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Using Large Eddy Simulatio	on
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: Journal of Turbomachine	ery
-7 <u>(3)</u>	Date of Publication (VOR* Online) <u>8 October 2024</u>
<u>https://asmedigi</u>	italcollection.asme.org/turbomachinery/article/147/3/031002/
ction URL: <u>1206153/Investi</u>	gating-the-Unsteady-Dynamics-of-a-Multi-Jet
	First Investigating the Unsteady Using Large Eddy Simulatic Christian Morsbach, Marce Michael Schroll, Christian V : Journal of Turbomachine 7 (3) https://asmedig ction URL: 1206153/Investi

*VOR (version of record)

DOI:

https://doi.org/10.1115/1.4066508

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1 Nomenclature

2 Roman letters

- D = Pipe or jet diameter [m]
- 4 e_N = Statistical error on the mean after N realizations
- 5 f = Frequency [Hz]
- 6 H =Channel height [m]
- 7 L = Length [m]
- 8 p = Pressure [Pa]
- 9 P = Axial pipe or jet spacing [m]
- 10 q = Heat flux magnitude [W m⁻²]
- 11 Q = Q-criterion for vortex visualization [s⁻²]
- 12 r =Cross flow ratio
- 13 t = Time [s]
- 14 T = Temperature [K]
- 15 u, v, w = Cartesian velocity components [m s⁻¹]

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Journal of Turbomachinery

Investigating the unsteady dynamics of a multi-jet impingement cooling flow using large eddy simulation

We investigate the unsteady behavior of an in-line jet impingement array of nine jets at a Reynolds number of 10000 in a narrow channel subjected to a developing cross flow of up to 25% of the bulk jet velocity. To this end, we present an improved version of a previously published large eddy simulation (LES) now with resolved turbulence at the inflow boundaries. After a careful analysis of the transient behavior and statistical convergence of the LES, we discuss the time-averaged heat transfer characteristics of the configuration compared to numerical references of similar configurations. We then show how the large-scale unsteadiness increases from jet to jet. Both space-only and spectral proper orthogonal decompositions (POD and SPOD) are used to discuss the large-scale organization of single jets and multiple jets in combination. The latter shows a qualitative change in the unsteady behavior of the temperature footprint on the impingement wall with increasing cross flow.

Keywords: impingement cooling, large eddy simulation, unsteady analysis, modal decomposition

V = Volume [m ³]	16
x, y, z = Cartesian coordinates [m]	17
Greek letters	18
Δ = Cell size or length [m]	19
λ = Thermal conductivity [W m ⁻¹ K ⁻¹]	20
$\lambda_i = \text{POD or SPOD eigenvalue of mode } i$	21
v = Kinematic viscosity [m ² s ⁻¹]	22
ϕ = POD or SPOD mode	23
$\sigma_i = \text{SVD}$ singular value	24
Dimensionless groups	25
Ma = Mach number	26
Nu = Nusselt number	27
Re = Reynolds number	28
St = Strouhal number	29
Superscripts and subscripts	30

aw = Adiabatic walls

31

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- 32 bulk = Spatial average over cross section
- c = Convective
- 34 jet = Jet value
- 35 wall = Wall value
- 36 rel = Relative value
- 37 ref = Reference value
- s = Sampling
- 0 =Stagnation value
- 40 $\|$ = Parallel to wall
- + = Wall unit

42 Operators

- 43 $\overline{\Box}$ = temporal average
- 44 $\langle \Box \rangle$ = spatial average

45 1 Introduction

In modern gas turbines engines, the thermodynamic efficiency 46 is affected by the turbine inlet temperature and the compression 47 ratio. Hence, high-pressure turbine blades often face temperatures 48 exceeding their material's melting point. To withstand these con-49 50 ditions, an active cooling system, which utilizes air extracted from the compressor, is mandatory. However, diverting air for cooling 51 reduces the engine's overall efficiency. A commonly used cooling 52 53 technique for turbine blades is impingement cooling, which typically employs arrays of jets that direct cooling air onto the hot 54 internal surfaces. The efficiency of impingement cooling is cru-55 56 cial, as it directly impacts the overall performance and longevity of high-pressure turbine parts. A major drawback of impingement 57 cooling is the creation of hot spots, resulting in uneven cooling. In-58 59 troducing periodic variations in the flow can improve its interaction with the hot surface, effectively mitigating the hot spot effect. The 60 flow's unsteadiness disrupts the thermal boundary layer, enhancing 61 heat transfer. Hence, predicting the heat transfer rates in complex 62 63 cooling systems is difficult and often results in non-optimized designs using too much cooling air. Effectively implementing novel 64 strategies necessitates a comprehensive understanding of the un-65 steady behavior of jet flow. 66

In the past, heat transfer analysis primarily focused on steady-67 68 state conditions. However, examining the dynamic behavior of the flow can provide a deeper understanding, allowing for strategic 69 70 alternation of the impingement domain to enhance heat transfer 71 efficiency. A comprehensive overview of basic steady-state physical phenomena and advancements in impingement jet heat transfer 72 73 over the past decades is documented in several review papers. Recent review papers such as Weigand and Spring [1] and Barbosa 74 75 et al. [2] describe the flow phenomena and interactions, providing correlations for heat transfer and discussing recent developments 76 77 regarding heat transfer enhancements. Dutta and Singh [3] specifically focus on heat transfer enhancements, such as the use of ribs 78 and surface obstructions, as well as features that increase the sur-79 80 face area in impingement jet setups, while Plant et al. [4] discuss the literature on both jet impingement and sprays. Comprehen-81 sive reviews and evaluations of various numerical methods, such 82 83 as Reynolds-averaged Navier-Stokes (RANS), Large Eddy Simulation (LES), and Detached Eddy Simulation (DES), for predicting 84 85 impingement jets, with a particular emphasis on single jet setups, have been presented by Shukla and Dewan [5] and Zuckerman and 86 87 Lior [6].

