^{-15}
10^3 s	6×10^{-14}	2×10^{-14}	2×10^{-15}	2×10^{-15}	n/s	1×10^{-14}	1×10^{-17}	6×10^{-16}
10^4 s	3×10^{-14}	7×10^{-15}	n/s	3×10^{-15}	n/s	5×10^{-15}	4×10^{-18}	2×10^{-16}
10^5 s	Long-term drift $< 10^{-10}$ / year	Long-term drift $< 10^{-15}$ / day	n/s	$< 2 \times 10^{-14}$	n/s	n/s	n/s	n/s
10^6 s			n/s	n/s	n/s	n/s	n/s	n/s
Longest reported (continuous) τ (s)			1600	700,000	600	180,000	30,000	30,000
Clock transition frequency/wavelength	6.8 GHz	1.4 GHz	657 nm	532 nm	420 nm	778 nm	698 nm	729 nm
Clock transition natural linewidth			0.4 kHz	300 kHz	1450 kHz	330 kHz	6 mHz	140 mHz
SWaP Budgets ^{b,c}								
Mass (kg)	3.4	18.2	n/s	$21 + 10^b$	$10^d + 10^b$	$12^e + 10^b$	< 250	n/s
Power (W)	35	60^f	n/s	$44 + 66^b$	$20^d + 66^b$	$25^e + 66^b$	n/s	n/s
Volume (l)	3.2	26.3	$300 + 7^b$	$33 + 7^b$	n/s	$8^e + 7^b$	< 1000	540
Complexity								
# Lasers	n/a	n/a	2	1	1	1	5	6
Vacuum chamber			Yes	No	No	No	Yes	Yes
Cavity pre-stabilization	n/a	n/a	Yes	No	No	No	Yes	Yes
TRL	9	9	4	4-5 ^g	4	4	4	4

