

CEOS SAR WGCV 2023: Committee on Earth Observation Satellites Working Group on Calibration and Validation

CyCLOPS: The Establishment of an Integrated GNSS / SAR Geohazards Monitoring and Cal/Val Infrastructure in the Southeastern Mediterranean Region

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Oberpfaffenhofen, Tue Oct 17, 2023









The Objectives of CyCLOPS

What is CyCLOPS and for what is it meant for?

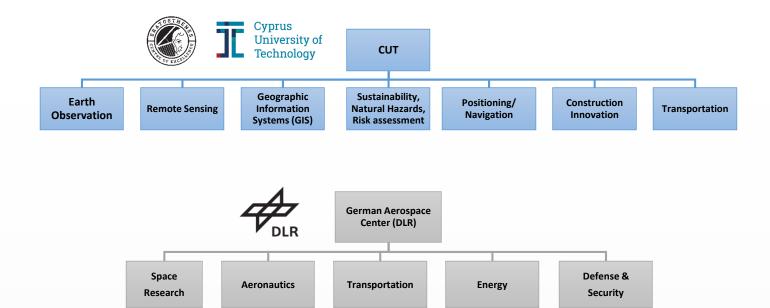
CyCLOPS is a Strategic Research Infrastructure co-funded by the European Union and the Republic of Cyprus to:

- Promote the study of Solid Earth processes and Geohazards in Cyprus and the EMENA region;
- Establish a novel calibration and validation site to further promote and enhance the use of EO Satellite
 Missions;
- Augment the existing geodetic infrastructure;
- Form the basis for a new modernized National Geodetic Reference Frame and augment Regional and International Frames;
- Promote critical geodetic and geophysical initiatives on monitoring Natural Hazards.



Consortium and Supporters

Who we are...



Supporters:



Department of Geological Survey



Department of Lands & Surveys



Cyprus Ministry of Defense



Cyprus Association of Rural & Surveying Engineers



Cyprus Electricity
Authority

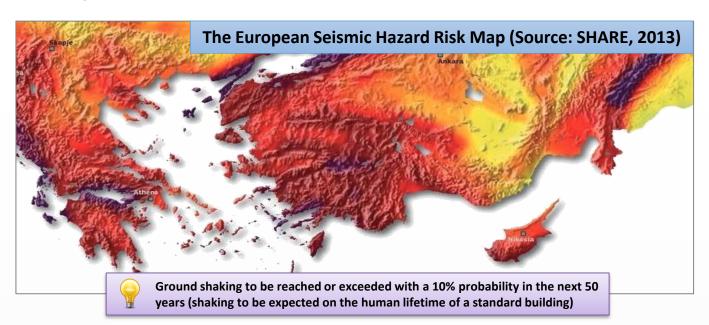


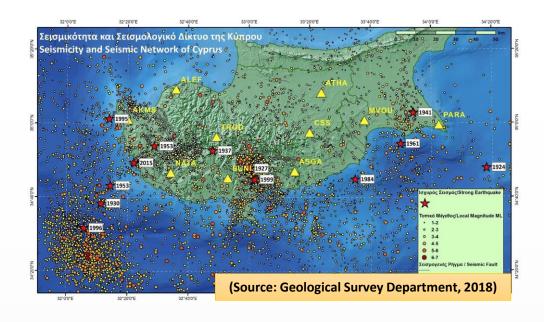
European Plate Observing System



Natural Hazards in Cyprus

Earthquakes and Landslides

















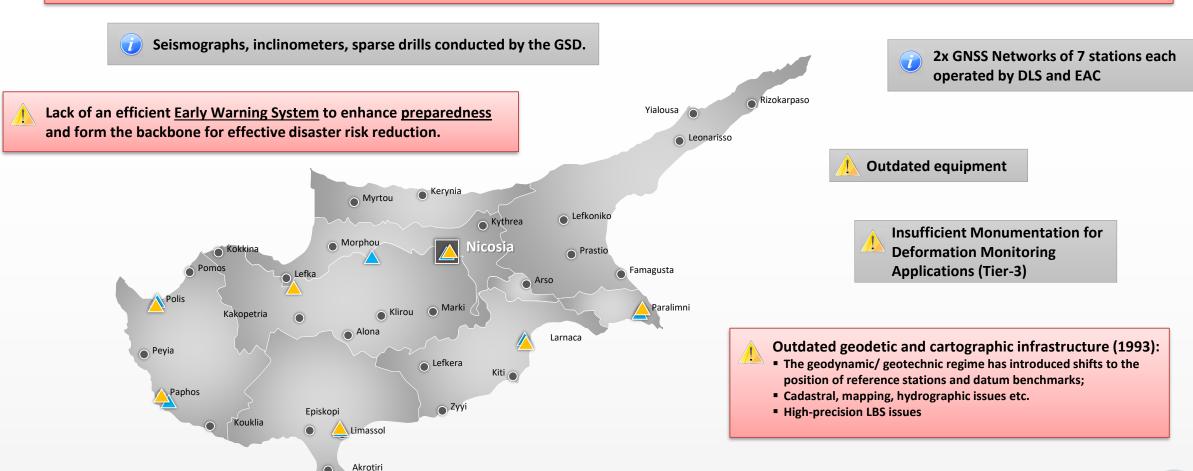
Natural Hazards in Cyprus



Current Infrastructure and Existing Gaps



Current infrastructure for monitoring and better understanding natural hazards is limited to conventional equipment.





