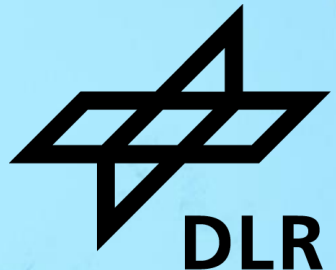


IMPROVING L1 PRODUCT QUALITY FOR IMAGING SPECTROMETERS WITH RESPONSE FUNCTION-BASED POST-PROCESSING

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German Aerospace Center (DLR)



DLR User Service OpAiRS



- Team at DLR Earth Observation Center (EOC) Oberpfaffenhofen
- Operates and calibrates airborne and ground based earth observation spectrometers
- ISO 9001 certified entity since 2007
- Builds upon more than 30 years of expertise



Calibration Home Base (CHB)



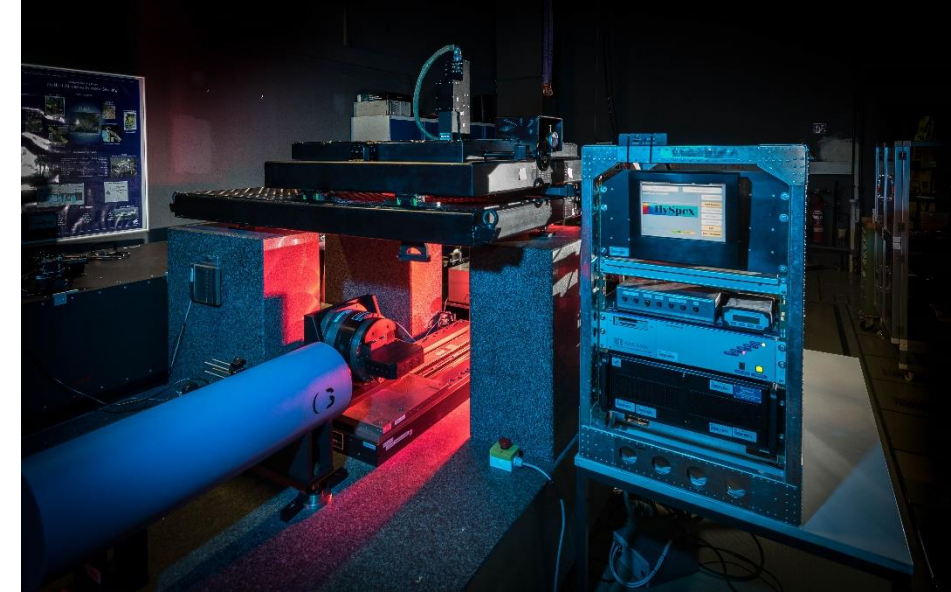
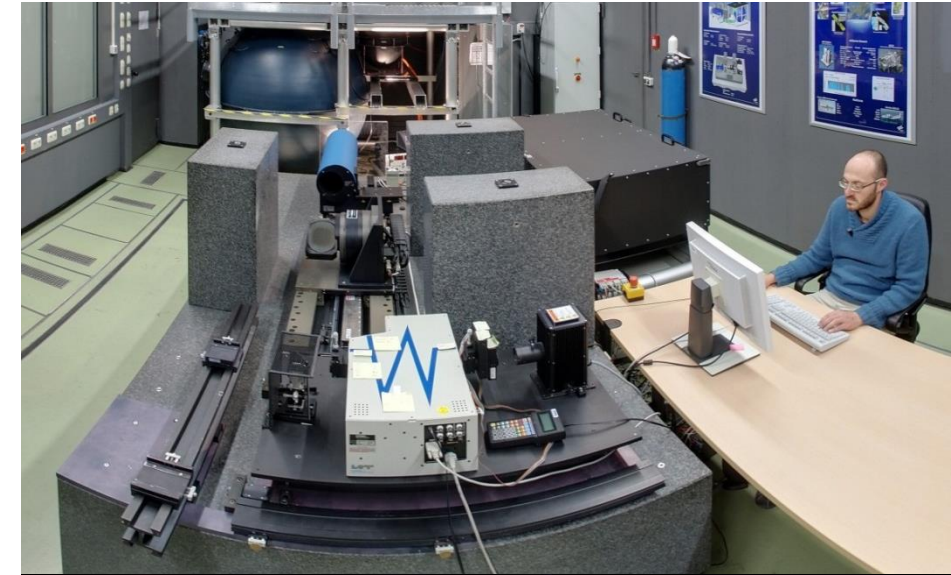
Operational Setups

- Geometric Response Function
- Spectral Response Function
- Radiometric Response & Polarization

