

# Generation of magnified raster tiles using shift tiles to improve situational awareness

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**Abstract**—Maritime infrastructures are an important part of society in many aspects (safety and security, economy, environment) and therefore require special protection. From ensuring uninterrupted global trade and economic stability to safeguarding national security and protecting coastal communities, the comprehensive situational awareness picture plays a vital role in preserving the safety and security of these vital assets.

To improve the operators' situational awareness, this work suggests a novel way to provide non-linear scaling of maps to enable legacy front-ends to provide a high resolution view of disconnected areas without requiring the user to change their viewport. So-called shift tiles are generated to scale different parts of given maps, allowing users to apply the desired scaling effect to any base map, regardless of the client being used.

**Index Terms**—maritime infrastructures, situational awareness, GIS, maps, tiles, shift tiles, raster tiles, magnified maps

## I. INTRODUCTION

Maritime infrastructures hold significant societal importance, encompassing aspects such as the economy, the environment, and safety and security. The fact that more than 80% of global trade volume is transported by ships highlights the critical role of maritime infrastructures in the global economy [1]. Consequently, a comprehensive situational awareness picture is essential in this context.

Research in various domains has addressed methods to enhance maritime situational awareness. Depending on the specific use case, studies may focus on aspects such as cyber security [2]–[4] or sensor data fusion [5], [6]. Regardless of the use case, important locations of interest, such as ports, are often dispersed over vast distances. These specific sites require detailed observation, while simultaneously considering larger areas that need to be monitored as a whole, albeit with less focus on individual details.

To address this challenge, operators often need to constantly switch between higher resolution, zoomed-in views of specific locations and a broader view of the entire area. Alternatively, they may keep multiple viewports open simultaneously. However, it would be advantageous to have a situational awareness picture that offers a focused view of regional areas, such as harbours, while also providing a clear overview of the surrounding water areas, such as seas. This would eliminate the need for users to switch between different views or

maps, enabling them to maintain their situational awareness seamlessly.

In previous studies, magnifying effects for map applications have been presented to cater to diverse use cases [7]–[10]. However, these solutions are typically dependent on the client displaying the data, making it challenging to adapt them to existing situational awareness picture frameworks. In contrast, this work proposes focusing on the middleware while keeping the interfaces unchanged. Consequently, neither the server nor the client needs to be modified to incorporate the shift effect for receiving map material.

## II. MOTIVATION

Our approach aims to enhance the observability of the maritime situation by incorporating maps that depict both dispersed local infrastructures, such as ports, and larger areas, such as seas. To achieve this goal, we utilize raster tiles that employ a magnifier effect to showcase detailed views of interesting areas on the map, while still considering the broader regions.

To implement the distortion effect on different base maps using predefined parameters, we require a mechanism that can transmit the distortion information independently from the map material. To fulfil this requirement, we generate shift tiles based on the idea of Normal Maps which are commonly used in computer graphics. These tiles can be seamlessly applied to existing base maps and, by providing them in slippy tile format, can be accessed and, if necessary, further processed by existing applications.

## III. PRELIMINARIES

**Slippy map tiles** are essentially a naming convention for map tiles. The earth is divided into squared tiles and each tile is addressed with the variables  $x$ ,  $y$  and  $z$ . The rows and columns are represented by  $x$  and  $y$  and  $z$  represents the zoom factor, meaning that implicitly, a quad tree is created, with the zoom factor defining the depth at which to look for a map tile and  $x$  and  $y$  specifying the node to look for – meaning that there are  $2^z$  available coordinates for each zoom level  $z$ . With the lowest zoom factor 0, the whole earth is mapped with only one tile. Each time the zoom factor is increased by one, the