There exists rather limited literature on high-fidelity simula-88 89 tions of single-row impingement configurations in narrow channels. While there are Direct Numerical Simulation (DNS) studies 90 on single impinging jets in the relevant Reynolds number regime 91 of $O(10^4)$ [7,8], configurations involving multiple jets have been 92 93 investigated in the recent years using LES due to the increased computational effort required to resolve larger domains. Hossain 94 95 et al. [9] claim to have published the first LES study of such a 96 narrow-channel configuration which was validated with Particle Image Velocimetry (PIV) and Temperature Sensitive Paint (TSP). 97

They simulated 5 jets at a Reynolds number of 15 000 spaced 5D 98 (jet diameters) apart, which impinge on a heated plate of width 99 5D at a distance of 3D, using a second-order accurate commercial 100 flow solver with the subgrid stresses modelled by the wall-adapting 101 local eddy-viscosity (WALE) model. Their simulation resolved a 102 small part of the plenum over the short pipes of one jet diameter 103 length. Not only the impingement wall but also the side walls of 104 the channel were heated with a constant heat flux boundary condi-105 tion. Both in terms of velocity field and heat transfer they showed 106 consistent results with the experiments. While the channel of Hos-107 sain et al. [9] was closed to one end, such that the jets are exposed 108 to a self-generated developing cross flow, Otero-Pérez et al. [10] 109 presented a configuration in which they were able to prescribe de-110 fined cross flow profiles as an inlet boundary condition. It consists 111 of 3 jets at a Reynolds number of 10000 and a Mach number of 112 0.3, which impinge on a plate with a constant heat flux at a distance 113 of 4.5D. In their parametric study, they varied the jet spacing with 114 values of 5D, 10D and 15D for the case without cross flow and 115 subjected the jets at 10D spacing with both laminar and turbulent 116 cross flow boundary layer profiles at different velocities. While 117 they also employed the WALE model for the subgrid stresses, they 118 used an in-house fourth-order accurate finite fifference (FD) solver 119 with skew-symmetric convective fluxes and a filter to avoid numer-120 ical oscillations [11]. Since their configuration featured spanwise 121 periodic boundary conditions instead of solid walls, it technically 122 represents a 2D array of jets instead of a single row of jets in a 123 channel. Note, that their spanwise domain size was always equal 124 to the axial jet spacing. Their analysis focused mainly on the in-125 fluence of the different parameters on the heat transfer in terms of 126 local and spanwise-averaged Nusselt number. 127

Other recent LES studies are geometrically different from the 128 configuration considered in this paper. Draksler et al. [12] pre-129 sented an analysis of a hexagonal array of jets at a Reynolds num-130 ber of 20000 impinging on a heated plate at a distance of 4D. 131 They showed that LES was able to reproduce the relevant physical 132 effects such as fountain flow due to wall jet collision and negative 133 production of normal stresses near the impingement wall. In a 134 follow-up paper, Draksler et al. [13] presented an analysis of grid 135 dependence and statistical errors on first and second moments of 136 velocity. Yet another type of configuration was investigated by 137 Nguyen et al. [14]. Here, the cross flow was varied in a pipe 138 feeding a linear array of 7 jets at a Reynolds number of 5000, 139 which are spaced at 2.25D and impinge on a heated flat plate of 140 $20D \times 15D$ mounted at a distance of 3D in an even larger domain 141 allowing the jet fluid to expand laterally in a nearly undisturbed 142 manner. Besides the cross flow in the pipe, they also varied the 143 Mach number. They used a lattice Boltzmann method to perform 144 an LES, which they validated against PIV and infrared thermog-145 raphy data. A configuration representative of the cooling scheme 146 within a vane was introduced by Laroche et al. [15] where jets 147 at a mean Reynolds number of 10 000 are directed in to the con-148 cave, narrow leading edge region at a distance of 6.4D as well as 149 onto flat plates at a distance of 2D. It was analyzed both exper-150 imentally and with a hybrid RANS/LES method implemented in 151 a second-order accurate, unstructured in-house code. The hybrid 152 RANS/LES showed advantages over conventional RANS schemes 153 in terms of heat transfer prediction. 154

While most of the studies listed above focus on time-averaged 155 results and turbulence statistics, Yang et al. [16] also discuss the 156 unsteady behavior of a single row of 10 jets fed from a plenum 157 with cross flow through pipes of length D, which impinge onto a 158 cylindrical target at a distance of 3D and are spaced at 3D. They in-159 vestigate the configuration both experimentally with time-resolved 160 surface temperature measurement techniques and numerically us-161 ing steady and unsteady RANS simulations with a commercial 162 flow solver. While this study included a variation of jet Reynolds 163 number from 10000 to 20000, the same authors present a more 164 detailed analysis of the unsteady effects for the Reynolds number 165 of 15000 [17]. In both papers, they connect the unsteadiness of 166 the jets with a Kelvin-Helmholtz (KH)-like shedding of the cross 167



Fig. 1 Computational domain of the LES with heated portion of the wall marked in black and instantaneous turbulent structures for case C1 visualized by isosurface of $QD^2/w_{ref}^2 = 5$

Table 1 Geometrical properties of the configuration

Pipe diameter	D	0.0152m
Pipe separation	Р	5D
Pipe length	L_{pipe}	3D
Channel height and width	H	5D
Heated length	$L_{x,\text{heated}}$	55D
Heated width	$L_{\rm v,heated}$	4.45D
Position jet 7	x _{iet7}	0
Closed channel end	xend	-39.6D
Outflow	x _{outflow}	38.8D

168 flow downstream of the blockage caused by the jets. Another re-169 cent study by Rönnberg and Duwig [18] discusses the unsteady 170 heat transfer and associated flow features in a single impinging jet 171 configuration. The authors demonstrate how modal decomposition 172 techniques can be successfully applied to extract knowledge on the 173 large scale organization in the flow even if the relative energy in 174 these modes is low.

In the present paper, we focus on unsteady effects in a generic 175 176 configuration of nine cooling jets with a separation of 5D in a square channel. The cooling jets with an average Reynolds num-177 ber based on the jet diameter of 10 000 impinge on a heated plate at 178 179 a distance of 5D with a constant wall heat flux. The configuration is not only realized numerically but has also been set up with good 180 181 optical access for PIV measurements, which limited the jet bulk Mach number to 0.045. It was initially introduced by Tabassum et 182 al. [19] with a focus on RANS approaches compared to temporally 183 averaged PIV and a baseline LES with a wall heat flux of 5000 184 W/m^2 . We extend the presentation and discussion of our origi-185 186 nal LES setup along with a sensitivity study related to the inflow boundary conditions. Therefore, an additional LES is considered, 187 where resolved turbulence is introduced at the previously laminar 188 189 inflow boundaries. We will investigate the effect of these modified 190 boundary conditions on the development of the cooling jets and their heat transfer characteristics. The primary aspect of this study 191 192 is our focus on the unsteady behavior of the interacting jets. We 193 will assess the (potential) coupling between adjacent jets and those further apart using modal decomposition techniques. To the best 194 195 of our knowledge, no modal analyses based on high-fidelity simulations of single-row impinging jets with steady-state inflow can be 196 found in the literature to date. We seek to provide valuable insights 197 necessary for the design of advanced cooling channel geometries 198 targeted at improved efficiency of the cooling system. 199

