



Leveraging a large-scale radiative transfer simulation for an emulator based retrieval scheme of sun-induced fluorescence in HyPlant imagery

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FluoMap: Sun-induced fluorescence (SIF) prediction from different imaging sensors

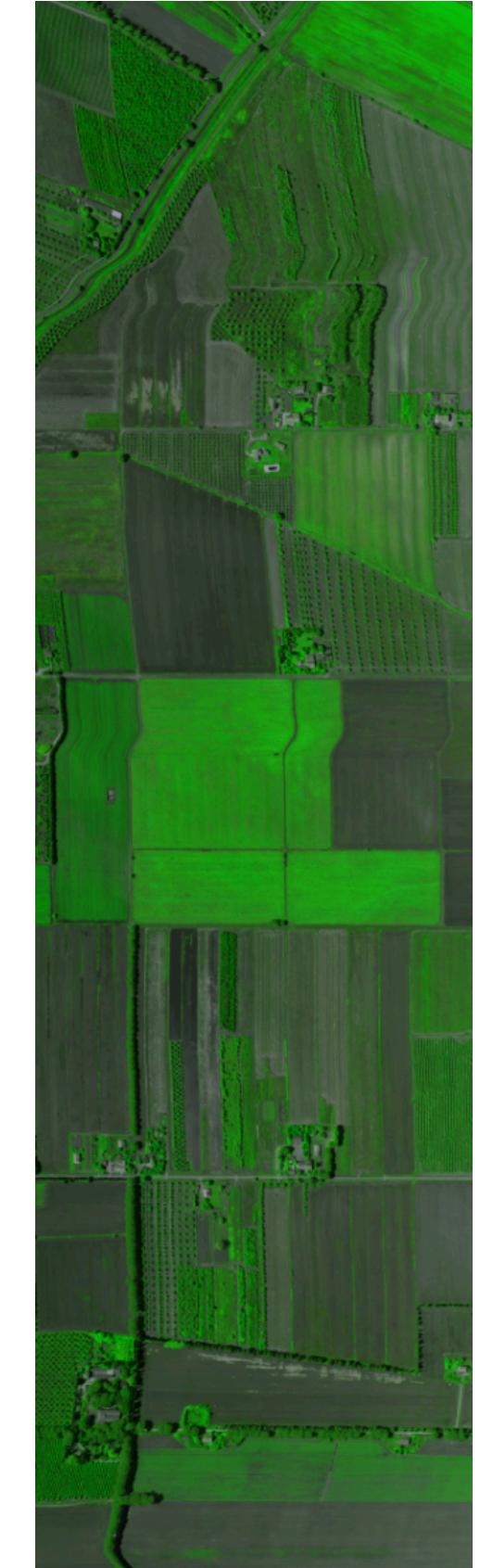
- ▶ SIF estimation from imagery
 - ▶ from **different sensors**: HyPlant, DESIS
 - ▶ at **multiple spatial scales** (0.5m - 2m / 30m)
- ▶ **Model development and intercomparison**
 - ▶ Corresponding data sets acquired in 2020 and 2023

DESIS



Along track

HyPlant FLUO



Along track

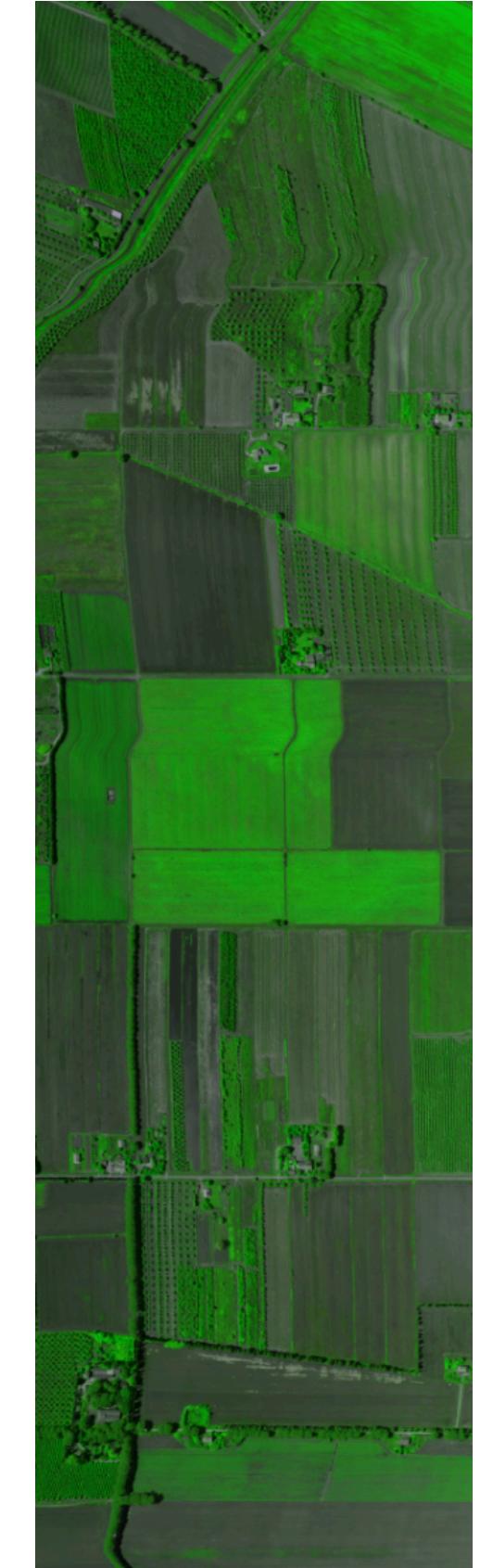
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DESIS