Commercial Opportunities through Quantum Clocks



Credit: ENISA

Communication



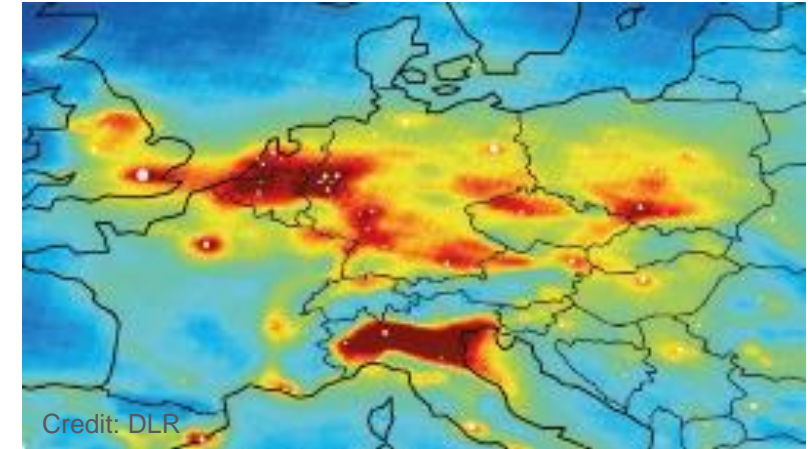
Credit: DLR

3D Radar



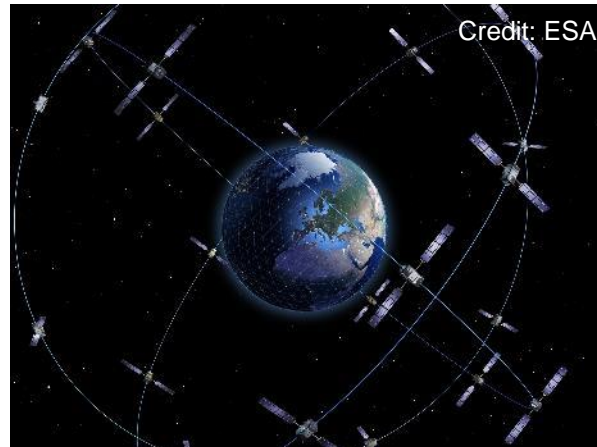
Credit: DLR