Earth Observation & Natural Hazards

Most Prominent EO Techniques for Monitoring Geohazards

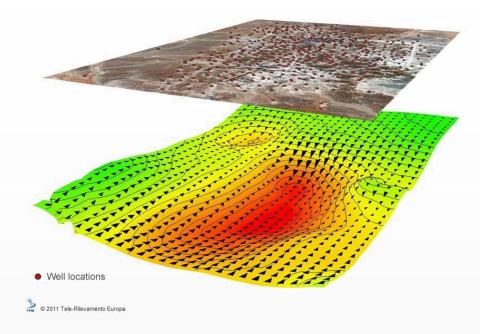


Global Navigation Satellite Systems (GNSS)



mm-level <u>absolute</u> displacement and velocity determination for a <u>single</u> point on the Earth

Synthetic Aperture Radar (SAR, InSAR, PSI)



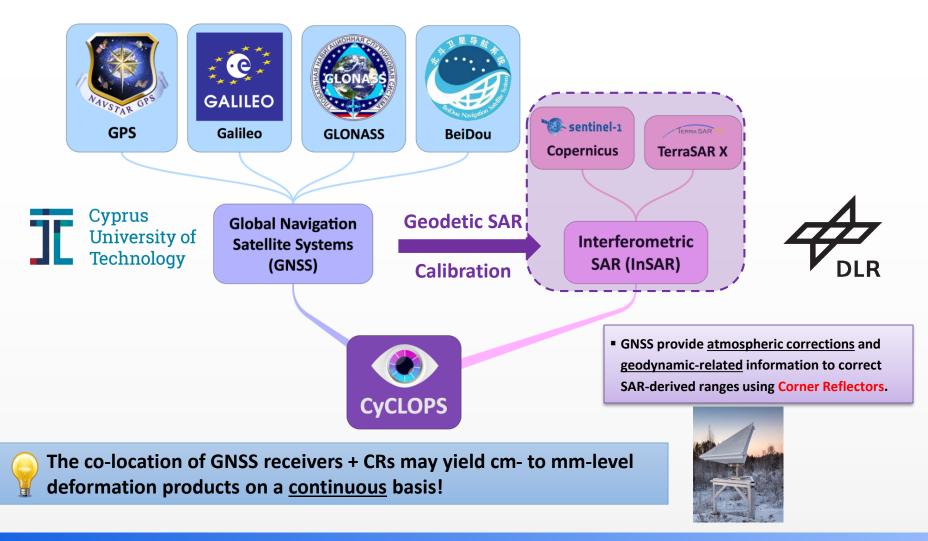
~cm- to mm-level <u>relative</u> displacement and velocity determination with <u>high resolution</u>