200 2 Numerical setup

The configuration investigated with LES represents a slight modification of the experimental setup as briefly discussed by Tabassum



Fig. 2 Schematic of the flow topology focusing on jets 6, 7 and 8 (adapted from [20])

et al. [19]. It consists of nine pipes which feed the jet fluid into a square channel with a heated impingement wall as sketched in Figure 1. Notably, the channel remains closed to the left, exposing the jets to a self-generated, developing cross flow. The geometrical properties of the configuration are summarized in Tableau 1. Note that the origin of the coordinate system is on the heated wall below the center of jet 7. 209

Figure 2 illustrates the flow dynamics the impingement jet array 210 under self-induced cross flow, specifically focusing on jets 6, 7, and 211 8. A free jet emerges from the impingement hole, entraining the 212 surrounding fluid ((a)). In the stagnation zone, the fluid encounters 213 an adverse pressure gradient, decelerating its velocity to zero (B). 214 Following impingement, the pressure field accelerates the flow ra-215 dially, leading to the formation of wall jets (©). These wall jets 216 collide with those from neighboring impingement jets, creating a 217 fountain flow that ultimately forms a vortex (D). The fluid is then 218 219 displaced towards the side walls by adjacent jets, guiding it along the walls to the hole plate ([®]). A portion of this fluid recycles 220 back into the jet, while the remainder merges with the cross flow, 221 recirculating in a corkscrew movement towards the outlet (). The 222 cross flow significantly deflects the jet's trajectory towards the tar-223 get, enhancing shear forces and, consequently, reducing the heat 224 transfer (@). The cross flow around the jet induces a vortex pair 225 parallel to the impingement jet axis (\mathbb{B}) . 226

Numerically, the heated wall is realized through a constant heat 227 flux boundary condition, while all other solid walls are treated as 228 adiabatic. At the outflow, a 1D non-reflecting boundary condi-229 tion based on a characteristics formulation [21] controls the time-230 averaged pressure, which was determined iteratively to yield the 231 experimental mass flow. The inflow conditions for each jet pipe 232 are extracted from preliminary RANS computations of the config-233 uration including the plenum [19] to be able to account for the 234 non-homogeneous velocity distribution and to reproduce a vena 235 contracta effect. They are prescribed as temporally constant 2D 236 distributions using local Riemann boundary conditions. 237

We use TRACE's finite volume (FV) method to solve the fil- 238

Table 2 Simulated operating conditions

Case	C1	C2	C3
Re _{jet} Ma _{iet}		10 000 0.034 to 0.03	7
$q_{\rm wall}$ / Wm ⁻² Inflow	5000 Laminar	5000 Turbulent	2000 Laminar
$t_{\rm simulation}/t_{\rm c}$	1118.9	1072.0	443.7

Table 3 Area-averaged and maximum wall adjacent cell sizes in wall units (reproduced from [19])

Domain location	$\Delta \mathbf{x}_{\parallel}^{+}$		у	+ 1
	avg	max	avg	max
Pipes	15.78	80.13	0.42	1.54
Impinging wall	15.63	79.76	0.41	1.17
Upper wall	9.15	35.49	0.22	1.94
Side walls	14.76	49.96	0.31	0.93

tered compressible Navier-Stokes equations using a second-order 239 accurate, density based scheme applying MUSCL reconstruction 240 with $\kappa = 1/3$ [22] for the convective fluxes. A fraction of 10^{-2} 241 of Roe's numerical flux [23] is added to a central flux to avoid 242 odd-even decoupling. The viscous fluxes are computed using cen-243 tral differences. Time integration is performed using a third-order 244 accurate Runge-Kutta method [24]. The subgrid stresses are com-245 246 puted using the WALE model of Nicoud and Ducros [25]. This solver setup has successfully been used to generate LES data of 247 turbomachinery flows [26-28]. 248

Three different operating conditions have been computed as 249 summarized in Tableau 2. The first case C1 is the same setup 250 251 as described by Tabassum et al. [19] but with a longer period sampled to allow for the analysis of low-frequency phenomena. Apart 252 from the good agreement of time-averaged data between LES and 253 PIV, Schroll et al. [29] have shown that local unsteady effects ex-254 255 tracted from high-speed PIV were reproduced consistently for this case. The cases C2 and C3 represent variations of the boundary 256 conditions. It was expected that missing resolved turbulence might 257 be a reason for the discrepancies between PIV and LES observed 258 259 in the jet velocity profile reported by Tabassum et al. [19]. Therefore, case C2 introduces resolved turbulence at the inflow bound-260 aries through a Synthetic Turbulence Generator (STG) as proposed 261 262 by Shur et al. [30], which is supplied with the turbulent kinetic energy and dissipation rate distribution from the preliminary RANS 263 264 computation. For the sake of completeness, we also list case C3, 265 which was intended to be more closely aligned with measurements using TSP (cf. Schroll et al. [29]) but will not be analyzed in detail 266 in this paper. 267

The domain is meshed in a block-structured topology as shown 268 for the region around jets 6 and 7 in Figure 3. To ensure an appro-269 270 priate resolution of the pipe boundary layers, a butterfly topology (OH) was chosen, which extends into the channel and follows the 271 expected jet deflection. Across the pipe, there are 15 cells in the 272 O-block and 30×30 cells in the central H-block. The extended pipe 273 274 O-blocks are surrounded by another O-block to relax the near wall 275 resolution and the rest of the channel is filled with H-blocks which 276 are appropriately refined towards all solid walls. The z-direction 277 of the square channel is discretized with 210 cells resulting in a 278 total of 6.7×10^7 cells for the entire configuration. As summarized in Tableau 3, the maximum non-dimensional cell sizes of the wall 279 280 adjacent cells are in line with recommendations for LES [31] while the area-averaged values are well below these guidelines. The grid 281 resolution in the jet shear layers and remaining channel was con-282 firmed to be adequate by comparing the spatial cut-off scale and the 283

estimated Kolmogorov length scale $\Delta_{\rm cut}/l_{\eta} = V^{1/3}/(v^3/\epsilon)^{1/4}$ [32].



Fig. 3 Details of the computational surface mesh around jets 6 and 7 cut in half at y = 0 with two out of five elements shown per index direction. Colors indicate different surface blocks.