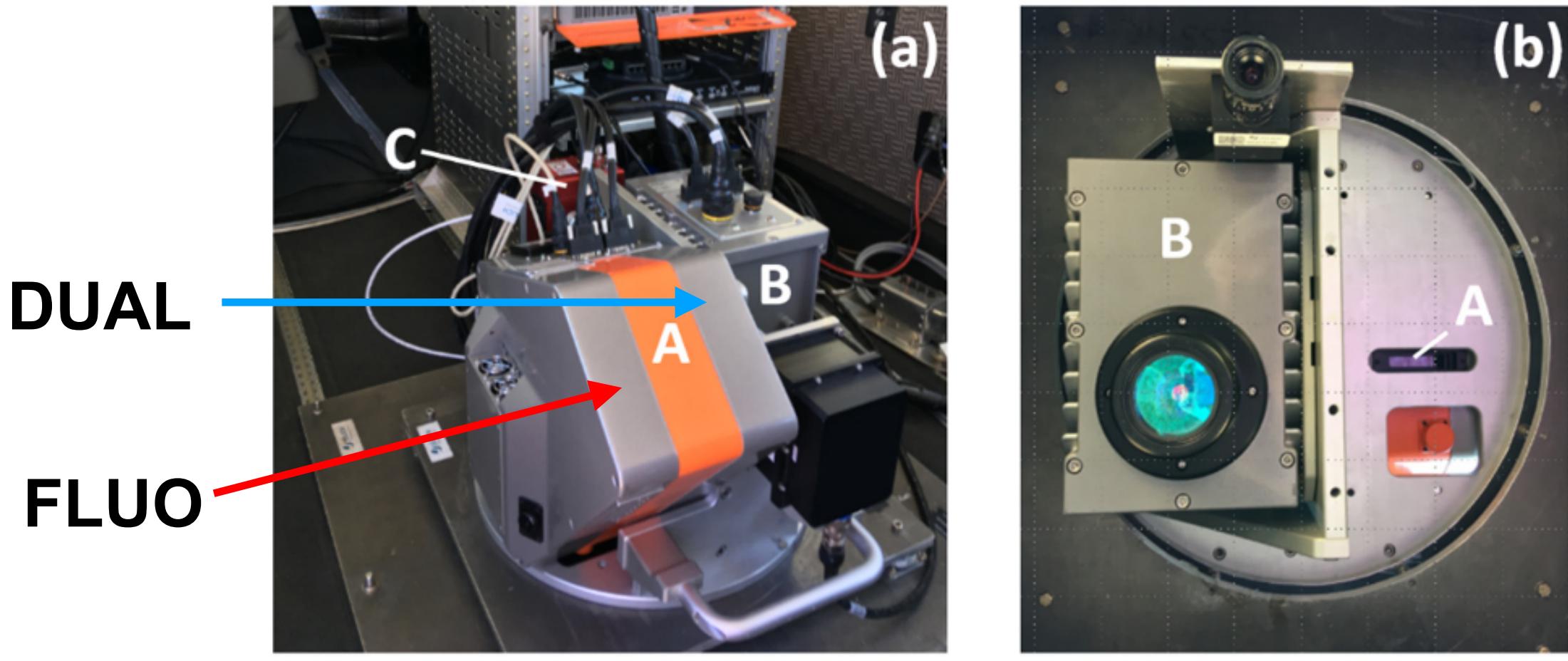


HyPlant FLUO



Model Development with FLEX' Airborne Demonstrator HyPlant

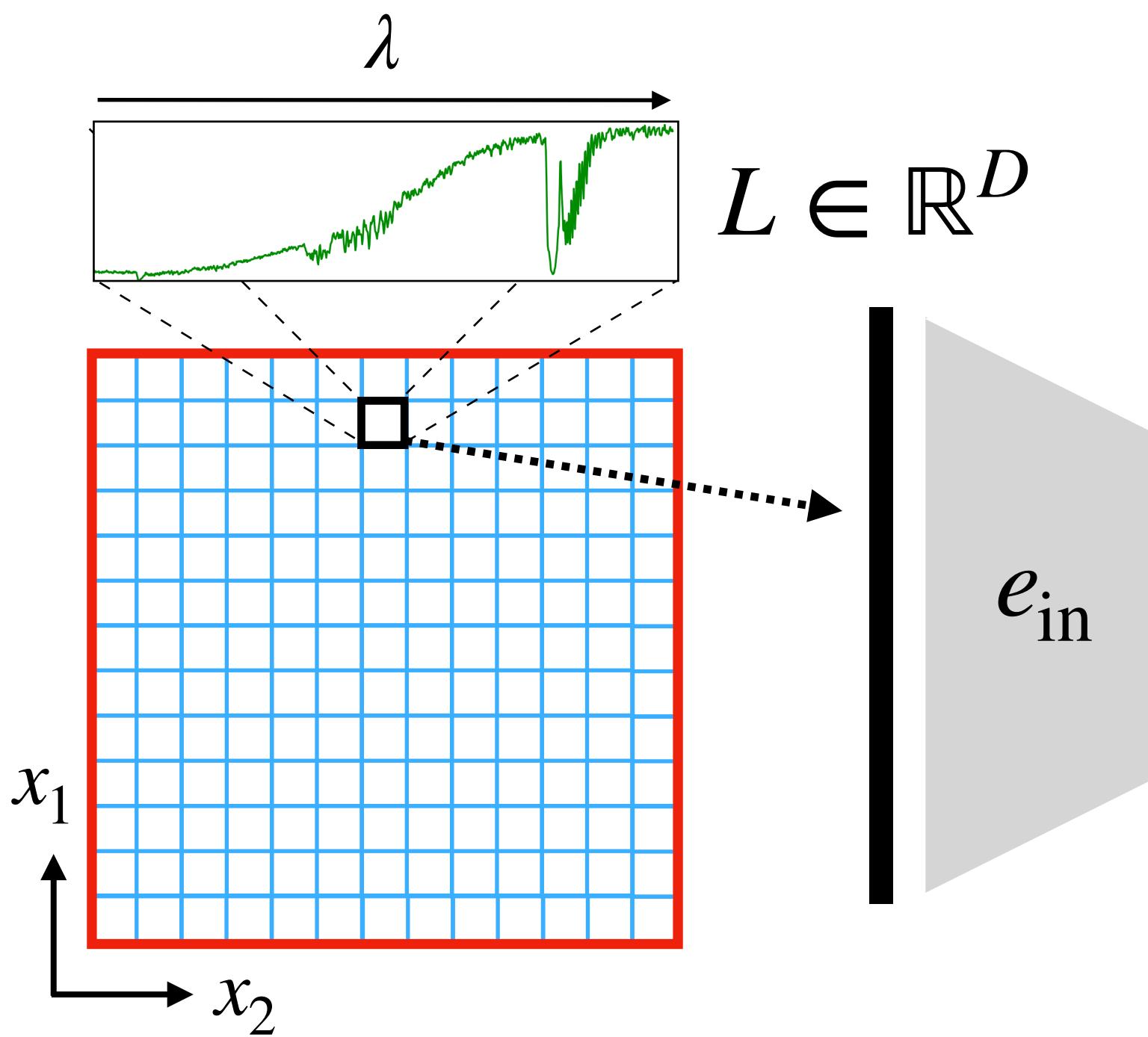
- ▶ FLUO is the **airborne demonstrator** for **FLEX**
- ▶ 0.24 nm FWHM, 0.11 nm SSI
- ▶ 6 years of comparable campaign acquisitions
- ▶ > 770 acquisitions, $384 \times [2000, 10'000]$ px
- ▶ Operational Baseline SIF Retrieval Methods
 - ▶ *Spectral Fitting Method (SFM)*, Cogliati et al. 2019
 - ▶ *Improved Fraunhofer Line Discrimination (iFLD)*, Damm et al. 2022



We extend the Spectral Fitting Method Neural Network (SFMNN) with accurate forward simulation

