Removing Hanging Faces from Tree-Based Adaptive Meshes for Numerical Simulations – an implementation in t8code

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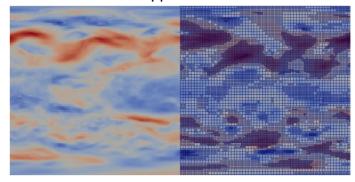


Adaptive Mesh Refinement (AMR) in Numerical Applications with t8code

Why AMR?

- Many mathematical applications are based on mesh structures
- The element size correlates with the accuracy (but also with the computational costs)
- AMR as a compromise of high accuracy and computational efficiency

numerical application with AMR





Adaptive Mesh Refinement (AMR) in Numerical Applications with t8code

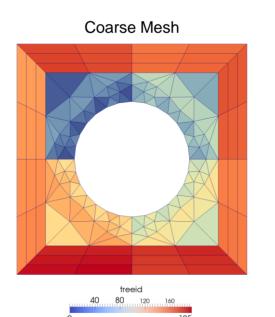
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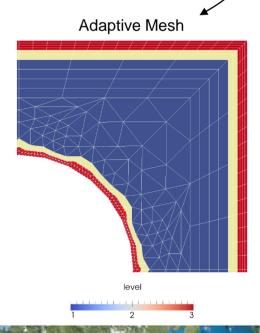
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t8code ("tetcode"):

- A open-source C/C++ library for parallel AMR [4]
- Tree-based hybrid meshes
- · Adaptive refinement of each tree
- A modular Space-filling Curve Index (SFC Index) for element enumeration

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Coarse Mesh Adaptive Mesh

numerical application with AMR

How does tree-based AMR work?



- **Refinement criterion**: refine an element E in the mesh if $E \cap G \neq \emptyset$
- Refinement: the replacement of an element E by its children: $E \to \{C_0, C_1, C_2, C_3\}$ with $\cup_i C_i = E$

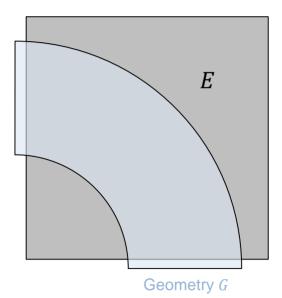
Refinement Level

0

Tree

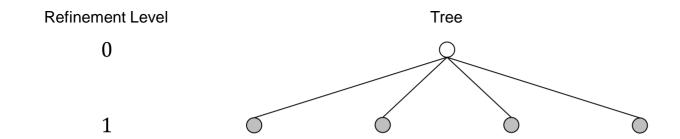
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Adaptive Mesh

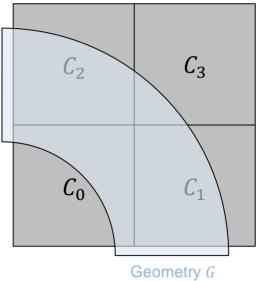




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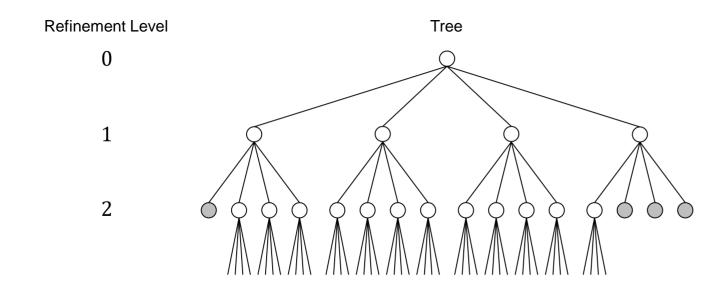




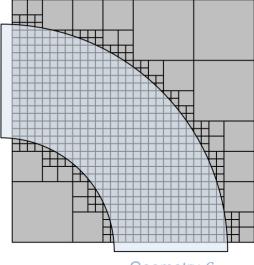




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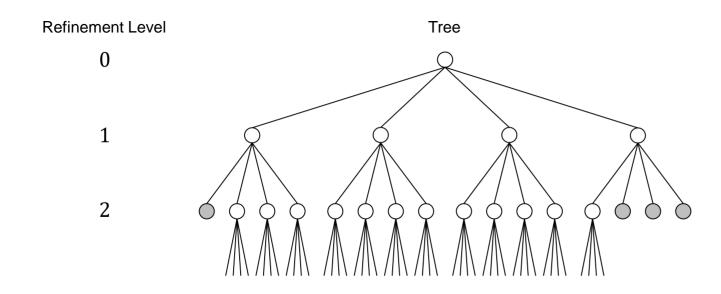
Adaptive Mesh



