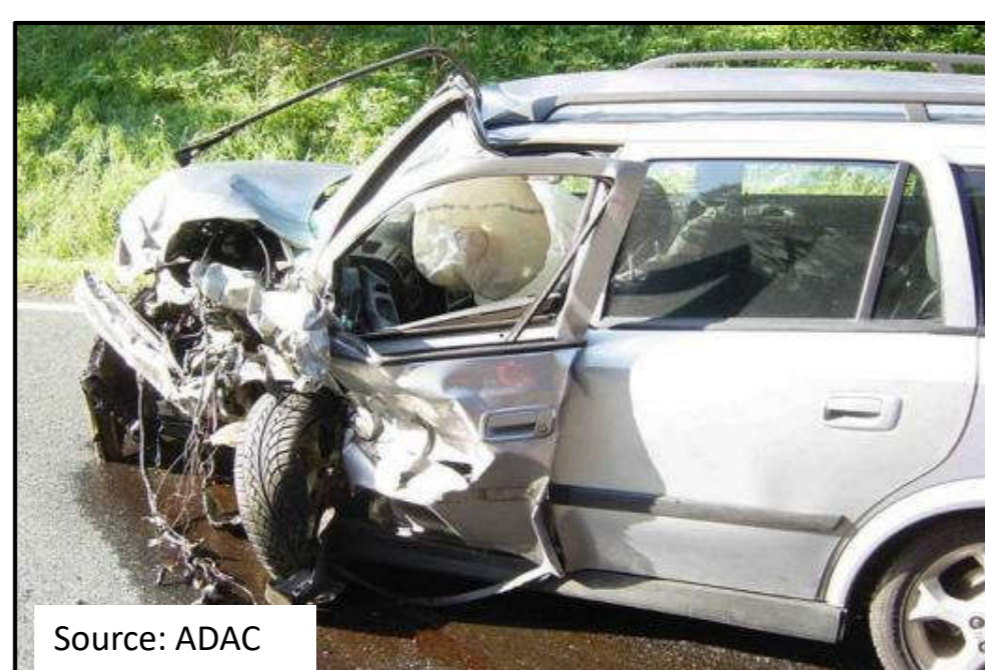


Oliver Deisser

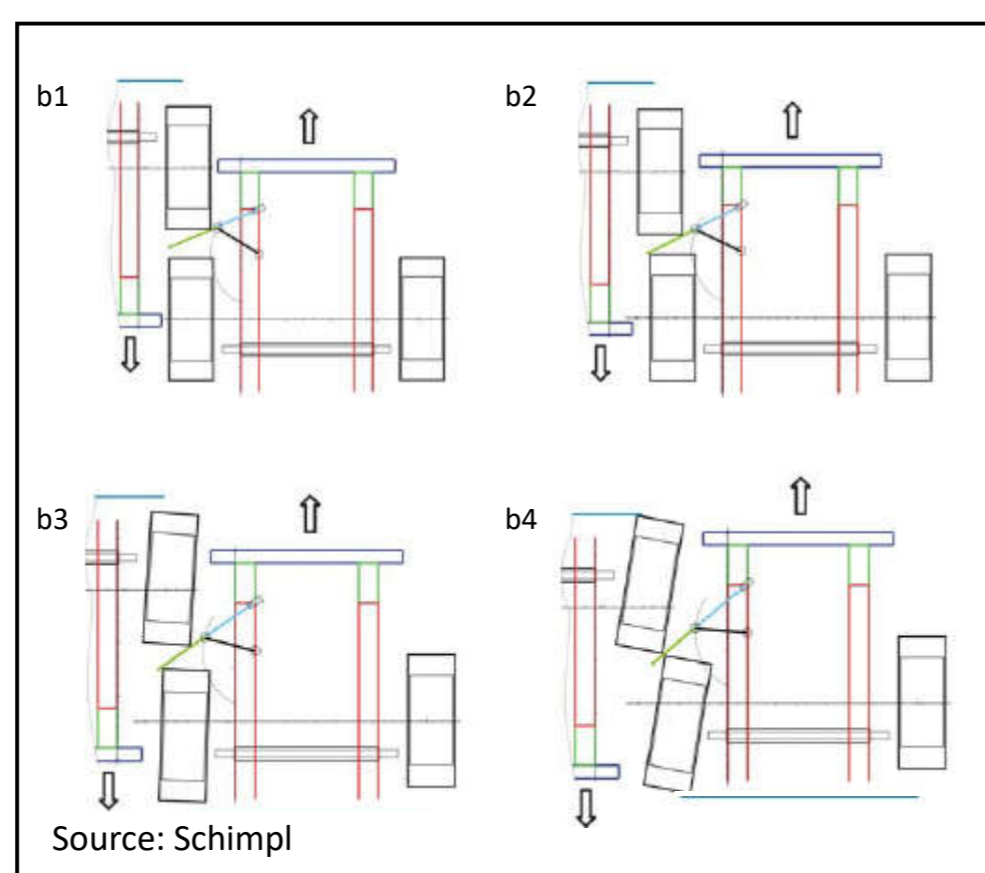
