

#### **Emulator-based Neural Network Prediction for SIF Retrieval in** the O<sub>2</sub>-A Absorption Band

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Mitglied der Helmholtz-Gemeinschaft

FluoMap: a Helmholtz Al funded project



#### What is Sun-Induced Fluorescence (SIF)?



12.06.23 Mitglied der Helmholtz-Gemeinschaft

![](_page_1_Picture_4.jpeg)

![](_page_1_Picture_5.jpeg)

![](_page_1_Picture_6.jpeg)

Agricultural use cases 

![](_page_1_Picture_8.jpeg)

→ ESA Earth Explorer FLEX **Global Fluorescence** estimations

![](_page_1_Picture_10.jpeg)

![](_page_1_Picture_11.jpeg)

### **Airborne HyPlant Spectrometer**

- FLUO is the **airborne demonstrator** for **FLEX**
- 0.24 nm FWHM, 0.11 nm SSI
- 5 years of comparable campaign acquisitions
- 773 acquisitions, 384 × [2000, 10'000] px
- **Operational Baseline SIF Retrieval** Methods
  - Spectral Fitting Method (SFM), Cogliati et al. 2019
  - Improved Fraunhofer Line Discrimination (iFLD), Damm et al. 2022

![](_page_2_Picture_10.jpeg)

![](_page_2_Picture_11.jpeg)

![](_page_2_Picture_12.jpeg)

## **Airborne HyPlant Spectrometer**

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![](_page_3_Picture_10.jpeg)

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[mW nm]

-sensor

at

**O**<sub>2</sub>-**A** 

![](_page_3_Figure_12.jpeg)

Flight direction  $[2 \times 10^3, 10^4]$ 

![](_page_3_Picture_14.jpeg)

## **Spectral Fitting Methods to Retrieve Fluorescence**

- Conventional Least Squares Optimization in Spectral Fitting Method (SFM)
  - Data inefficiency:
     no benefits from statistical relationships
  - Slow:
     Individual fit of each spectral pixel
  - Model failure: in topographically variable terrain

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![](_page_4_Figure_6.jpeg)

![](_page_4_Picture_7.jpeg)

# **Spectral Fitting Method Neural Network (SFMNN)**

Input

![](_page_5_Figure_2.jpeg)

![](_page_5_Picture_5.jpeg)

# **Spectral Fitting Method Neural Network (SFMNN)**

Input

![](_page_6_Figure_2.jpeg)

![](_page_6_Picture_5.jpeg)

## **Loss and Constraint Formulation Self-Supervised Loss Formulation for Signal Reconstruction**

- Inversion under incomplete knowledge of physical process is **ill-posed**.
- Architectural **constraint** formulation: difference in spatial variation of terms contributing to radiance signal

$$\begin{split} \ell(y, \hat{y}) &= \left(\ell_{R,f} + \gamma_{f} \ell_{f} + \gamma_{N} \ell_{\text{NDVI}}\right)(y, \hat{y}) \\ &= \left\langle \left(y(\lambda) - \hat{y}(\lambda)\right)^{2} + \gamma_{f} \left(w_{\lambda} \left(y(\lambda) - \gamma_{N} \hat{f} \delta \left(\text{NDVI}_{y} \leq t\right)\right)\right) \right\rangle \\ &+ \gamma_{N} \hat{f} \delta \left(\text{NDVI}_{y} \leq t\right) \end{split}$$

![](_page_7_Picture_4.jpeg)

![](_page_7_Figure_5.jpeg)

![](_page_7_Picture_6.jpeg)

![](_page_7_Figure_7.jpeg)

#### Simulation of HyPlant At-sensor Radiance

- Radiative Transfer Modelling (MODTRAN)
- Extensive coverage of observational conditions
- Inclusion of topographic variation

![](_page_8_Figure_4.jpeg)