Geometry G

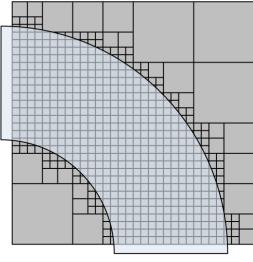


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• Hanging Faces: the intersection of an elements vertex with an other elements face

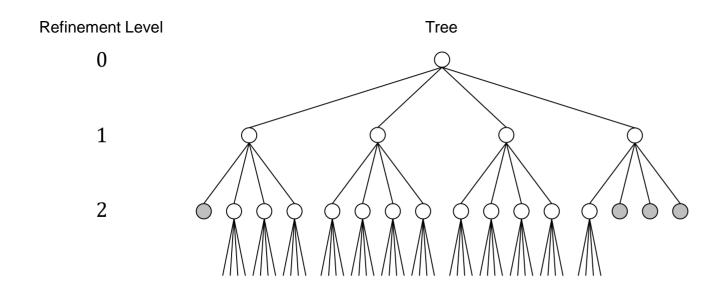
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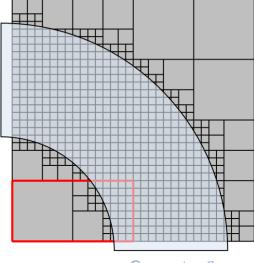


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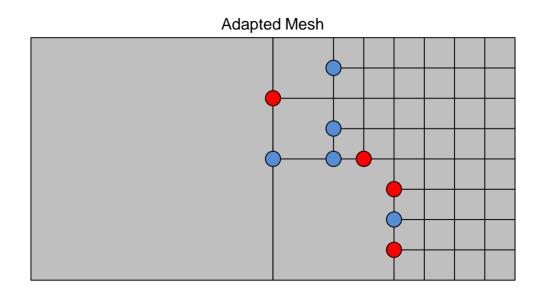
Geometry G

How can we make the mesh conformal after adaptation?



Removing hanging faces is a two-step procedure*:

- 1. Remove red nodes: balance the mesh
- 2. Remove blue nodes: use transition cells of triangular subelements



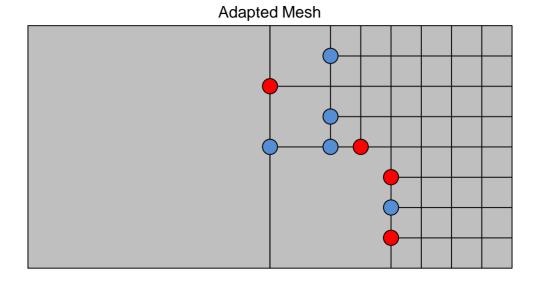


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1. Balancing:

In balanced meshes, the maximum level difference of neighboring elements is 1.





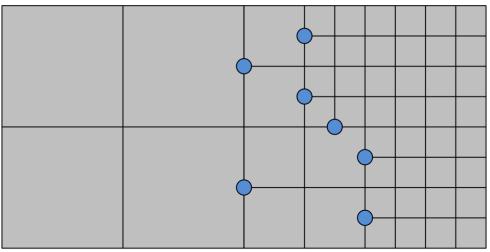
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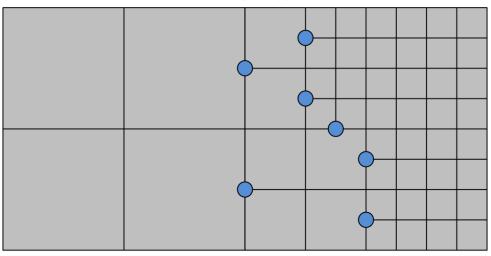
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2. Transitioning:

A transitioned mesh is a mesh that is conformal due to the insertion of **transition cells** T - families of **triangular subelements** $\{S_0, S_1, ..., S_n\}$.