In the following, all physical quantities will be normalized us-285 ing the following set of reference values: the jet diameter D, 286 the maximum vertical velocity w_{ref} and the bulk total tempera-287 ture $T_{ref} = T_{0,jet1}$ of jet 1. We define a convective time scale as 288 $t_{\rm c} = D/w_{\rm ref}$. For the current study, we sampled primitive variables 289 and their gradients on the impingement wall of the channel with a 290 resolution of 300×30 and on the y = 0 plane of the channel with 291 a resolution of 280×30 at a rate of $f_s t_c = 13.45$. Full 3D solu-292 tions allowing for later extraction of spatially higher resolved data 293 were sampled at a rate of $f_s t_c = 5.35$ using TRACE's ParaView 294 Catalyst [33] interface and have also been used in the following 295 analyses if required. In addition to the temporally resolved data 296 sets, statistical moments allowing to obtain the budget terms of the 297 Reynolds stress transport equations were computed online at the 298 full spatial resolution. 299

Before any averaging or unsteady analysis can be conducted, 300 it has to be ensured that transients from the initialization have 301 been washed out of the domain and statistically steady flow has 302 been established. This is often done by a rather subjective in-303 spection of integral quantities such as mass flows or forces acting 304 on surfaces. We choose to employ the marginal standard error 305 rule (MSER) [34] on the spatially resolved data sets as described 306 in detail by Bergmann et al. [27]. Figure 4 shows the estimated 307 end of the initial transient $t_{\text{transient}} w_{\text{ref}}/D$ for the vertical velocity 308 component w (top) on the plane y = 0 and for the temperature T on 309 the impingement wall at z = 0 (*bottom*) for the case C1. For better 310 orientation, the positions of the pipes are marked on the top axis 311 and as circles, where appropriate, and the mean flow is illustrated 312 as streamlines. At many locations, the MSER determines an end 313 of the initial transient for t = 0. This can be explained by the 314 fact that the simulation was restarted from an already existing LES 315 solution after a correction of the inflow boundary conditions. A 316 majority of the locations is marked converged at well below $100t_c$. 317 Exceptions can be found in the low-speed areas between the jets 318 with the largest values between jets 1 and 2 and between 4 and 319 5. On the impingement wall, the maximum transient times can be 320 found close to the channel side walls where the heated portion of 321 the wall ends. 322

A more quantitative analysis of the estimated transient times 323 is presented in Figure 5. At the bottom, we plot the probability 324



Fig. 4 Transient time computed with MSER (C1) for vertical velocity component w on slice at y = 0 (*top*) and temperature T on heated wall (*bottom*). The mean flow is illustrated with streamlines. Positions where frequency spectra are compute marked with red squares and circles.



Fig. 5 Statistical analysis of transient times (C1) for velocity w, wall shear stress $\tau_{w,x}$ and temperature T on slice at y = 0 and heated wall with probability density function (*bottom*) and cumulative area fraction of transient below given time (*top*)

density function (PDF) of the transient end times over the two sub-325 326 domains shown in Figure 4 with additional information about the temperature on the y = 0 plane and the shear stress on the im-327 pingement wall, while the top panel shows the cumulative fraction 328 329 of transient end times smaller than the current. The shear stress 330 on the impingement wall is the fastest converging quantity with roughly 90% of the time signals showing statistical convergence 331 according to the MSER before $7t_c$. The temperature on the wall 332 333 and the velocity in the y = 0 plane follow a similar trend in the PDF and by $100t_c$ 99.5% of the time signals have converged. Only 334 the temperature in the y = 0 plane shows slightly slower conver-335 336 gence. After a similarly steep decay in the PDF until $50t_c$, the rate at which more time signals converge becomes considerably slower 337 and only 92.7% of the signals show statistical convergence after 338 $100t_c$. We set our global end of transient to $100t_c$ since we do not 339 340 evaluate this particular quantity in further analyses. Nevertheless, we consider it worthwhile showing this behavior as it should raise 341 awareness about the intricacies of initial transient detection. 342

343 3 Time-averaged results

To put our later discussion of the unsteady dynamics into a perspective, we start with an analysis of the heat transfer on the impingement wall. The temperature distribution on the wall can

be written in terms of a Nusselt number

$$\operatorname{Nu}(x, y) = \frac{q_{\operatorname{wall}}(x, y)D}{\lambda(x, y) \left(T_{\operatorname{wall}}(x, y) - T_{\operatorname{ref}}\right)}$$
(1) 348

347

with the local thermal conductivity $\lambda(x, y)$, the local wall temper-349 ature $T_{\text{wall}}(x, y)$ and a reference temperature T_{ref} . The latter would 350 ideally be taken as the local adiabatic wall temperature $T_{aw}(x, y)$, 351 requiring another simulation with $q_{\text{wall}} = 0$. At low Mach numbers, 352 the reference temperature is typically chosen as $T_{ref} = T_{0,jet}$ [35], 353 which, as Otero-Pérez and Sandberg [11] argued, might not be 354 a good choice. To assess the influence of the choice of T_{ref} in 355 our case, we extrapolated $T_{aw}(x, y)$ using the two laminar inflow 356 simulations with different wall heat fluxes C1 and C3 [11]. The re-357 sulting Nusselt number distribution yielded negligible differences 358 to the one obtained with $T_{ref} = T_{0,jet}$. Therefore, we can refrain 359 from running another simulation to obtain $T_{aw}(x, y)$ for the turbu-360 lent inflow case. This is in line with the reasoning by Nguyen et al. 361 [14], who decided against a scaling of the case to a higher Mach 362 number because that would invalidate the choice of $T_{ref} = T_{0,jet}$. 363

Figure 6 shows the time-averaged Nusselt number distribution 364 (top) on the impingement wall for the laminar inflow case C1. The 365 relative 68% confidence interval (CI) of the mean (bottom) was 366 computed following the method described by Bergmann et al. [27]. 367 While the mean value was computed from the online time average 368 at full spatial resolution, the CI has to be computed from the full 369 time series, which was sampled at reduced spatial resolution as 370 described above. Note that the lateral bounds of the heated area 371 can be identified by values of $\overline{Nu} = 0$ close to the channel side 372 walls. The CI is only shown for the heated area. The distribution 373 of the mean has already been discussed in detail by Tabassum et al. 374 [19]. Generally, the increasing cross flow can be seen to move the 375 impingement point of the jets downstream and change the shape 376 of the high Nusselt number area under the jet from circular to a 377 crescent moon shape. Secondary maxima between the jets can be 378 attributed to the recirculation resulting from the colliding wall jets 379 which brings colder fluid down to the wall, cf. Nguyen et al. [14]. 380

