

CHIME LEVEL 2A AND 2B: ATMOSPHERIC CORRECTION AND HIGHER-LEVEL PROCESSING

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16.04.2024

















Objectives (L2A)

Copernicus Hyperspectral Imaging Mission for the Environment (CHIME)

L2 Algorithms & Processors Prototyping & Development (CHIME-L2)

CEOS ARD Level 2A land & water – open source software

Level 2S (based on Level 1B), Level 2A (based on Level 1C (default) or Level 2S), (DLR with Telespazio France, UV)

Level 2H/F (harmonization & fusion CHIME and SBG based on Level 1C) (Telespazio France)

Level 2A Operational Processor (ACRI-ST)

TOA to BOA, pixel classification, e.g. clouds, AOT/W\

evel 2A open source software

- Uncertainties (UZH with NPL)
- Integration on CEM-PAL (ACRI-ST)
- Cal/Val (L2A: Planetek
- (generic) Open Source (modular) Library (for atmospheric correction) (DLR)

The Copernicus Hyperspectral **Imaging Mission For The** Status

Marco Celesti, Kevin Alonso, Valentina Boccia, Lauren Despoisse, Antonio Gabriele, Ferran Gascon, Nafiseh Ghasemi, Claudia Isola, Giuseppe Ottavianelli, Anke Schickling, Helene Strese, Heidrun Weber, Jens Nieke

Environment (CHIME): Current

Them.Sess. 2-1: EnMAP's first two vears in orbit-current status and recent activities I Them.Sess. 2-4: EnMAP's first two vears in orbit-current status and recent activities II

Them.Sess. 2-7: Status and applications of the PRISMA mission at the turn of 5 years in orbit

Them.Sess. 2-6: Advances in DESIS data products and applications



Them.Sess. 2-8: Results from the EMIT imaging spectroscopy mission on the International Space Station

Objectives (L2B)

Copernicus Hyperspectral Imaging Mission for the Environment (CHIME)

L2 Algorithms & Processors Prototyping & Development (CHIME-L2)

■ Level 2B – open source software

improved masking (DLR)

canopy & leaf (UV) ↓

Latest Status of the Vegetation Traits Retrieval Processor and Models in the Context of Chime Mission Preparation

José Luis García Soria, Miguel Morata, Jochem Verrelst, Ana Belén Pascual-Venteo, Katja Berger, Cinzia Panigada, Giulia Tagliabue, Ana María Sánchez Montero

■ soil & mineralogy (GFZ) →

Progress in the Development of the L2B Mineral Module for the CHIME E2E Simulator (CHEES).

<u>Karl Segl</u>, Stéphane Guillaso Guillaso, Saeid Asadzadeh, Massimo Musacchio, Ana Maria Sánchez Montero

Progress in the Development of the L2B Soil Module for the CHIME-E2E Simulator

Stéphane Guillaso, Karl Segl, Robert Milewski, Stefano Pignatti, Raffaele Casa, Ana Maria Sánchez Montero

■ Level 2B – open source software

- Uncertainties (UZH with NPL)
- Integration on CEM-PAL (ACRI-ST)
- Cal/Val (L2B: CzechGlobe)
- (generic) Open Source (modular) Library (DLR)

The Copernicus Hyperspectral Imaging Mission For The Environment (CHIME): Current Status

Marco Celesti, Kevin Alonso, Valentina Boccia, Lauren Despoisse, Antonio Gabriele, Ferran Gascon, Nafiseh Ghasemi, Claudia Isola, Giuseppe Ottavianelli, Anke Schickling, Helene Strese, Heidrun Weber, Jens Nieke



Them.Sess. 2-1: EnMAP's first two years in orbit- current status and recent activities I Them.Sess. 2-4: EnMAP's first two years in orbit- current status and recent

activities II

Them.Sess. 2-7: Status and applications of the PRISMA mission at the turn of 5 years in orbit

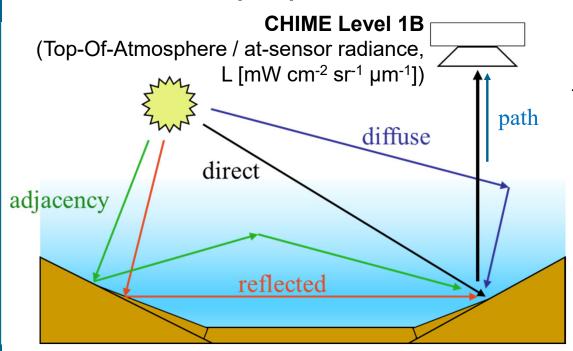




Them.Sess. 2-8: Results from the EMIT imaging spectroscopy mission on the International Space Station



