

On the Theory of Discrete, Adaptive Space Filling Curves

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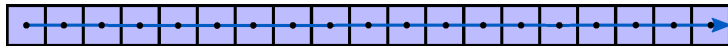
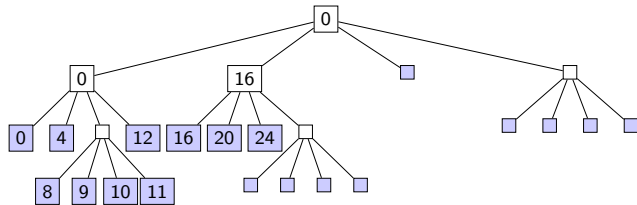
David Knapp (Uni Bonn and DLR)

SIAM Conference on Parallel Processing 2020



Knowledge for Tomorrow





Intro

In this talk, we want to define a proper mathematical framework for SFCs in AMR.



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But wait: Don't we already have definitions?



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Yes, but...



Intro

Most definitions of SFCs have at least one of these issues:

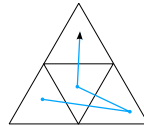
- Come from an analytical point of view
- Are not explicit
- Only on uniform subdivisions
- Actually allow stuff that should be illegal
- Restrict us to $1 : 2^d$ refinement



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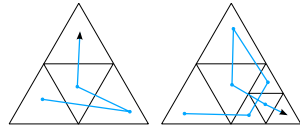
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Theorem

Let X be an SFC, then Y holds.



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We need a rigorous definition of X to correctly proof the theorem.



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We want a standalone definition suited for AMR, that is:

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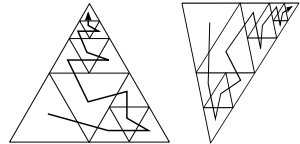
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We want a standalone definition suited for AMR, that is:

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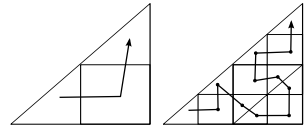


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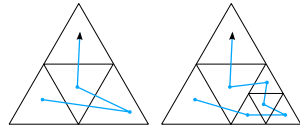
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- Allows for Code generation



Disclaimer

There exist lots of approaches where discrete SFCs are explicitly or implicitly described.
Not everything we present here is entirely new.
But maybe its the first time, we do it rigorously.



Idea

What is an SFC?



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Some ordering of our elements.

$$\text{AMR mesh} \xrightarrow{\text{SFC}} \{0, 1, 2, 3, \dots\} \quad (1)$$



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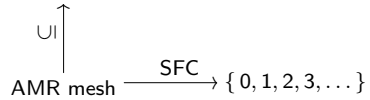
$$\text{AMR mesh} \xrightarrow{\text{SFC}} \{0, 1, 2, 3, \dots\} \quad (1)$$

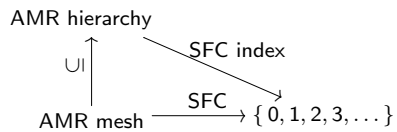
Adaptive meshes are not alone, they come with a refinement hierarchy!



AMR hierarchy

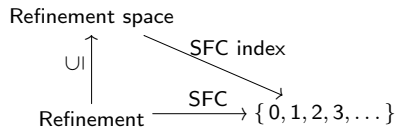
(2)





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Refinement spaces

Definition (refinement space)

A **refinement space** consists of:

- A set \mathcal{S} , the **elements**
- A map $\ell: \mathcal{S} \rightarrow \mathbb{N}_0$, the **level**
- Maps $R^l: \ell^{-1}(l) \rightarrow \mathcal{P}(\mathcal{S}^{l+1})$, the **refinement maps**

such that



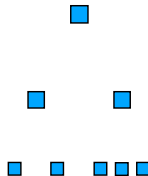
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 $l = 0$

 $l = 1$

 $l = 2$



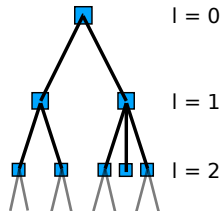
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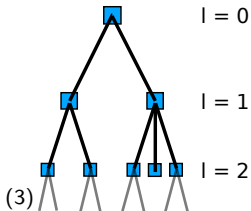
such that

- Every element of level $l > 0$ has a **unique parent**:

$$\bigcup_{E \in \mathcal{S}^l} R^l(E) = \mathcal{S}^{l+1}.$$

$$R^l(E) \cap R^l(E') = \emptyset \text{ for } E \neq E' \in \mathcal{S}^l$$

- $\mathcal{S}^0 = \{ \mathcal{E}_0 \}$



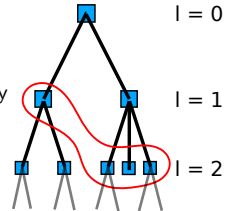
(4)

Refinements

Definition (refinement)

A **refinement** of a refinement space \mathcal{S} is a subset \mathcal{S} constructed via successively refining level 0, thus:

- $\mathcal{S} = \mathcal{S}^0$ is a refinement.
- $\mathcal{S} \setminus E \cup R^l(E)$ is a refinement for each $E \in \mathcal{S}$.