Earth Observation & Natural Hazards



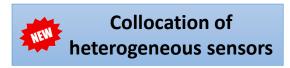


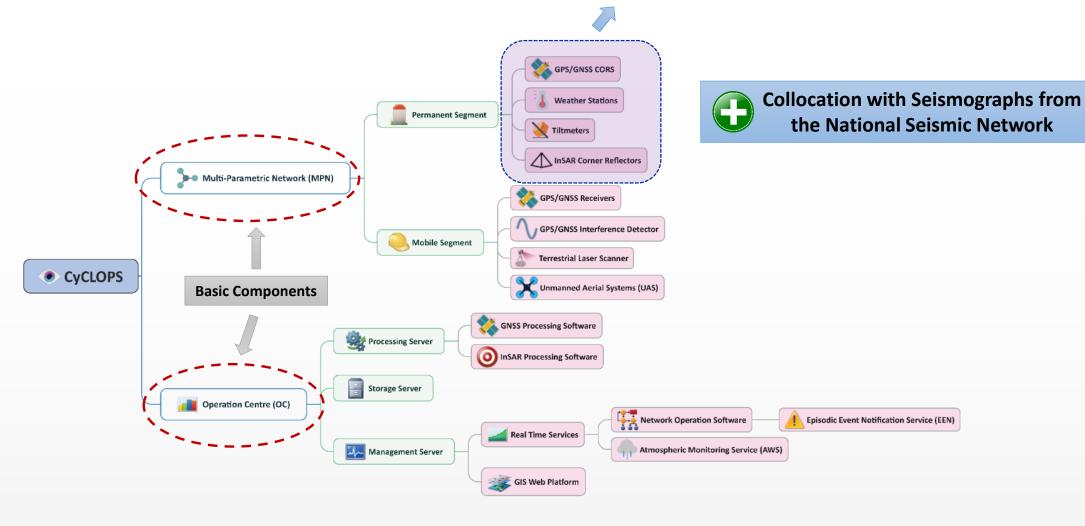




CyCLOPS Architecture

Conceptual Design

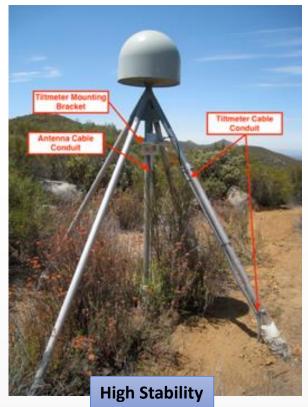






GNSS CORS Infrastructure

What kind of GNSS Equipment is used in High Precision GNSS Applications?









GPS/ GNSS Antennas are installed on top of very stable monuments at the points of interest.



Ideally, reference points must be located on and attached to solid bedrock.

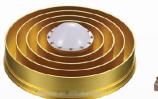


Monumentation and Equipment Features

Infrastructure Highlights:

- 6x GPS/GNSS CORS are deployed throughout Cyprus on highly stable monuments:
 - Shallow-drilled braced quadpods (UNAVCO);
 - Vertical stainless-steel truss (sub-mm vibration at wind speeds of 140Km/h);
 - Choke Ring Antennas for enhanced multipath mitigation and high phase center stability;
 - SCIGN-compatible radome and mount;
 - Absolute antenna calibration files to support Galileo in displacement determination;
- IGS-compliant weather stations (Vaisala PTU307) and tiltmeters;
- Dual SAR Trihedral Corner Reflectors (two in each site) in opposite facing configuration.



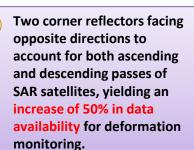












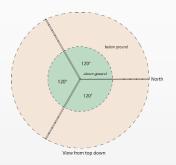


Tier-1/2 GNSS CORS Monumentation Considerations



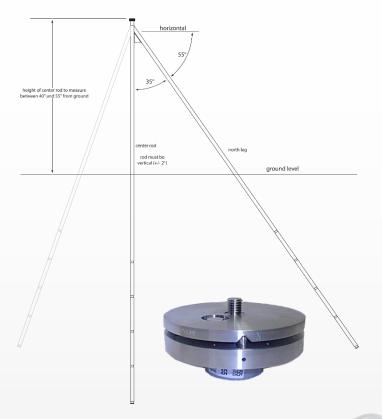


Weld threaded adapter at top. Be sure adapter tapers upward beforehand! Gusset detail - weld in place



Compliance with UNAVCO Specs for High Stability Monumentation

Shallow Drilled Braced Quadpod Monumentation





Installation of ASGA (Shallow Drilled Braced Quadpod)







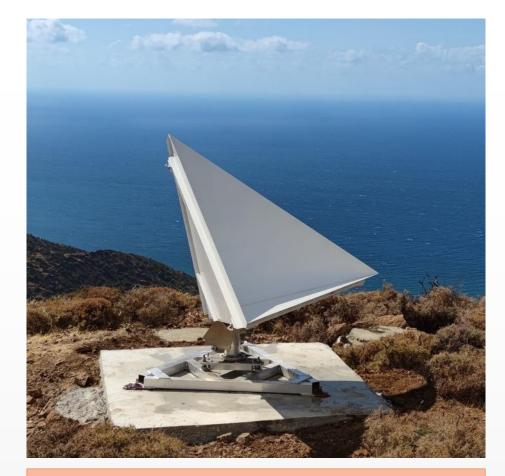
Installation of SOUN (Stainless Steel Truss)



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Permanent Segment (PS) – Implementation Phase

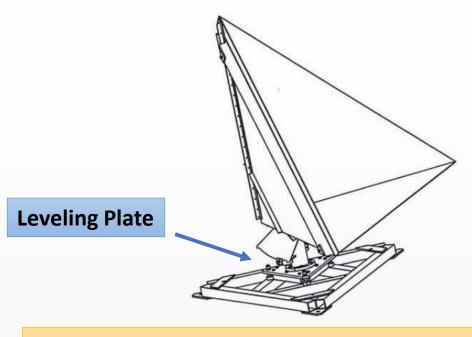
Triangular Trihedral Corner Reflectors (CR)



Cost: 6.3K EUR/unit

Azimuth Adjustment Range: -180° to +180°

Elevation Adjustment Range: -10° to +45°



Support for Sentinel-1, TerraSAR-X, COSMO-SkyMed etc (1.5m inner length)



Permanent Segment (PS) – Implementation Phase

Installation of CRs

- As in the case of GNSS monuments, the process begun by clearing the area, and excavating until revelation of bedrock;
- A thin layer of concrete was cast on top of exposed bedrock;
- The corner reflectors (CR) were then attached to bedrock, at a depth of 1m, by means of specifically designed anchors and very high-quality epoxy resin.
- The CRs were also fenced to avoid any disturbance by animals.