The relative CI increases with increasing cross flow from left to 381 right. For each jet, the largest relative errors can be found in the 382 regions of the colliding wall jets and the interaction with channel 383 side wall. With increasing cross flow, this region with large error 384 moves downstream towards the impingement area of the respective 385 jet until it nearly coincides with the stagnation point in jet 9. This 386 is already a hint towards larger scale unsteadiness compared to jet 387 1, which basically contains only small scale turbulence leading to 388 small CI values. While the average CI is at roughly 1.8%, the 389 maximum values of 6% can be found under jet 8. We will later 390 exclude jets 8 and 9 from the unsteady analysis to avoid boundary 391 effects. 392



Fig. 6 Time-averaged Nusselt number and relative 68% confidence interval on heated wall for laminar inflow case C1



Fig. 7 Comparison of time- and spanwise-averaged Nusselt number (Nu)_{span} on heated wall

For a quantitative comparison of the three computed cases, we 393 show the time- and spanwise-averaged Nusselt number $\langle \overline{Nu} \rangle_{span}$ for 394 395 the three cases compared with the RANS results of Tabassum et al. $[19]^2$ in Figure 7. RANS generally overestimates the heat transfer 396 maxima in the jet stagnation regions due to excessive production 397 of turbulent kinetic energy [19] and predicts the Nusselt minima 398 slightly further downstream than the LES. The differences between 399 the LES results are subtler. Cases C1 and C2 produce nearly 400 identical results with the exception that the heat transfer in the 401 jet stagnation region is slightly larger for the laminar inflow case 402 than for the turbulent inflow case. This can be explained by less 403 turbulence in the initial shear layers of the jet leading to a reduced 404 mixing with the surrounding fluid and thus larger potential core 405 of the jet. The magnitude of this variation is even lower than the 406 variation due to the change in heat flux boundary condition, which 407 was deemed as minor by Tabassum et al. [19]. 408

Figure 8 shows the jet deflection defined as relative downstream 409 shift of the Nusselt number maximum $(x_{Nu_{max}} - x_{jet})/D$ over the 410 relative bulk cross flow velocity $\langle \overline{u} \rangle_{\text{bulk,channel}} / \langle \overline{w} \rangle_{\text{bulk,jet}}$. A jet with no deflection will give $(x_{\text{Nu}_{\text{max}}} - x_{\text{jet}})/D = 0$ as it is found 411 412 413 for jet 1 in all computations. The bulk cross flow velocity is 414 computed as an area average over the square channel at a position 2.5D upstream of the respective jet center. All three LES show 415 416 practically the same behavior and we only plot cases C1 and C2 417 for a clearer presentation. Two distinct ranges of linear relation between the jet deflection and cross flow ratio can be observed for 418 419 both cases. After an initial slow increase in jet deflection at low cross flow ratios, it increases more rapidly from jet 4 onward with 420 higher cross flow ratios. The RANS results [19] on the other hand 421 422 show a more varying slope along the nine jets.

To put our results into perspective, we also included the jet deflection derived from Otero-Pérez et al. [10] Fig. 5(a) for both



Fig. 8 Jet deflection over cross flow for cases C1 and C2 in comparison with numerical [9,10,19] and experimental [36] references in rectangular channels and experimental results with a cylindrical impingement target [16]

laminar (diamonds) and turbulent cross flow (squares).3 Note that425their channel height and width are 4.5D and 10D, respectively, and426that they have used periodic boundaries in the spanwise direction.427Furthermore, in contrast to our simulations upstream of jet 7, their428initial cross flow does not contain any secondary flow motions and429

$$r(n) = r_0 + \frac{n\pi D^2}{4HL_{\rm v}}$$

with H/D = 4.5, $L_y/D = 10$ and the initial cross flow ratio $r_0 = 0.2$.

²Compared to Tabassum et al. [19], who used a constant thermal conductivity, we recomputed the Nusselt number using Équation (1) with the local thermal conductivity.

 $^{^{3}}$ The cross flow ratio downstream of the n^{th} jet was estimated assuming incompressible flow as



Fig. 9 Temporal evolution of spanwise-averaged Nusselt number $(Nu)_{span}$ for the turbulent case C2

430 the jets are injected into the channel as laminar top hat profiles. Considering all these differences, the results seem consistent. A 431 second comparison is shown with the results of Hossain et al. [9] 432 433 at $Re_{iet} = 15\,000$ (triangles), whose configuration is also realized with one closed end and a cross flow driven by the jets only.⁴ 434 435 Since their channel height is only 3D, the jet deflection is significantly lower. Their configuration also shows a strong increase in 436 deflection after the third jet, which is consistent with their mea-437 sured Nusselt number distribution. Stoy and Ben-Haim [36], on 438 the other hand, show a non-linear best fit to experiments conducted 439 at several jet Reynolds numbers with H/D = 3.05 and $L_v/D = 12$ 440 (dotted line). Note that input data was sampled for single jets with 441 442 incoming cross flow at velocity ratios between 0.13 and 0.4 and, hence, do not cover the low cross flow regime of our first four 443 jets. Yang et al. [16] also report jet deflection over jet number 444 $Re_{iet} = 15\,000$ (crosses). The relative cross sectional area of their 445 cylindrical channel is roughly 2.5 times smaller than in our config-446 447 uration leading to a stronger increase in cross flow velocity with jet number⁵. As above, due to the short distance to the impingement 448 target of 3D, the jet deflection grows significantly more slowly. 449

450 4 Unsteady dynamics

A first impression of the unsteady behavior under the developing 451 452 cross flow is presented in Figure 9 by the temporal evolution of the spanwise-averaged Nusselt number $(Nu)_{span}$ over the length of the 453 channel for the case C2. The first three jets exhibit relatively minor 454 oscillations of the Nusselt number primary and secondary maxima 455 456 with slowly increasing amplitude from jet to jet. This plot allows to assess the direction in which flow structures travel by analyzing 457 their slope. Here, structures moving both upstream (negative, e.g. 458 459 white dashed line in inset lower right) and downstream (positive, 460 e.g. black dashed lines) can be observed. Around jet four multiple qualitative changes can be found: First, upstream moving structures 461 practically disappear, indicating, that the upstream wall jets cannot 462 balance the existing cross flow in a spanwise-averaged sense. Sec-463 ond, as in the temporally averaged distribution (cf. Figure 7) no 464 more secondary maxima can be observed. Finally, the oscillations 465 increase more drastically from this point on. These changes corre-466

⁵Cross flow ratio for the configuration of Yang et al. [16] estimated assuming a 240° circle segment for the channel cross section as

$$r(n) = r_0 + \frac{n\pi}{16\left(\frac{2\pi}{3} + \frac{\sqrt{3}}{4}\right)}$$

with $r_0 = 0$.