SFC index

Definition (SFC index)

An **SFC index** \mathcal{I} is a map

$$\mathcal{I}: \mathcal{S} \rightarrow \mathbb{N}_0 \quad (5)$$

- $\mathcal{I} \times \ell: \mathcal{S} \rightarrow \mathbb{N}_0 \times \mathbb{N}_0$ is injective. **Restricted to a level, \mathcal{I} is unique.**
- E ancestor of $E' \Rightarrow \mathcal{I}(E) \leq \mathcal{I}(E')$. **Refining does not decrease the index.**
- $\mathcal{I}(E) < \mathcal{I}(\hat{E})$ and \hat{E} not a descendant of $E \Rightarrow \mathcal{I}(E) \leq \mathcal{I}(E') < \mathcal{I}(\hat{E})$ for all descendants E' of E . **Refining is 'local'.**



SFCs

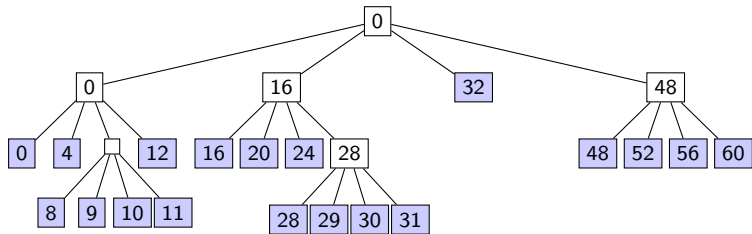
Definition (Space-filling curve)

A (discrete) **Space-filling curve** is an SFC index restricted to a refinement.

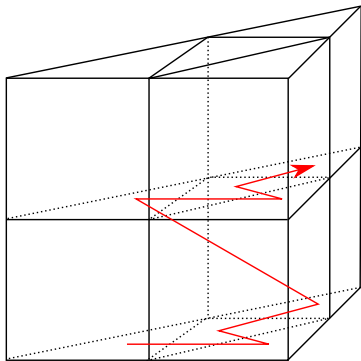
$$\mathcal{I}_{|\mathcal{S}}: \mathcal{S} \rightarrow \mathbb{N}_0 \quad (6)$$



A 4x4 grid illustrating the steps of a breadth-first search algorithm. The grid is divided into four 2x2 quadrants. Blue lines and arrows show the search path from the start cell (1,1) to the goal cell (4,4). The path is: (1,1) → (1,2) → (2,2) → (2,3) → (3,3) → (3,4) → (4,4). The arrows indicate the direction of the search at each step.



Cross product



The diagram shows a 3D tensor (a cube) on the left, which is equal to the product of a 2D tensor (a parallelogram) and a vector (a vertical line with an arrow) on the right. The 3D tensor is divided into two parts by a vertical dashed line. The 2D tensor is a parallelogram with a red zigzag line and an arrow. The vector is a vertical line with a red arrow pointing upwards.

Cross product

Definition (Cross product of refinement spaces)

Let $(\mathcal{S}_1, R_1, \ell_1)$ and $(\mathcal{S}_2, R_2, \ell_2)$ be refinement spaces. The cross product $\mathcal{S}_\times = \mathcal{S}_1 \times \mathcal{S}_2$ is defined via

- $\mathcal{S}_\times^I := \mathcal{S}_1^I \times \mathcal{S}_2^I$
- $\ell_\times(E_1, E_2) := \ell(E_1) = \ell(E_2)$
- $R_\times^I(E_1, E_2) := R_1^I(E_1) \times R_2^I(E_2) \subset \mathcal{S}_1^{I+1} \times \mathcal{S}_2^{I+1} = \mathcal{S}_\times^{I+1}$

Proposition

The cross product is a refinement space.