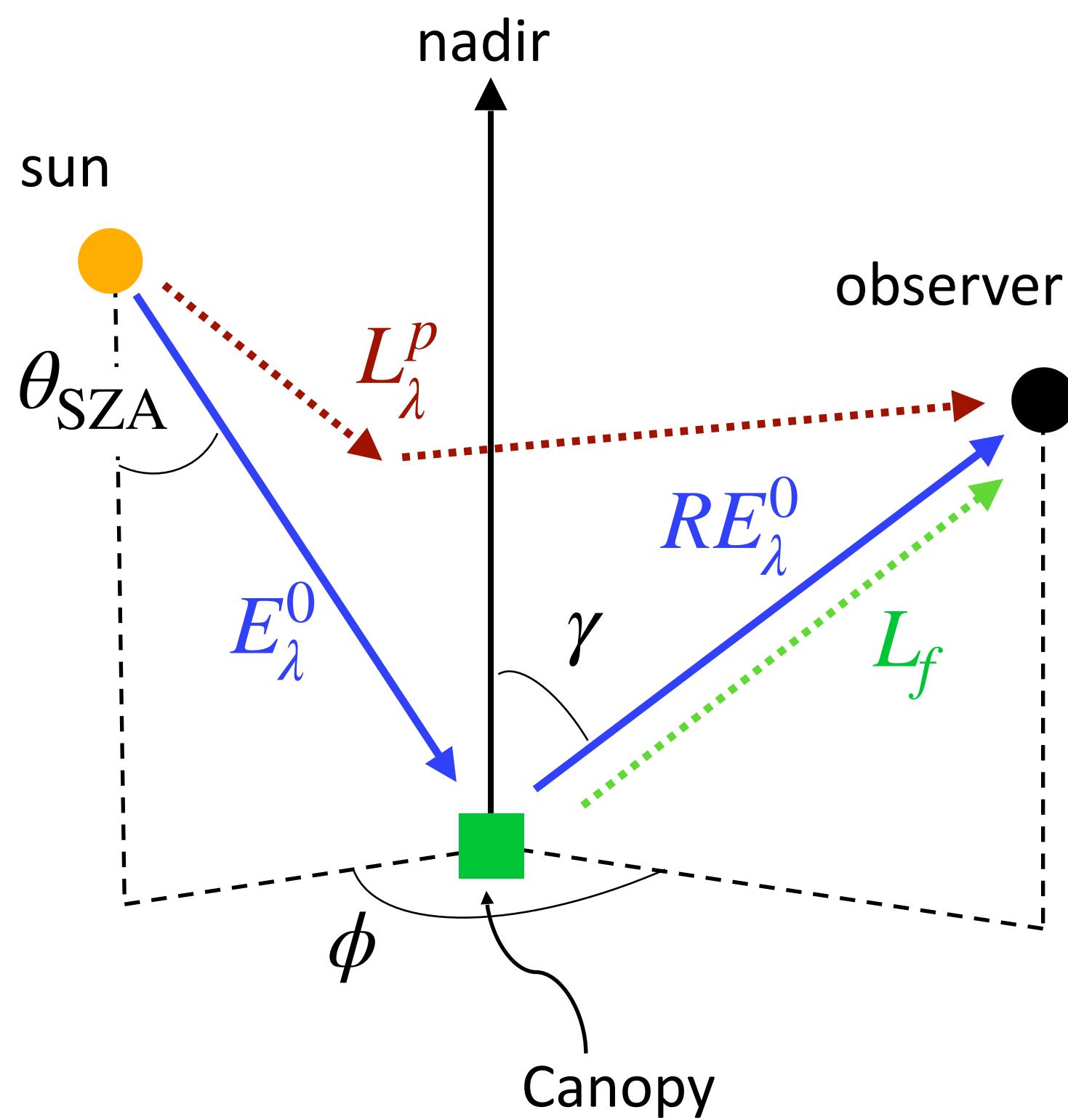
[Buffat et al, IGARSS 2023](#)

Buffat et al. 2024, submitted



- ▶ Train an **encoder** e_{in} and **decode** to physical parameters \underline{p}
 - ▶ Physical, physiological and sensor-related constraints enforced by **loss and architecture**
 - ▶ **Four-stream model** \hat{L} allows for self-supervised training
 - ▶ Yields performance comparable to SFM (Cogliati et al. 2019)
- $\underline{v} \in \mathbb{R}^d \longrightarrow \underline{p} \longrightarrow \hat{L}(\underline{p})$
- ▶ Leverage exact radiative transfer models (RTMs) to improve \hat{L}

Strategy



$$L_\lambda = \left(\frac{RE_\lambda^0}{\pi} + L_f \right) T_\lambda + L_\lambda^p$$

RE_λ^0 : Reflected solar irradiance

L_f : Fluorescence Emission

L_λ^p : Path radiance

$\theta_{\text{SZA}}, \gamma, \phi$: Solar zenith, Viewing and Relative Azimuth Angle