CR Installation at ALEV



GNSS CORS + CR Collocation (ALEV)



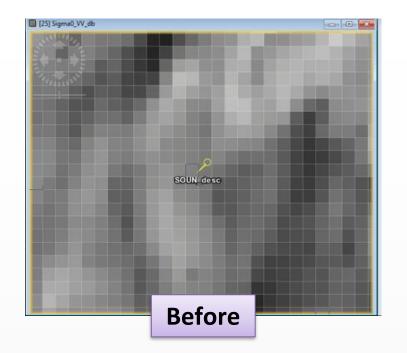
GNSS CORS

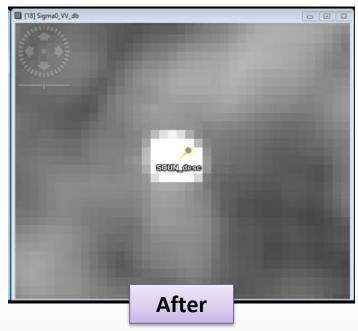


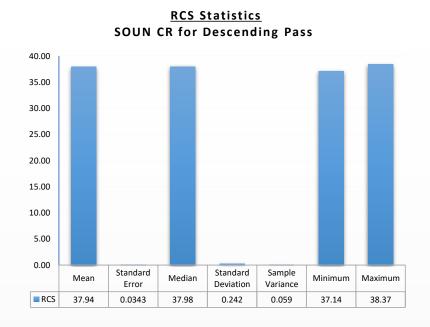
CR for Descending Pass









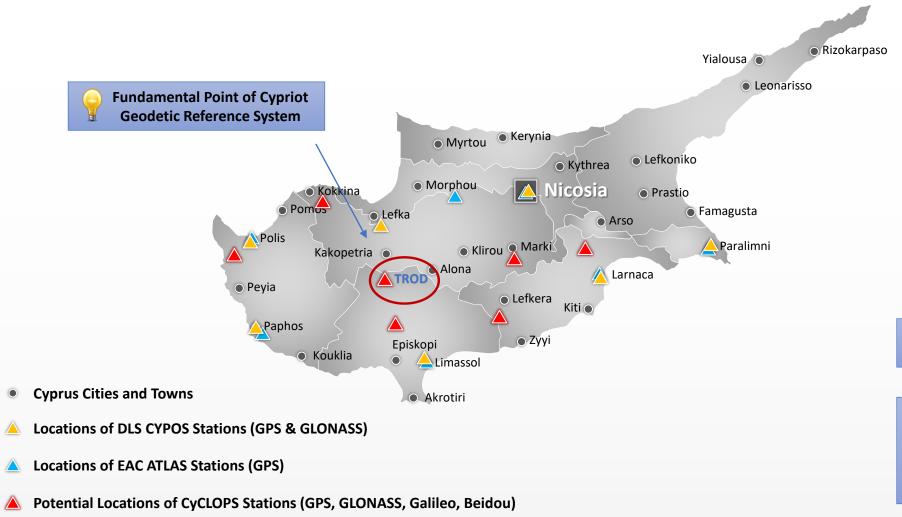




The impact of a CyCLOPS Corner Reflector on a radar acquisition (before and after installation)



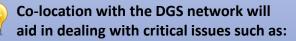
The Permanent Segment (PS) – Site Locations











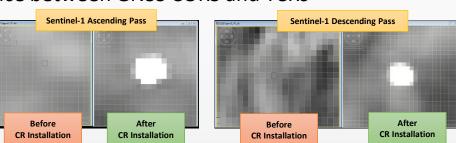
- Energy Redundancy
- Communication Redundancy
- Restricted Access (Equipment safety)



The Permanent Segment

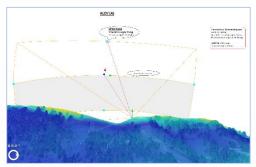
Determination of the most suitable sites for GNSS CORS/ InSAR CR collocation

- A semi-automatic GIS-based multi-criteria methodology was developed according to current research literature considering a multitude of parameters:
 - Geological background,
 - Terrain slope and aspect,
 - Land ownership (state parcels),
 - Land cover and access,
 - Sigma Nought values,
 - Incidence Angle,
 - LoS and distance between GNSS CORS and TCRs

