SHIP WAKE DETECTABILITY IN TERRASAR-X IMAGERY – SUMMARY AND APPLICATIONS FOR WAKE DETECTION

TerraSAR-X / TanDEM-X Science Team Meeting 2023 Björn Tings, DLR – Remote Sensing Technology Institute, 19.10.2023



Detectability of wakes





Wake components in SAR





Wake detectability modelling Wake component dataset

- ~3000 TerraSAR-X wake samples in the dataset
- Vessel information retrieved from AIS
- Wake components manually retraced
- Proportion of main wake components in the used dataset:

Wake component	Proportion (rounded to integer)
Near-hull turbulence (nt)	59%
Turbulent wake (tw)	61%
Kelvin wake arm (kw)	21%
V-narrow wake arm (vw)	27%



Wake detectability modelling Influencing parameters



• Nine Influencing parameters affecting the detectability:

Symbol with index <i>x</i> _i	Influencing Parameter Name	Description
<i>x</i> ₁	AIS-Vessel-Velocity	Velocity of the vessel derived from AIS messages interpolated to the image acquisition time
<i>x</i> ₂	SAR-Wind-Speed	Wind speed estimated from the SAR background around the vessel using the CMOD-5h or XMOD-2 geophysical model function
<i>x</i> ₃	Incidence-Angle	Incidence angle of the radar cropped full performance value range
<i>x</i> ₄	AIS-Length	Length of the corresponding vessel based on AIS information
<i>x</i> ₅	AIS-CoG	The course over ground based on AIS information relative to the radar looking direction (0° means parallel to range and 90° mean parallel to Azimuth).
<i>x</i> ₆	SAR-Significant-Wave-Height	Significant wave height estimated from the SAR background around the vessel using the SAR-SeaStaR algorithm
<i>x</i> ₇	SAR-Significant-Wave-Length	Wave length estimated from the SAR background around the vessel using the SAR- SeaStaR algorithm
<i>x</i> ₈	AIS-CoG-SAR-Wave-Direction	Absolute angular difference between AIS-CoG and wave direction estimated from the SAR background around the vessel using the SAR-SeaStaR algorithm
<i>X</i> 9	AIS-CoG-WRF-Wind-Direction	Absolute angular difference between AIS-CoG and wind direction estimated by the Weather Research and Forecasting Model (WRF) nearby the vessel.

Wake detectability modelling Procedure for analysis of detectability

- Localizing moving vessels by AIS data collocated with SAR images
- Filtering of SAR-artifacts not related to ship movements
- Manual inspection
- Extracting influencing parameters
- Modelling of detectability
- Estimation of uncertainty
- Plotting and Interpretation



Wake detectability modelling Visualization of feature space

Wake detectability modelling Modelling the wake component detectability

- Wake component length l_w is used as indicator for wake component detectability
- Training a Support Vector Regression model f_w for mapping wake component length l_w to the influencing parameters x_i:

 $l_w = f_w(X^{9D})$, with $X^{9D} = \{x_1; x_2; x_3; x_4; x_5; x_6; x_7; x_8; x_9\}$ and w denotes wake component

• Detectable Length Metric (DLM, figure of merit for detectability) is calculated by normalizing l_w linearly between a minimum and maximum boundary:

$$DLM_{w} = g_{w}(l_{w}) = \frac{l_{w} - l_{w}^{min}}{|l_{w}^{max} - l_{w}^{min}|},$$

hyperparameter settings are:			
hyperparameter name	value		
Kernel type	polynomial		
Kernel degree d	2		
error tolerance ε	0,001		
error weighting C	1,0		
gradient γ	0,0		
offset β	0		

Wake detectability modelling Visualization of feature space with detectability model

- Gray hyperplane represents the detectability model
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Applications of wake detectability models Dissection of 9D non-linear model for turbulent wakes

- View into the models provide insight on dependency between influencing parameters and detectability of wake components (here turbulent wakes)
 - The vertical axis is labelled with [DLM] due to figure of merit for detectability being
 Detectable Length Metric

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Applications of wake detectability models Characteristics of influences