Journal of Turbomachinery



Fig. 10 Premultiplied power spectral density of pressure in jet shear layers at $(x_{jet} + 0.3D, 3.5D)$ (*top*) and axial velocity *u* close to impingement wall above Nusselt maximum at $(x_{Nu,max}, 0.2D)$ (*bottom*)

late with the increased slope in jet deflection (cf. Figure 8). From 467 jet 7 onwards, events can be observed in which very hot fluid (yel-468 low) travels through the impingement region indicating a complete 469 separation of the jet. Examples are marked with the black dashed 470 lines. For jets 7 and 8, these occur rather sporadically at rates of 471 about once every $200t_c$. The ninth jet, which lacks a downstream 472 neighbor, separates at a much higher rate, in some instances with 473 intervals below $20t_c$. To exclude these boundary effects in the 474 further analysis, we will not consider jets 8 and 9 from here on. 475

Before analyzing larger scale organization in the flow, we need 476 to identify the relevant frequencies. For this reason, Figure 10 477 shows the premultiplied power spectral density (PSD) below jets 478 1, 3, 5 and 7 in the shear layer at $(x_{jet} + 0.3D, 3.5D)$ (top, marked 479 with squares in Figure 4) and above the impingement point given 480 by $(x_{Nu,max}, 0.2D)$ (bottom, marked with circles in Figure 4). In 481 the shear layer, the pressure p was used as a variable, while we 482 plot the PSD of the axial velocity u close to the wall. The spectra 483 were obtained using Welch's method [37] with a window of $76t_c$ 484 and an overlap of 50%, allowing to resolve a minimal frequency 485 of $0.0131/t_c$. We also compare the cases C1 with laminar inflow 486 (left) and C2 with turbulent inflow (right). Within the jet shear 487 layers, a clearly dominant peak can be found centered at the natu-488 ral frequency of shear-layer instabilities of $St = ft_c = 0.6$ [38]. Its 489 amplitude is consistent over all jets and boundary conditions with 490 the exception of jet 1 with turbulent inflow, which dominates the 491 other jets of both cases by a factor of 4. With this notable excep-492 tion, the peaks centered at this frequency are rather broad. Their 493 width taken at a tenth of the peak value increases from 0.5 for jet 494 1 to 1.5 for jet 7 for case C1. Note that for the downstream jets, 495 the high frequency flank of the peak becomes a part of the turbu-496 lent inertial range. For case C2 with turbulent inflow, in contrast, 497 the width of the peaks remains relatively constant at 1.5, mainly, 498 because jet 1 already shows a well-developed inertial range. Close 499 to the impingement wall, in the spectrum of the axial velocity, this 500 peak cannot be identified anymore. At high frequencies above 0.6, 501 a turbulent spectrum can be found as indicated by the black dashed 502 lines, representing a decay of the PSD proportional to $f^{-5/3}$. More 503 interesting for the current investigation, however, is the lower end 504 of the spectrum. Here, we can see a growth in amplitude over the 505 jets up to an order of magnitude for frequencies below 0.1. This 506 is a first indication of larger-scale, low-frequency organization in 507 the flow with increasing cross flow ratio. Note, that the amplitudes 508 are almost two orders of magnitude below the dominant jet vortex 509 shedding and the connected largest turbulent structures. This will 510 complicate the identification of such structures by pure investiga-511

⁴Cross flow ratio estimated with H/D = 3, $L_y/D = 4$ and $r_0 = 0$.



Fig. 11 SPOD premultiplied eigenvalues of velocity modes in plane y = 0 for jets 2 with low cross flow and 7 with high cross flow for case C2 with turbulent inflow

512 tion of eigenvalues obtained from modal analysis as they will not 513 show clearly dominant peaks.

For the sake of clarity, we limit the following analysis to the case 514 C2 with turbulent inflow. A Spectral Proper Orthogonal Decom-515 516 position (SPOD) [39-41] has been performed with a time series 517 of fluctuating velocity \mathbf{u}' using a turbulent kinetic energy (TKE) 518 norm. We consider the plane y = 0 separately for jet 2 as the first jet experiencing low cross flow and jet 7 in a high-cross-flow 519 520 environment. The data sets extend $\pm 2.5D$ around the jet center in axial direction and cover the complete channel height. The block 521 size for Welch's method has been chosen as $76t_c$ with 50% overlap 522 523 as above.

Figure 11 shows the resulting premultiplied eigenvalues λ_i for all 524 525 resulting modes with the area between the first two modes shaded 526 in red to indicate potential low-rank behavior. As expected after the discussion above, no distinct peaks dominating by an order of mag-527 528 nitude stand out of the spectrum. Rather, we see that at frequencies 529 below the turbulent inertial range, the first mode dominates by a maximum factor of roughly 1.5 for jet 2 while it dominates by a 530 531 factor of 1.5 at low frequencies to a factor of 3 at $ft_c = 0.4$ for jet 532 7. We now select a low, medium and high frequency with large separation between the first two modes, marked by the vertical 533 534 dashed lines. For each of these frequencies, we plot the respective 535 first SPOD mode ϕ for all three velocity components u, v and w(indicated in the plots) in Figure 12. At medium and high (*mid*-536 dle and bottom) frequencies, mode shapes can be found which are 537 typical for vortex shedding [40]. They are most clearly visible in 538 539 the *u* and *w* velocity components and follow the jet trajectory from the orifice to the impingement plate ((a)). Their intensity increases 540 from with distance from the orifice before they are damped by the 541 542 presence of the wall. Significant amplitudes in the spanwise component v are only found in jet 2 (B). For jet 7, the latter start to 543 544 increase in amplitude at even higher frequencies around 0.6, which 545 is not shown here. Note that the mode shapes are normalized and do not represent physical amplitudes. They have to be interpreted 546 547 in combination with the respective eigenvalues (cf. Figure 11), which show that the first mode is roughly 2 times more energetic 548 for jet 7 compared to jet 2 at the medium and high frequencies. 549