Urban Flight



Credit: DLR

Global Height Reference



Credit: ESA

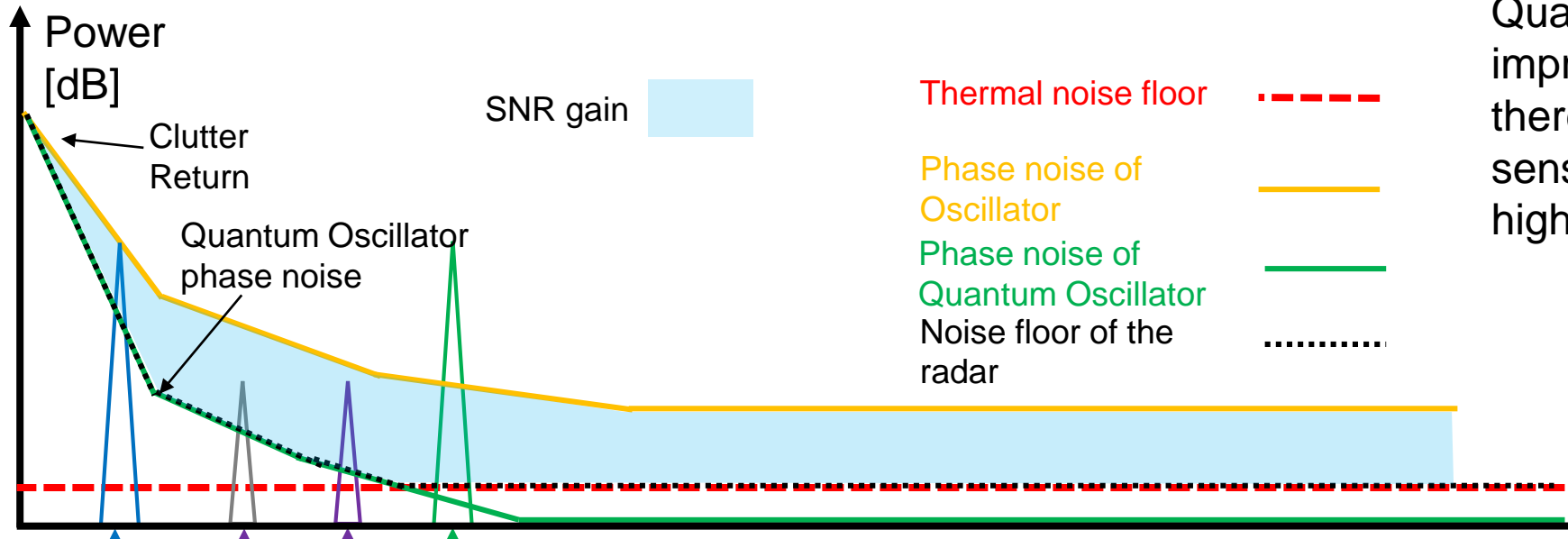
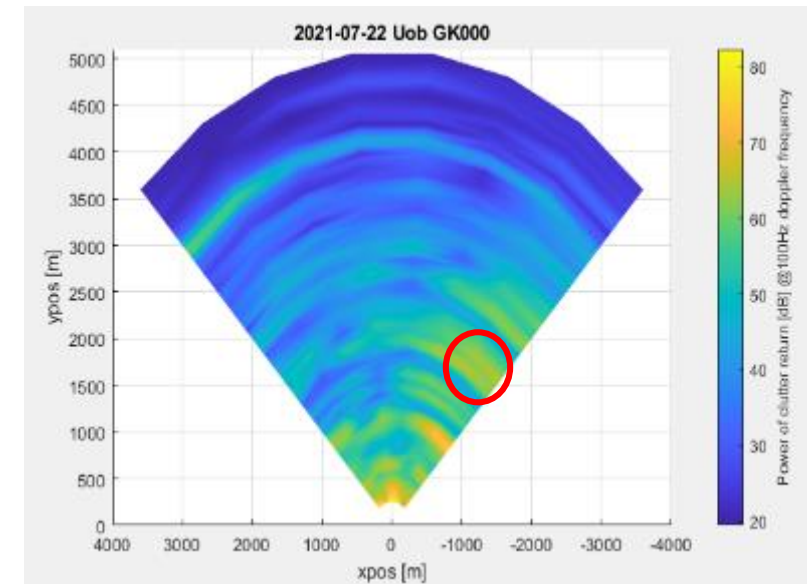
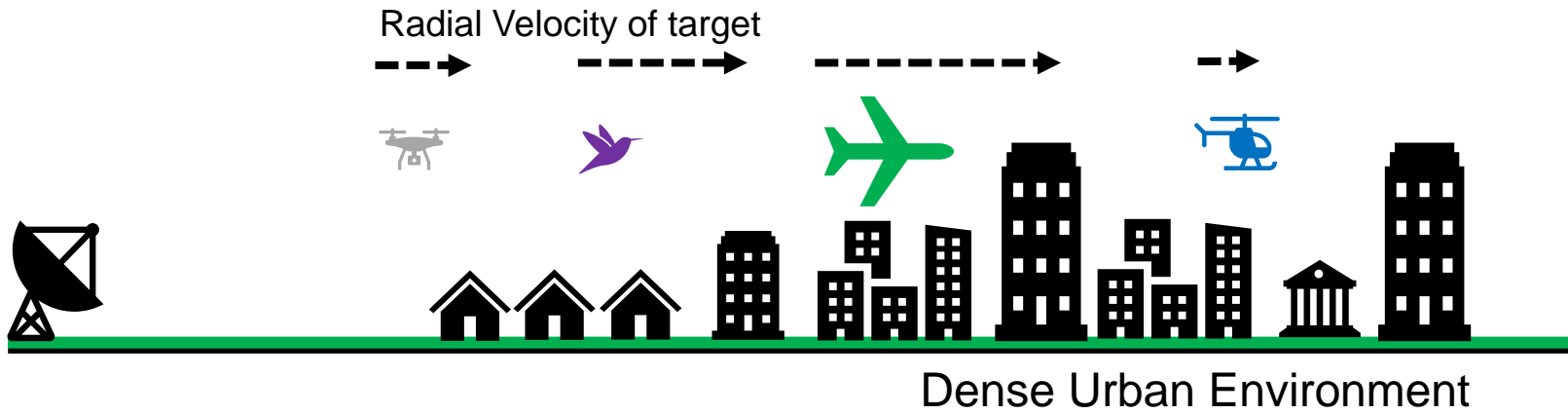
Satellite Navigation