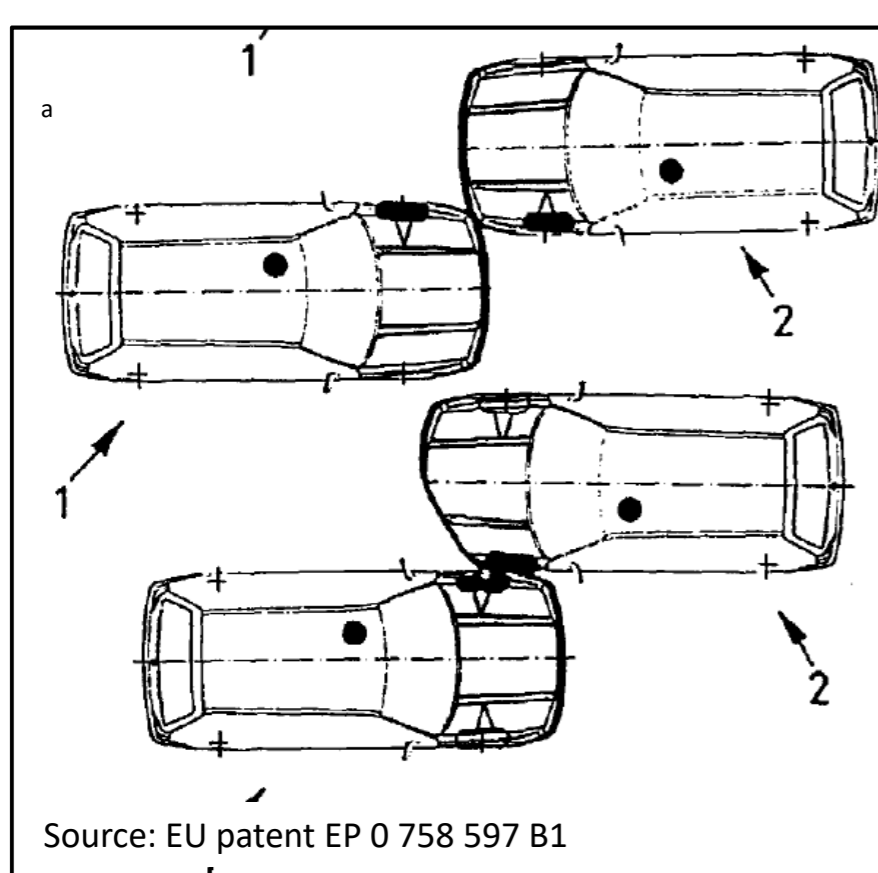
# Innovative design steps towards a safe active lightweight chassis for an electric vehicle