	Para	ameter	HyPlant DB
	Atmosphere	model	mid-latitude summer
		$H_2O$ [cm]	0.3 - 3.0
		$O_3$ [DU]	332
		$AOT_{550}$ []	0.05 - 0.40
13 paramete	rs	aerosol model	rural
		g []	[-1,+1]
	Geometry	TA [°]	0–20
		SZA [°]	20 - 55
		RAA [°]	0–180
		$h_{ m gnd} \ [{ m m}]$	0–300
		$h_{ m sen} \; [ m km]$	0.659–0.691 agl 1.543–1.598 agl
	Surface	$ ho_{740}$ []	0.05 - 0.60
		${\rm d} ho/{\rm d}\lambda~{ m [nm^{-1}]}$	0-0.008
		$F_{737}/F_0$	0–8
	Sensor	$\delta_{\lambda} \; [\mathrm{nm}]$	[-0.080, +0.023]
		$\delta_{ m FWHM}~[ m nm]$	[-0.040, +0.040]

#### **Emulation of HyPlant At-sensor Radiance**

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- High-dimensional regression problem (13  $\rightarrow$  349 dims)
- A set of regression models were tested
- Polynomial of 4<sup>th</sup> degree (P4) is precise enough
- P4 was used as forward simulator in SFMNN

![](_page_9_Figure_6.jpeg)

![](_page_9_Picture_7.jpeg)

#### **Comparison with in-situ measurements**

- Small set of synchronous SIF ground measurements
- Good correlation
- Absolute errors impacted by systematic biases
- Might be caused by domain gap between simulations and HyPlant observations

Data Set			MAE	MAE[calib]	
		$r^{\mathrm{pear}}$	$\rm mW~nm^{-1}$	$^{1} {\rm m}^{-2} {\rm sr}^{-1}$	N
CKA-2020 (600m)	SFM SFMNN iFLD	<b>0.85</b> 0.78 0.53	$egin{array}{c} {f 0.43} \pm {f 0.05} \ 0.90 \pm 0.03 \ 0.41 \pm 0.07 \end{array}$	$0.17 \pm 0.02$ $0.18 \pm 0.04$ $0.24 \pm 0.01$	18 18 18
SEL-2018 (600m)	SFM SFMNN iFLD	0.91 <b>0.93</b> 0.82	$0.53 \pm 0.07$ <b>0.40 <math>\pm</math> 0.03</b> $0.61 \pm 0.09$	$0.11 \pm 0.00$ $0.11 \pm 0.00$ $0.18 \pm 0.00$	$     \begin{array}{c}       12 \\       12 \\       12 \\       12     \end{array} $

![](_page_10_Picture_8.jpeg)

![](_page_10_Picture_9.jpeg)

### **SIF Prediction in Topographically Variable Terrain**

SFM

![](_page_11_Picture_2.jpeg)

![](_page_11_Picture_3.jpeg)

**SIF** [mW nm<sup>-1</sup> sr<sup>-1</sup> m<sup>-2</sup>] **SIF** [mW nm<sup>-1</sup> sr<sup>-1</sup> m<sup>-2</sup>]

#### **SFMNN**

![](_page_11_Figure_8.jpeg)

# **Diurnal SIF Dynamics are phenologically plausible**

- Time series from repeated flights
- Second order derivative  $\beta$  as a measure for diurnal SIF dynamics

![](_page_12_Figure_3.jpeg)

![](_page_12_Picture_4.jpeg)

![](_page_12_Picture_5.jpeg)

![](_page_12_Picture_6.jpeg)

![](_page_12_Picture_7.jpeg)

![](_page_12_Picture_10.jpeg)

![](_page_12_Picture_11.jpeg)

-0.3

![](_page_12_Figure_13.jpeg)

![](_page_12_Figure_14.jpeg)

#### **Conclusions & Outlook**

- The emulator-based neural network prediction achieves correlation comparable to SFM on a data set of in-situ measurements.
- Further analysis is needed to establish the reasons for systematic errors in absolute SIF prediction.
- The impact of the topographic variation on the atmospheric transfer is compensated in SFMNN.
- SFMNN predicted diurnal SIF dynamics are physiologically plausible.
- The possibility to extend this method to other sensors is currently being evaluated:
  - DESIS (onboard the ISS) in FluoMap
  - FLEX, simulated hyperspectral imagery

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#### **FluoMap Project Members**

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![](_page_13_Figure_15.jpeg)

**Deutsches Zentrum** für Luft- und Raumfahrt

![](_page_13_Picture_17.jpeg)

![](_page_13_Picture_18.jpeg)