Influencing parameter	Summary on characteristics of influences on detectability of wake components "↑": Wake components better detectable "≈": Detectability of wake components hardly influenced "n.a.": No statement available in scientific publication				
	Near hull turbulences±	Turbulent wakes	Kelvin wake arms	V-narrow wake	
Vessel's velocity	↑ for faster ships ⁿ	↑ for faster ships ⁿ	↑ for faster ships ^b	↑ for faster ships ^b	
Vessel's length	↑ for larger ships ⁿ	↑ for larger ships ⁿ	↑ for larger ships ^b	↑ for larger ships ⁿ	
Vessel's course over ground	↑ for CoGs parallel to range direction, when vessel's velocities are at most moderate ⁿ	~	↑ for CoGs parallel to Azimuth direction ^b	↑ for CoGs parallel to Azimuth direction ^b	
Incidence angle	↑ for larger incidence angles, when vessel's velocities are at least moderate ⁿ	↑ for smaller incidence angles	↑ for smaller incidence angles ^b	↑ for smaller incidence angles ^b	
Wind speed	↑ for lower wind speeds ⁿ	↑ for lower wind speeds ^b	↑ for lower wind speeds ^b	↑ for lower wind speeds ^b	
Sea state's wave height	≈ ⁿ	≈ ^t	≈ ^t	≈ ^t	
Sea state's wave length	↑ for higher wave lengths, when wind speeds are at least moderate ⁿ	↑ for lower wave lengths, when wind speeds are at least moderate ⁿ	≈ ⁿ	≈ ⁿ	
Sea state's wave direction	≈ ⁿ	↑ for wave directions parallel to CoG, when wave lengths correspond to swell waves ⁿ	↑ for wave directions parallel to CoG n	≈ ⁿ	
Wind direction	≈ ⁿ	↑ for wind directions perpendicular to CoG ⁿ	~	↑ for wind directions perpendicular to CoG ⁿ	

Applications of wake detectability models Tuning of wake detectors

Wake detector based on YOLOv4:

Precision	Recall	True-Negative-Rate	Accuracy	F1-Wert
0,759	0,506	0,000	0,373	0,607

• YOLOv4 wake detector with static threshold for filtering of false alarms:

Precision	Recall	True-Negative-Rate	Accuracy	F1-Wert
0,742	0,264	0,429	0,247	0,390

• YOLOv4 wake detector with dynamic threshold for filtering of false alarms (based on $l_{wX} = f_w(x_3, x_4, x_5, x_6, x_7, x_8, x_9, x_{pol})$):

Precision	Recall	True-Negative-Rate	Accuracy	F1-Wert
0,824	0,483	0,357	0,399	0,609

Applications of wake detectability models Estimation of vessel's velocity

• Inversion of $f_w(X^{9D})$ with respect to vessel's velocity x_1 :

 $f_{w}^{x_{1}-1}(l_{w}', x_{2}, x_{3}, x_{4}, x_{5}, x_{6}, x_{7}, x_{8}, x_{9}, x_{pol}) = x_{1}$ where $l_{w}' = DLM_{w} |l_{w}^{max} - l_{w}^{min}| + l_{w}^{min}$

• Method estimates vessel's velocity required as a minimum so that the respective wake component appears at least with length l'_w in a SAR image

	Near-hull turbulences	Turbulentwakes	Kelvin wake arms	V-narrow wakes	Highest confidence value
RMSE (m/s)	4,60	2,45	1,17	4,86	2,71

Applications of wake detectability models Wake detectability comparison between sensors

- In case the bars are not visible in the plots, this means $\overline{DLM_{w,s}} = 0$.
- Detectability difference $\overline{\Delta DLM_{w,s_1,s_2}}$ are indicated by colored symbols
- Uncertainties RMSE_{w,s} are visualized for each sensor by error bar.
- X-Band better for detection of Kelvin wake arm and Vnarrow wakes

Summary & Conclusion

- Detectability of ship wakes is influenced by ship properties, image acquisition settings and environmental conditions (influencing parameters)
- Characteristics of influences are reproduced by detectability models
- > Determined characteristics are in good agreement with literature
- Ability of SAR missions to detect ship wakes can be compared
- X-Band is better suited for detection of Kelvin wake arms and V-narrow wakes than C-Band

> Precision of wake detectors can be improved by dynamic thresholds

New method for estimation of vessel's velocity by model inversion suggested, performance can keep up with state-of-the-art methods

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About

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Author: Björn Tings

Institute: DLR – Remote Sensing Technology Institute

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Thank you! Questions? Critics?