Co-funded by ESA for APEX calibration

Research & Development

- Non-linearity correction
- Straylight correction
- Temperature dependence



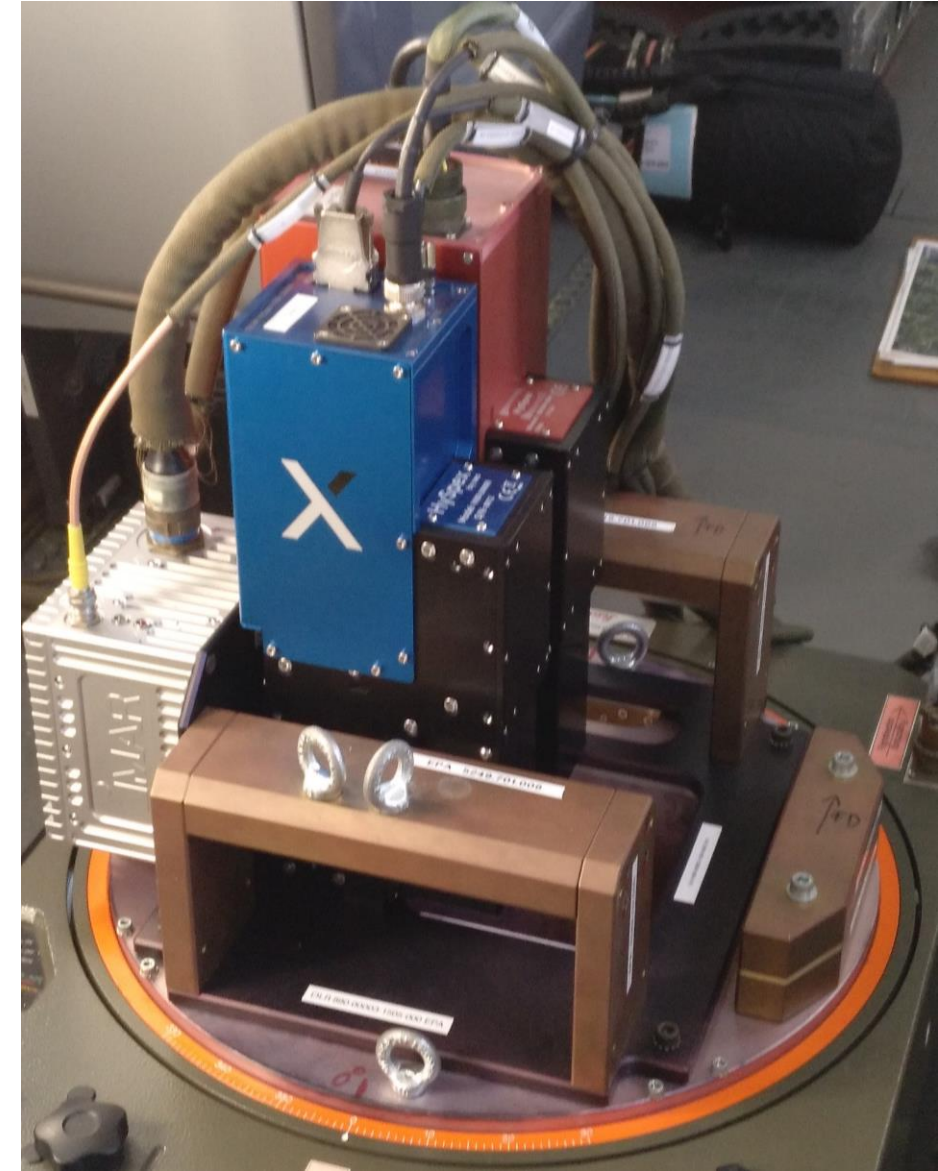
Airborne Sensor Systems

HySpex-B

- HySpex VNIR-3400N + SWIR-384
- $N \rightarrow$ **Nyquist (sampled)**
- Operational since 2023
- Typical *hyperspectral* sensor

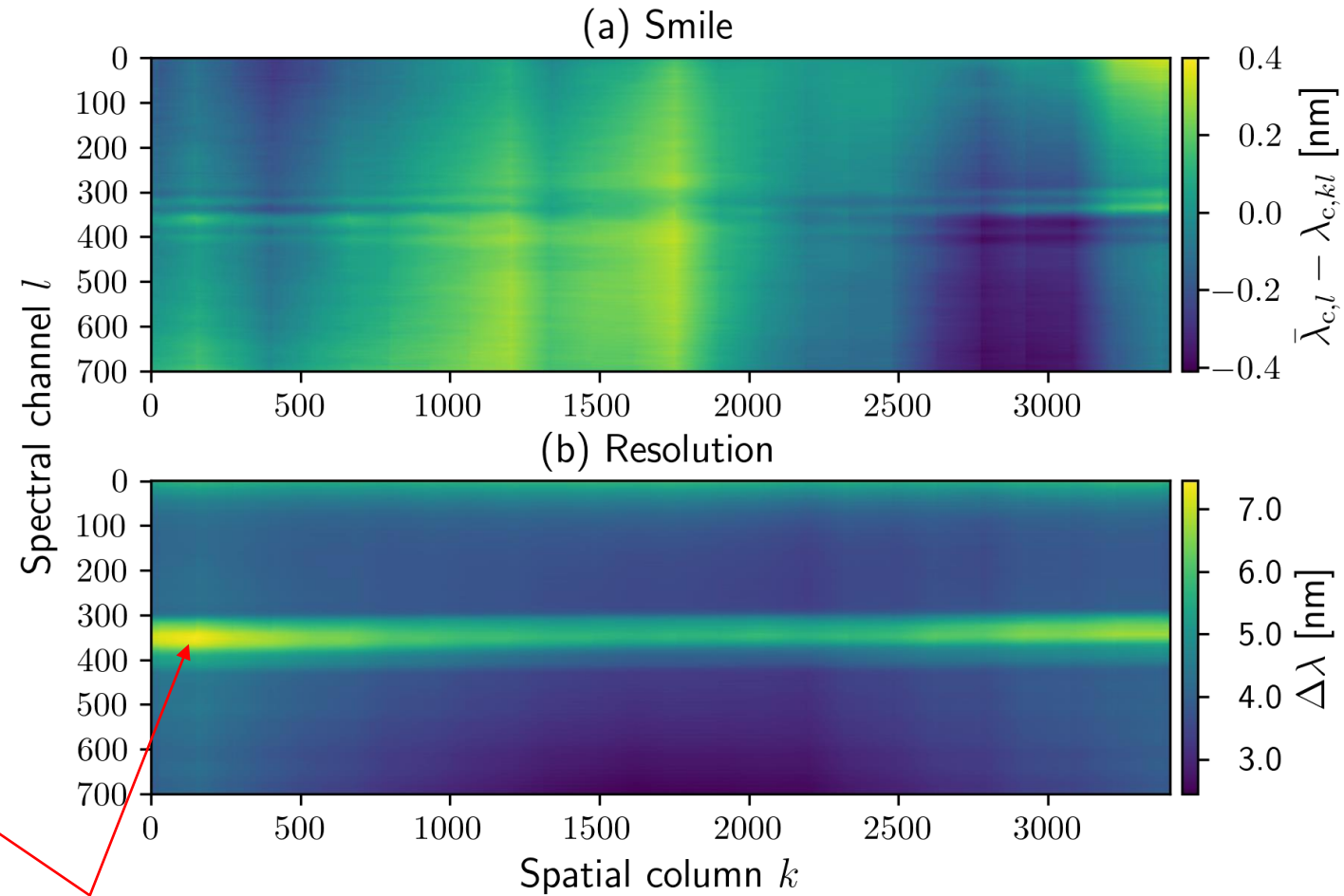
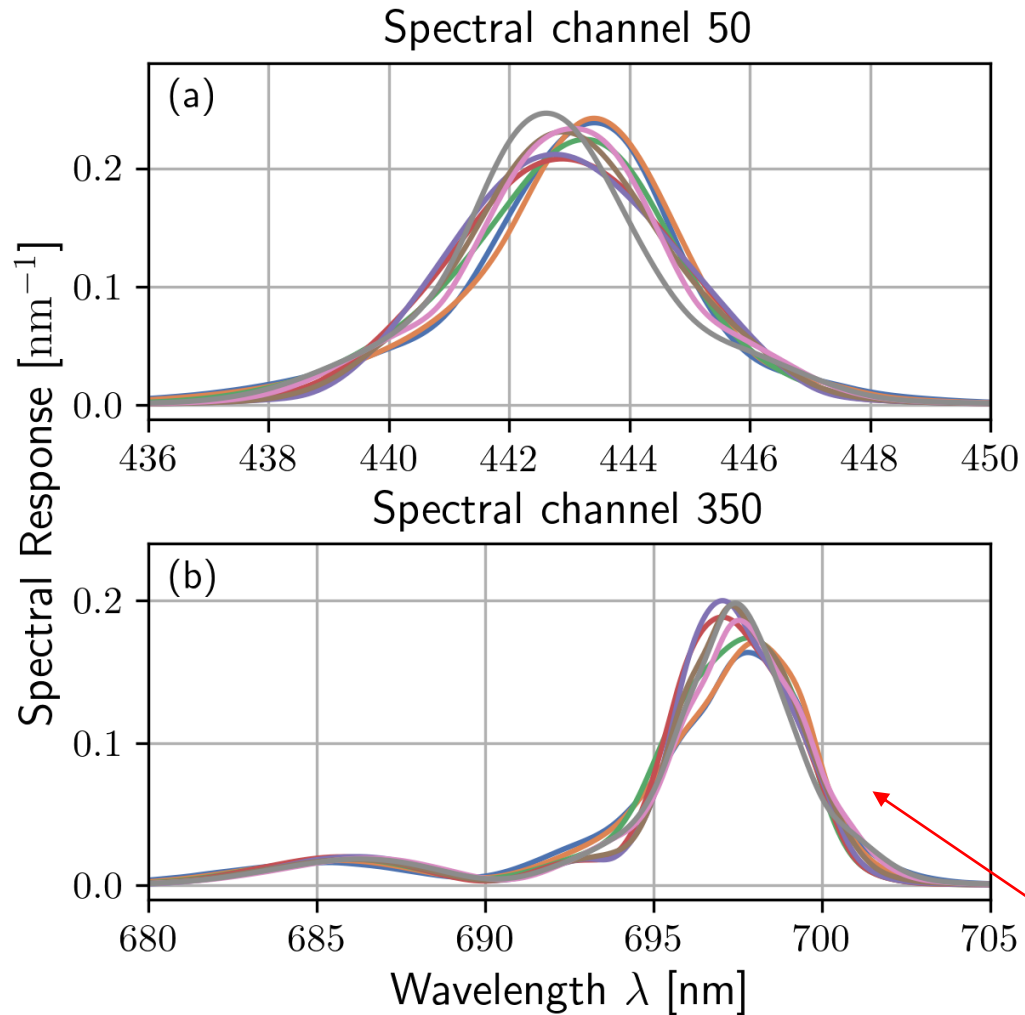
HySpex (EnMAP demonstrator)