Tight Emulator Integration

Integrate Emulator directly in the predictor network

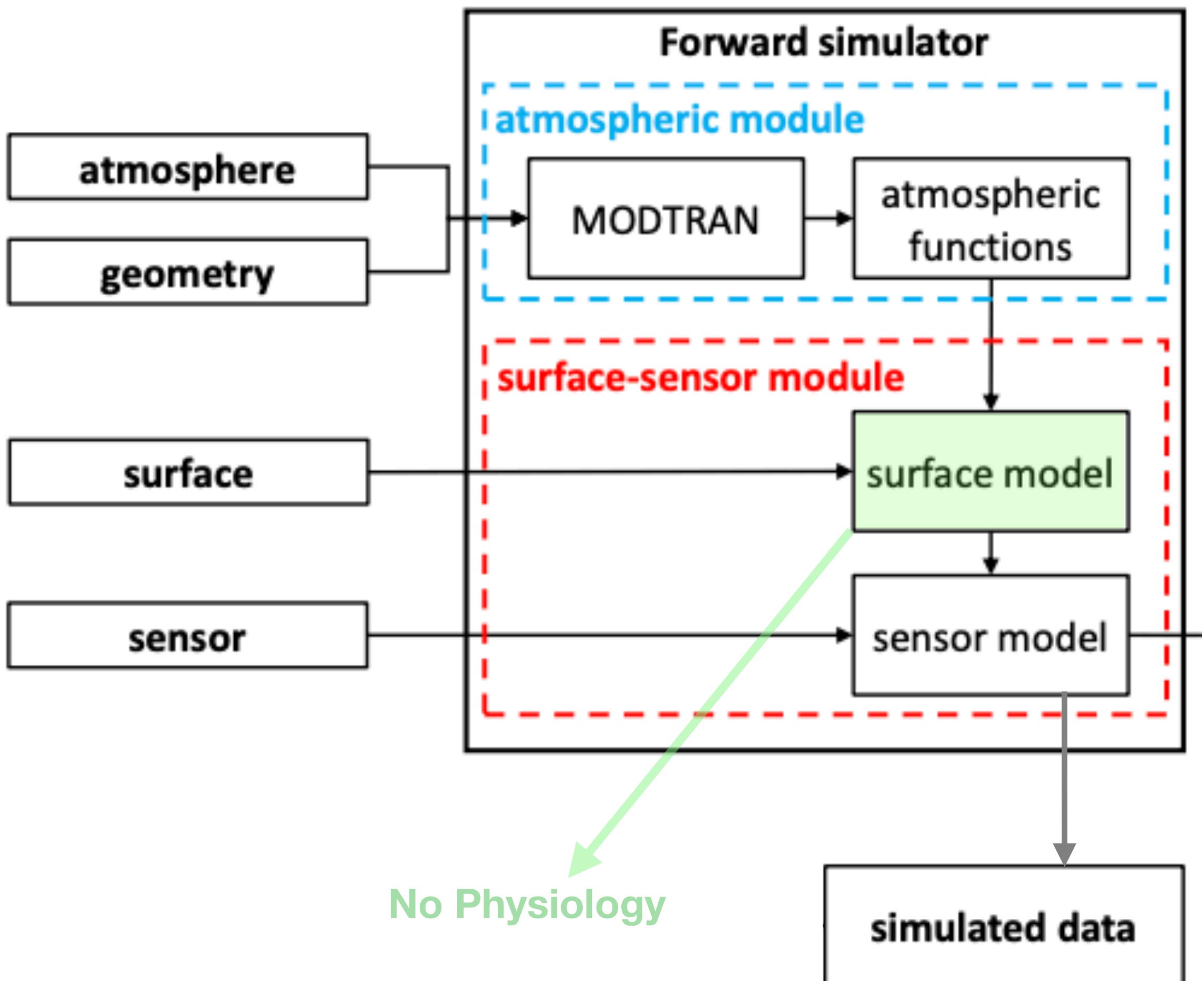
Self-supervised Neural Network Training

Constraint & Loss Formulation

Simulation and emulation of atmospheric radiative transfer and sensor response

- ▶ Dedicated **simulation tool** for radiances around **O₂-A** absorption band
 - ▶ Atmosphere & geometry: MODTRAN6
 - ▶ Reflectance & SIF: parametric models
- ▶ **Dense sampling** of parameter space
 $\sim 1.5 \times 10^7$ HyPlant samples
- ▶ **Emulator: 4th order polynomial** approximates the simulations very well
 - ▶ Fast computation
 - ▶ Easily integrated in a neural network

