PRETTY MISSION PREPARATIONS: STEPS TO FOSTER GRAZING-ANGLE REFLECTOMETRY



GFZ

Helmholtz Centre

POTSDAM

- (1) German Aerospace Center DLR-SO, Neustrelitz, Germany
- (2) Institute for Space Stud. Catalunya IEEC, ICE-CSIC, Barcelona, Spain
- (3) German Res. Centre for Geosci. GFZ, Potsdam, Germany
- (4) Beyond Gravity Austria BGA, Vienna, Austria

IEEC

(5) Norwegian Univ. of Sci. and Tech. NTNU, Trondheim, Norway







Norwegian University of Science and Technology

 \Box NTNU

Outline



- PRETTY Mission Overview
- Grazing Angle Reflectometry: Preparation Studies
- Preliminary Results over Caribbean
- Preliminary Results over Hudson Bay
- Summary & Outlook



PRETTY Mission Overview

PRETTY Mission Parameters

PRETTY (Passive REflecTometry and dosimeTrY)

- ESA CubeSat mission, developed by an Austrian consortium led by Beyond Gravity Austria
- Size: 30 x 10 x 10 cm³
- Orbit: SSO, altitude 560 km
- GNSS-R antenna: RHCP, limb pointing, 15 dBic
- GNSS-R range of elevations: 5° to 15° elevation
- GNSS-R signal carrier: L5



PRETTY Mission Main Payload

Passive REflecTometry and dosimeTrY

- GNSS-R instrument PACO (PARIS Correlator) for altimetry (interferometric and conventional sampling) at slant and grazing geometries
- Radiation dosimeter (total ionizing dose and single-event effects)



Photo: PACO Receiver unit for ground-based testing



Scheme: PRETTY sat. layout

Objective and Challenges

- Obtain complex waveform data in grazing angle Reflectometry
- Retrieve the sea surface height from coherent carrier phase observations
- Disturbances to be considered
 - Irregularities on Earth surface (land, ocean roughness)
 - Irregularities in Earth's atmosphere (ionosphere, troposphere)
- Challenges for PRETTY
- Small contract involving
 - NTNU (Norway)
 - GFZ (Germany)
 - DLR-SO (Germany)
 - TUB (Germany)
 - ICE-CSIC/IEEC (Spain)
- to support Beyond Gravity in scientific questions







Grazing Angle Reflectometry: Preparation Studies

Considerable Factors

Sea Surface

- Roughness (Sea State)
- Penetration (e.g. Sea Ice)
- •

Atmosphere

- Refraction (neutral gas and plasma distribution)
- Scintillation (Plasma Depletion, Space Weather)
- • •

Receiver & Transmitter

- Position & Attitude uncertainty (of vessel, aircraft or satellite)
- Antenna & Instrumental parameter (e.g. gain pattern)
- •



A: coastal setup

B: aircraft

C: small satellite

degree of disturbance

First Step – Target Areas



Roughness Disturbance

 select targets/periods to maximize scientific outcome in limited duty cycle of PACO instrument

Simulation of coherent obs. probability

- Priority to areas with high probability of coherent reflections
- More than three decades (1990 to 2021) analyzed Significant Wave Height (SWH) from the ECMWF ReAnalysis-5 (ERA5).
- Several scenarios wind-driven waves, combined windswell waves and wind speed thresholds considered
- Threshold set based on Rayleigh criterion
- Average probability map on global scale for differents month are produced.





Second Step – Algorithm Theoretical Baseline Document





Preliminary Results over Caribbean

Reflection Track Reference

Example Events of CyGNSS Mission



- + receiver ground track
- reflection track

Venezuela Event

- GPS PRN 12 by CYG ID 4 on 2017/09/08 23h17 UTC
- local evening (equatorial plasma bubbles?)

Bahamas Event

- GAL PRN 1 by CYG ID 8 on 2017/09/20 16h37 UTC
- local noon

Cuba Event

- GAL PRN 5 by CYG ID 5 on 2018/10/14 04h56 UTC
- local night

All three Events

• elev. angle between 13° ... 15°

Ionosphere Reference Data





NEDM model

 $\times 10^{11}$

6

5

3

2

1

(1)

-8.0

m

-60

-70

[m⁻³]

dens.

el.

