

Vortex-induced stall on an actively twisted highly loaded model rotor blade

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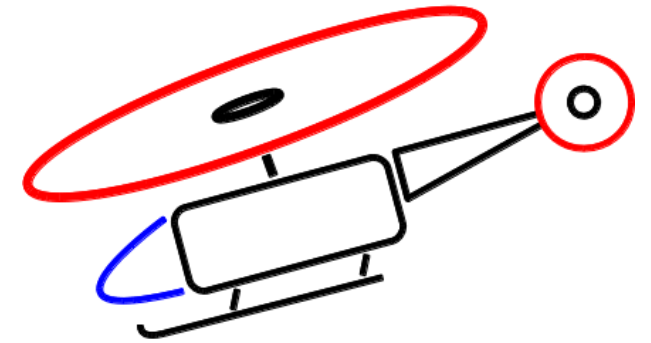
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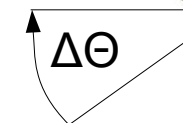
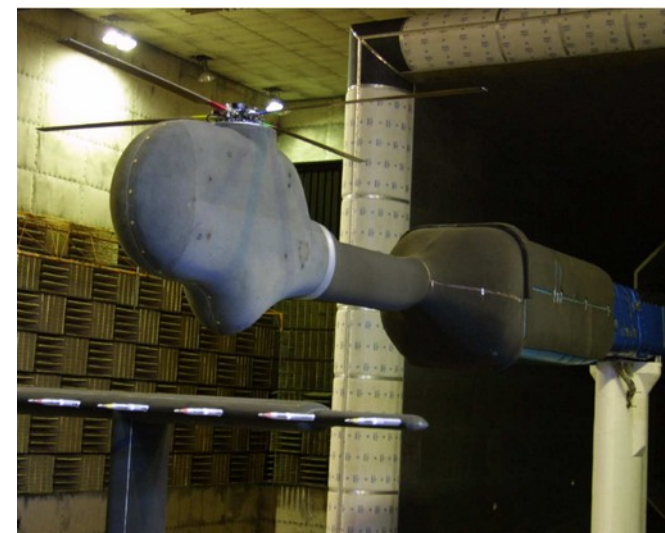
Motivation & Introduction

- Helicopter rotor blade sections operate in very different flow conditions
- The difficulty is that a passively designed rotor blade is always a trade-off of the various flow & flight conditions
- Many blade control devices have been studied, in the STAR II project shown here, actively twisted blades are investigated
- STAR II is a consortium of 8 research centers (7 participated in the vortex induced stall, high load activity)
- Test matrix has been simulated before the wind tunnel test, this presentation is about the vortex-induced stall condition (half RPM to stay within testing limitations)

Piezo-electric actuators almost over full-span

0-5/rev actuation with different phases

Schematic of STAR II blades

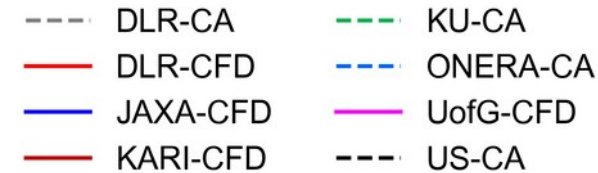


STAR II will be tested like HART II blade in DNW LLF

Overview

- Methodology
- Simulation results
 - Baseline thrust sweep
 - Actuation sweeps
- Summary





Methodology

- All results are fluid-structural coupled
 - Two major groups:
 - Comprehensive analysis (CA) codes
 - CFD/CA coupled analysis
 - CA codes use vortex wake models
 - CFD codes similar order in their resolution
- some noticeable differences in the approaches