Cross product

Definition (Cross product of SFC indices)

The cross product index $\mathcal{I}_\times = \mathcal{I}_1 \times \mathcal{I}_2$ on $\mathcal{S}_1 \times \mathcal{S}_2$:

$$\mathcal{I}_\times : \mathcal{S}_1 \times \mathcal{S}_2 \rightarrow \mathbb{N}_0 \quad (7)$$

defined recursively by

$$\mathcal{I}_\times(E_1, E_2) := \mathcal{I}_\times(P_1, P_2) + m_1^{>l} m_2^{>l} (\text{sibid}_1(E_1) * \#\text{siblings}(E_2) + \text{sibid}(E_2)) \quad (8)$$



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where

$$m^{>l} := \prod_{i>l} \max_E |R^i(E)| \quad (9)$$

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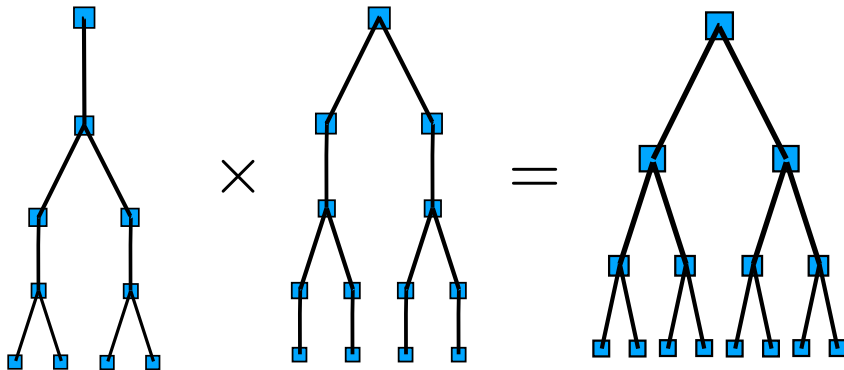
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Proposition

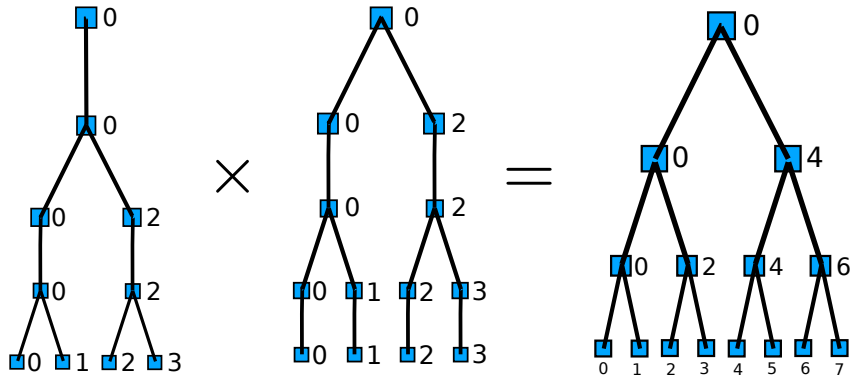
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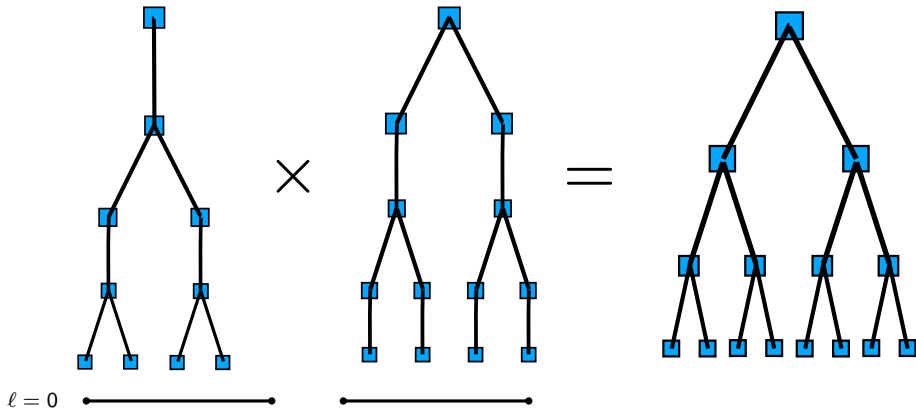
An interesting example