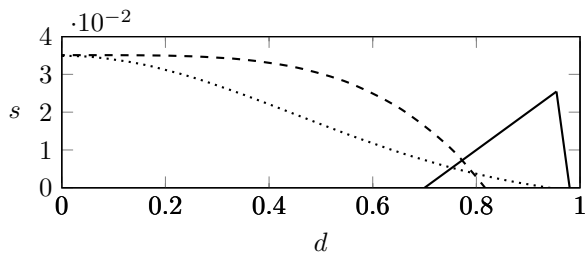


Figure 3. Unified shift functions for  $x$ ,  $y$  and  $z$  with distance to  $c$  in relation to magnifier effects radius. The horizontal axis denotes the distance  $d$  in relation to the radius and the vertical axis represents the shift  $s$  of the considered pixel. The solid plot shows the values used for the shift on the  $x$  and  $y$  axes. Two different functions are used for the shift on the  $z$  axis. The dotted and dashed plots show these used functions. While the dotted plot uses Gaussian function the dashed plot uses a fourth grade function for the  $z$  shift. By multiplying this value with the unit vector, the shift is obtained.

approach use-case agnostic and adaptable to a wide range of requirements. However, this flexibility naturally leads to the question of *how* these tiles are generated.

In the specific context of magnifying glasses, this work presents a shift map service that does not rely on pre-calculated shift maps. Instead, the service generates the necessary maps procedurally, utilizing parameters provided via the request query string. To illustrate this solution for a particular use case, the generation process will be outlined below.

The shift information for the *shift tiles* is generated differently for the  $z$  axis than for the  $x$  and  $y$  axes. This is shown in Figure 3. A function for the  $z$  shift is the Gaussian formula (dotted). This means that the closer the pixel under consideration is to the centre  $c$  of the magnifier effect, the larger the shift on the  $z$  axis is generated. The shift flattens out towards the edge of the magnifier effect. Thus, at the edge of the magnifier effect and beyond, there is no more  $z$  shift. After all, there is no magnification effect beyond the edge of a magnifying glass.

The next function used is a 4th degree function (dashed) like  $-d^4 + n$  where  $d$  is the distance from the pixel under consideration to the centre and  $n$  is how deep the  $z$  shift is at maximum. So how much the  $z$  shift is around  $c$ . If the function gives a negative result, a  $z$  shift of 0 is set. If a  $z$  shift greater than one is required, this function keeps the rings of the individual  $z$  layers narrow, so that the edge of the magnifying effect remains relatively narrow compared to the Gaussian function.

The plot in Figure 3 also shows the proportional shifts for the  $x$  and  $y$  coordinates using the distance  $d$  of the pixel coordinate to the centre  $c$  of the magnifying glass effect in relation to each other. For the  $x$  and  $y$  axes respectively, no shift is generated around the centre  $c$  (solid) – instead, the centre of the circle is merely shifted to the next zoom level via a  $z$  shift of 1. Beyond a radius of more than 70%,  $x$  and  $y$  shifts take over, giving a smooth transition from the enlarged centre to the surrounding, original map data. To get the correct shift from the value of Figure 3, it must be multiplied by the unit vector.

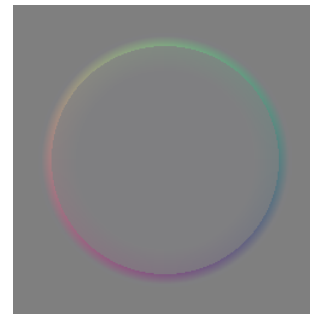


Figure 4. Shift tile with the distortion values of Figure 3. For presentation purposes, the colours have a higher contrast than the real shift tiles to illustrate their values in a range that is visible to the human eye.

An example of a shift tile can be seen in Figure 4. It is easy to see the ring representing the shift on the  $x$  and  $y$  axes. The colour of the shift values of the  $z$  axis, on the other hand, is more subtle – as a value of 1 represents the next higher zoom level (and thus a magnification by a factor of 2), the values tend to be lower, making them harder to see.

## VII. RESULTS

Figure 5 shows the resulting maps generated using the proposed shift tiles, showing the fishing port of Bremerhaven. For the map in the middle, the magnifier effect was generated with the Gaussian function. You can clearly see from the wide border that as the distance to the centre increases, the shift value becomes smaller only very slowly (see Figure 3, dotted line). The map on the right, on the other hand, has only a narrow border.

It is easy to see that the magnifier effect with the fourth degree function requires less area for the distortion effects. Thus, there is more space for regular map information on this map than on the map in the middle. As intended, both maps show one area in more detail (high zoom level) without neglecting the rest of the port.