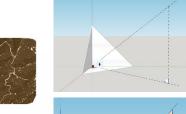




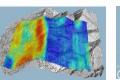


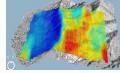










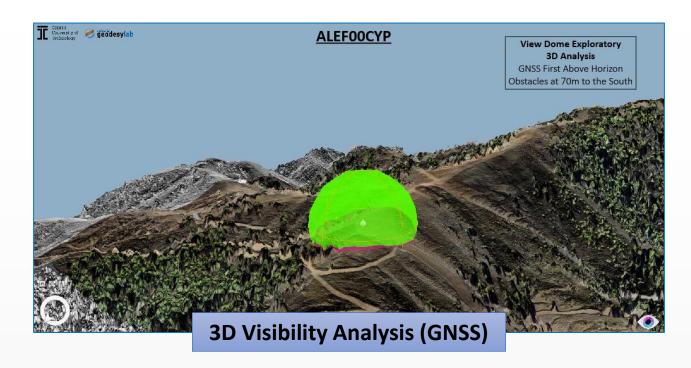


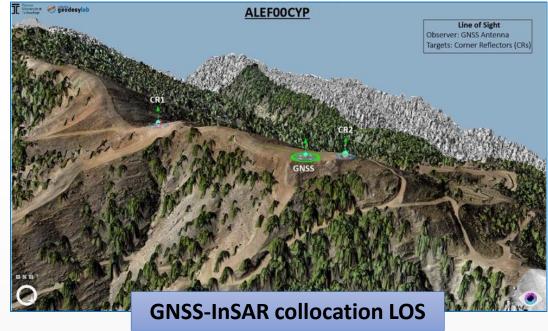




Permanent Segment (PS) – Determination of Site Locations

3D Visibility Analysis and Assessment

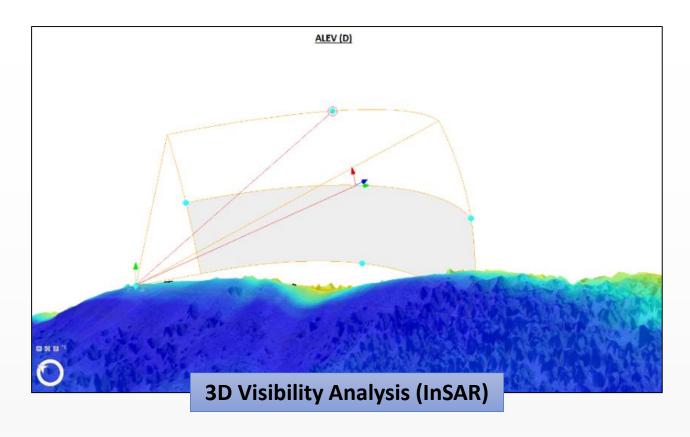


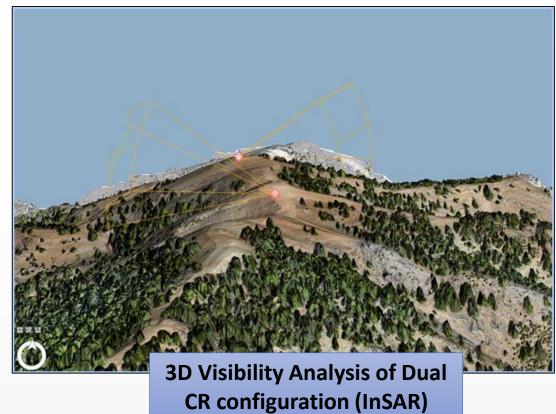




Permanent Segment (PS) – Determination of Site Locations

3D Visibility Analysis and Assessment

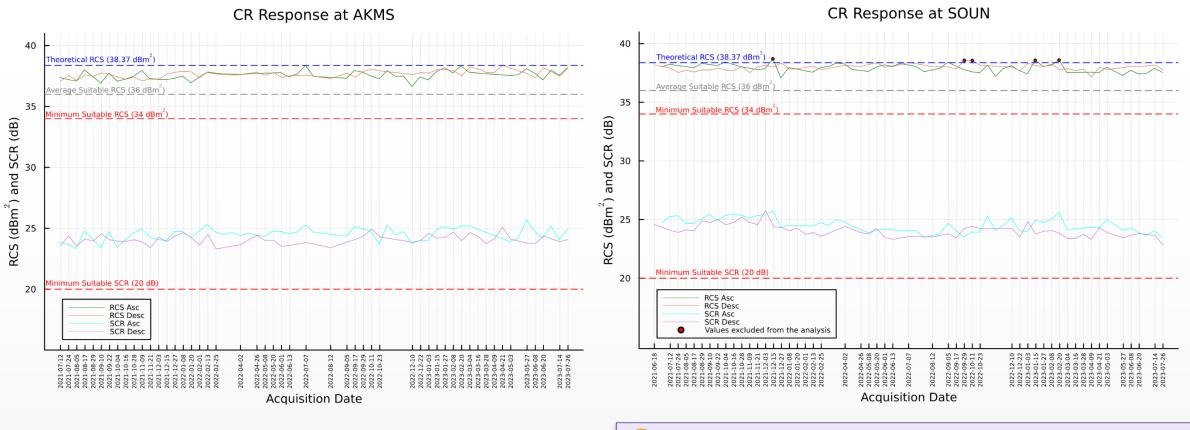






The Permanent Segment (PS) – CR Performance Assessment

RCS and **SCR** Estimation



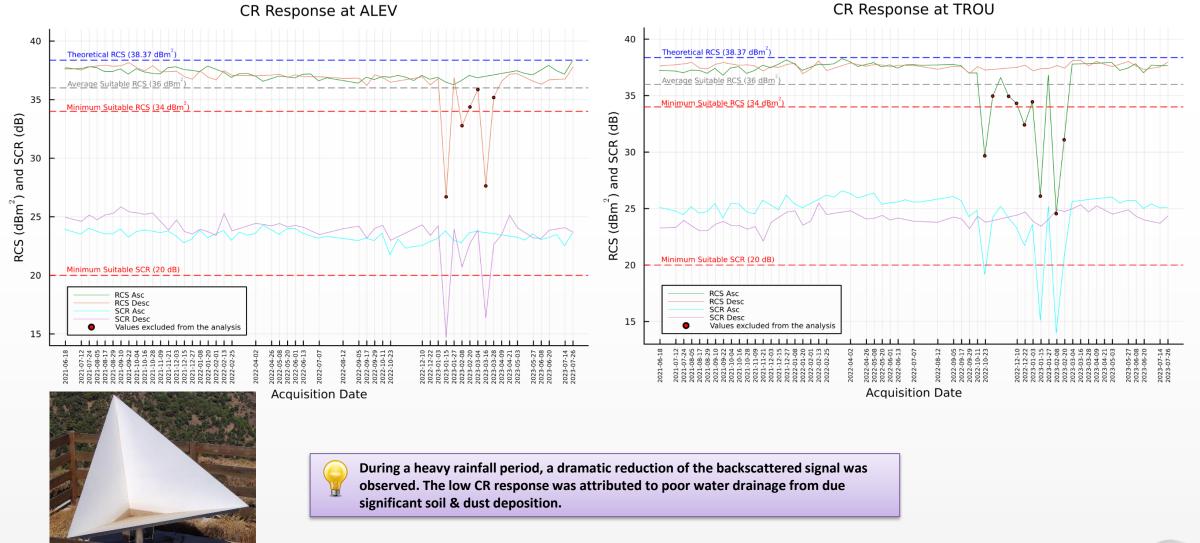


Some estimated RCS values for CRs (i.e., SOUN, MATS, ASGA) appear to exceed the theoretical RCS value. This discrepancy highlights imperfections in the calibration of Sentinel-1 imagery.



The Permanent Segment (PS) – CR Performance Assessment

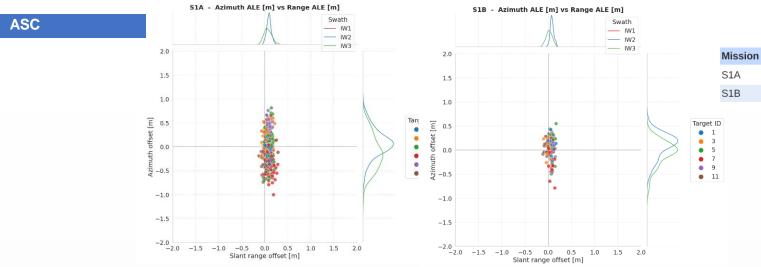
RCS and **SCR** Estimation



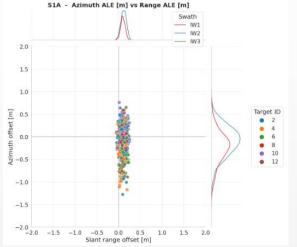


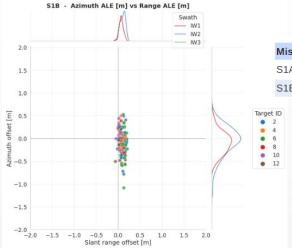
The Permanent Segment (PS) – CR Performance Assessment

Geolocation Accuracy



DESC





Mission	Num Obs	Range ALE [m]	Azimuth ALE [m]