Credit: DLR

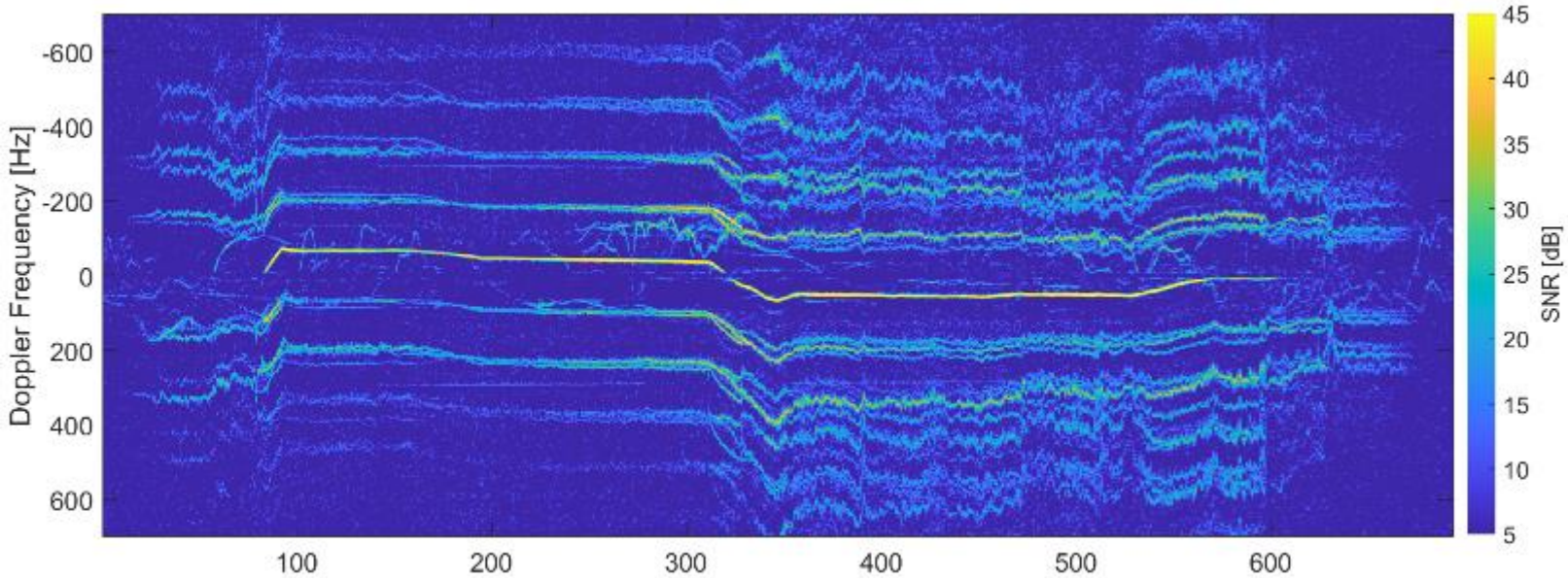
Autonomous Vehicles

Noise limitations in radar

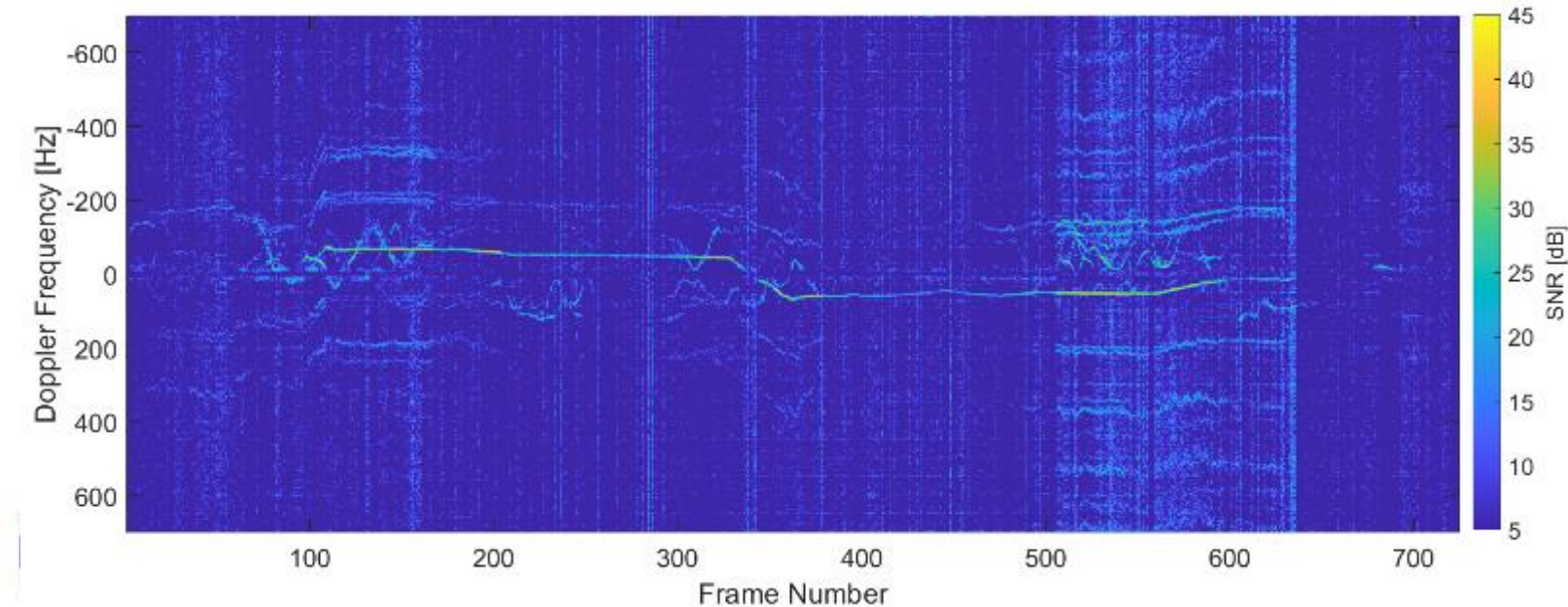


Quantum oscillators provide improved phase noise