- HySpex VNIR-1600 + SWIR-320me
- Acquired for EnMAP preparation in 2011
- Extensively calibrated



Exemplary Results for VNIR-3400N

Similar information is available since 2013 for the original HySpex System



spectral order filter

We were quite optimistic in 2013 ...



- State-of-the-art sensor system
- Extensive knowledge about key calibration data
- Expected to see significant improvements in surface reflectance and derived EO products
- This hope never materialized

What was going on!?

What we learned



- Atmospheric Correction assumes Gaussian SRFs (free-form not supported)
- FWHM and shape are assumed to be constant within one band. Center wavelengths (smile/keystone) are allowed to change, though.
- VNIR and SWIR spectra are interpolated to common spatial grid before Atmospheric Correction (to enable combined VNIR/SWIR treatment)

A lot of measurements did not find their way into derived products!

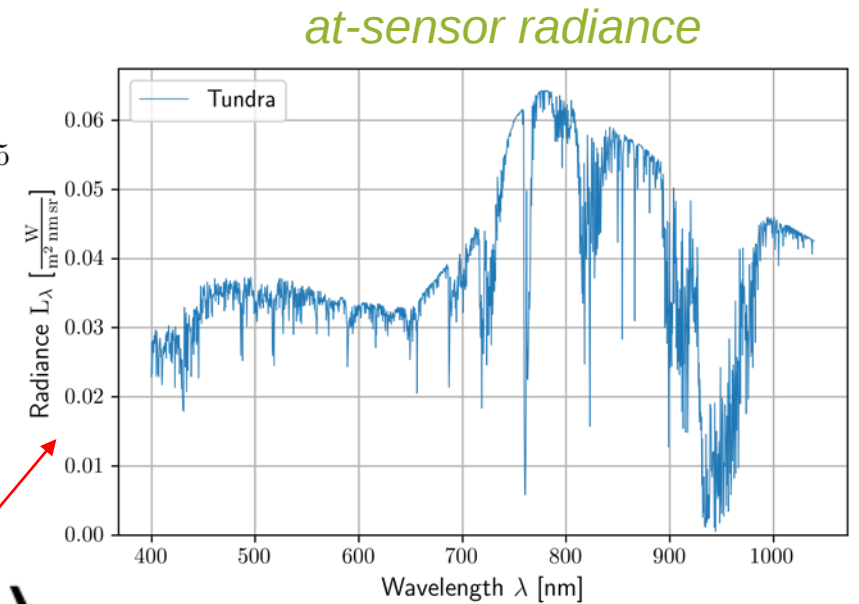
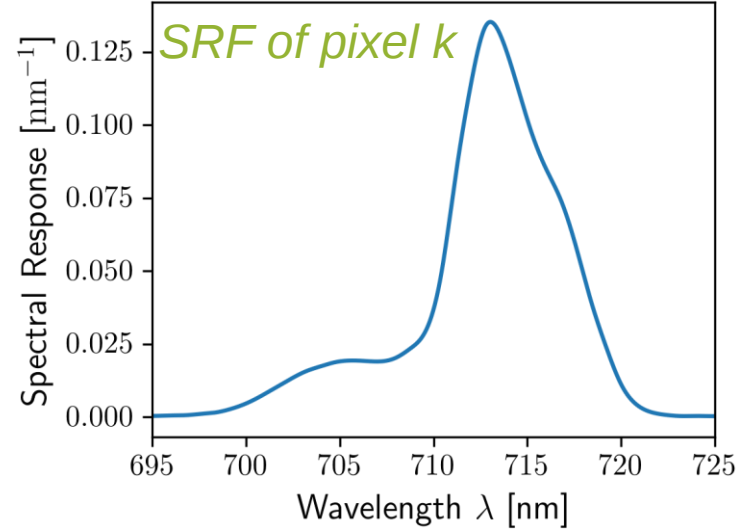
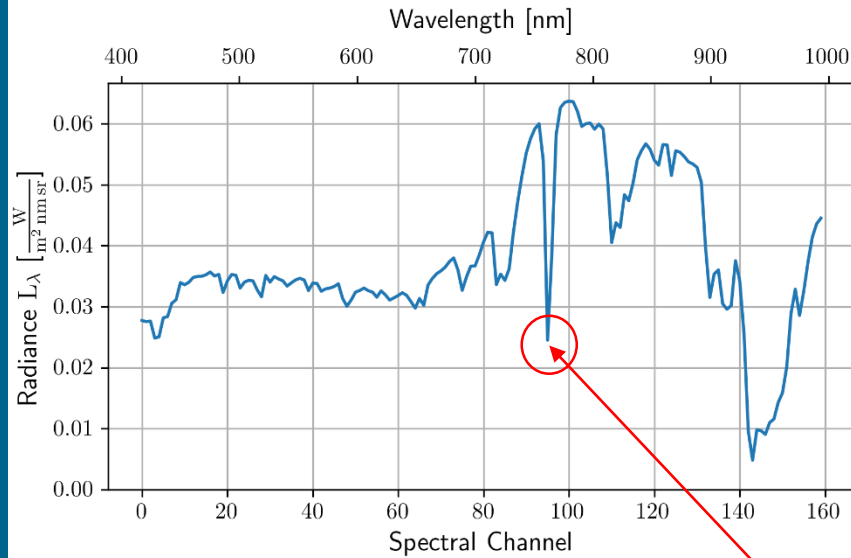
Question

Is it possible to create a L1C product, which ...

