# QUANTUM SENSORS AND TIMING FOR REAL-WORLD APPLICATIONS

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# UK National QT Hub in Sensors and Timing Funders, Partners and Collaborators



EPSRC funding £59.5M, collaborative projects with over 85 companies: £150M





### Roadmap to Applications



For Atom Interferometry, see also: Nature Reviews Physics 1, 731 (2019)





### Atomic Quantum Sensors: Atoms Manipulated by Lasers



Unprecedented sensitivity for measuring gravity, rotation, time and magnetic fields





### Selected Quantum Sensor Applications



Sensing into the ground

Underground risk in infrastructure projects → 0.5% GDP Sensing brain function



Dementia: 1% GDP ADHD: 1% GDP Sensing small objects in the air



Sensing position and movement



~7% GDP



The World Economic Forum has recognised **Quantum Sensing** as one of the top 10 emerging technologies for 2020



### Gravity Gradients for Construction



Underground risk in infrastructure projects → 0.5% GDP



Drainage



Leakage from canals and reservoirs



Voids leading to sinkholes



Badger setts



isity of mine entries in an urban setting. West Midlands. [Topography based on C vey mapping © Crown Copyright and Database Right 2011]. Ref: Geoscientist. Ap





Collaboration: physics, civil engineering, geophysics, industry

### Microgravity Surveys and their Limitations

#### Example: Brown Field Site Survey



UNIVERSITY<sup>OF</sup> BIRMINGHAM



Classical microgravity sensors are sufficiently sensitive to deliver useful information!

#### BUT:

They take 5-10 min/measurement point

Sensor drift needs to be corrected by periodically returning to a calibration point

In this example: 1 month for 1 ha with 3 sensors and 4 persons

→ Commercial uptake hindered by cost of operation, not the sensitivity of the instrument





### Why do Gravity Measurements take so much Time?







### Solution: Gravity Gradiometry







# Tunnel detection with quantum gradiometry

Survey over tunnel



Tunnel centre localised to:  $\pm 0.19$  m, horizontal; -0.59/+2.3 m, vertical

*Nature* volume 602, pages590–594 (2022)

# Enabling Gravity Cartography

- Relevant to a range of applications, including:
  - Water monitoring
  - Infrastructure
  - Archaeology
  - Agriculture
  - Navigation



# Towards compact sensors

Person-portable and moving platform devices underway





**Exploitation in new start-up:** 

Delta g limited



### Schematic Setup of a Quantum Navigation System



### Quantum Sensors and Timing: Opportunities in PNT

#### Map Matching for Positioning

Gravity gradient

Magnetic Fields





→ Providing absolute position
without any communication
(including under water)
→ Collision alert (?)

#### **Inertial Sensors for Navigation**

Acceleration and Rotation



- $\rightarrow$  Low drift
- $\rightarrow$  Low bias
- $\rightarrow$  Ingredients for INS

**Clocks for Timing** 



 $\rightarrow$  On board holdover

 $\rightarrow$  GNSS spoofing alert



→ Time references
→ Transportable time





### Quantum-Magnetoencephalography – Spin off from QT





#### Cerca:

Joint venture spin-off between Magnetic Shields and Nottingham University Founded in 2020

First systems delivered internationally £6M turnover in first year >£50M requests for quotations



#### Impact Opportunities:

Epilepsy: 60M people worldwide

Dementia: 1% GDP

Schizophrenia: 1% of population

Trauma: 100.000 / year in UK



A new generation of quantum sensors have enabled 'wearable' brain imaging technology



50 channel whole head system 2020







### Quantum Clocks Potential to Change Business Models

**Timing today: Centralized model** 



#### Timing via Global Navigation Satellite Systems:

- f "Free" to use
- Worldwide availability
- <sup>+</sup> 30 ns within UTC
- → Widespread use in industry and critical national infrastructure
- Can be easily spammed or spoofed
- Is not available everyehere (e.g. underwater)
- Risk to critical infrastructure in case of conflict
- Potential limits to communication



### Quantum Clocks Potential to Change Business Models

Timing future: "Edge" model



#### Quantum "Edge" Timing:

- + Resilience
- Network architectures with higher bandwidth and better energy efficiency
- Architectures for safe autonomous vehicles
- \* Improved air and space surveillance
- Not "free" to use
- Will need 10-15 years of development to reach full potential



### Microwave (old) and Optical (new) Quantum Clocks

A quantum clock replaces the manmade frequency reference in a classical clock (e.g. a pendulum) with an atom



Microwave atomic transition is used to discipline a quartz oscillator

Optical atomic transition is used to discipline a laser

100.000 higher frequency → faster sychronization & higher precision



### Why are Optical Clocks Disruptive?

So far: "linear" relationship between SWAP-C and stability



![](_page_19_Picture_0.jpeg)

### Why are Optical Clocks Disruptive?

So far: "linear" relationship between SWAP-C and stability

![](_page_19_Figure_3.jpeg)

### DLR-QT Optical Clock Technology

![](_page_20_Picture_1.jpeg)

#### GPS Solutions (2021) 25:83 https://doi.org/10.1007/s10291-021-01113-2

Table 1 Summary of the key figures of the different optical clock technologies, together with the corresponding figures of the Galileo RAFS and PHM