and therefore improve the sensitivity of the radar in high clutter regions

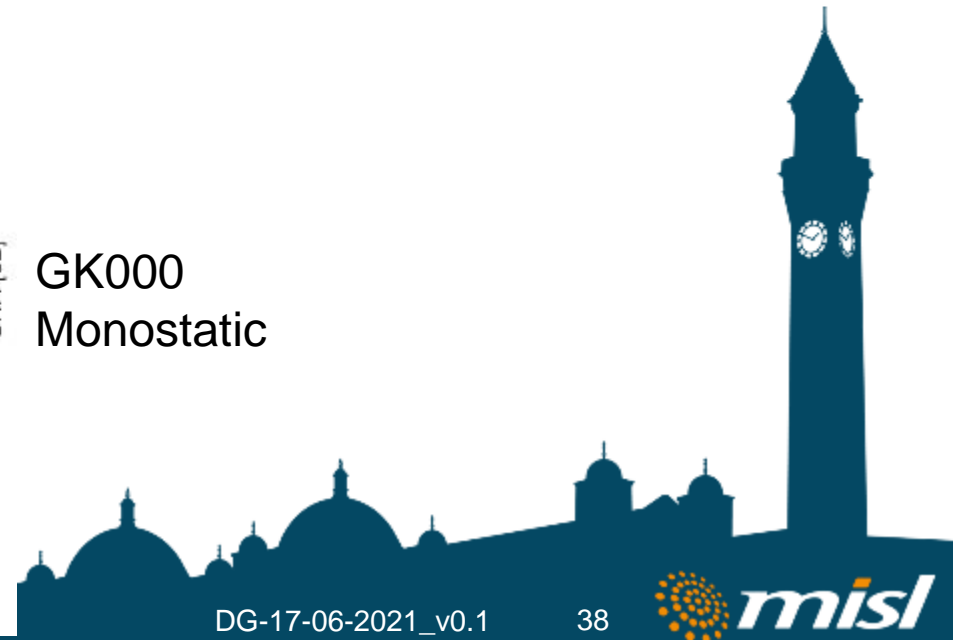
Better oscillator: more features



GK007
Monostatic
(Better oscillator)