- ...enables users to profit from **all** our calibration measurements (e.g. full SRF instead of just center wavelength & FWHM)
- ...fosters incorporation of high-quality sensor characterization into higher level products
- ...simplifies working with L1 data for non-experts by reducing complexity



Physical Model

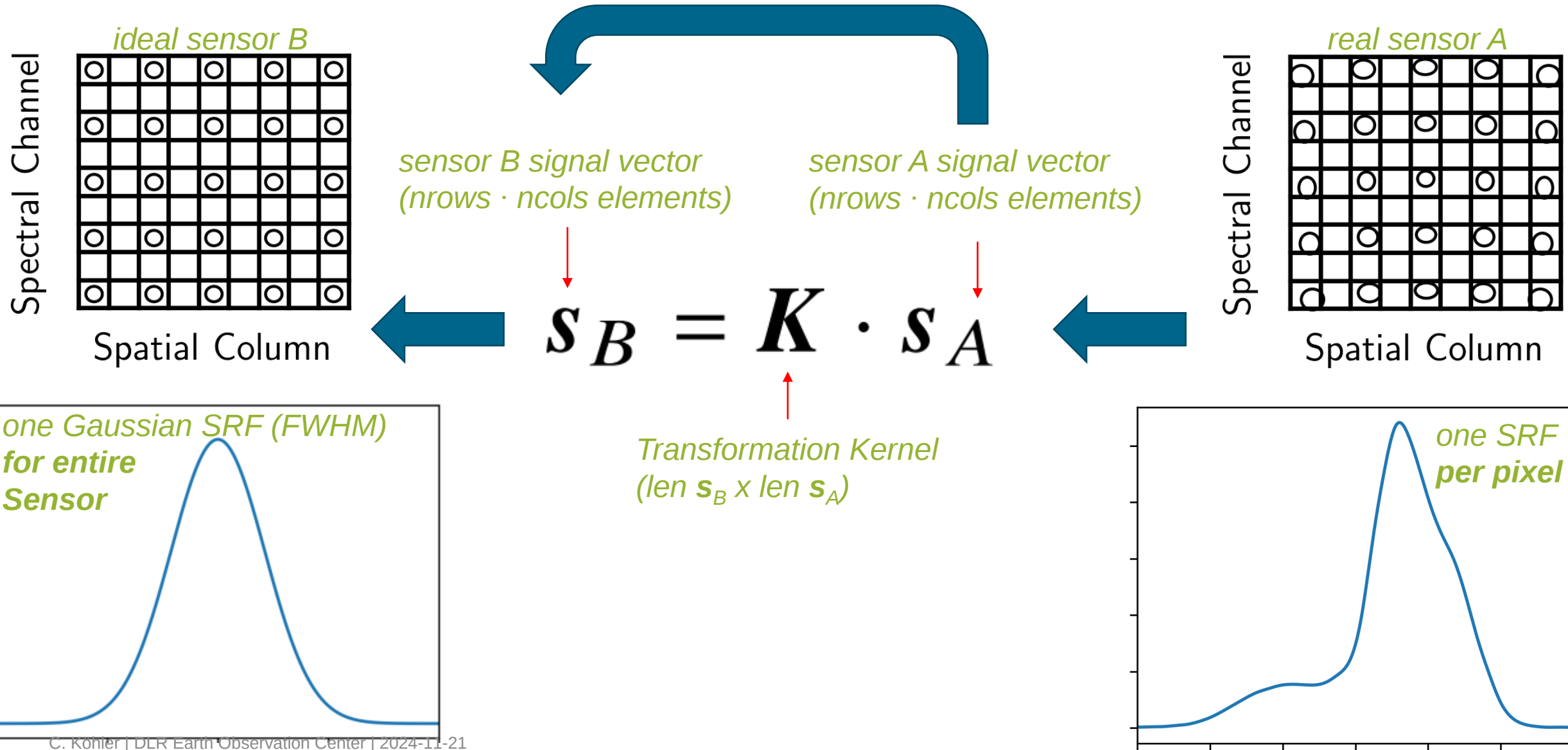


$$s_k = \langle f_k, L_s \rangle$$

*signal measured by pixel k
(a number)*

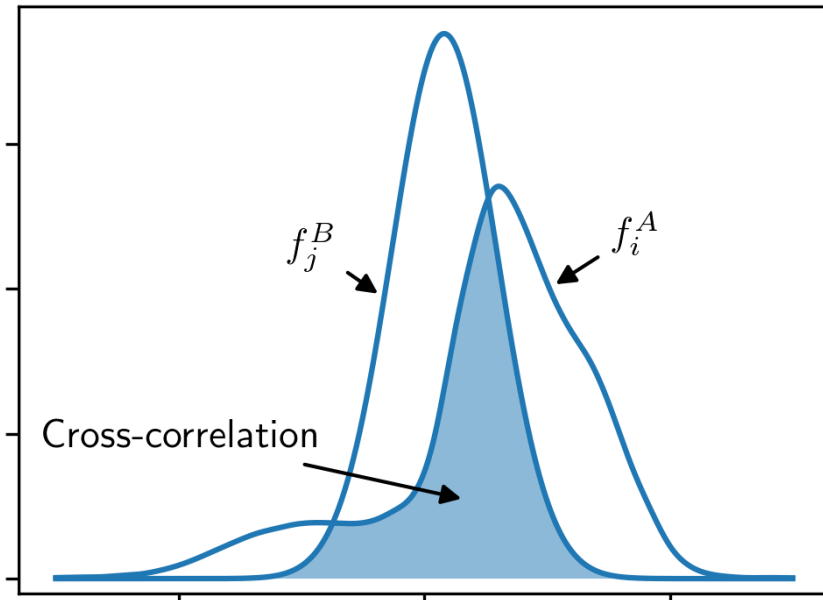
scalar product (integral)

Idea



The Convolution Kernel

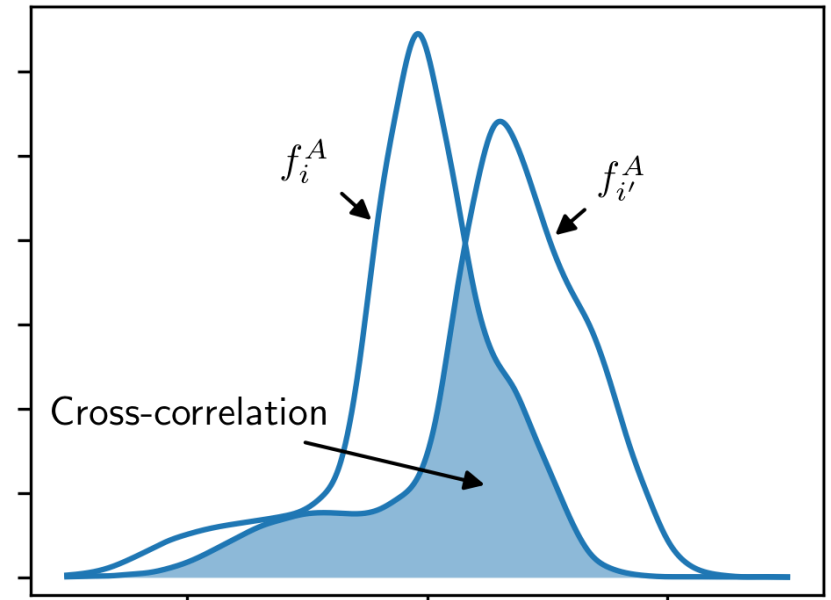
$$\mathbf{C}_{ij}^{BA} := \langle f_i^B, f_j^A \rangle$$