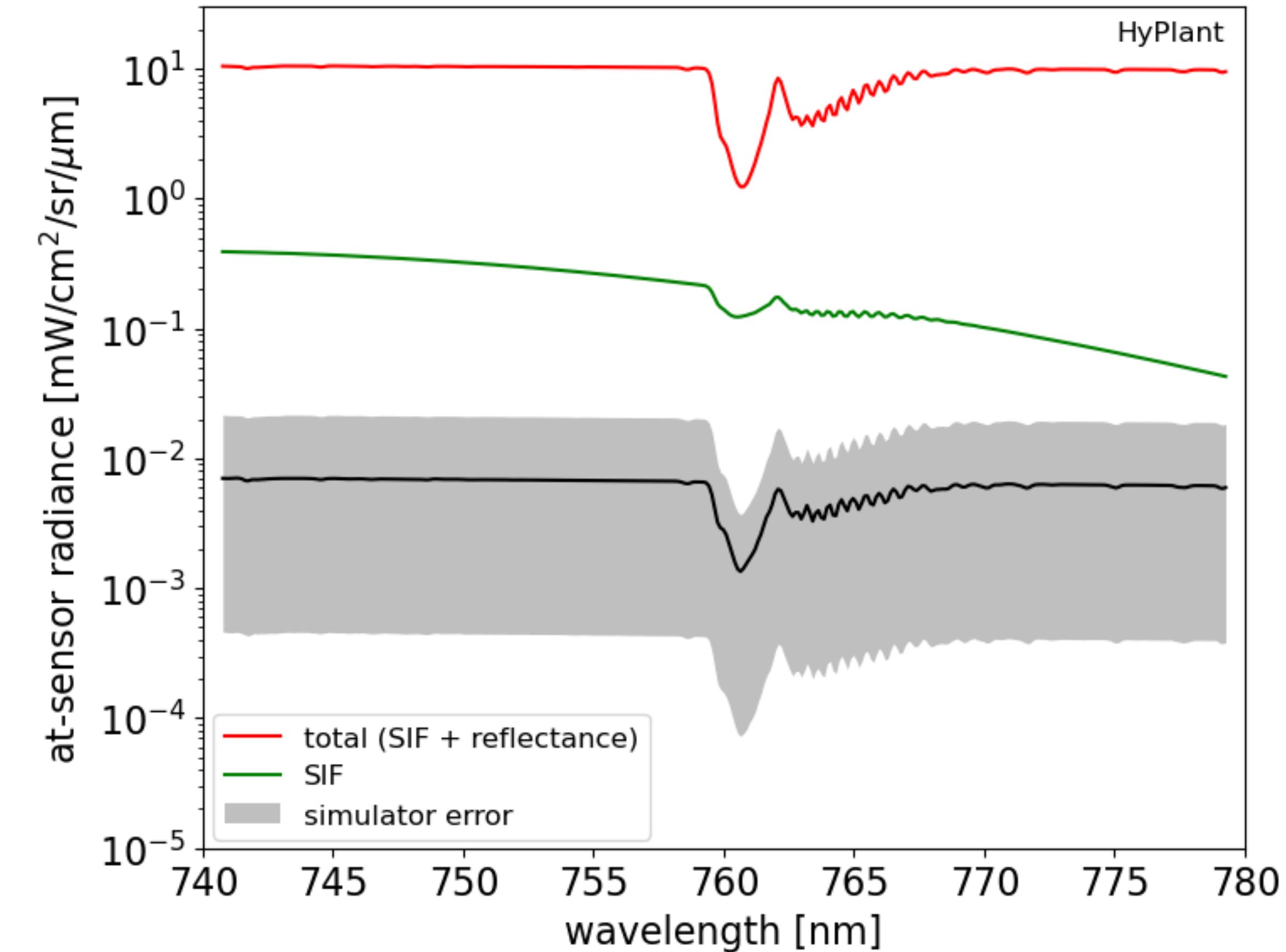
Pato et al. (2024), submitted



Simulation and emulation of atmospheric radiative transfer and sensor response

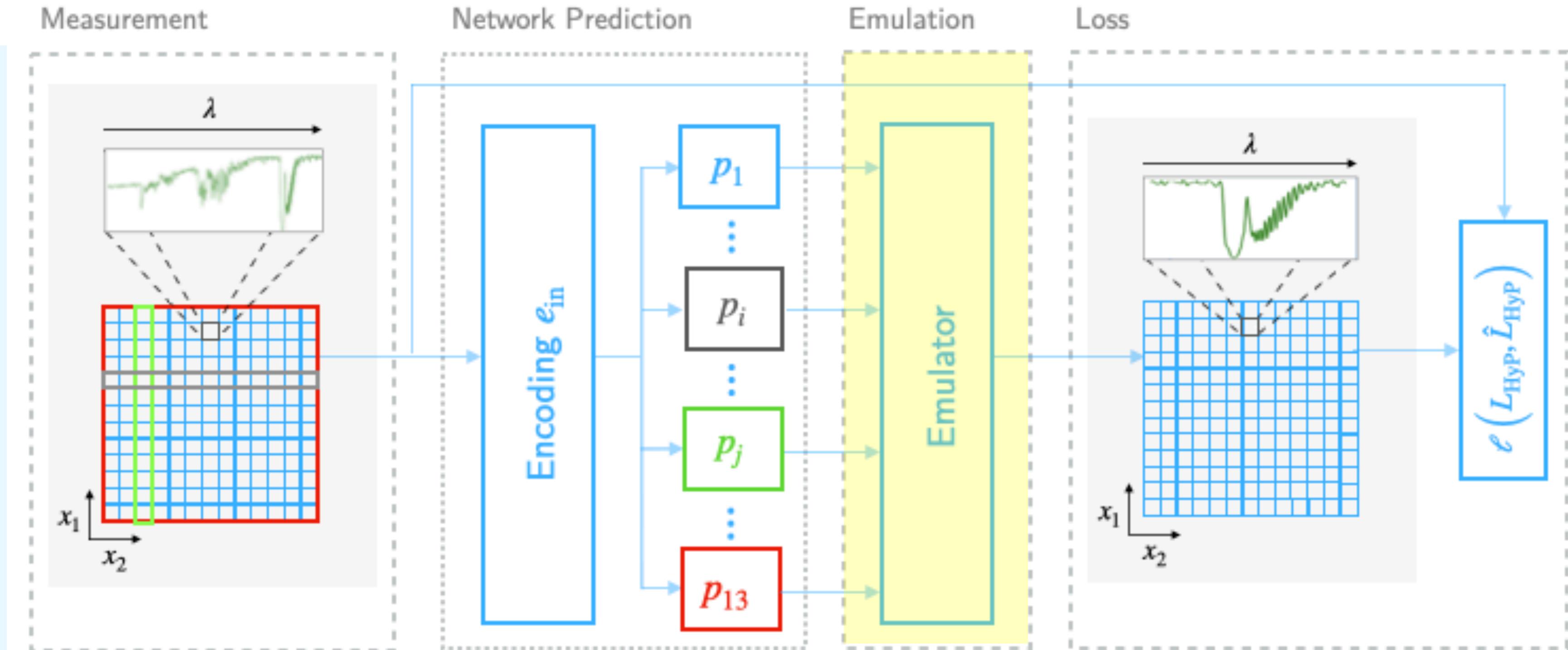
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Emulator integration in a neural network architecture

- ▶ Pre-training + Fine-tuning
- ▶ Specialized **loss**
- ▶ Architectural **constraints**:
 - ▶ Pixel: Reflectance, SIF
 - ▶ Patch: Atmosphere
 - ▶ Across-Track: Sensor



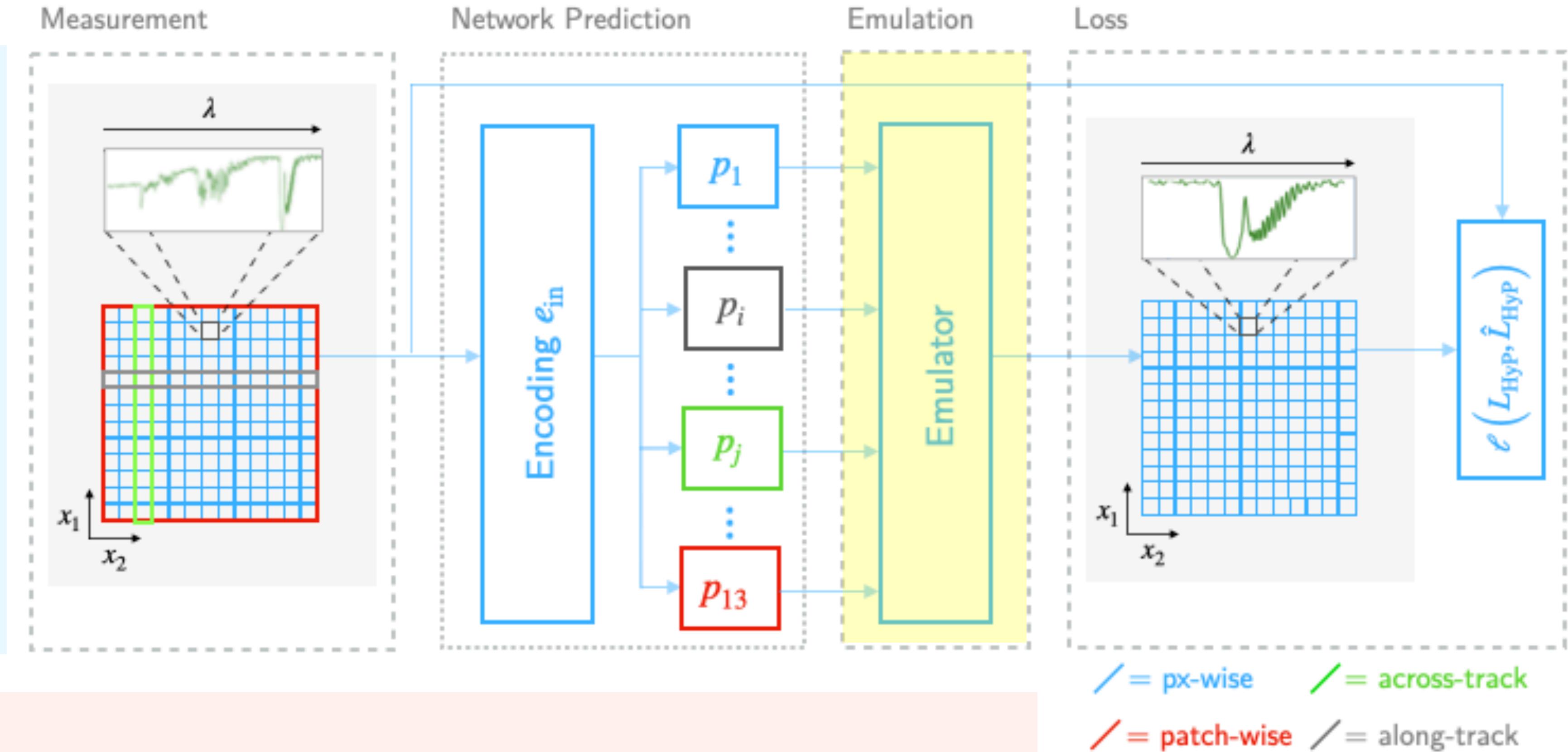
$$\ell(L, \hat{L}) = (\ell_{\text{MSE}} + \gamma_f \ell_f + \gamma_N \ell_{\text{NDVI}}) (L, \hat{L})$$

