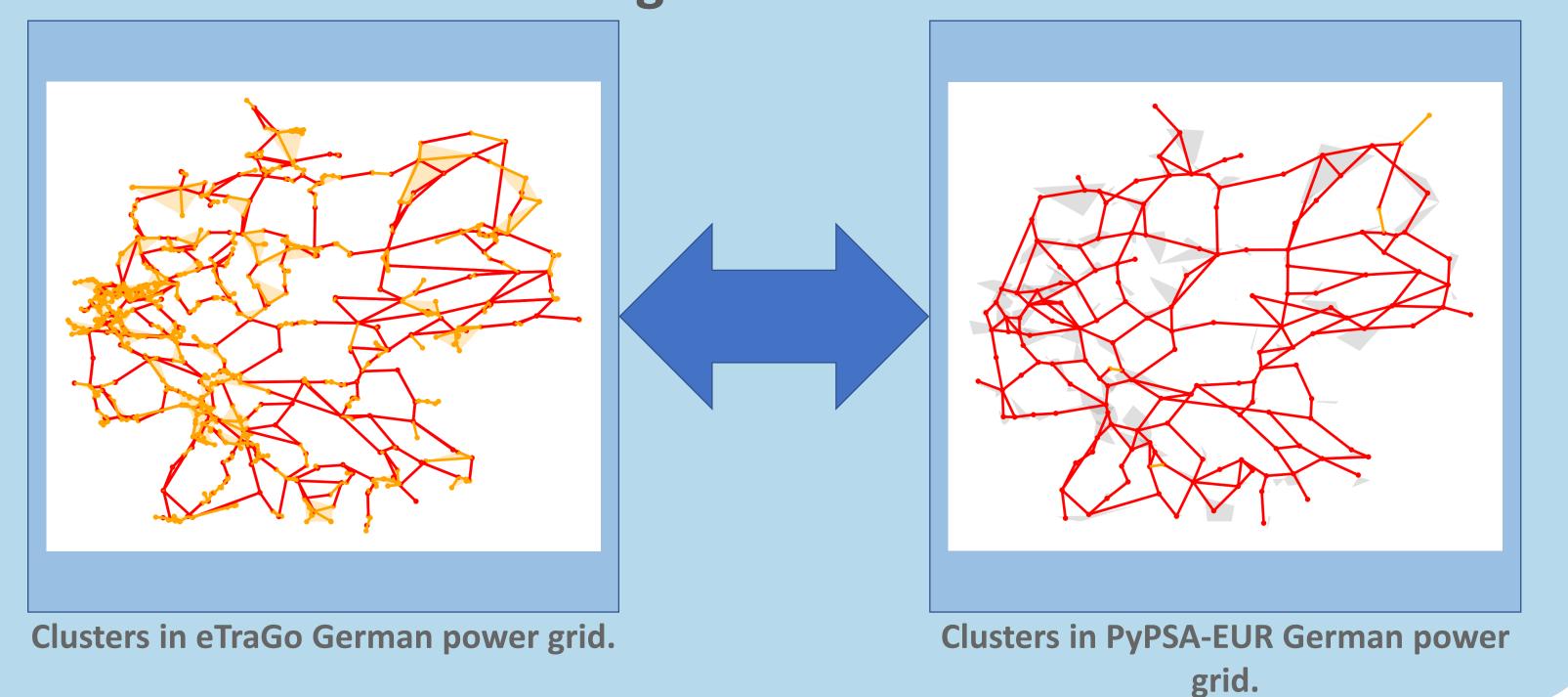
GRID MATCHING TOOL Enabling the interaction between georeferenced grid models

Oriol Raventós ¹, Abhilash Bandam ², Theresa Groß ², and Ontje Lünsdorf ¹ https://gitlab.com/dlr-ve-esy