$$\mathbf{C}^{BA} = \mathbf{K} \mathbf{C}^{AA}$$

*Kernel can be computed from
Cross-correlation matrices*

$$\mathbf{C}_{ij}^{AA} := \langle f_i^A, f_j^A \rangle$$



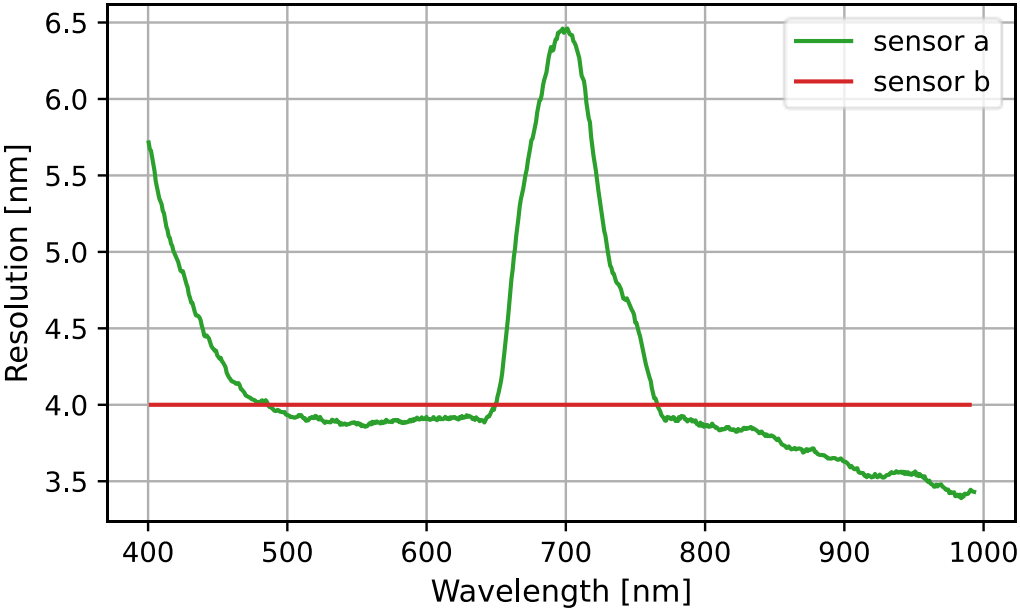
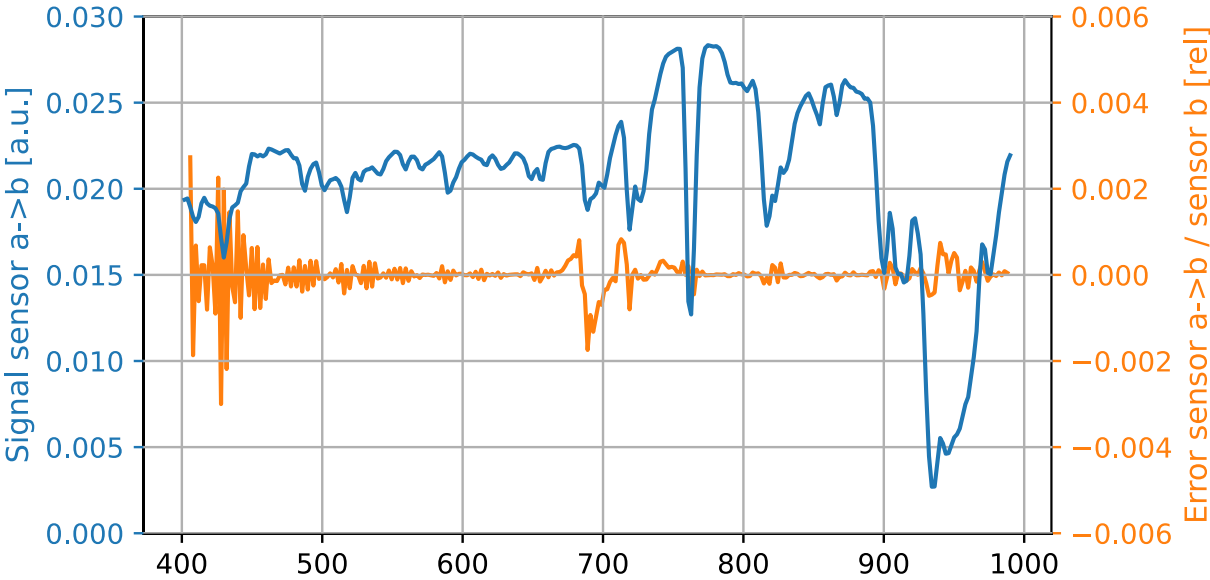
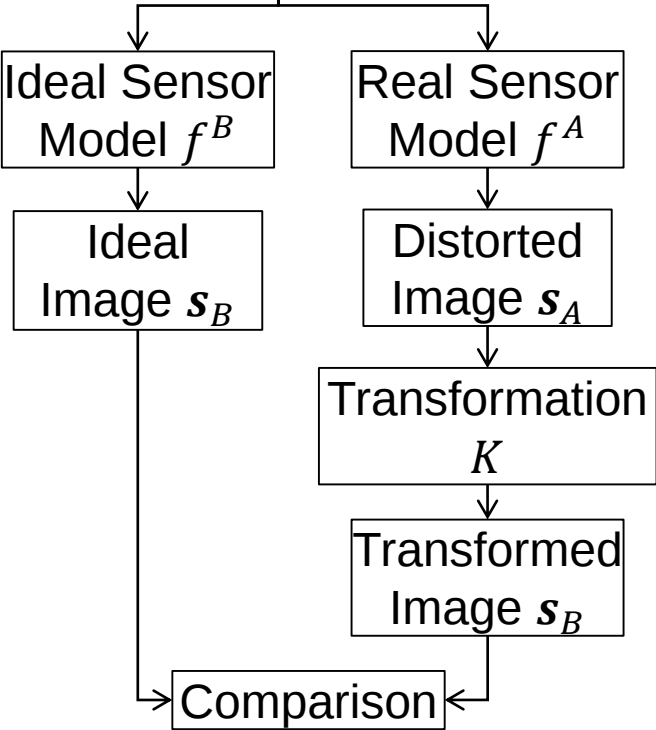
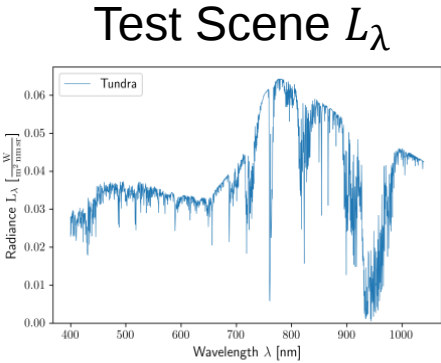
$$\hat{\mathbf{K}} = \arg \min_{\mathbf{K}} \left\{ \left\| \mathbf{K} \mathbf{C}^{AA} - \mathbf{C}^{BA} \right\|_2^2 + \gamma^2 \left\| \mathbf{K} \mathbf{\Gamma} \right\|_2^2 \right\}$$