CHIME L2A (1/3)



$$L = L_{path} + L_{direct} + L_{diffuse} + L_{reflected} + L_{adjacency}$$

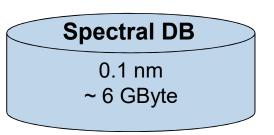
CHIME Level 2A

(Bottom-Of-Atmosphere / ground reflectance, ρ [unitless] [0;1])

$$\rho = f(L, L_{path}, E_{direct}, T, E_{diffuse}, DEM, ...)$$



Radiative transfer simulations (based on libRadtran) & TSIS-1 solar irradiance spectra (used by Sentinel-2)

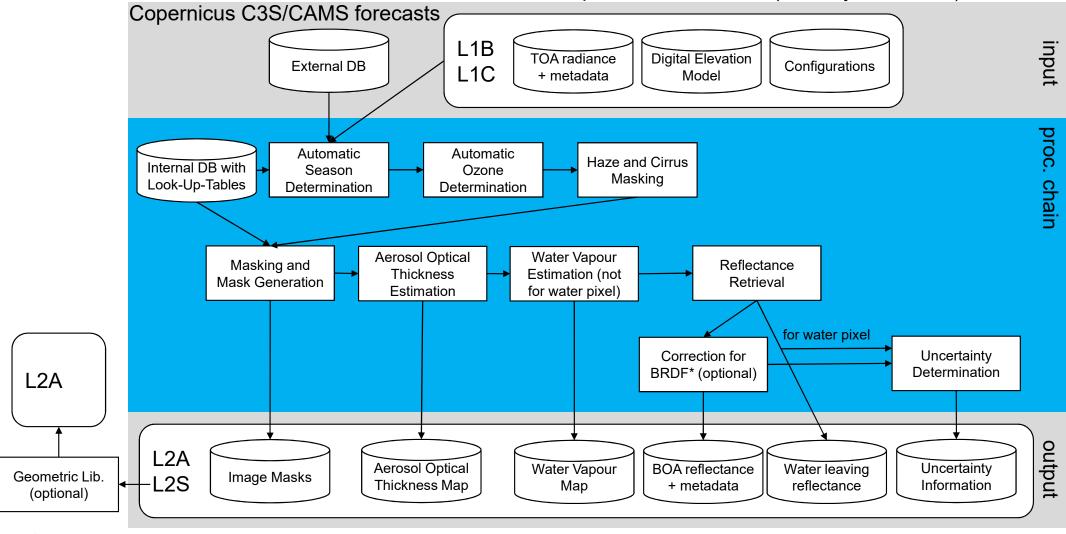


(Atmospheric) Look-Up-Tables

Parameter	Range [units]	Grid points [units]	
Visibility	7, 10, 15, 23, 40,	80, 120 [km]	
Solar zenith angle	0. – 80. [°]	10 [°]	
View zenith angle	0. – 20. [°]	10 [°]	
Relative azimuth	0 – 180. [°]	30 [°]	
Water vapor column	0.4, 1.0, 2.0, 2.9,	4.0, 5.0 [cm]	
Ground elevation	0.0, 0.7, 1.5, 2.5, 4.0 [km]		

CHIME L2A (2/3)

Copernicus 30 m DEM (used by Sentinel-2)



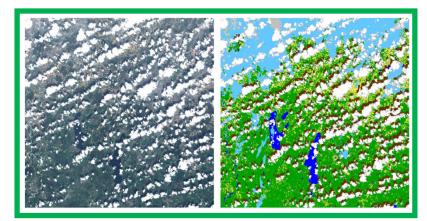
Schedule & Software



△ Phases	1780 Tage	Mon 06.11.23		
Phase 1	482 Tage	Mon 06.11.23		DLR
Phase 2	1038 Tage	Mit 10.09.25		/ DLR
Phase 3	260 Tage	Mon 03.09.29		
■ Milestones	1520 Tage	Mon 06.11.23		
Prep. Meeting (MS1)	1 Tag	Mon 09.10.23		
KO (MS1)	1 Tag	Mon 06.11.23	ESI	
SRR1	1 Tag	Die 23.01.24		DLR [CHIME L2A Processor Requirement Baseline] established
PDR (MS2)	2 Tage	Mon 07.10.24		[Report on CHIME L2A ATBD (Algorithm Theoretical Basis Document)] next,
System CDR (MS3)	2 Tage	Mon 02.12.24		Europe
CDR (MS4)	2 Tage	Mon 08.09.25		onsidering results of ACIX/CMIX
SRR2	1 Tag	Mon 08.12.25		DLR
FAT1 (with training) (MS5)	2 Tage	Mon 25.05.26		■ DLR
OSAT1 (MS5)	1 Tag	Mit 27.05.26		I to the second of the second
FAT2 (MS6)	1 Tag	Fre 26.11.27		DLR
OSAT2 (with training) (MS6)	2 Tage	Mon 29.11.27		and the control of th
ORR (MS7)	2 Tage	Fre 01.09.28		■ Europe
Launch	0 Tage	Fre 01.12.28		◆ 01.12
IOCR	2 Tage	Mit 30.05.29		■ Europe
FR (MS8)	1 Tag	Fre 31.08.29		ESRIN