↑ ↑ ↑

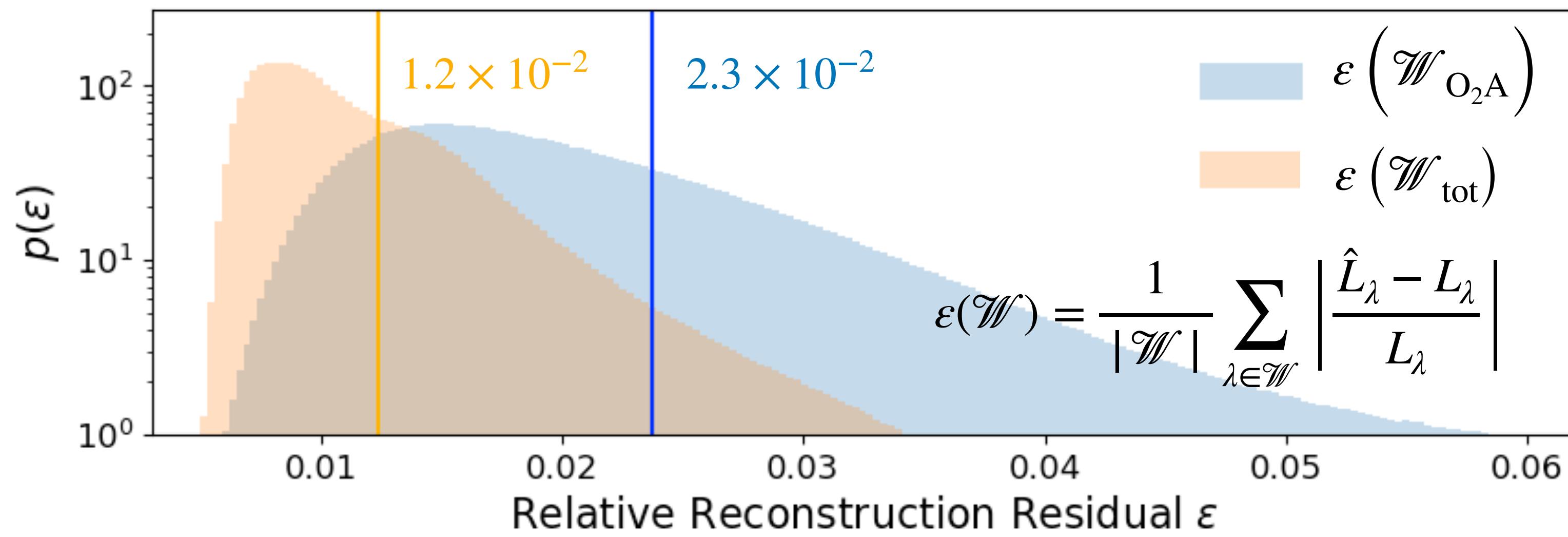
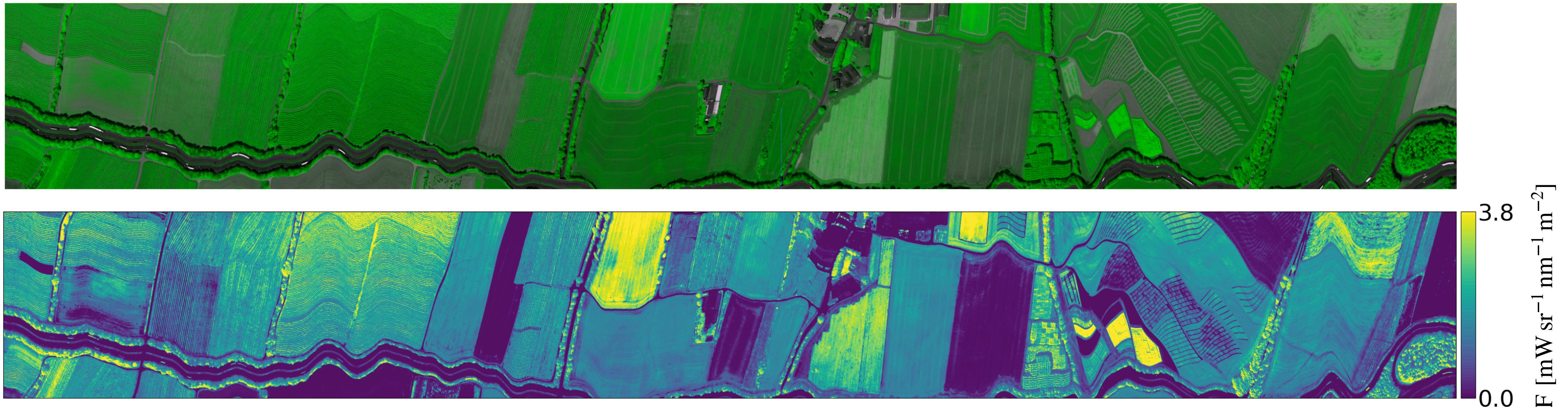
Residual loss SNR-based weighting Physiological prior