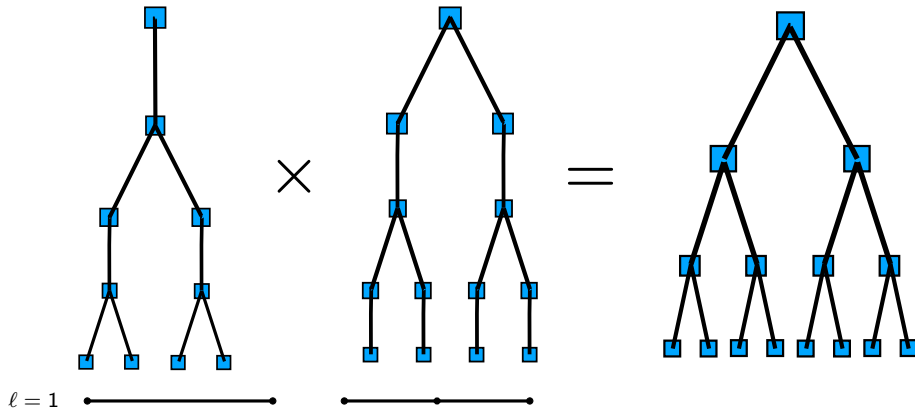
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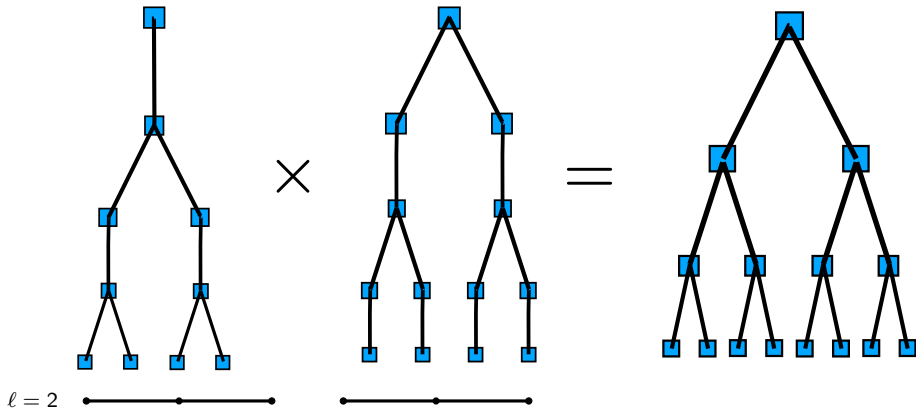
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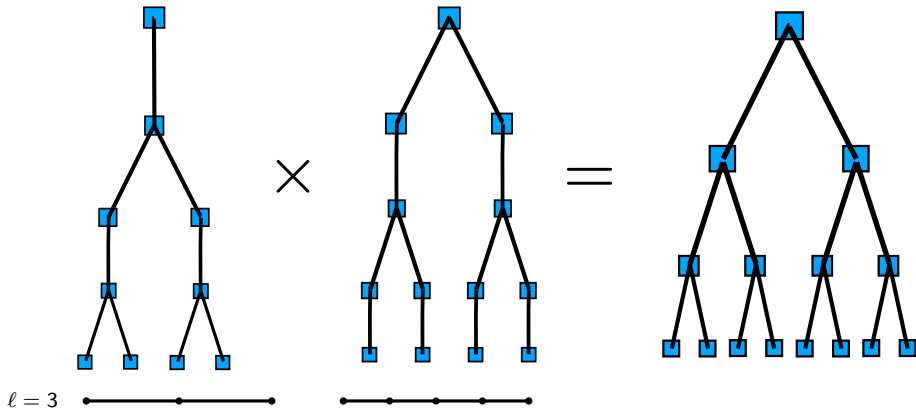
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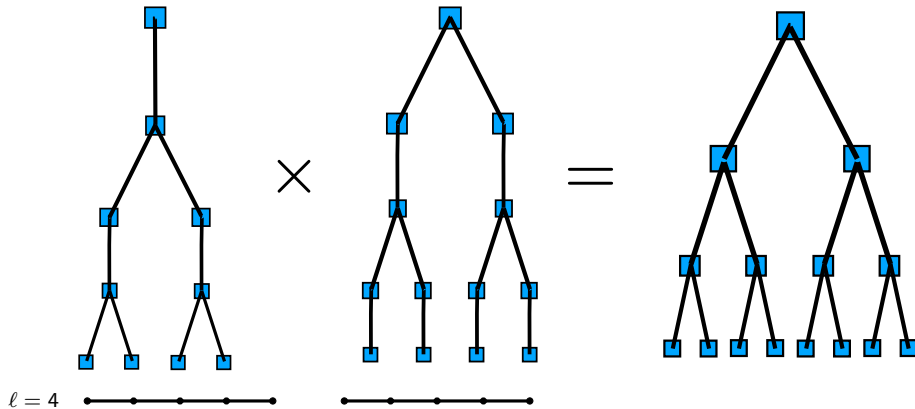
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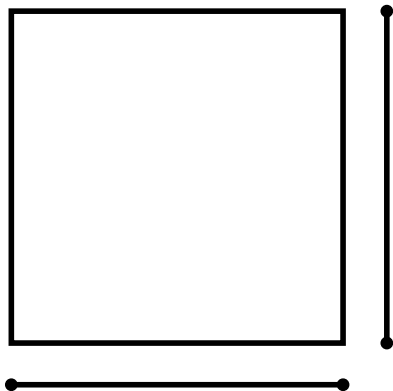
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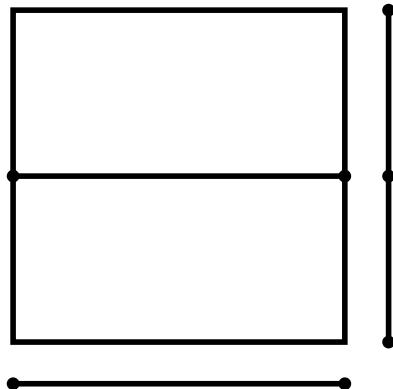
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$$\ell = 0$$