S1A	474	0.111 ± 0.057	-0.155 ± 0.338
S1B	130	0.093 ± 0.056	-0.069 ± 0.279
315	100	0.030 ± 0.000	-0.003 ± 0.213

Range ALE [m]

 0.081 ± 0.066

 0.052 ± 0.060

Azimuth ALE [m]

 -0.020 ± 0.331

 0.018 ± 0.250

Num Obs

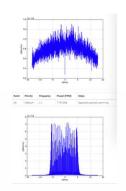
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The Mobile Segment (MS)

Mobile Segment Monumentation and Equipment Highlights

- 5x mobile GNSS CORS will be deployed to selected areas of interest (AoI).
 - Same receivers and antennas with the Permanent Segment;
 - GNSS equipment, weather station and tilt-meter will be mounted in specifically designed configurations (enclosures) with redundant energy supply (solar powered) and bidirectional communication (airFiber) with the Operation Center.
 - All receivers come with a Spectral Analyzer to identify unwanted interference prior to installation;
- 1x Terrestrial Laser Scanner will enable imminent high-density geospatial data acquisition for monitoring landslides and dynamic incidents;
- 1x Tactical-grade UAV, which offers high-resolution terrain mapping (~1hr of operation per battery) and supports large-scale data acquisition;
- 2x MetaSensing Electronic Corner Reflectors (ECRs) collocated with the GNSS CORS.