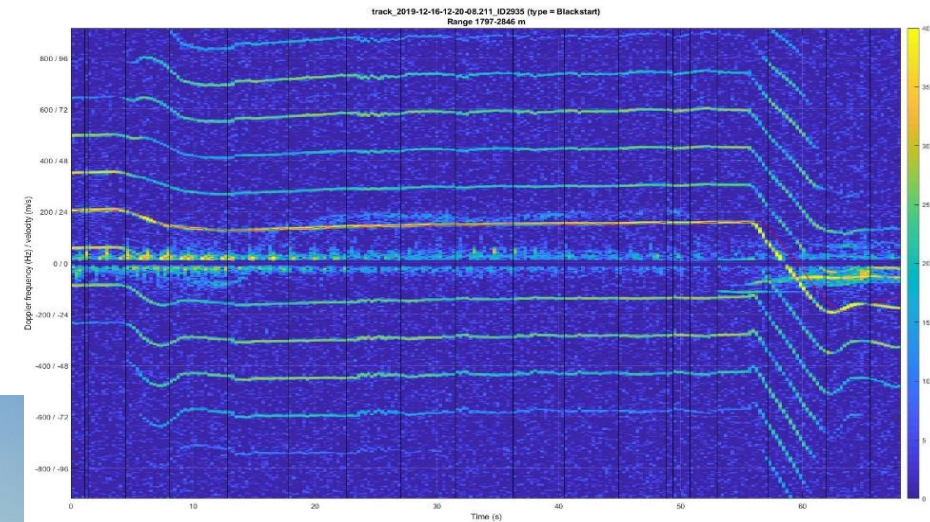
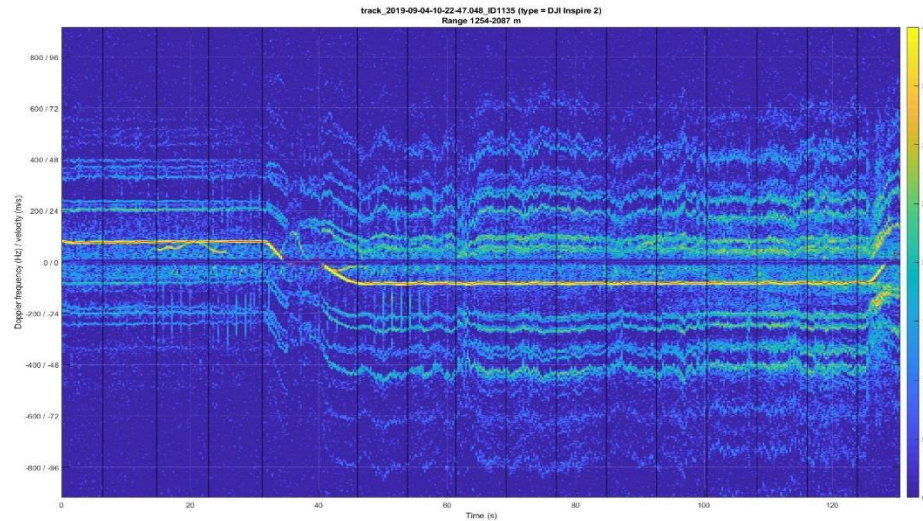