Comprehensive codes

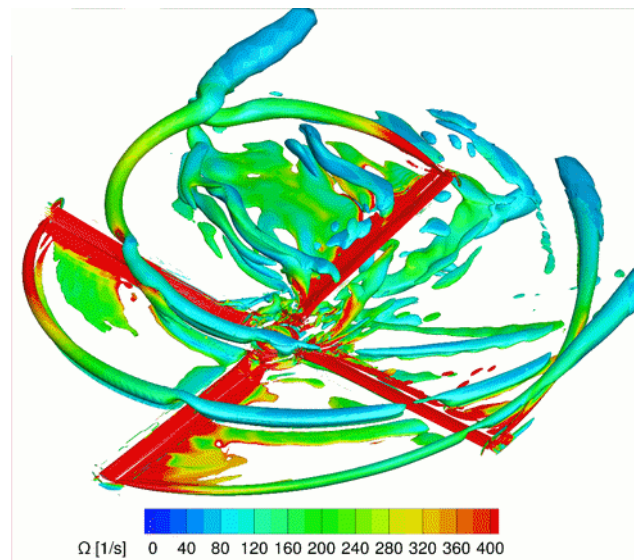
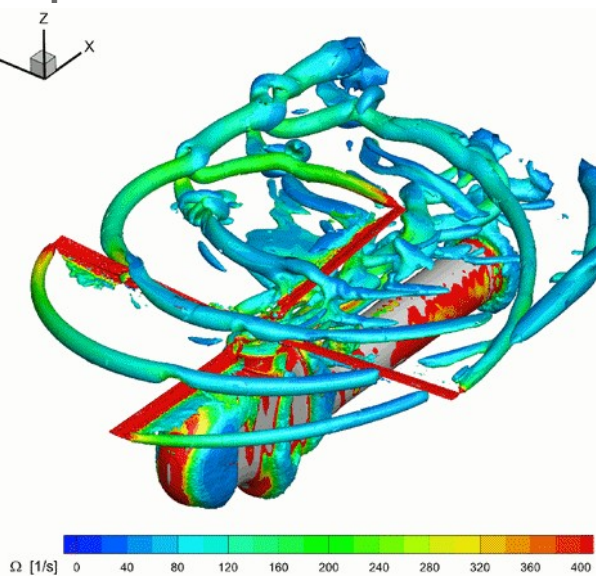
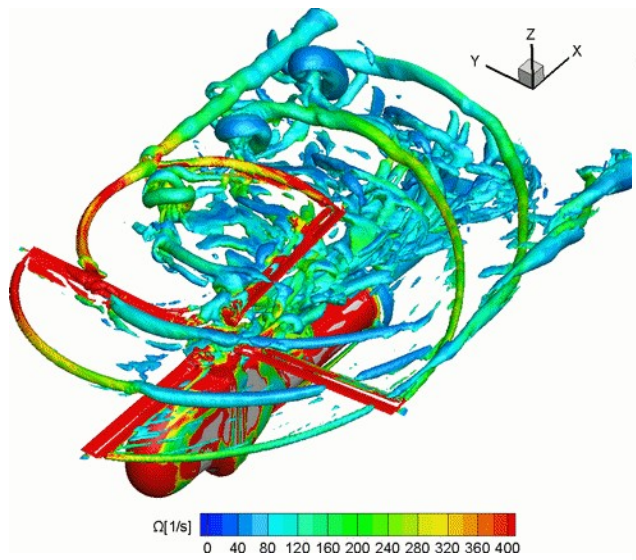
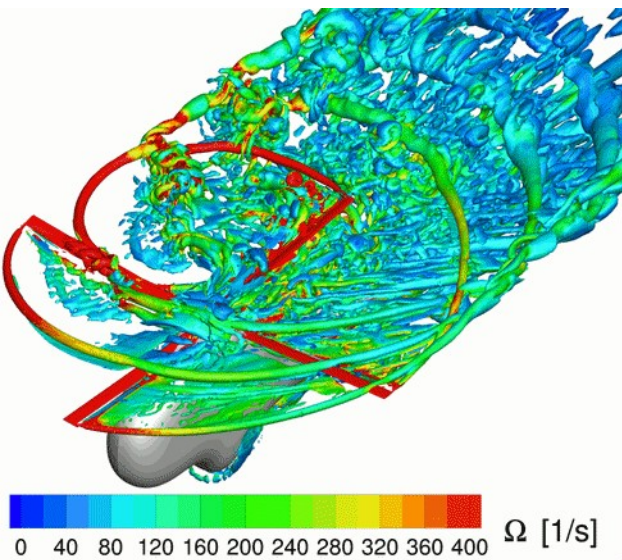
| | DLR-CA | KU-CA | ONERA-CA | US-CA |
|-------------------|--------|-------|----------|-------|
| box | no | no | no | no |
| fuselage | yes | no | no | no |
| init. tip core | 0.033 | 0.5 | 0.3 | 0.8 |
| blade elements | 20 | 16 | 25 | 28 |
| azimuth step size | 2° | 15° | 5° | 15° |