L2A PROtotype processors & related OpenSourceLibrary

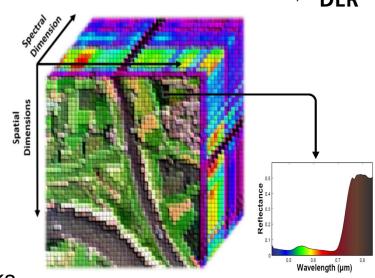
- 02.12.2024 (System CDR), 08.09.2025 (CDR),
 27.05.2026 (FAT1/OSAT1), 26.11.2027 (FAT2/OSAT2)
- L2A OPerational processorS
 - 27.05.2026 (FAT1/OSAT1), 26.11.2027 (FAT2/OSAT2)
- L2H/F processor
 - 26.11.2027 (FAT2/OSAT2)
- L2B processor & related OpenSourceLibrary
 - 27.05.2026 (FAT1/OSAT1), 26.11.2027 (FAT2/OSAT2)
- Cal/Val tools
 - 27.05.2026 (FAT1/OSAT1), 26.11.2027 (FAT2/OSAT2), 01.09.2028 (ORR)



CHIME L2A (3/3)

- Combined land & water processor
- Most algorithms already successfully applied on other hyperspectral sensors (e.g. EnMAP)
 for retrieval over land
- Most algorithms already consistent and harmonious to Sentinel-2
- Several improvements required and planned:
 - Use of Copernicus C3S/CAMS forecast models as fallbacks
 - Masking, based on Sentinel-2, but considering CEOS ARD, modified algorithms for cloud and cloud shadows, and more bands to avoid masks confusions
 - Remark: pixels classified to be used for the atmospheric correction algorithms
 - AOT retrieval over water and water leaving reflectance
 - Retrieval for inter-sensor comparisons, e.g. BRDF correction
 - Rigorous uncertainty propagation from L1B/L1C to L2A (and L2B) based on sensitivity analysis

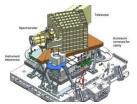




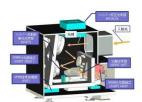
CHIME L2H/F



- Provide CHIME-like surface reflectance from different hyperspectral missions, in particular SBG, namely using SBG-VSWIR products as additional input
 - for long-term time-series covering timespan of several hyperspectral missions, e.g. EnMAP
 - for denser time-series covering mitigation of data unavailability, e.g. SBG, due to cloud cover



EMIT (JPL) (2022 -)



HISUI (Japan) (2019 -)



DESIS (TBE & DLR) (2018 -)



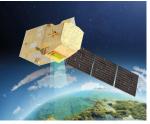
EnMAP (DLR) (2022 -)



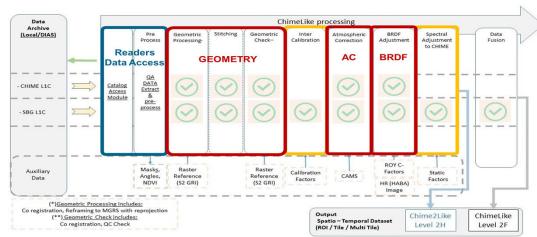
PRISMA (ASI) (2019 -)



SBG-VSWIR (NASA) (~2027)



CHIME (Copernicus) (~2028)



