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shear-strain definitions in the
literature and the consequences in
composite design and application**

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A comment on different thermal shear-strain definitions in the literature and the consequences in composite design and application

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1. Motivation

Shear strains in context of classical-laminate theory (CLT) are usually based on engineering strain formulation γ_{xy} , instead of the tensorial description using ε_{xy} . Some authors define thermal shear strains as $\gamma_{Txy} = \alpha_{Txy} \cdot \Delta T$. Others define $\varepsilon_{Txy} = \alpha_{Txy} \cdot \Delta T = \frac{1}{2} \cdot \gamma_{Txy}$, which causes a conflict. This investigation aims to highlight this confusing fact for uses. The individual formulations from literature are cross-checked and compared here with results of a simple ABAQUS FE model¹.

2. Formulations in the literature

Table 1 shows definitions found in the literature.

Table 1: Thermal shear strain definition

| Source | Definition |
|------------------------|---|
| Reddy [2, p.99] | $\varepsilon_{xy} = \alpha_{xy} \cdot \Delta T$ |
| Nettles [2, p.44] | $\varepsilon_{xy} = \alpha_{xy} \cdot \Delta T$ |
| VDI [3] + HSB [4, p.4] | $\gamma_{xy} = \alpha_{xy} \cdot \Delta T$ |
| ESAComp [8] | $\gamma_{xy} = \alpha_{xy} \cdot \Delta T$ |
| Jones [7, p.242] | $\gamma_{xy} = \alpha_{xy} \cdot \Delta T$ |
| Schürmann [5, p.234] | $\gamma_{xy} = \alpha_{xy} \cdot \Delta T$ |
| Moser [10, p.252] | $\varepsilon_{xy} = \frac{1}{2} \cdot \alpha_{xy} \cdot \Delta T$ |

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¹Note, that the MSC NASTRAN documentation [11] indicates the use of the engineering strains as well, leading to the conclusion that the presented ABAQUS-related recommendations are valid for NASTRAN as well

It can be seen that α_{xy} is defined differently as $\gamma_{xy} = 2 \cdot \varepsilon_{xy}$. The VDI [3] notation, which is pursued in the industry-driven HSB as well, is used hereafter to show the relation between thermal expansion in the material coordinate system and the global system.

2.1. VDI background and notation

According to VDI [3] and HSB [4, p.4] laminate CTEs are defined as followed.

$$\{\alpha_T^0\} = (\alpha_{Tx}^0, \alpha_{Ty}^0, \alpha_{Txy}^0)^T = [A]^{-1} \sum_{k=1}^n ([Q']_k \cdot \{\alpha'_T\}_k \cdot t_k) \quad (1)$$

with the 'rotated' ply CTEs being linked to the ply material CTEs by

$$\{\alpha'_T\} = [T_\varepsilon] \cdot (\alpha_{\parallel}, \alpha_{\perp}, 0)^T \quad \text{with} \quad [T_\varepsilon] = \begin{bmatrix} m^2 & n^2 & -mn \\ n^2 & m^2 & mn \\ 2mn & -2mn & (m^2 - n^2) \end{bmatrix} . \quad (2)$$

The strains in the UD-material COS and the laminate COS read

$$\{\varepsilon_T\} = \Delta T \cdot (\alpha_{\parallel}, \alpha_{\perp}, 0)^T \quad , \quad \{\varepsilon'_T\} = \Delta T \cdot (\alpha_{Tx}, \alpha_{Ty}, \alpha_{Txy})^T \quad (3)$$

and can be transferred using

$$\{\varepsilon'_T\} = [T_\varepsilon] \cdot \{\varepsilon_T\} \quad . \quad (4)$$

Thus, α_{Txy} refers to engineering strain formulation, as $\gamma_{Txy} = \alpha_{Txy} \cdot \Delta T$.

3. Single-ply test case

Now, the expansion behavior of a single UD ply shall be examined. Lets assume a $\theta = 45^\circ$ ply angle. For the single 45° -ply case, Equation 1 simplifies to:

$$\begin{bmatrix} \alpha_{Tx}^0 \\ \alpha_{Ty}^0 \\ \alpha_{Txy}^0 \end{bmatrix} = \begin{bmatrix} 0.5 & 0.5 & -0.5 \\ 0.5 & 0.5 & 0.5 \\ 1 & -1 & 0 \end{bmatrix} \cdot \begin{bmatrix} \alpha_{\parallel} \\ \alpha_{\perp} \\ 0 \end{bmatrix} = \begin{bmatrix} 0.5 \cdot (\alpha_{\parallel} + \alpha_{\perp}) \\ 0.5 \cdot (\alpha_{\parallel} + \alpha_{\perp}) \\ \alpha_{\parallel} - \alpha_{\perp} \end{bmatrix} \quad (5)$$

With the example UD-ply CTEs provided in Nettles [1]: $\alpha_{\parallel} = -0.04$ ppm/K and $\alpha_{\perp} = 18.0$ ppm/K the ply's expansion properties in the global coordinate system are

$$\begin{bmatrix} \alpha_{Tx}^0 \\ \alpha_{Ty}^0 \\ \alpha_{Txy}^0 \end{bmatrix} = \begin{bmatrix} 8.98 \\ 8.98 \\ -18.04 \end{bmatrix} \quad \text{ppm/K.} \quad (6)$$

Figure 1 shows the facts of the simple 100 mm x 100 mm ABAQUS model which considers an temperature step of $\Delta T = 100$ K.