CFD coupled comprehensive codes

| | DLR-CFD | JAXA-CFD | KARI-CFD | UofG-CFD |
|-------------------------|------------|--------------------|----------|------------|
| box | yes | yes | yes | no |
| fuselage | yes | yes | yes | no |
| order | 4 | 4 | 2 | 3 |
| turbulence | SA-DDES-R | Menter SST | SA | Menter SST |
| transition | empirical | γRe_θ | no | no |
| blade resolution | 128x64x128 | 141x81x157 | - | 142x64x148 |
| background $\Delta x/c$ | 14% | 10% | 15% | 15% |
| total # grid pts | 15 M | 88 M | 29 M | 35 M |
| step | 0.25° | 0.1° | 1.0° | 0.25° |



Simulation Results – Vorticity Fields @ $c_T/\sigma = 0.13$



DLR-CFD
4th order, DDES,
 $\Delta x/c=14\%$

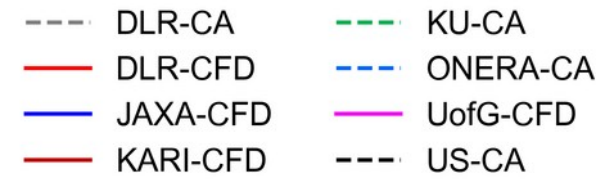
JAXA-CFD
4th order, URANS,
 $\Delta x/c=10\%$

KARI-CFD
2nd order URANS,
 $\Delta x/c=15\%$

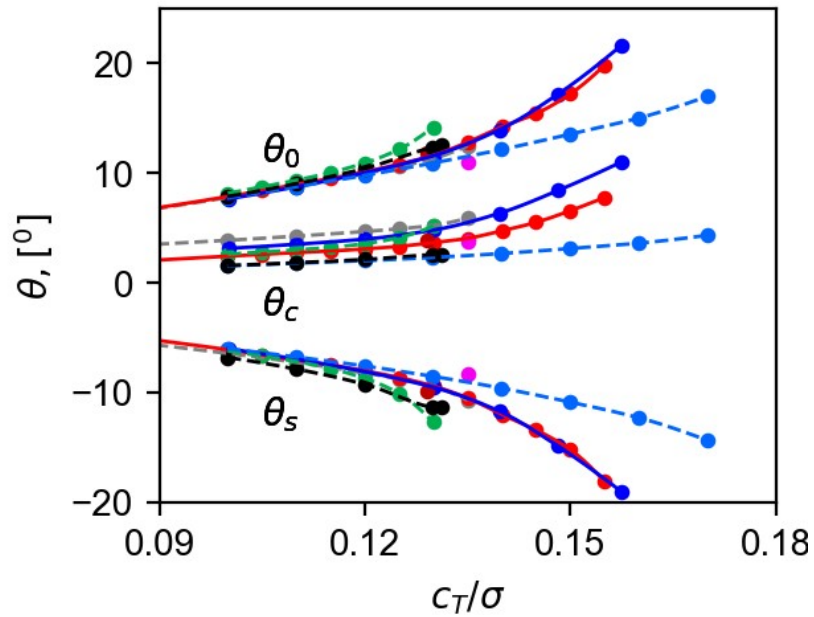
UofG-CFD
3rd order URANS,
 $\Delta x/c=15\%$