Emulator integration in a neural network architecture

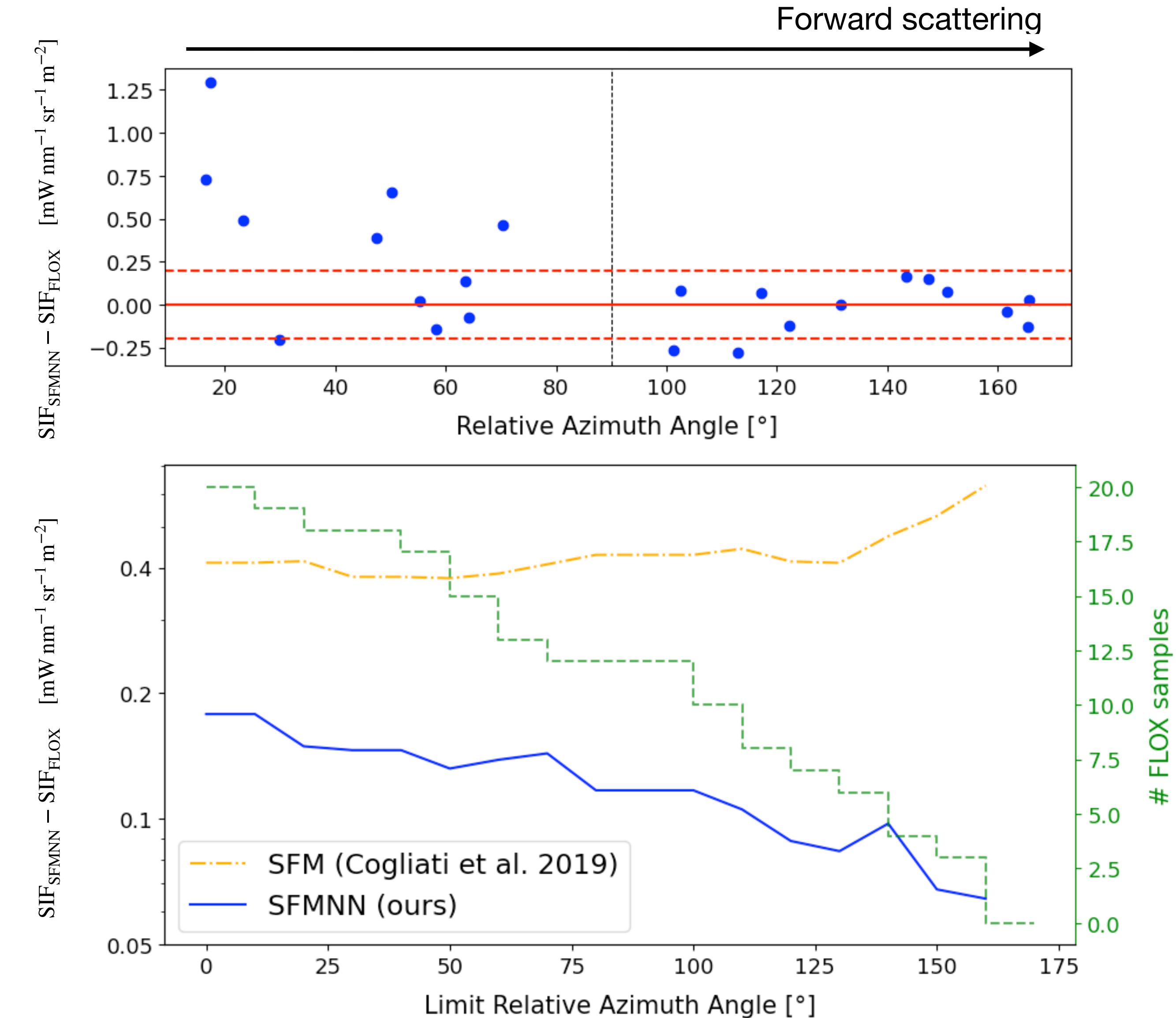
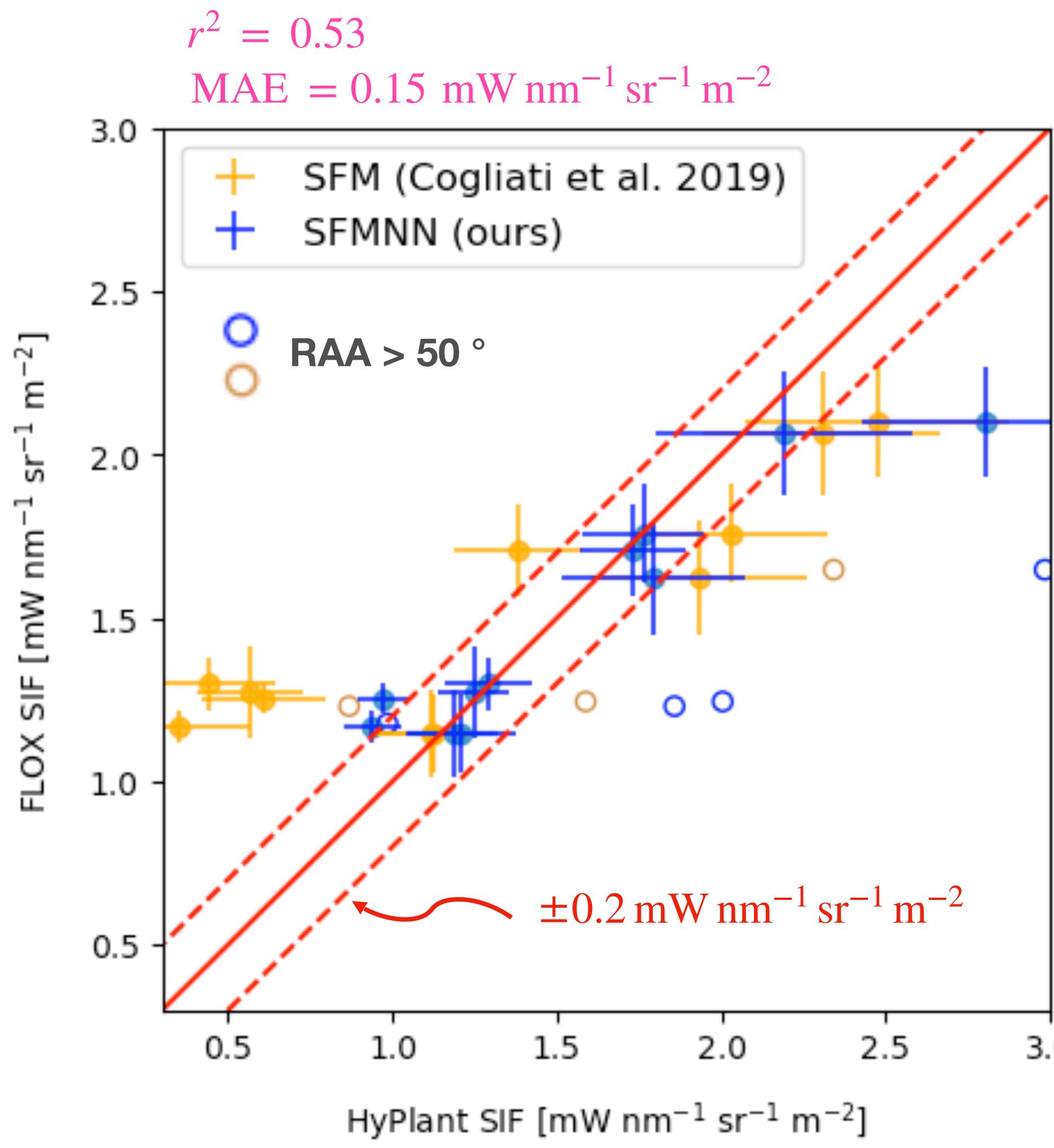
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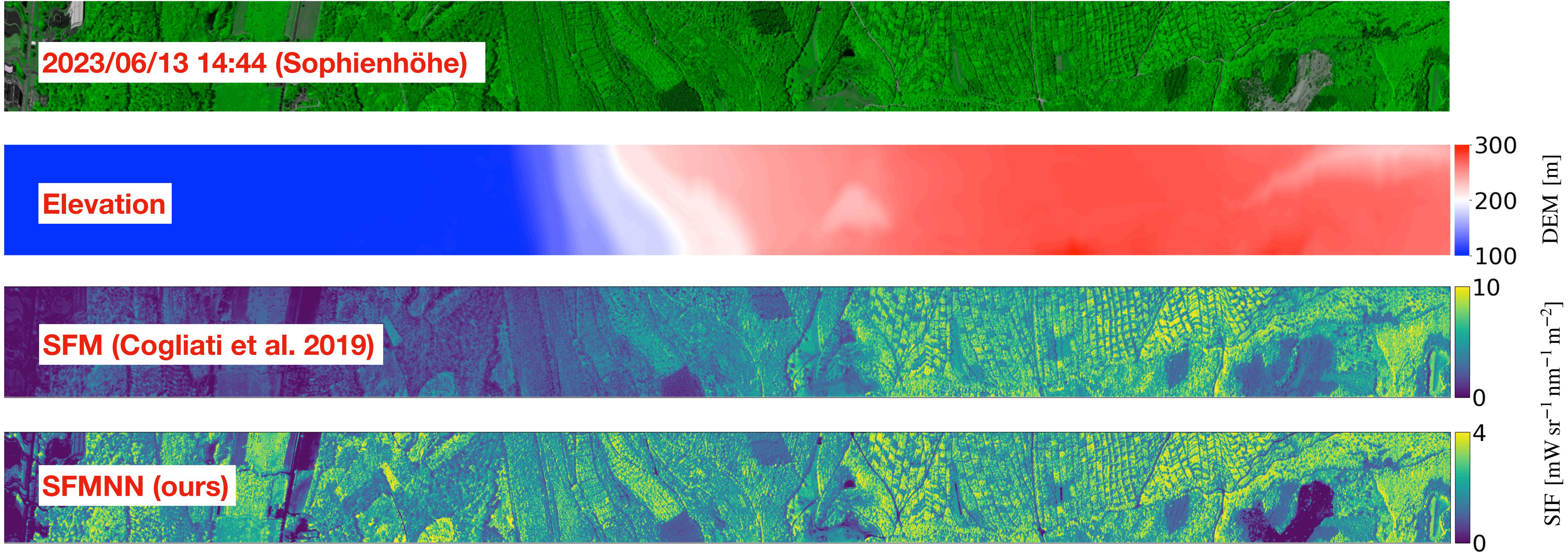
Reconstruction errors