GK000
Monostatic



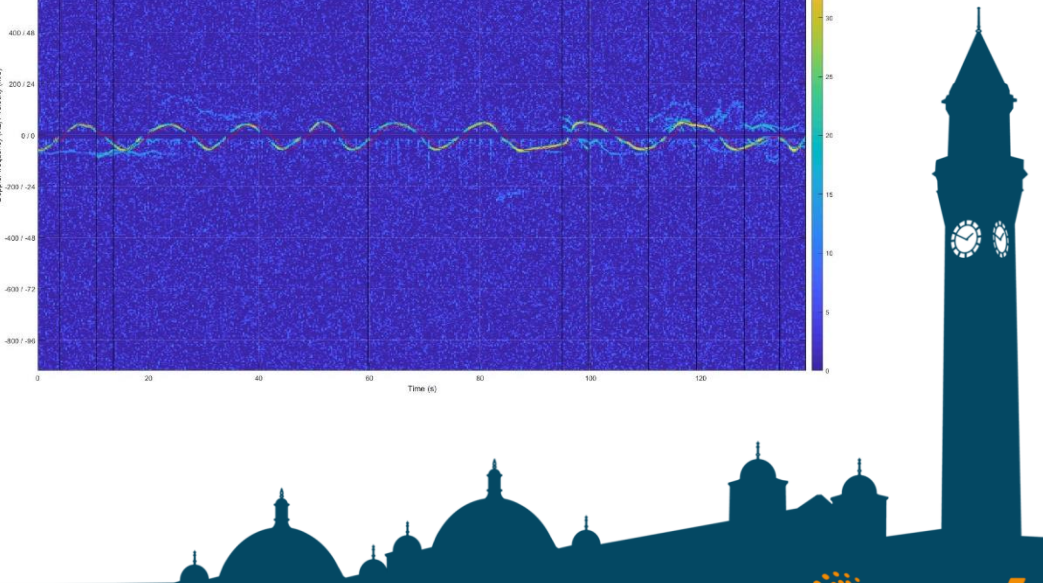
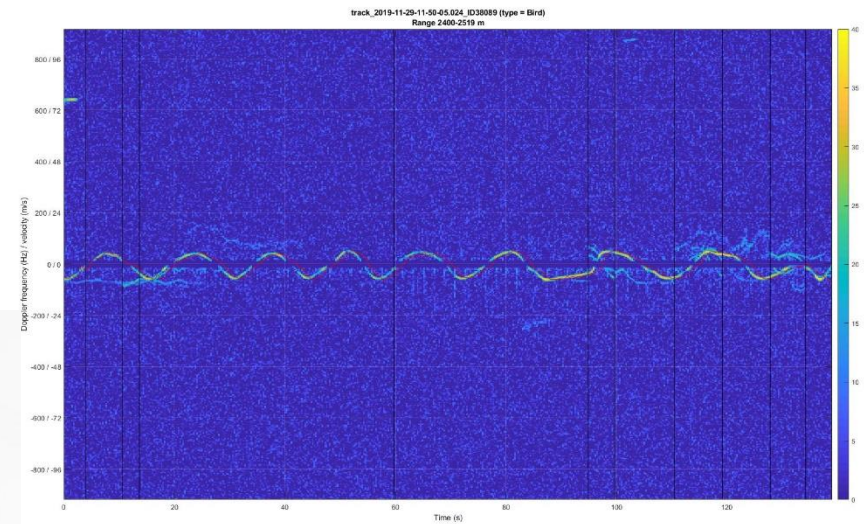
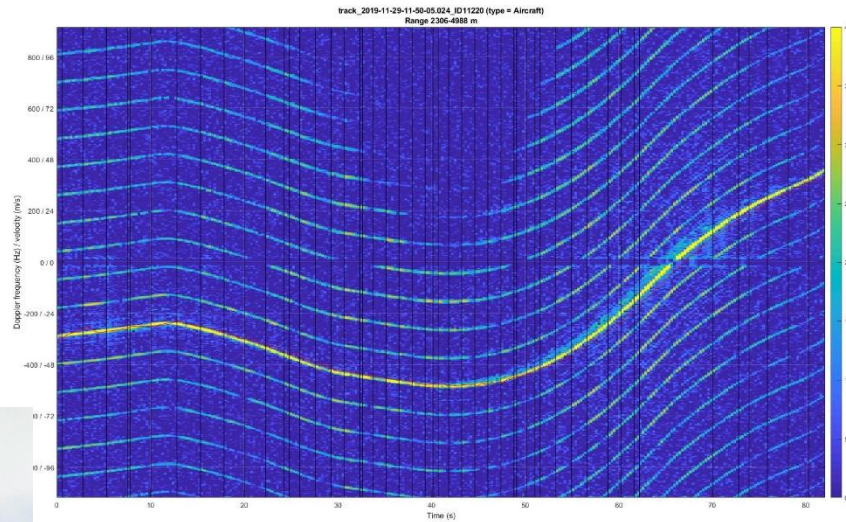
Discrimination via Micro-Doppler

Rotary wing vs Fixed Wing



Discrimination via Micro-Doppler

Opportune targets – Light aircraft vs large bird



Radar Improvement with better Oscillator – Drone Tracking

Small Drone Tracked by two radar

Side-by-side comparison: Tracker output



Radar#1
Purple lines



DJI Mini Mavic 2



Radar#2
Yellow Line - Better Phase Noise

Thank you for your attention



Questions?