- General vortex trajectory very similar among partners
- Different strength of tip vortices and severity of separation captured
- 4th order simulations (with DDES) capture more secondary structures than 2nd order (URANS) simulations

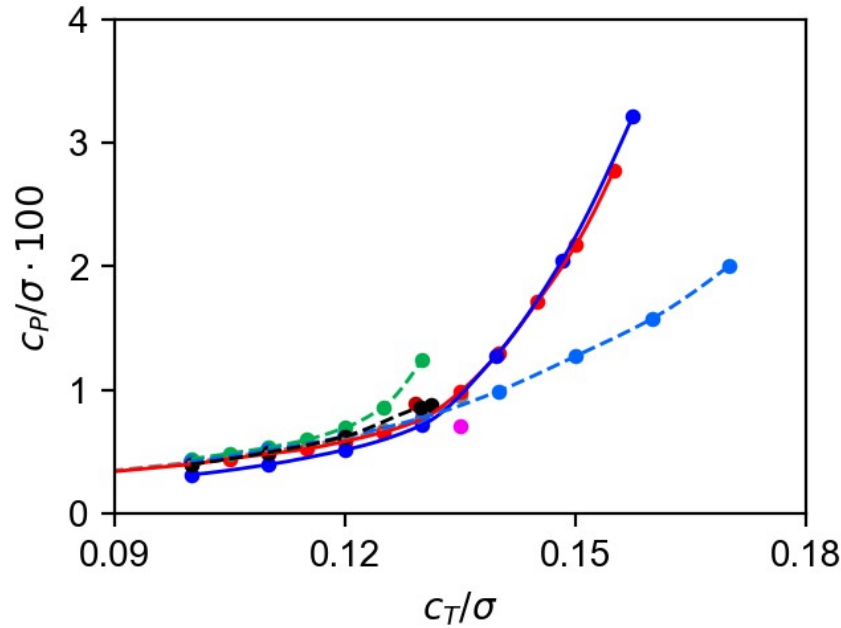




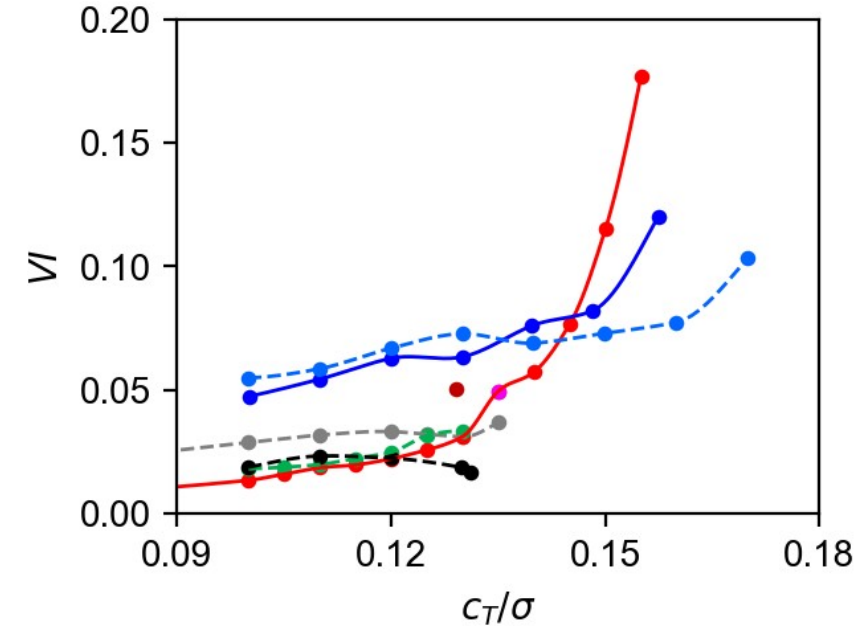
Thrust Sweep – Integral Results



Pitch control angles