Tikhonov solution



Sensor A	Sensor B	Application
HySpex	“ Better ” HySpex	<i>homogeneous L1C product smart binning</i>
HySpex	CHIME	<i>CHIME validation</i>
CHIME	Sentinel-2	<i>cross-validation</i>
CHIME	Sentinel-5p	<i>wishful thinking!</i>

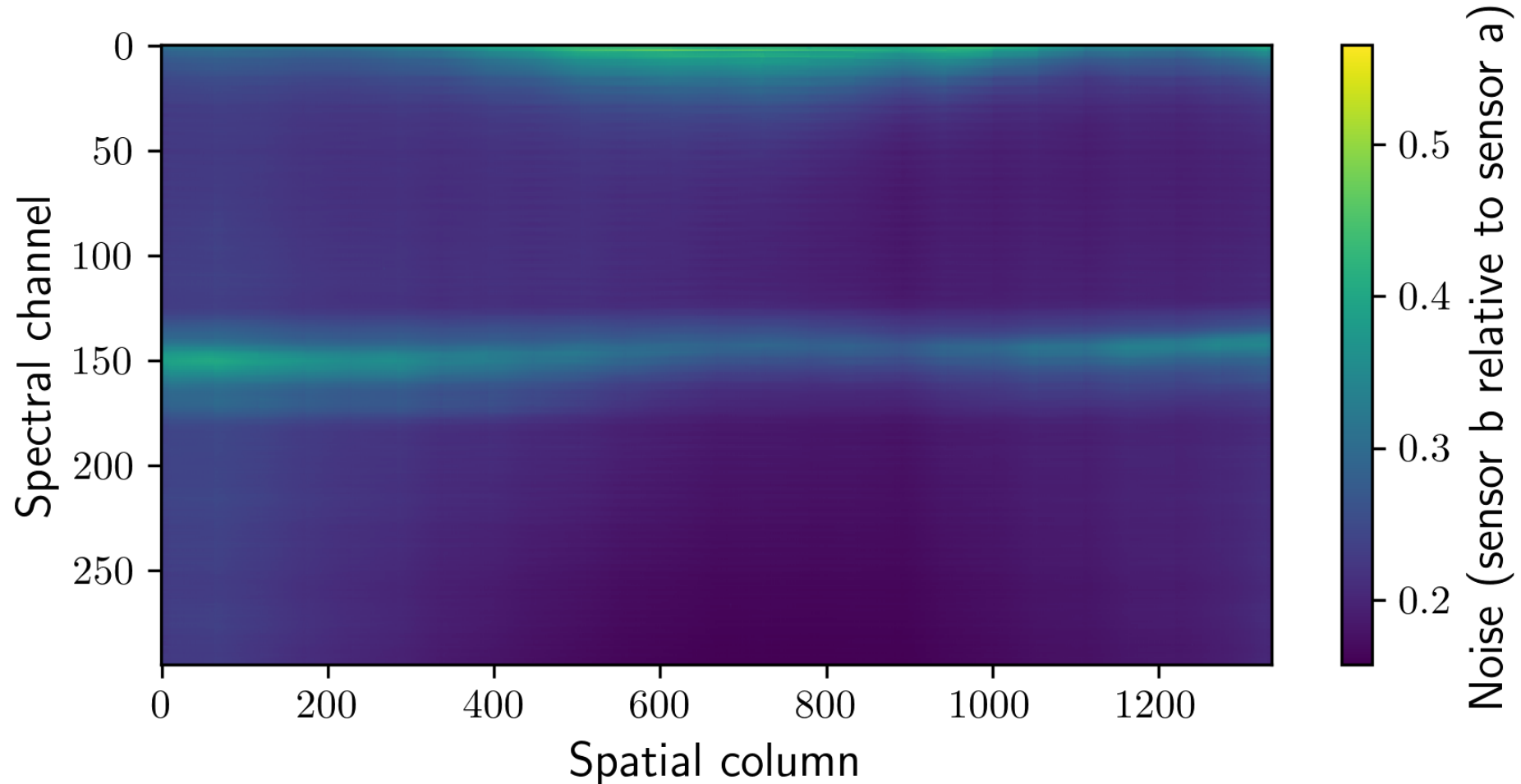
Simulation Study VNIR-3400N



VNIR-3400N Uncertainty after Smart Binning

$$\Sigma^B = K \Sigma^A K^T$$