Balanced Mesh





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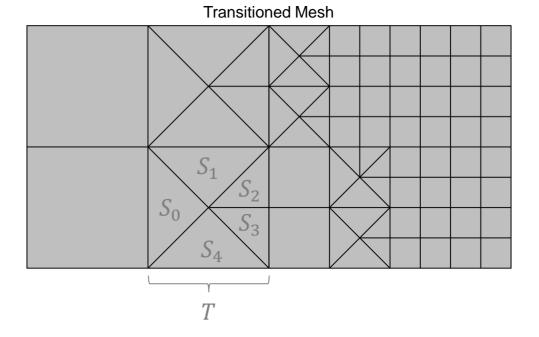
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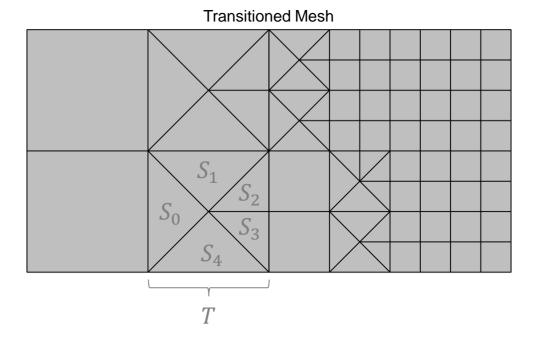
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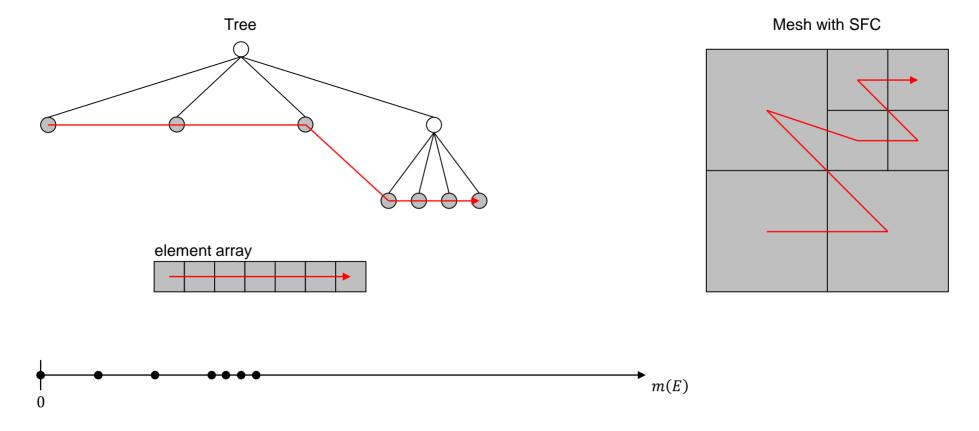
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How can we find neighbors in transitioned meshes? Lets find a suitable SFC Index!

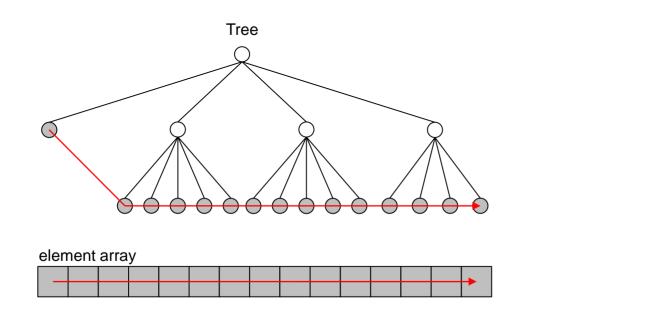


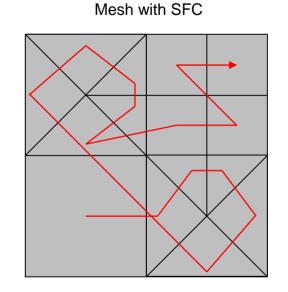
• t8code uses the **Morton-Index** $m(E) \in \mathbb{N}_0$ to enumerate its elements