550 At the low frequency (Figure 12 top), larger structures can be identified. It has to be mentioned though, that these vary quite 551 strongly with the chosen frequency as could be expected from the 552 broadband nature of the spectrum. Independently of the frequency, 553 554 however, they show large amplitudes mainly very close to the impingement wall in the axial velocity u (©) representing an axial 555 oscillation of the stagnation point. The corresponding mode in 556 557 the vertical velocity w shows the strongest modulation along at the upstream edge of the jet. While this structure extends from im-558 559 pingement wall to orifice for jet 2 ((D)), it is more closely bound to the near wall area z/D < 2 for jet 7 (E). Significant contributions 560 from the spanwise velocity v can only be found for jet 7, where a 561 large structure exists in the upper half of the channel (), hinting 562 at some kind of shedding of the cross flow behind the blockage 563

of the jet itself. This is the clearly dominant effect in mode 2 at 564 this frequency, which is not shown here due to space constraints. 565 The Strouhal number for wake vortices behind a jet in cross flow 566 at a comparable velocity ratio and Reynolds number was found to 567 be around 0.13 by Fric and Roshko [42]. This corresponds to a 568 non-dimensional frequency of $ft_c = 0.017^6$ with the cross flow 569 ratio for jet 7 (cf. Figure 8). With the frequency resolution possi-570 ble by our choice of block size, we cannot extract a mode for this 571 frequency exactly but possibly see a first harmonic connected with 572 this phenomenon at $ft_c = 0.04$. Yang et al. [17] offer a detailed 573 discussion of this shedding mechanism driving the unsteadiness of 574 the jets based on an unsteady RANS simulation. 575

As a final analysis, we turn to the temperature footprint of the 576 jets on the impingement wall. The SPOD eigenvalue spectrum for 577 the temperature T on sections of the wall under the single jets re-578 vealed that no high-frequency content can be found so close to the 579 wall and that notable low-rank behavior could only be identified 580 for $ft_c < 0.1$. Hence, we took a different approach for the wall 581 data set and resorted to space-only Proper Orthogonal Decompo-582 sition (POD), which will give modes that can contribute a whole 583 spectrum of frequencies to the complete signal. Again, we analyze 584 subsets covering $\pm 2.5D$ around the jet centers, this time in both x-585 and y-direction. 586

Figure 13 shows the relative eigenvalues $\lambda_{rel,i}$ of the first five 587 POD modes for jets 1 to 7 analyzed separately and for jets 2-4 588 and 5-7 analyzed in combination, respectively. A first observa-589 tion is that the relative eigenvalue of the first mode increases from 590 2.4% for jet 2 to 12.2% for jet 7. An exception is jet 4, which 591 shows a reduced eigenvalue compared to the upstream one. Com-592 paring the eigenvalues with the development of the maxima in the 593 spanwise-averaged Nusselt number (cf. Figure 7) shows a corre-594 lation of Nusselt reduction with increasing eigenvalue of the first 595 mode. This can be seen as a quantification of the argument that 596 the Nusselt number distribution becomes more smeared by a more 597 intense movement of the jet. This correlation also holds for the 598 increase in the Nusselt maximum from jet 3 to 4. The contribution 599 of the second mode increases up to jet 6 (with a slight drop for 600 jet 3), where it dominates the third mode by a factor of 2.1. Jet 601 7, however, is dominated by mode 1 only. A spectral analysis of 602 the POD time coefficients revealed that they are, indeed, associated 603 with low frequencies only. 604

The corresponding shapes of the first three modes ϕ_T for jets 2 605 to 7 are shown in Figure $14.^8$ In the low-cross-flow environment 606 of jets 2 to 4, the primary movement of the jet leads to a spanwise 607 variation of the surface temperature with low temperature at y/D =608 -2 in phase with high temperature at y/D = 2 and vice versa (@). 609 Mode 2 primarily describes the temporal variation in the wall jet 610 collision region about 1.5D to 2.5D upstream of the respective jet 611 center (a) and is likely connected with an oscillation of the jet in 612 the cross flow direction as this region shows a 180° phase shift 613 compared to the downstream side of the jet (©). When the cross 614 flow increases further, the shapes of mode 1 and 2 switch from 615 jet 4 to 5. Now, the dominant mode is the axial oscillation of the 616 temperature, while the spanwise oscillation corresponds to mode 617 2. Note, that the gap between modes 1 and 2 has reduced from 618 jet 3 to 4 and is roughly constant for jets 4 and 5, which seems 619 consistent with a change in dominant effects. While all previous 620 mode shapes have been nearly symmetric about the y = 0 plane, 621 jet 6 presents an exception as its modes 1 and 2 appear to be a mix 622

⁶We can write the Strouhal number as

$$St = \frac{f D}{\langle \overline{u} \rangle_{bulk, channel}} = f t_c \frac{w_{ref}}{\langle \overline{w} \rangle_{bulk, jet}} \frac{\langle \overline{w} \rangle_{bulk, jet}}{\langle \overline{u} \rangle_{bulk, channel}}$$

7,

$$\lambda_{\text{rel},i} = \frac{\sigma_i^2}{\sum_{j=1}^N \sigma_j^2}$$

can be obtained from a Singular Value Decomposition (SVD), which yields the singular values σ_i [43].

⁸Note that the sign of the complete mode can change without changing the meaning.



Fig. 12 First SPOD mode for velocity in plane y = 0 at low, medium and high frequency for jets 2 with low cross flow and 7 with high cross flow for case C2 with turbulent inflow



Fig. 13 POD relative eigenvalues $\lambda_{\text{rel},i} = \sigma_i^2 / \sum_{j=1}^N \sigma_j^2$ of first five temperature modes on impingement wall evaluated for single jets and combinations for case C2 with turbulent inflow

of the axial and spanwise oscillations (). With jet 7, the axial mode regains its dominance over the second mode with a factor of 3 such that most of the temperature variation can be attributed to axial oscillations (). For the higher modes, for which mode 3 is shown as a representative, we see more complex patterns of combined axial and spanwise oscillations and their eigenvalues no longer dominate.

In order to investigate the interaction between the jets in different 630 cross flow regimes, PODs of the wall data set with windows around 631 jets 2-4 and jets 5-7, whose eigenvalues for the first five modes are 632 633 also shown in Figure 13, have been performed. Compared to the analysis of the single jets, the first two modes combined contribute 634 less to the total energy, with 5.8% and 6.7%, respectively. Fig-635 ure 15 shows the shapes of the first three modes. First of all, 636 traces of the mode shapes observed in the analysis of the single 637 jets can be found here as well, but with the additional phase in-638 formation over multiple jets showing non-negligible organization 639 of the flow on large scales. In the low-cross-flow regime (left), 640 a phase shift of 180° can be clearly identified between adjacent 641 jets (e.g. (a)) with jets 2 and 4 swinging in phase in the spanwise 642