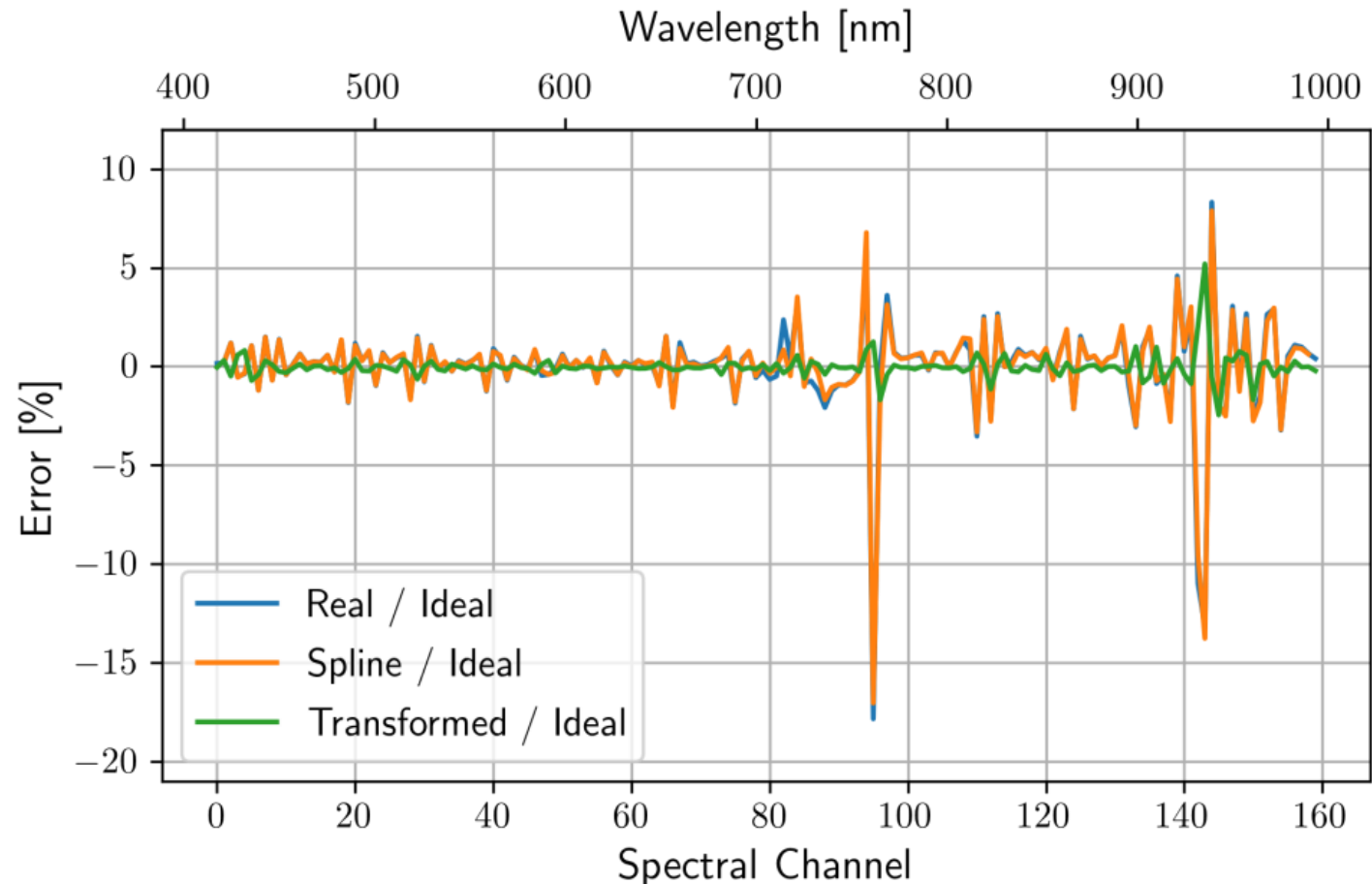
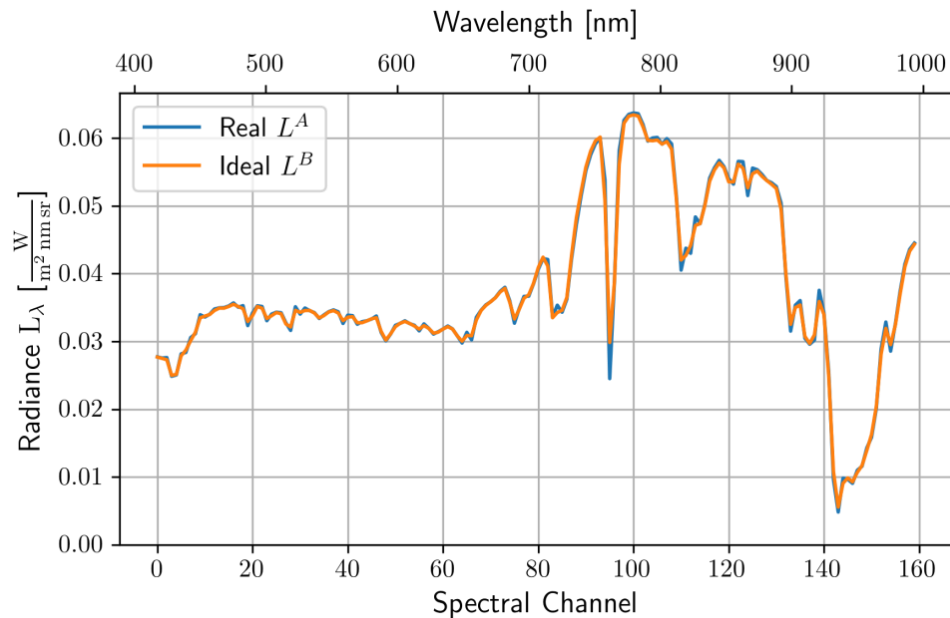
uncertainty propagation



Simulation Study VNIR-1600



- ~1.4 channels / FWHM
- Larger errors compared to oversampled sensor
- Smaller errors compared to conventional methods



Current HySpex 3400N Processing Settings

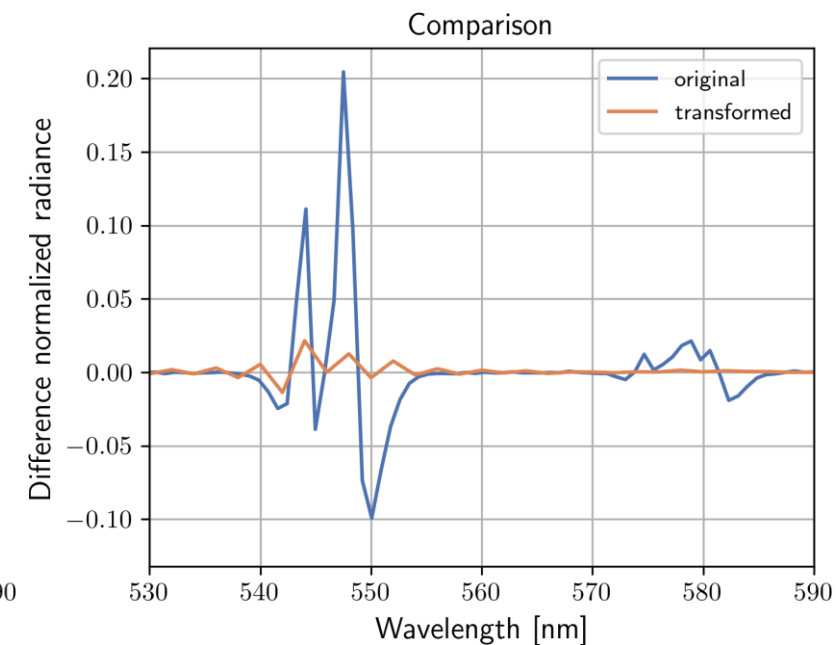
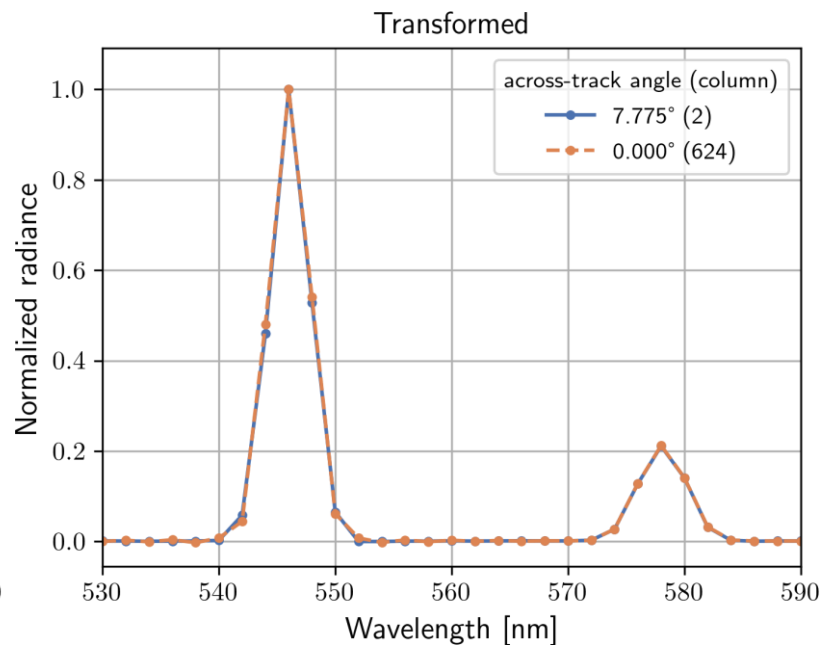
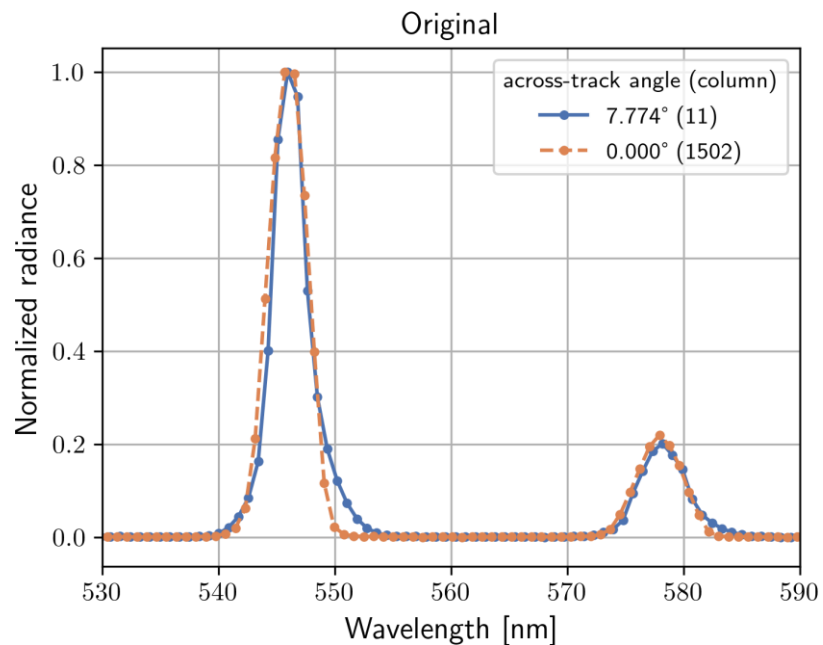