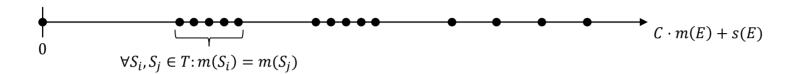




• In transitioned meshes, we extend the Morton-Index by adding the **Subelement-Index** $s(E) \in \mathbb{N}_0$

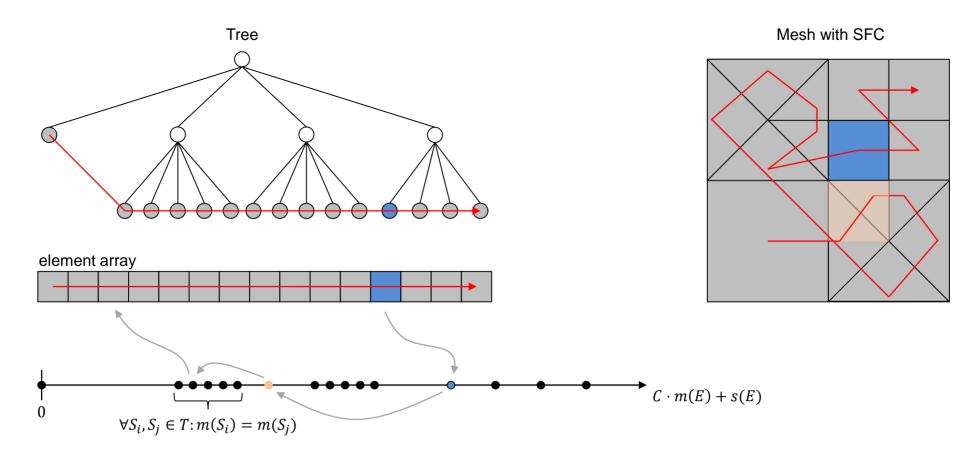






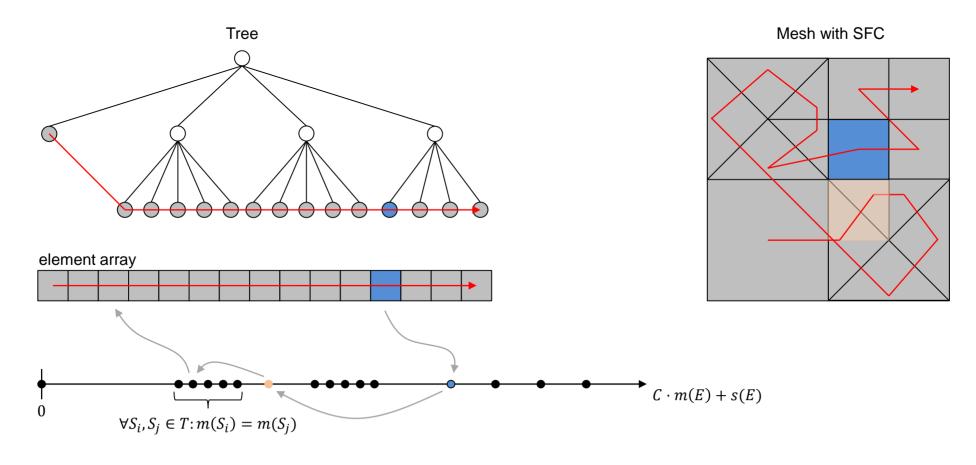


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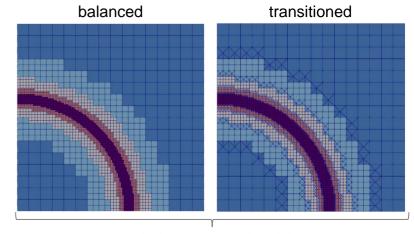
But is this approach efficient?