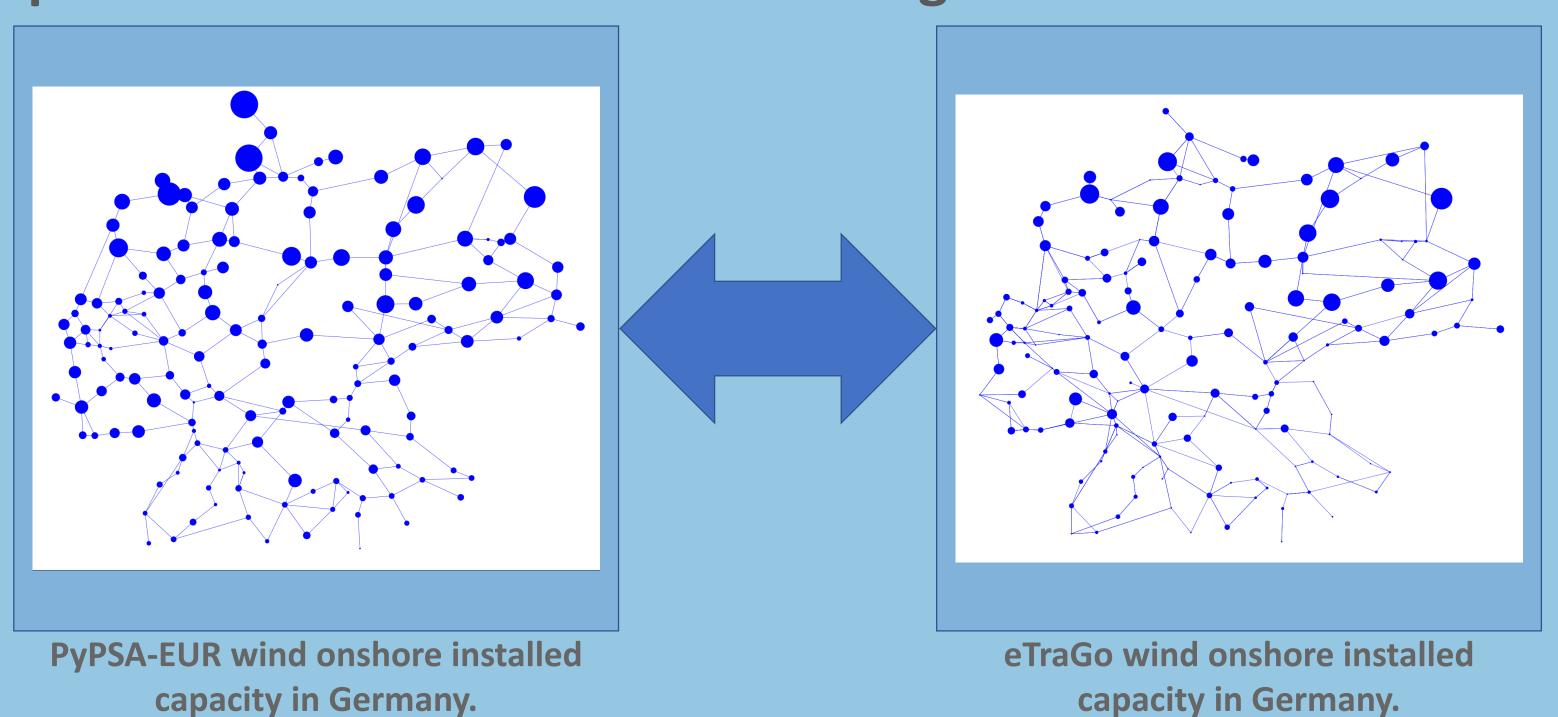
Gird Matching: Identification of clusters of nodes between two grid models

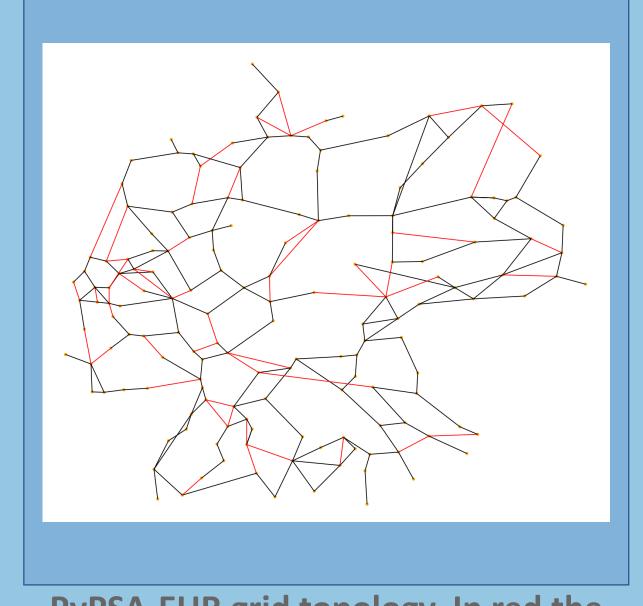
Method to match grids A and B:

- Let $f: A \to B$ assign to each node in A the closest node in B (using the Euclidean distance) and $g: B \to A$ vice versa.
- Nodes a = g(f(a)) in A are in one-to-one correspondence with nodes b = f(g(b)) in B. They are the **centers** of the clusters.
- The rest of the nodes are assigned to a center using the shortest path in each grid.



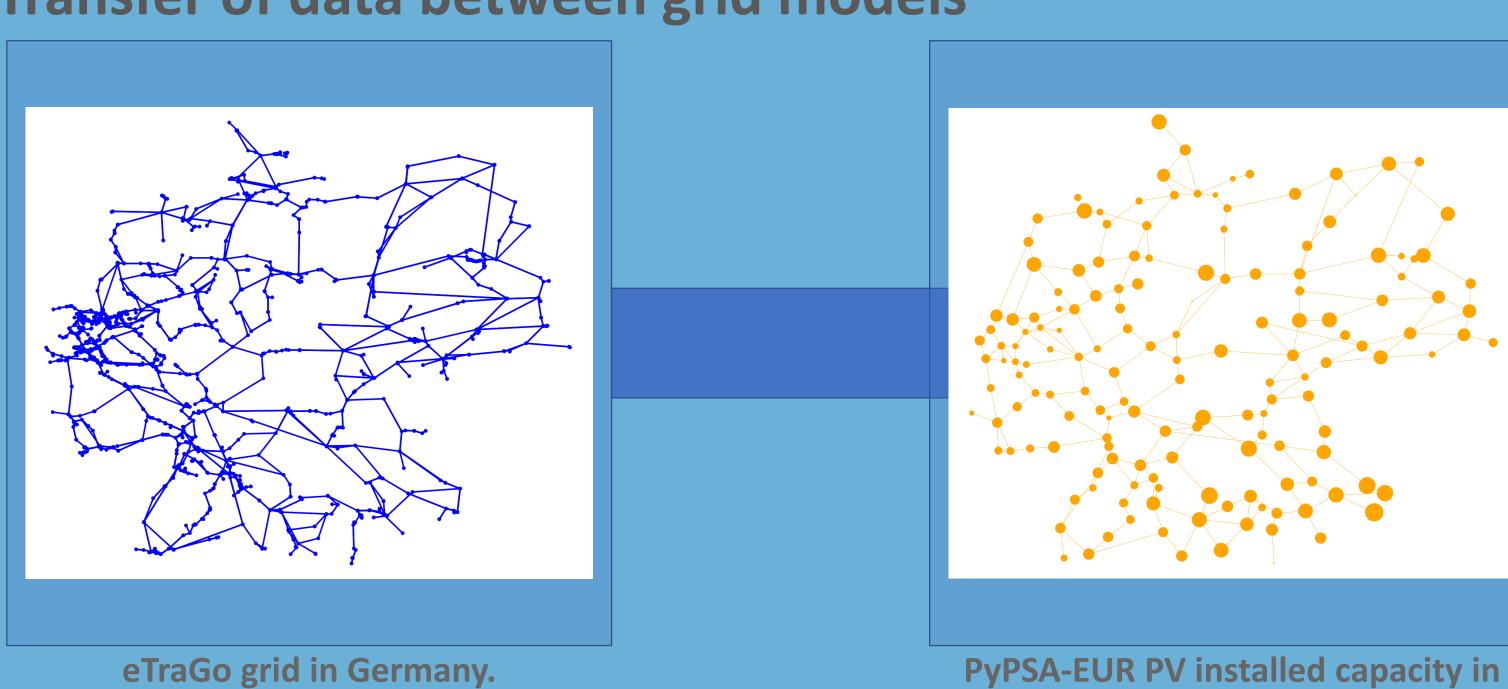
Comparison of data between different grid models