Parameter	Sensor A	Sensor B
Spatial columns	3408	1337 <i>smart binning</i>
Spectral channels	700	295 <i>smart binning</i>
Smile [nm]	<0.8	0
Keystone [mrad]	<0.14	0
Angular resolution [mrad]	0.09 – 0.43	0.44
Spectral resolution [nm]	2.5 – 7.5	4 <i>super resolution</i>
SRF and ARF shape	Spline model (complicated)	Gaussian

Experimental Validation of VNIR3400N Resampling



- Mercury lamp coupled into integrating sphere
- Isolated spectral emission lines → high frequency stress test
- Comparison of two spatial columns (across-track angles)



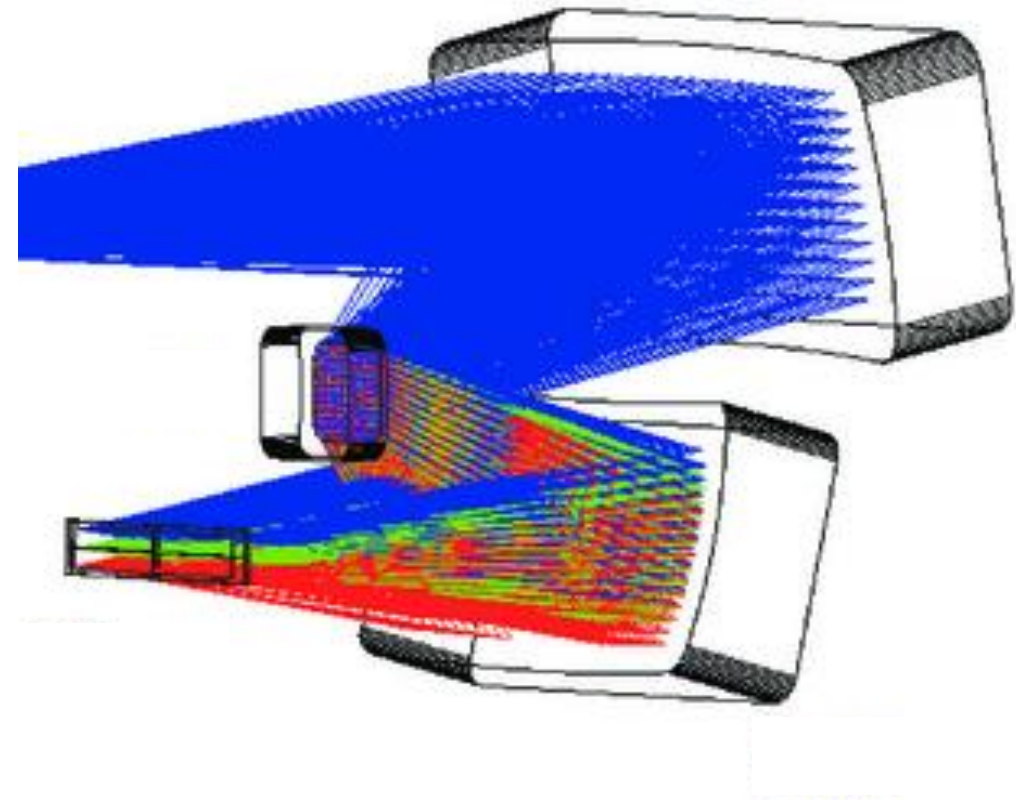
Implications on L1 Processing

- Convolution Kernel is *big data*
 - ~ 941 billion elements for HySpex VNIR
 - 7.5 TB at full resolution
 - 5.5 GB in practice (sparse matrix)
- Processing Time
 - Moderately optimized python code
 - VM with 16 CPUs @ 2.5 GHz, 128 GB RAM
 - 3-4 frames per second HySpex VNIR
 - ~50 frames per second HySpex SWIR
- Reduces complexity of all following processing steps
- Only 16 % of HySpex VNIR data points remain after *smart binning*



Implications on Future Sensor Design

- L1 post-processing can compensate for optical design imperfections
- Effectively reduces smile / keystone
- Denser sampling (Nyquist) required compared to typical hyperspectral sensors
- Response Functions have to be available (and stable)



Conclusions



- Kernel-based response function homogenization
 - corrects several optical artifacts
 - reduces data size by smart binning
 - reduces complexity of down-stream processing
 - delivers L1C products which are easier to adopt by the community

- Our findings have implications regarding the design of future sensors
 - Oversampling (spectral & across-track) improves data quality
 - Smile and keystone should not drive the optical design
 - Knowledge of the response functions (including in-orbit changes) is of paramount importance

- We should also take a closer look at along-track oversampling (scene inhomogeneity)

Title: **Improving L1 Product Quality for Imaging Spectrometers with Response Function-Based Post-Processing**

Date: 2024-11-21

Author: C. H. Köhler & A. Baumgartner

Institute: Remote Sensing Technology Institute, Oberpfaffenhofen

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Venue: ESA Workshop on Pre-Flight Calibration & Characterisation of Optical Satellite Instruments for EO
19 – 22 November 2024, Nordwijk, The Netherlands