Example of a Mobile







Mobile Segment (MS)

Mobile CORS & Electronic Corner Reflector Collocation







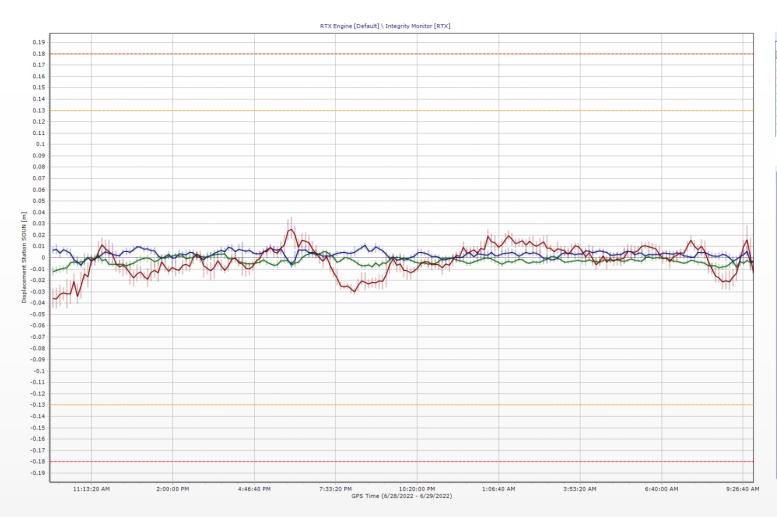


Oct 17, 2023

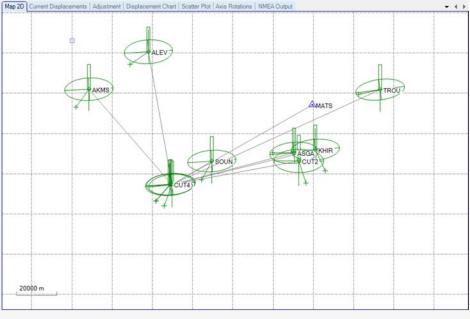


Real Time Services

Real Time Displacement Monitoring



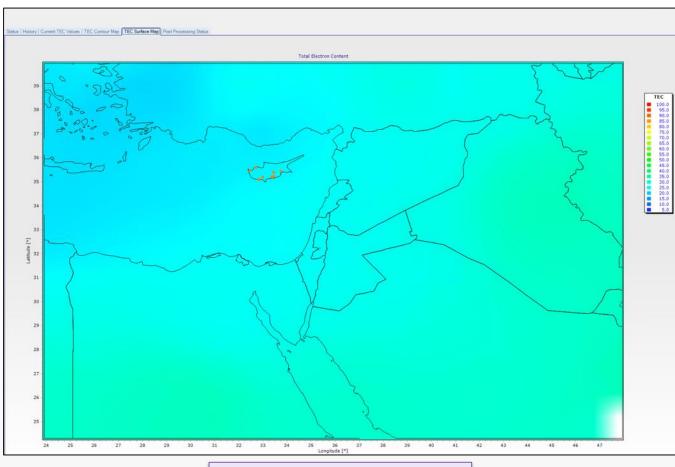
Status	Station Name	Station Code	Axis Rotation	Δ Northing [m]	Δ Easting [m]	∆ Height [m]	△20 [m]	∆3D (m)	3-a \(\Delta \) Northing [m]	3-σ Δ Easting [m]	3-σ Δ Height [m]	3-σ Δ 2D [m]
A	MATS	MATS		0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000
0	CUT3	CUT3		-0.003	-0.002	0.002	0,003	0.004	0.011	0.024	0.027	0.026
0	TROU	TROU		-0.001	-0.004	-0.006	0.004	0.007	0.012	0.027	0.029	0.030
0	AKMS	AKMS		-0.006	-0.004	-0.002	0,007	0.007	0.011	0.024	0.028	0.027
0	CUT4	CUT4		-0.005	-0.004	0.005	0.006	0.008	0.011	0.024	0.027	0.026
0	SOUN	SOUN		-0.002	-0.001	-0.009	0.003	0.009	0.011	0.024	0.027	0.026
0	ALEV	ALEV		-0.004	-0.006	0.007	0.007	0.010	0.012	0.024	0.027	0.026
0	ASGA	ASGA		0.000	-0.001	0.010	0.001	0.010	0.011	0.024	0.027	0.027
9	CAVO	CAVO		-0.009	-0.003	-0.010	0.010	0.014	0.008	0.017	0.019	0.019
0	KHIR	KHIR		-0.016	0.008	0.004	0.018	0.018	0.011	0.025	0.027	0.027
0	CUT2	CUT2		-0.014	0.005	-0.028	0.015	0.032	0.014	0.030	0.037	0.033