Campaign data set validation with in-situ SIF measurements in a winter wheat field

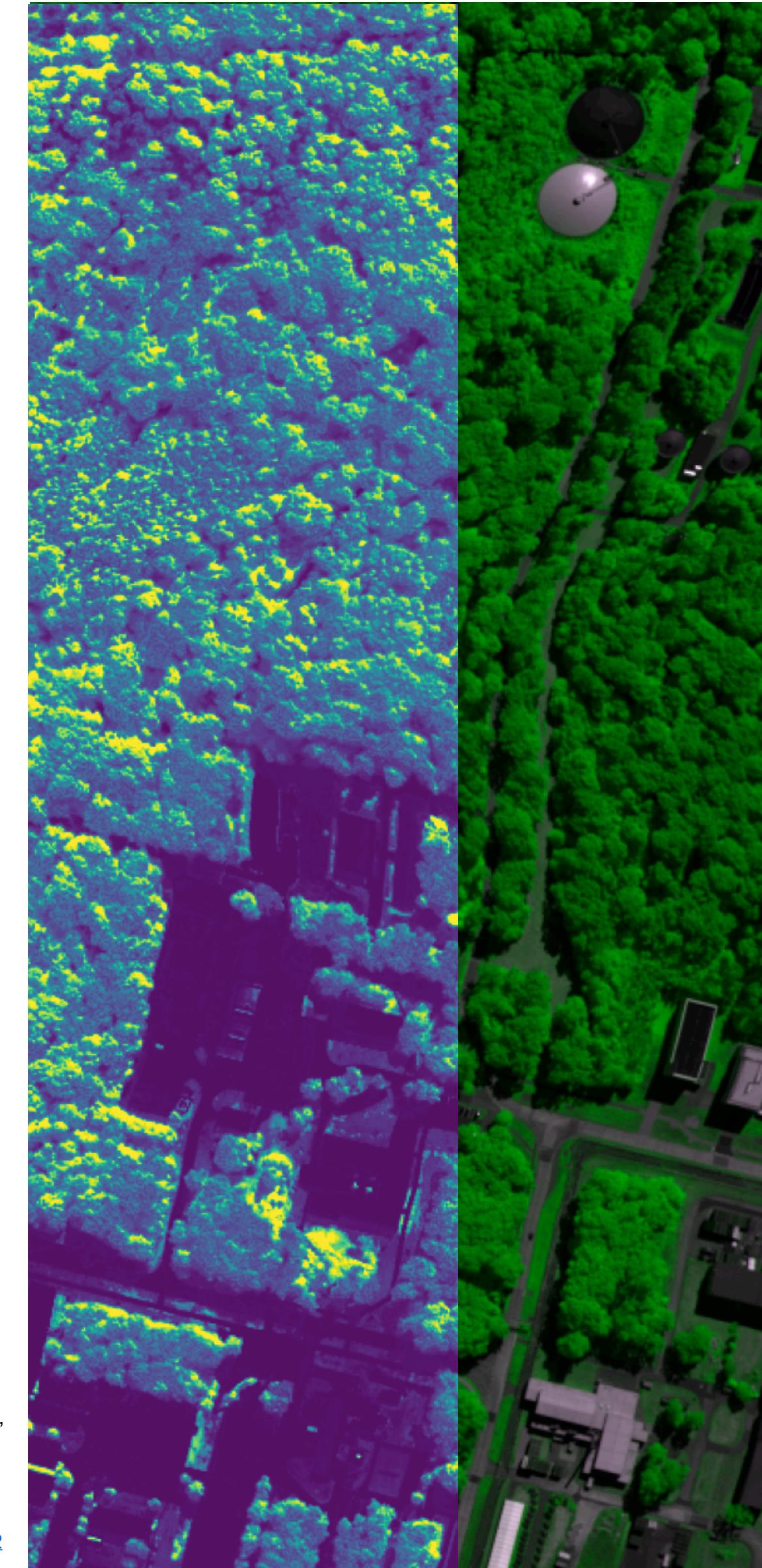


Pixel-wise parametrization allows for compensation of optical path differences in hilly terrain



Conclusion & Outlook

- ▶ The **hybrid SIF retrieval approach improves SIF predictions**
 - ▶ Extending simulation data base extension for larger validation study
- ▶ **Portability to other airborne and spaceborne sensors**
 - ▶ DESIS (see talk by Miguel Pato on Wed 16-17.30, DESIS session)
 - ▶ FLEX
- ▶ After training, the **retrieval model is fast**
 - ▶ Optimization isn't performed for each pixel.
 - ▶ Generalization of trained models across different domains (e.g. different campaigns) has not yet been established systematically.
- ▶ **Pixel-wise model parametrization** is possible without simplifications.
 - ▶ SIF prediction in hilly terrain can be addressed.



Backup

Parametrization

Parameter

Atmosphere	model	mls
	H ₂ O [cm]	0.3–3.0
	O ₃ [DU]	332
	AOT ₅₅₀ []	0.02–0.30
	aerosol model	rural
	g []	—
Geometry	TA [°]	0–20
	SZA [°]	20–55
	RAA [°]	0–180
	h_{gnd} [m]	0–300
	h_{sen} [km]	0.659–0.691 agl
Surface	ρ_{740} []	0.05–0.60
	s [nm ⁻¹]	0–0.012
	e []	0–1
	F_{737}/F_0	0–8
Sensor	δ_{CW} [nm]	[-0.080, +0.080]
	δ_{FWHM} [nm]	[-0.040, +0.040]