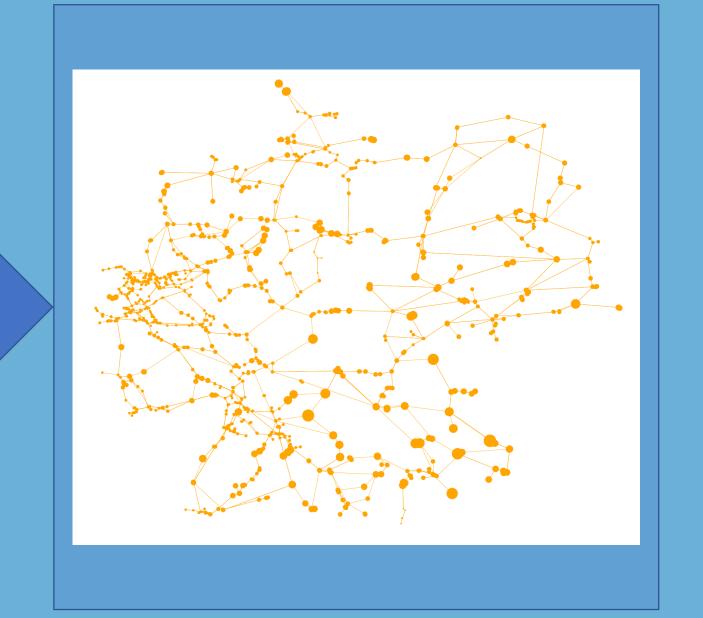




PyPSA-EUR grid topology. In red the lines missing in eTraGo.

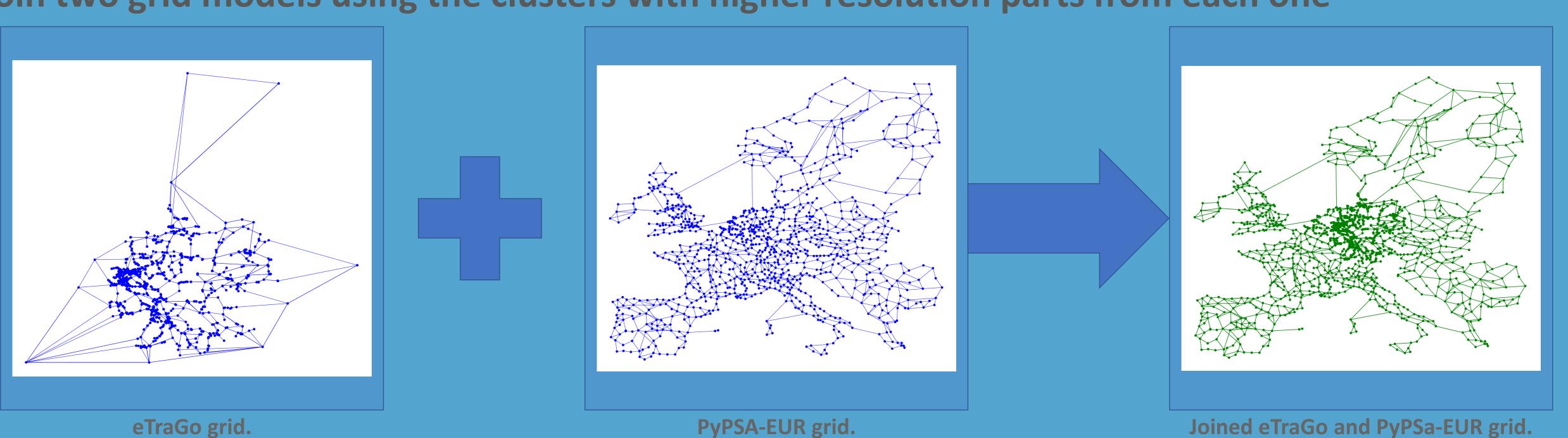
Transfer of data between grid models





PV installed capacity from PyPSA-EUR transferred to eTraGo.

Join two grid models using the clusters with higher resolution parts from each one



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[eTraGo] https://github.com/openego/eTraGo/tree/0.8.0





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