- global, empirical climatology
- continuous in time and space
- smallest features 2.5° (TEC map based)
- temporal scale (down to semidiurnal)
- provider DLR-SO**
- Ionosphere parameter of interest:

electron density ne

** German Aerospace Center, Institute for Solar-Terrestrial Physics

Jakowski & Hoque 2018

(1)phase excess path xmit to spc (1st ep.) 2 phase excess path xmit to rcv (1st ep.) (3)phase excess path spc to rcv (1st ep.)

Neutral Atmosphere Reference Data



- global, obs.-driven

ERA5 model

- horizontal grid (res.: 30km)
- vertical levels (res.: 10m ... ~6km)
- temporal scale (res.: 1h)
- provider ECMWF*
- Meteorological parameter of interest:

air pressure pair temperature Tspecific humidity q

* European Centre of Medium-range Weather Forecast

Hersbach et al. 2020

1 phase excess path xmit to spc (1st ep.)

3 phase excess path spc to rcv (1st ep.)

Bahamas Event





- O Mean sea surface height from DTU 21
- Coherent observation/track
 x reference epoch for amb. fix.
- Incoherent observation

- Iong surface dominated track 25 s
- after surface correction std(f) = 3.49 Hz
 (50 Hz sampling)

Cuba Event





- O Mean sea surface height from DTU 21
 - Coherent observation/track x reference epoch for amb. fix.
- Incoherent observation

- short surface dominated track 16 s
- after surface correction std(f) = 4.41 Hz
 (50 Hz sampling)

Venezuela Event



- Mean sea surface height from DTU 21
 - Coherent observation/track x reference epoch for amb. fix.
- Incoherent observation

- short surface dominated track 12 s
- after surface correction std(f) = 6.96 Hz
 (50 Hz sampling)

DLR



Preliminary Results over Hudson Bay

Reflection Track Reference





Western HB Event ¹⁾

- GPS PRN 15 by TDS-1 on 2015/01/18 17h20 UTC
- high elev. angle at spec. point (~ 58°)

Eastern HB Event 2)

- GPS PRN 13 by TDS-1 on 2015/01/18 17h20 UTC
- moderate elev. angle at spec. point (~ 30°)

Two sea-ice events over Hudson Bay (HB) with rather high SNR selected for analysis.

Li et al. 2017

Eastern Hudson Bay Event



- O Mean sea surface height from DTU 21
 - Coherent observation/track
 x reference epoch for amb. fix.
- Incoherent observation

very long surface dominated track 36 s

DLR

after surface correction std(f) = 5.93 Hz
 (50 Hz sampling)

Western Hudson Bay Event



- Mean sea surface height from DTU 21
 - Coherent observation/track x reference epoch for amb. fix.
- Incoherent observation



- longest surface dominated track (47 s) deviating from surface
- after surface correction std(f) = 6.96 Hz
 (50 Hz sampling)



Summary & Conclusion

Summary of analysis after surface correction



	PRN G12	PRN E05	PRN E05	PRN E01	PRN E01	PRN G13	PRN G15	
min. Elev. [°]	13	13	13	15	15	30	58	
yyyy-mm-dd	2017-09-08	2018-10-14	2018-10-14	2017-09-20	2017-09-20	2015-01-18	2015-01-18	
UT [HH:MM]	23:17	04:56	04:57	16:37	16:38	17:21	17:20	
LT [HH:MM]	18:35	23:19	23:27	11:21	11:26	11:32	11:13	
track length [s]	12	16	12	25	17	36	47	
resid. Dopp. [Hz]	0,03	0,05	-0,03	-0,09	0,24	0,05	-0,24	
iono. Dopp. [Hz]	0,04	0,00	0,00	0,02	0,02	-0,09	-0,04	
neut. Dopp. [Hz]	-0,06	-0,16	-0,18	0,12	0,12	0,09	0,01	
Dopp. Std [Hz]	6,96	4,41	4,44	3,49	3,91	5,93	3,89	
ampl. Index	0,61	0,36	0,40	0,26	0,33	0,43	0,36	
sig. wave hgt. [m]	0,74	0,36	0,36	0,81	0,81	n.n.	n.n.	
CyGNSS obs.*						TDS-1	TDS-1 obs.**	
over Caribbean						over Hud	<mark>over Hudson Bay</mark>	

Neutral atmo. correc.: * ERA5, ** Internat. Stand. Atmo.



- PRETTY data will allow to study complex waveform data at grazing elev.
- Algorithms defined for altimetric processing and disturbance analysis
- Grazing geometry may give further insight into atmospheric factors
- Test event of other missions (TDS-1 and CyGNSS) analyzed
- Started looking into Doppler and amplitude dependencies

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