## 1. Motivation

1.1. Current regulations, the lack of crash compatibility in reality

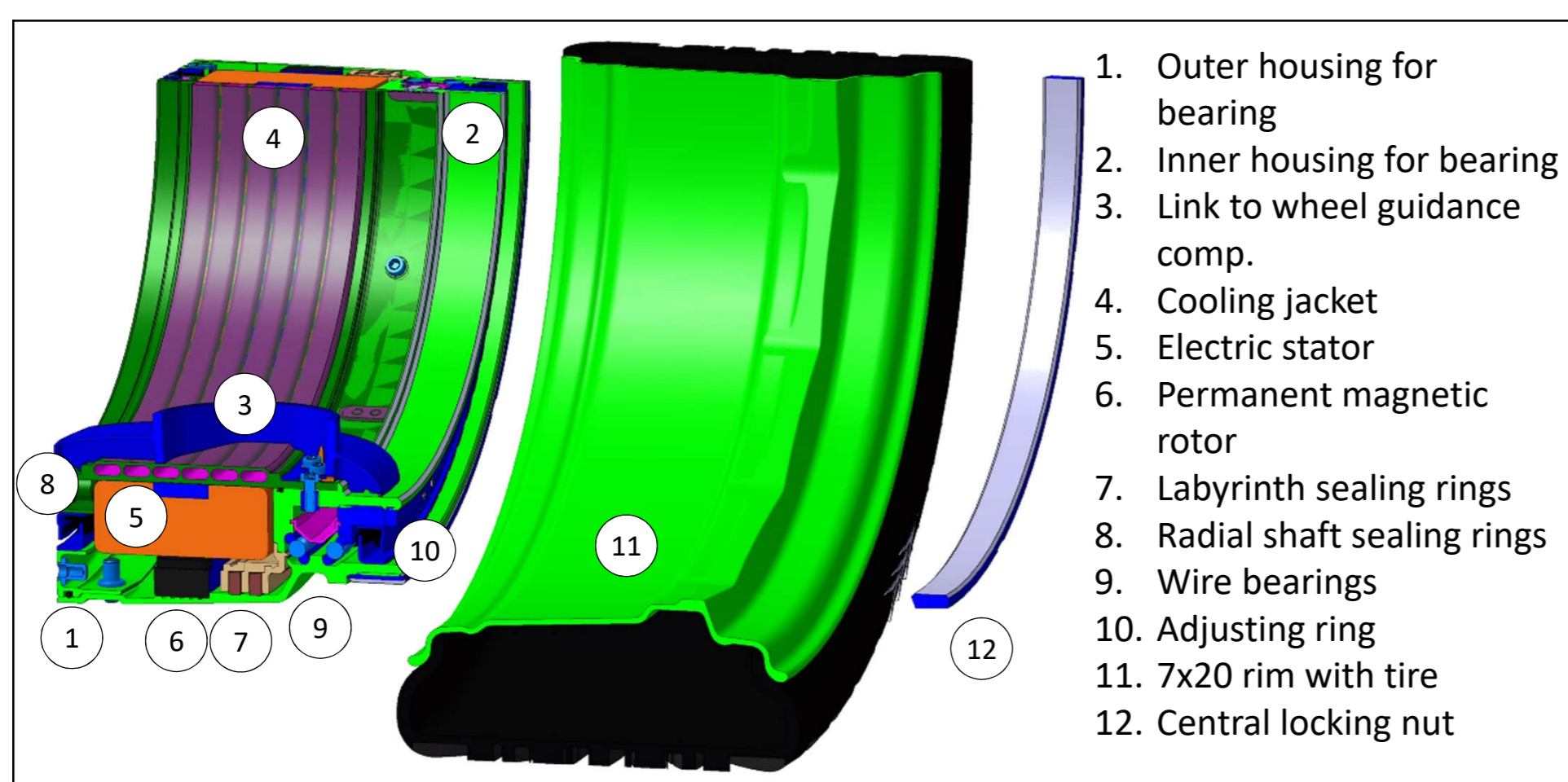


1.2. Deflection as an existing solution



## 2. The chassis system of the Next Generation Car – Urban Modular Vehicle (NGC-UMV)

2.1. The orbital wheel concept detailed design



2.2. Active two axis independent steering system



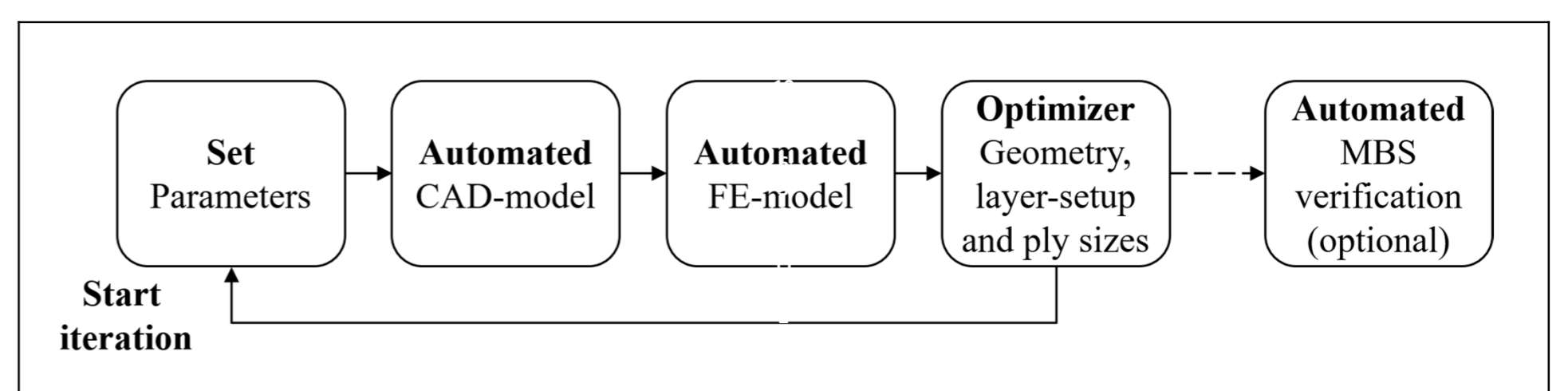
### Advantages of wheel independent steering:

- Reduced energy consumption
- Better driving performance
- High active safety potential

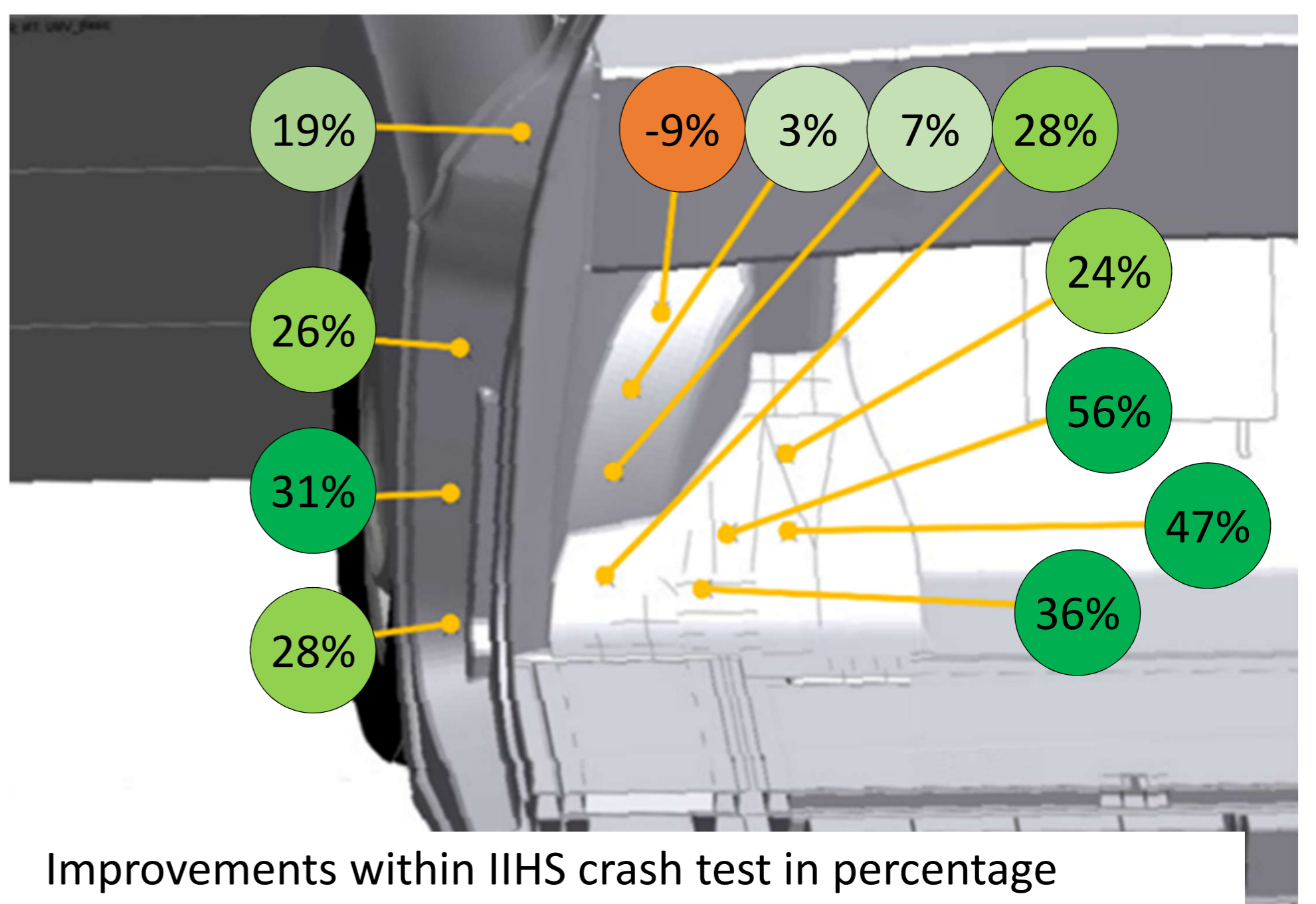
### Potential of Integration of a simple camber actuator, thus:

- Better grip
- Enhanced cornering stability

2.3. Virtual dimensioning process for the GFRP transverse leaf spring



2.4. The wheel as deflection shield is enough for an improvement in passive safety



## 3. Conclusion and Outlook

A methodical design and dimensioning of the transverse leaf spring is actually a work in progress. Also, the dimensioning and the calculation of the needed torsion moments and the energy demand of the two-axis steering system will be done during this project. The build-up of a functional demonstrator for the bearing is planned within this year. The final virtual integration of the suspension system into the NGC-UMV CAD model is the last step before a full functional demonstrator is build.

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