## VIII. FUTURE WORK

A very useful tool for this could be another service that offers, for example, the position data of ships using *Automatic Identification System (AIS)* [11] in near real time. With the help of the shift tiles, the coordinates for the pins in the map client would be adjusted, allowing them to be correctly displayed on the map with a magnifying glass effect. In this way, the positions of the ships are correctly displayed on the map despite the distortion effect, without the need for a new client.

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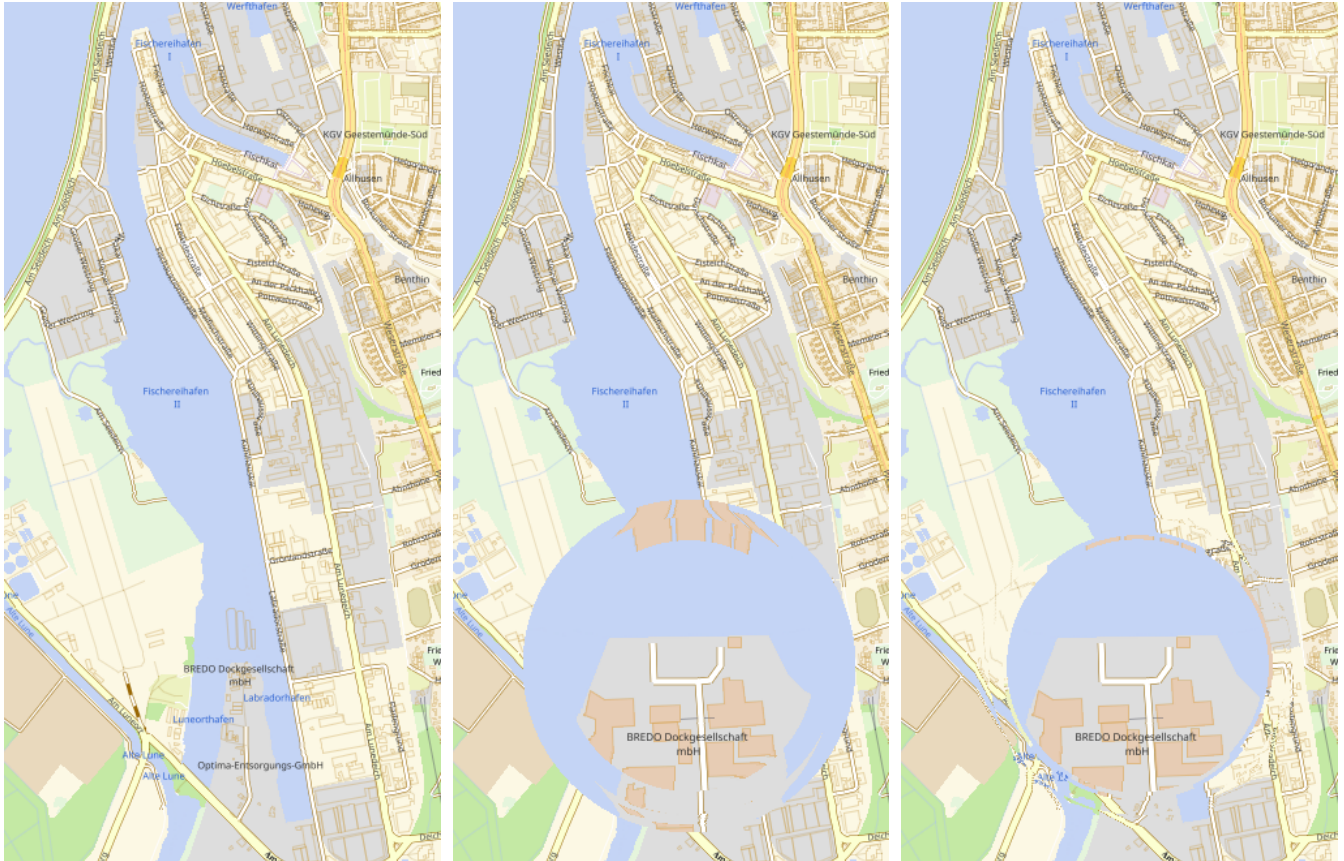


Figure 5. On the left side is the base map without any magnifier effects. The middle shows the result of the map with the magnifier effect using the Gaussian function for the  $z$  shift. On the right side is the map with the magnifier effect using the function of the fourth grade.

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