Journal of Turbomachinery

direction (B). Consistently with the previous analysis, the second 643 mode exhibits the largest amplitudes in the region where the wall 644 jets collide. With jets 2 and 4 showing clear in-phase behavior in 645 646 the high-temperature region (©), the data under jet 3 is relatively noisy, making it hard to judge if the respective region participates 647 in this collective movement. Mode 3 is then the first to connect an 648 axial oscillation behavior of jet 3 with a spanwise oscillation of jet 649 4 (b). This kind of combination becomes more dominant in the 650 high-cross-flow regime (right). Here, the first mode combines the 651 spanwise movement of jet 6 with the strong axial movement of jet 652 7 (E) while jet 5 is only weakly connected to this behavior via a 653 spanwise mode shape at low amplitude in phase with jet 7 (). Jet 654 5 also does not significantly participate in mode 2, which connects 655 the axial oscillation of jet 7 with a stronger asymmetric motion of 656 jet 6 (@). Mode 3 is the first mode with a significant contribution 657 of jet 5 showing a similar shape as jet 6 in mode 2 with a high 658 amplitude in the upstream region shifted towards the side wall and 659 the corresponding area with 180° phase shift located downstream 660 and at the opposite side wall (1). In summary, while the dominant 661 modes in low cross flow do not show an interaction of axial and 662 spanwise jet movement, the latter becomes the norm in high cross 663 flow. 664

5 Conclusions

We have presented an LES-based analysis of the unsteady dy-666 namics of a generic multi-jet impingement configuration consisting 667 of nine jets spaced at five jet diameters, which inject fluid into a 668 square channel of five jet diameters in height and width, heated on 669 the impingement wall with constant heat flux. Compared to pre-670 viously published results, which have validated the setup against 671 PIV data, the present paper has introduced a modification to the 672 inflow boundary conditions where synthetically generated resolved 673 turbulence is considered. We presented a thorough analysis of the 674 transient times of the simulation along with a 2D assessment of the 675 statistical errors of the Nusselt number on the impingement plate. 676 Although the influence of resolved turbulence at the inflow in terms 677 of heat transfer characteristics was found to be minor, the follow-678

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Fig. 14 First three POD modes of temperature T for single jets for case C2 with turbulent inflow

ing analysis has been conducted with this latest, in our view, more 679 appropriate data set. We showed how the large-scale unsteadiness 680 681 of the jets develops over the domain with increasing cross flow. Using POD and SPOD, we identified a low-cross-flow regime with 682 a relative bulk velocity below 0.1 and a high-cross-flow regime 683 between 0.1 and 0.2, between which the large-scale organization 684 of the flow undergoes both a quantitative and a qualitative change. 685 While the spanwise and axial oscillations of the jets were not con-686 687 nected in the low-cross-flow regime, more complex interactions of the neighboring jets could be identified with increasing cross flow. 688 For further improvement of existing cooling systems a deep un-689 derstanding of internal cooling flow characteristics essential. The 690 presented analyses will support the design of more complex cool-691 ing configurations with additional geometric features in the channel 692 aimed at utilizing or modifying the inherent large-scale unsteadi-693 ness of the flow. 694 This study has already set a benchmark for future innovative configurations like the ArcConic turbulator [20]. 695 This U-shaped device on the impingement plate enhances the jet 696 flow by redirecting cross flow, which stabilizes the jet flow and re-697 698 duces its unsteadiness. This stabilization results in a more uniform cooling throughout the system. Notably, it facilitates efficiency 699 improvements, with the average Nusselt number increased by up 700 to 16%. Especially at stagnation points, Nusselt number enhance-701 ments can reach up to 40%. Furthermore, the ArcConic ensures 702 a uniform Nusselt number distribution, effectively preventing the 703 degradation of downstream jets and contributing to an overall more 704 efficient cooling process. Such novel configurations will be consid-705 ered in more detail in future studies using unstructured high-order 706 707 Discontinuous Galerkin (DG) discretization methods.

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Fig. 15 First three POD modes of temperature T for jets 2-4 and jets 5-7 combined for case C2 with turbulent inflow

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871

775

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777 778

779

List of Figures

1	Computational domain of the LES with heated portion of the wall marked in black and instantaneous turbulent structures	
	for case C1 visualized by isosurface of $OD^2/w^2 = 5$	3
2	Schematic of the flow topology focusing on jets 6, 7 and 8 (adapted from [20])	3
3	Details of the computational surface mesh around jets 6 and 7 cut in half at $y = 0$ with two out of five elements shown	
-	per index direction. Colors indicate different surface blocks.	4
4	Transient time computed with MSER (C1) for vertical velocity component w on slice at $y = 0$ (<i>top</i>) and temperature T	
	on neated with <i>bottom</i>). The mean how is inustrated with streamines. Positions where frequency spectra are compute	5
-	marked with red squares and circles.	3
3	Statistical analysis of transfer times (C1) for velocity ψ , wall shear stress $\tau_{W,X}$ and temperature I on side at $y = 0$ and heat will with probability density function (better) and cumulating area fractions of transfer below given times (cn)	5
6	heated wan with probability density function (<i>bollow</i>) and cumulative area fraction of transient below given time (iop) .	5
0	The averaged fusser number and relative 0.8% contactice metric and on neared war to raminar milliow case C1	0
/	Comparison of time- and spanwise-averaged Nusseit number (Nul _{span} on heated wall	6
8	Jet deflection over cross flow for cases C1 and C2 in comparison with numerical [9,10,19] and experimental [36]	
0	references in rectangular channels and experimental results with a cylindrical impingement target [16]	6
9	Temporal evolution of spanwise-averaged Nusselt number $\langle Nu \rangle_{span}$ for the turbulent case C2	1
10	Premultiplied power spectral density of pressure in jet shear layers at $(x_{jet} + 0.3D, 3.5D)$ (top) and axial velocity u close	-
	to impingement wall above Nusself maximum at $(x_{Nu,max}, 0.2D)$ (bottom)	/
11	SPOD premultiplied eigenvalues of velocity modes in plane $y = 0$ for jets 2 with low cross flow and 7 with high cross	0
10	now for case C2 with turbulent inflow	8
12	First SPOD mode for velocity in plane $y = 0$ at low, medium and high frequency for jets 2 with low cross flow and 7	0
	with high cross flow for case C2 with turbulent inflow	9
13	POD relative eigenvalues $\lambda_{\text{rel},i} = \sigma_i^2 / \sum_{i=1}^{N} \sigma_i^2$ of first five temperature modes on impingement wall evaluated for single	
	jets and combinations for case C2 with turbulent inflow	9
14	First three POD modes of temperature T for single jets for case C2 with turbulent inflow	10
15	First three POD modes of temperature T for jets 2-4 and jets 5-7 combined for case C2 with turbulent inflow	11
List of	f Tables	
1		2
1	Geometrical properties of the configuration	3

2	Simulated operating conditions	4
3	Area-averaged and maximum wall adjacent cell sizes in wall units (reproduced from [19])	4