CHIME L2B



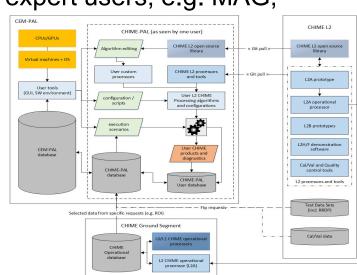
CHIME L2A / L2S Data + Uncertainty @ BOA ref CHIME L2A / L2S Masks (saturation / defective pix., cloud, snow, land/water, ...) (if required) Improved Masking Processor Static Auxiliary Masks (thematic masks of soil & vegetation fractional cover, urban areas (tbd)) (e.g., World Settlement Footprint) Internal L2A / L2S + Uncertainty @ BOA Ref with improved thematic masking (as L2A / L2S plus fractional cover masks for vegetation & soil) + Uncertainty **L2B Vegetation Processor** L2B Soil Organic Carbon Processor L2B Mineral Processor **HPPP** Kaolinite Abundance **Vegetation Priority Traits** Soil Organic Carbon (SOC) Leaf & Canopy Level + Uncertainty + Uncertainty (CNC, CWC, LNC, LWA, LMA) High + Uncertainty for each product Input Output L2B data quality L2B data quality **Priority** Preselection of pure dry bare Prototype ARTMO Output: L2BV products Kaolinite SOC of kaolinite bearing pixels **Products** classification) Uncertainty L2BV Processor SOC retrieval model database **Auxiliary Data** Auxiliary Data retrieval

CHIME-L2

CHIME-L2 OpenSourceLibrary and CEM-PAL

Input / Output Modules pen Source L2A Modules L2H/F Modules L₂B Modules **Utility** Modules

- (generic) Open Source (modular) Library (in particular, for atmospheric correction) to provide the users
 - visibility of and access to the CHIME L2 processing
 - ability to adopt CHIME L2 processing to their needs
- ability to integrate L2 processing for their missions in an open and transparent manner throughout the mission lifetime and beyond.
- CEM-PAL to provide the expert users, e.g. MAG,
 - virtual environments to efficiently realize and test algorithms
 - processing capabilities for CHIME L2 products
 - direct interfaces to CHIME L2 processors for future exploitation



CHIME L2 Cal/Val

- Plans, catalogues, tools and reports for products of CHIME L2 processors
- Plans (with test sites selection and procedures) for all phases from beginning and evolving
 - Pre-flight phase
 - Synthetic data from E2E simulations
 - Products from similar missions, e.g. EnMAP, PRISMA
 - Airborne measurements
 - Commissioning phase
 - CHIME L2 products
 - Cross-Comparison with other satellites
 - Operational phase
 - CHIME L2 products
 - Cross-Comparison with other satellites
 - Both phases
 - Other Cal/Val initiatives, e.g. ESA campaigns
 - L2A: RadCalNet, HYPERNETS, AERONET (OC)
 - L2B: observation networks (ICOS, NEON); campaign data; databases (ECOSIS, TRY, LUCAS, ESDB)

- Image, Masks, Maps and Metadata of Products
 - L2A
 - L2S
 - L2H/F
 - L2B Vegetation
 - L2B Soil Organic Carbon
 - L2B Kaolinite



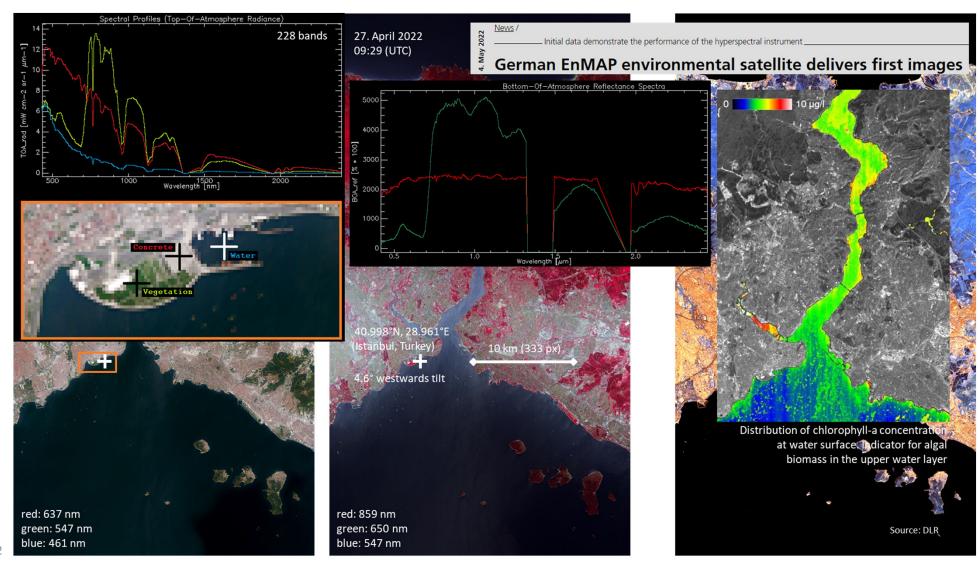












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