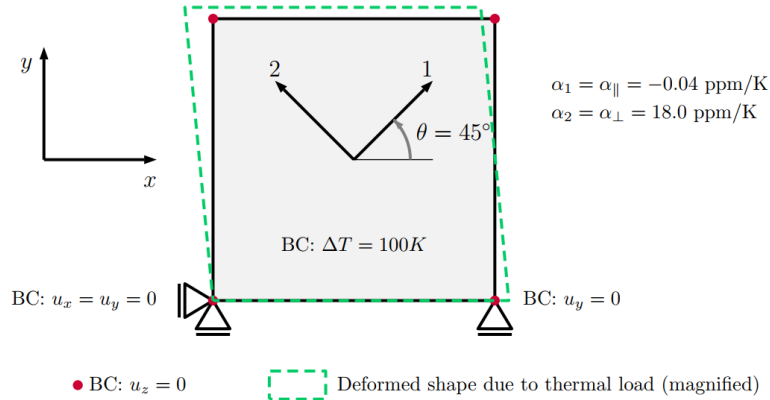


Figure 1: FE model description. 1 shows fiber direction, x,y present laminate coordinates

Figure 2 shows the important excerpt from the ABAQUS manual, saying that ABAQUS always provides shear strains in engineering notation.

Shear strains
 ABAQUS always reports shear strain as engineering shear strain, γ :
 $\gamma_{ij} = \epsilon_{ij} + \epsilon_{ji}$.

Figure 2: Engineering strain statement in ABAQUS manual [6]

Thus, following the VDI notation $\gamma_{Txy}^0 = \Delta T \cdot \alpha_{Txy}^0$, the shear-strain in the global coordinate system are calculated to $\gamma_{Txy}^0 = -18.04 \cdot 10^{-3}$.

Figure 3 shows the corresponding FE model result, with E_{12} in the legend referring to γ_{xy} .

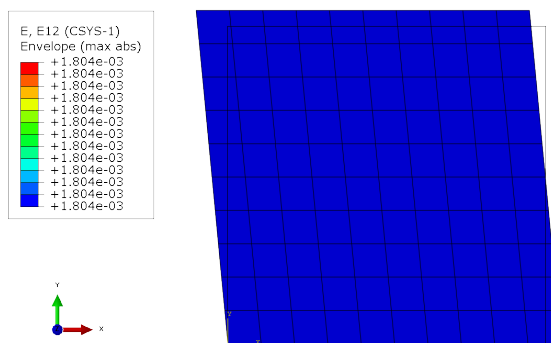


Figure 3: FE model shear strains in laminate coordinate system. Note that E_{12} refers to γ_{xy} .

The corresponding deformation plots are provided hereafter for completeness.

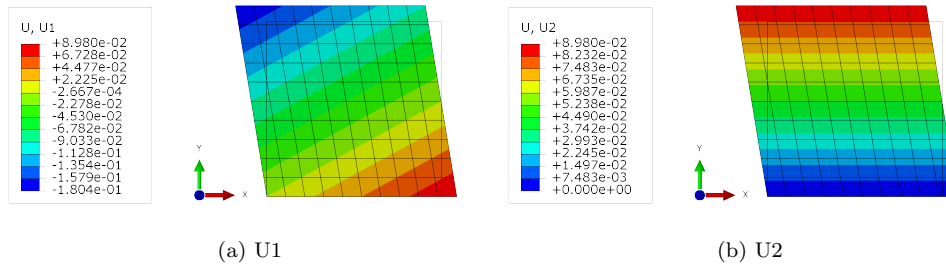


Figure 4: In-plane displacements from FE model

4. Conclusion

The VDI notation and other authors defines $\gamma_{Txy} = \alpha_{Txy}^0 \cdot \Delta T$. The FE model produced an identical result. According to the ABAQUS manual [6], the coefficient of thermal for in-plane shear strains can be defined as followed in the input file.

```
*Expansion, type=ANISO
 $\alpha_{11}$ ,  $\alpha_{22}$ ,  $\alpha_{33}$ ,  $\alpha_{12}^{Abaqus}$ ,  $\alpha_{13}$ ,  $\alpha_{23}$ 
```

When the definition of Nettles [1, p.44] and Reddy [2, p.99] ($\varepsilon_{Txy} = \alpha_{xy} \cdot \Delta T$) is used $\alpha_{12}^{Abaqus} \stackrel{!}{=} 2 \cdot \alpha_{xy}$ shall be used to model correct thermal shear strains. When VDI notation is used, the determined coefficients can be directly used $\alpha_{12}^{Abaqus} \stackrel{!}{=} \alpha_{xy}$, leading to:

```
*Expansion, type=ANISO
8.98e-06, 8.98e-06, 0., -18.04e-06, 0., 0.
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