Benchmarks

Testcase – comparing balanced and transitioned meshes:

- Construct a balanced mesh and its transitioned version
- Compare the LFN runtime of these meshes



min level 4, max level 8

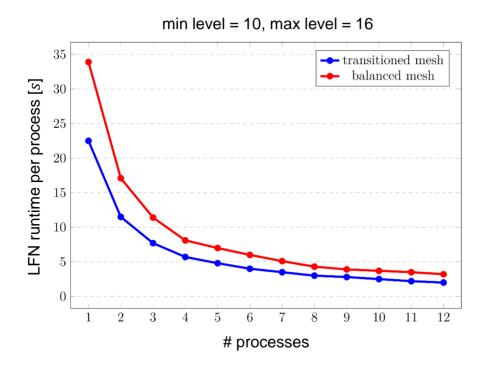


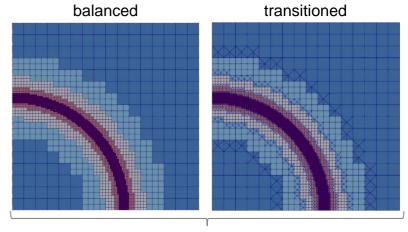
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Testcase – comparing balanced and transitioned meshes:

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Results:





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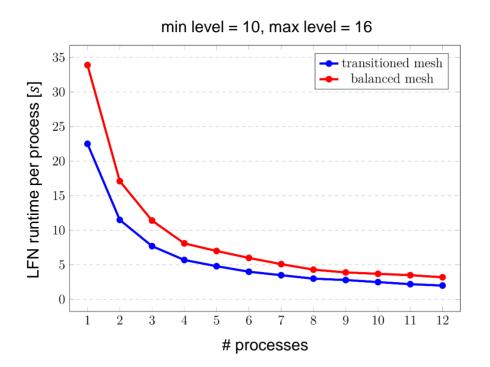


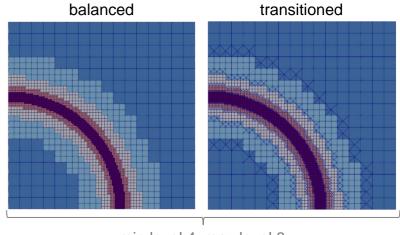
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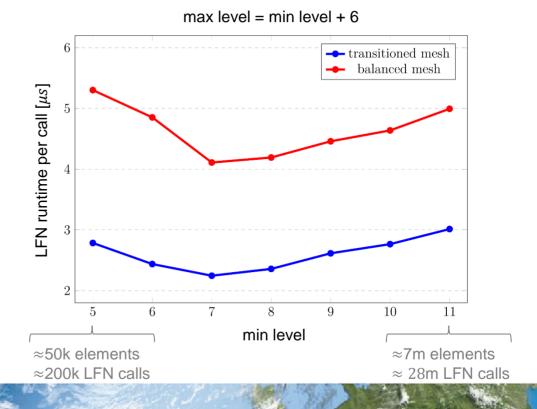
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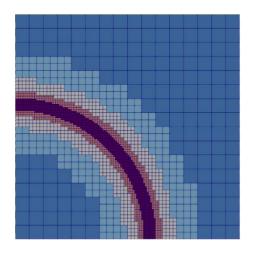


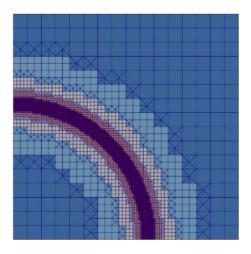
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Conclusion and Outlook



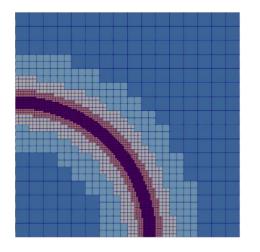


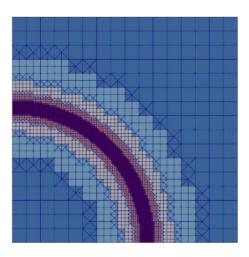
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Outlook/TODOs:

- Extension to 3D?
- · Large scale runtime tests
- Merging the new software features into the main code base of t8code



Thank you

Special thanks to Johannes Holke and Gregor Gassner for making this project possible.

Questions?

References

- 1. Florian Becker. "Removing hanging faces from tree-based adaptive meshes for numerical simulations". Master thesis. Universität zu Köln. 2021. https://elib.dlr.de/146849/1/RemovingHangingFacesFromTreeBasedAMR.pdf.
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