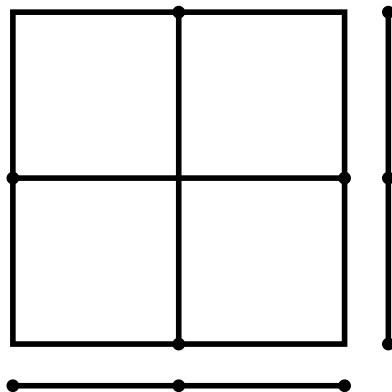
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$$\ell = 1$$



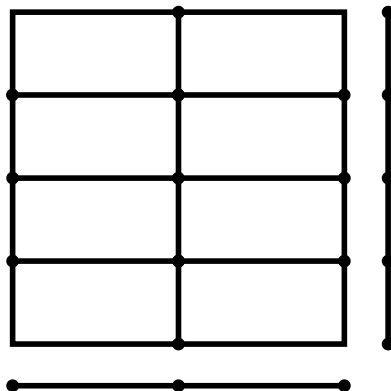
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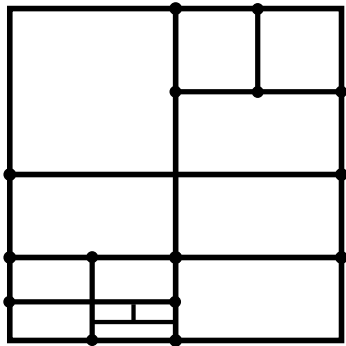
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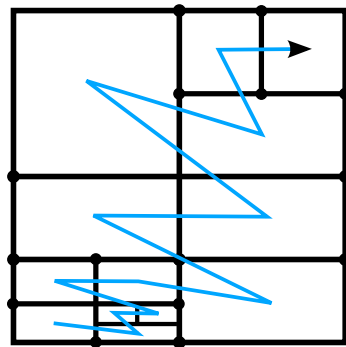
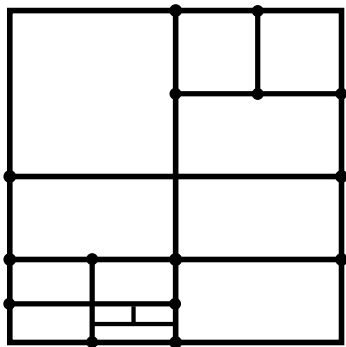
$$\ell = 3$$



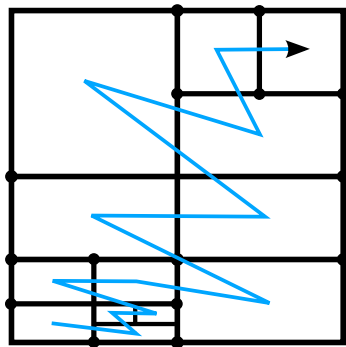
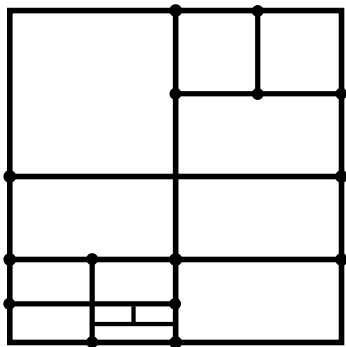
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⇒ An SFC for dyadic refinement.

Furthermore

- Can be straightforwardly extended to forest
- Can define partitions
- TODO: How to encode (face-)neighbors?
- TODO: Can we find other cross products?



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Thank you.

Questions?



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PhD thesis, Rheinische Friedrich-Wilhelms-Universität Bonn, 2018.



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