		Galileo RAFS	Galileo PHM	Ca beam	I2 MTS	Rb MTS	Rb TPT	Sr Lattice clock	Ca single ion clock
	References	Orolia datasheet (2016)	Leonardo data- sheet (2017)	Shang et al. (2017)	Schuldt et al. (2017); Döring shoff et al. (2019)	Zhang et al. (2017)	Martin et al. (2018)	Bongs et al. (2015); Origlia et al. (2018)	(Delehay and Lac- route 2018; Cao et al. 2017)
Frequency stabil- ity (in RAV @ integration time τ)	1 s 10 s 10 <sup>2</sup> s 10 <sup>3</sup> s 10 <sup>4</sup> s 10 <sup>5</sup> s 10 <sup>6</sup> s Longest reported (continuous) $\tau$ (s)	$3 \times 10^{-12}$ $1 \times 10^{-12}$ $3 \times 10^{-13}$ $6 \times 10^{-14}$ $3 \times 10^{-14}$ Long-term drift < $10^{-10}$ / year	$2 \times 10^{-12}$ $3 \times 10^{-13}$ $7 \times 10^{-14}$ $2 \times 10^{-14}$ $7 \times 10^{-15}$ Long-term drift < $10^{-15}$ / day	$5 \times 10^{-14}$ $2 \times 10^{-14}$ $5 \times 10^{-15}$ $2 \times 10^{-15}$ n/s n/s n/s 1600	$6 \times 10^{-15}$ $3 \times 10^{-15}$ $2 \times 10^{-15}$ $3 \times 10^{-15}$ $3 \times 10^{-15}$ $< 2 \times 10^{-14}$ n/s 700,000	$1 \times 10^{-14a}$ $4 \times 10^{-15a}$ $3 \times 10^{-15a}$ n/s n/s n/s n/s 600	$4 \times 10^{-13}$ $1 \times 10^{-13}$ $4 \times 10^{-14}$ $1 \times 10^{-14}$ $5 \times 10^{-15}$ n/s 180,000	n/s $1 \times 10^{-16}$ $4 \times 10^{-17}$ $1 \times 10^{-17}$ $4 \times 10^{-18}$ n/s n/s 30,000	n/s $6 \times 10^{-15}$ $2 \times 10^{-15}$ $6 \times 10^{-16}$ $2 \times 10^{-16}$ n/s n/s 30,000
Clock transition frequency/wave- 6.8 GHz 1.4 GHz length			657 nm	532 nm	420 nm	778 nm	698 nm	729 nm	
Clock transition natural linewidth			0.4 kHz	300 kHz	1450 kHz	330 kHz	6 mHz	140 mHz	
SWaP Budgets <sup>b,c</sup>	Mass (kg)	3.4	18.2	n/s	$21 + 10^{b}$	$10^{d} + 10^{b}$	$12^{e} + 10^{b}$	<250	n/s
	Power (W)	35	60 <sup>f</sup>	n/s	$44 + 66^{b}$	$20^{d} + 66^{b}$	25 <sup>e</sup> +66 <sup>b</sup>	n/s	n/s
	Volume (l)	3.2	26.3	$300 + 7^{b}$	33 + 7 <sup>b</sup>	n/s	$8^{e} + 7^{b}$	<1000	540
Complexity	# Lasers	n/a	n/a	2	1	1	1	5	6
	Vacuum chamber			Yes	N.	N	N	Yes	Yes
	Cavity pre-stabi- lization	n/a	n/a	Yes	No	No	No	Yes	Yes
TRL		9	9	4	4-5 <sup>g</sup>	4	4	4	4

![](_page_21_Picture_0.jpeg)

### Roadmap for Optical Clock Applications

#### **Business Advantage through Quantum Timing**

![](_page_21_Figure_3.jpeg)

# Noise limitations in the radar

![](_page_22_Figure_1.jpeg)

Dense Urban Environment

![](_page_22_Figure_3.jpeg)

2021-07-22 Uob GK000 5000 4500 4000 3500 E 3000 8 2500 2000 1500 1000 500 4000 3000 2000 1000 -2000 -3000 XDOS

Quantum oscillators provide improved phase noise and sensitivity of the radar in

## Better oscillator: more features

![](_page_23_Figure_1.jpeg)

# **Discrimination via Micro-Doppler**

Opportune targets – Light aircraft vs large bird

![](_page_24_Figure_2.jpeg)

### Radar Improvement with better Oscillator – Drone Tracking

### Small Drone Tracked by two radar

Side-by-side comparison: Tracker output

![](_page_25_Picture_3.jpeg)

Radar#1 Purple lines

![](_page_25_Picture_5.jpeg)

![](_page_25_Picture_6.jpeg)

![](_page_25_Picture_7.jpeg)

Radar#2 Yellow Line - Better Phase Noise

![](_page_25_Picture_9.jpeg)

![](_page_25_Picture_10.jpeg)

![](_page_25_Picture_11.jpeg)

### **DLR-QT, Ulm – Open for Collaboration**

![](_page_26_Figure_1.jpeg)

#### **Divisions**

![](_page_26_Picture_3.jpeg)

![](_page_27_Picture_0.jpeg)

### THANK YOU FOR LISTENING – QUESTIONS?