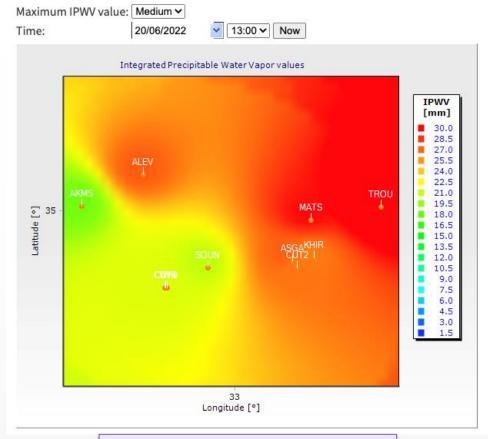
Real Time Services

Atmospheric Service





Integrated Precipitable Water Vapor Surface Map



Tropospheric Activity

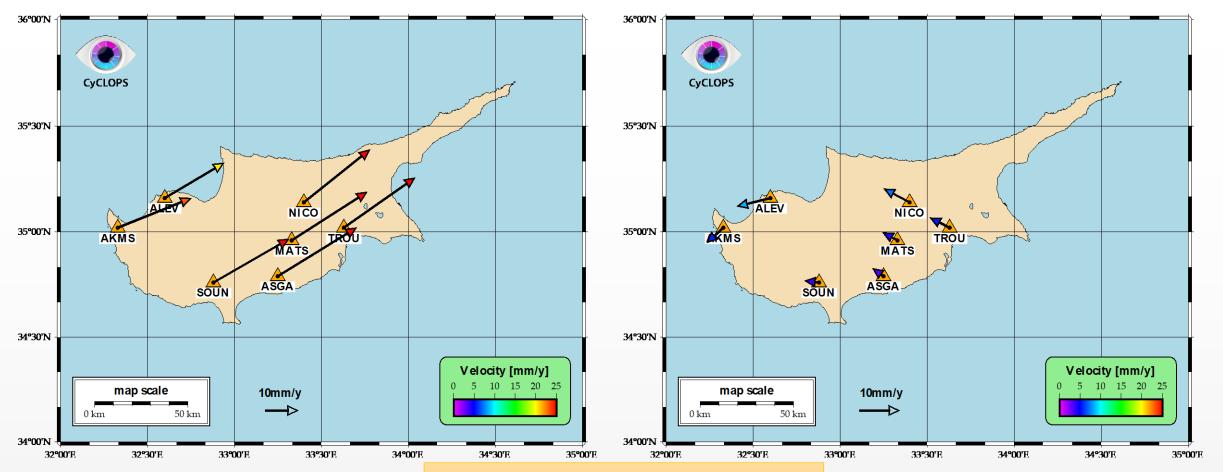


Preliminary Results

Towards a Cyprus Local Velocity Model

CyCLOPS CORS Horizontal Velocities (ITRF2014)

CyCLOPS CORS Horizontal Velocities (ETRF2014)



Processing Period: 08/2021 – 10/2022





CyCLOPS: A National Integrated GNSS/InSAR Strategic Research Infrastructure for Monitoring Geohazards and Forming the Next Generation Datum of the Republic of Cyprus



Considerations and Multi-Criteria Decision Analysis for the Installation of Collocated Permanent GNSS and SAR Infrastructures for Continuous Space-Based Monitoring of Natural Hazards

Thank you for your Attention!

Q+A Session







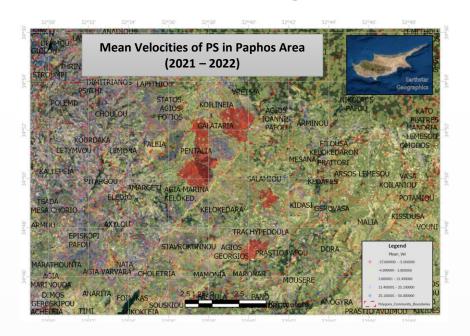


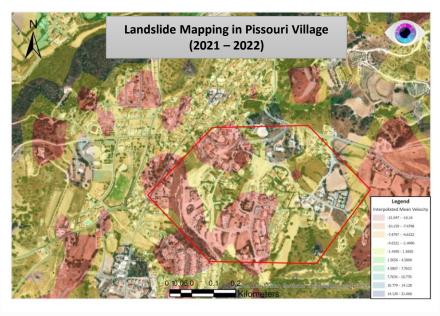


The project INFRASTRUCTURES/1216/0050 is co-financed by the European Union Regional Development Fund and the Republic of Cyprus through the Research and Innovation Foundation

Preliminary Results

GNSS + InSAR Processing









Use of Electronic Corner Reflectors for the first time in Cyprus

Landslide Detection and Mapping at Vassilico Open-Pit Mine