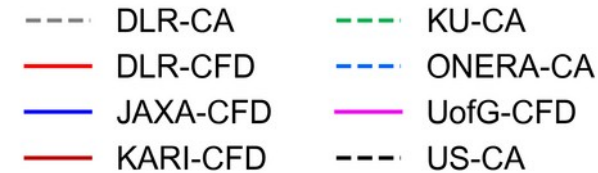
Required power



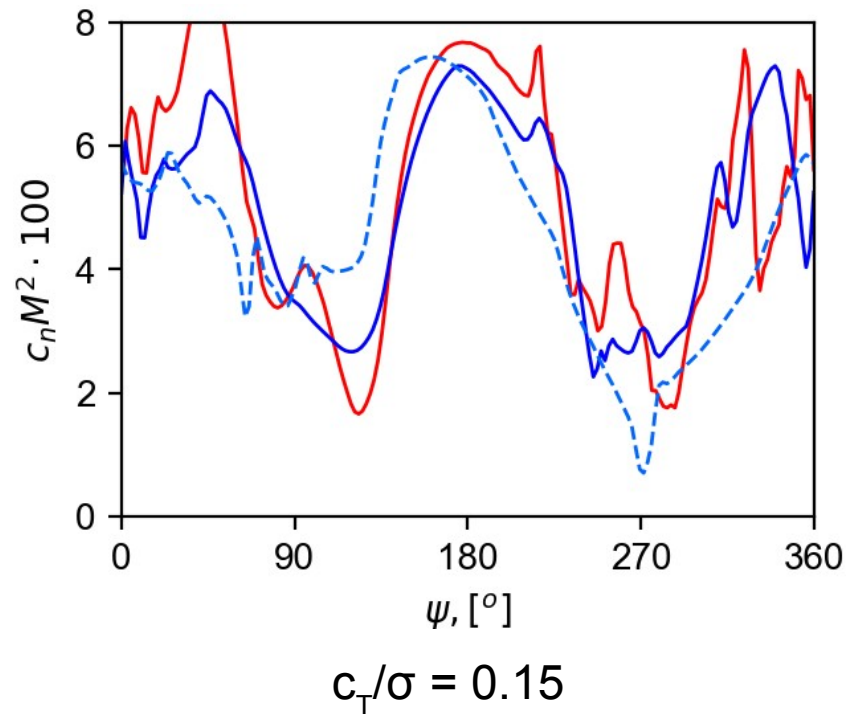
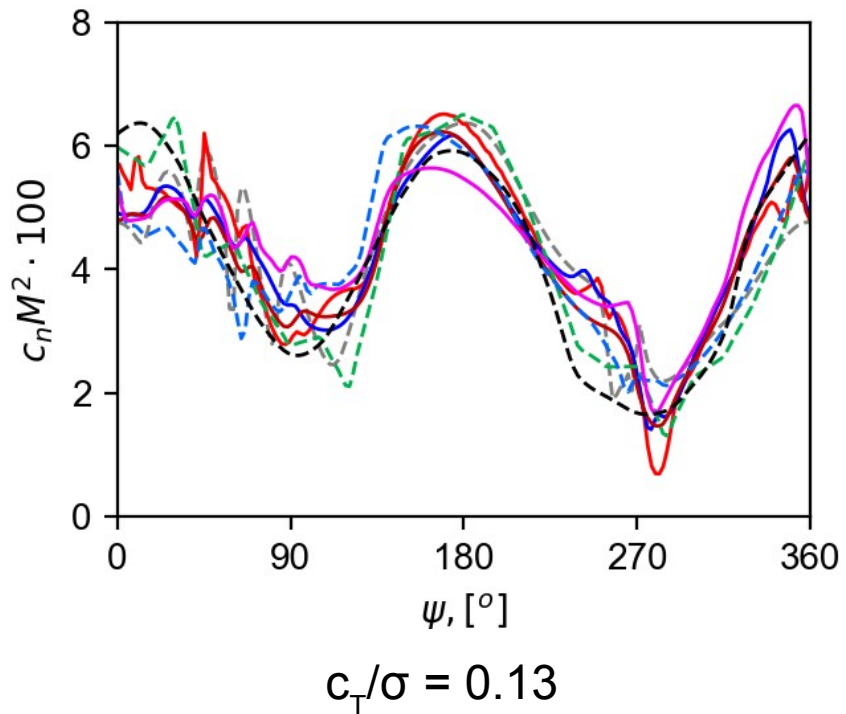
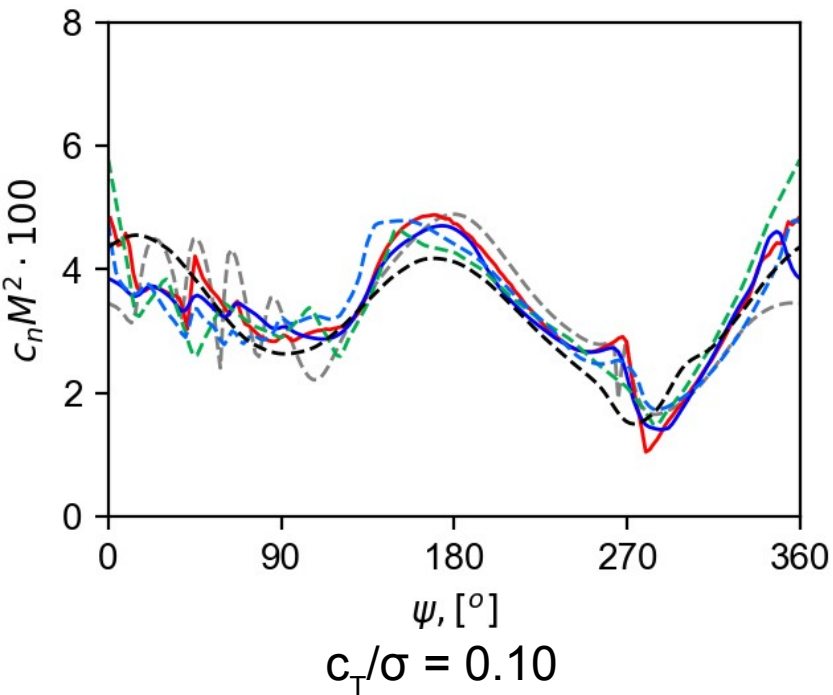
Vibration Intrusion Index (VI)

- General trend captured well by all methods at lower thrusts
- Change in gradient found in most curves with the onset of dynamic stall
- Maximum trimmable thrust ranges from $c_T/\sigma = 0.13 \dots 0.17$
- VI metric has the greatest discrepancies with roughly the same trends

$$VI = \sum_{i=4,8} \sqrt{\frac{(0.5F_{x,i})^2 + (0.67F_{y,i})^2 + (F_{z,i})^2}{W_0}} + \sum_{i=4,8} \frac{\sqrt{(M_{x,i})^2 + (M_{y,i})^2}}{RW_0}$$

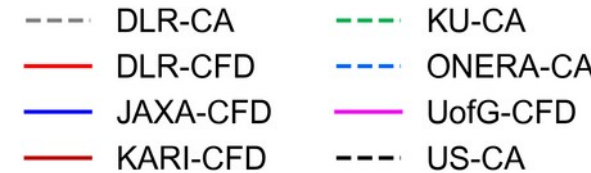


Thrust Sweep – Sectional Normal Force @ $r/R = 0.67$

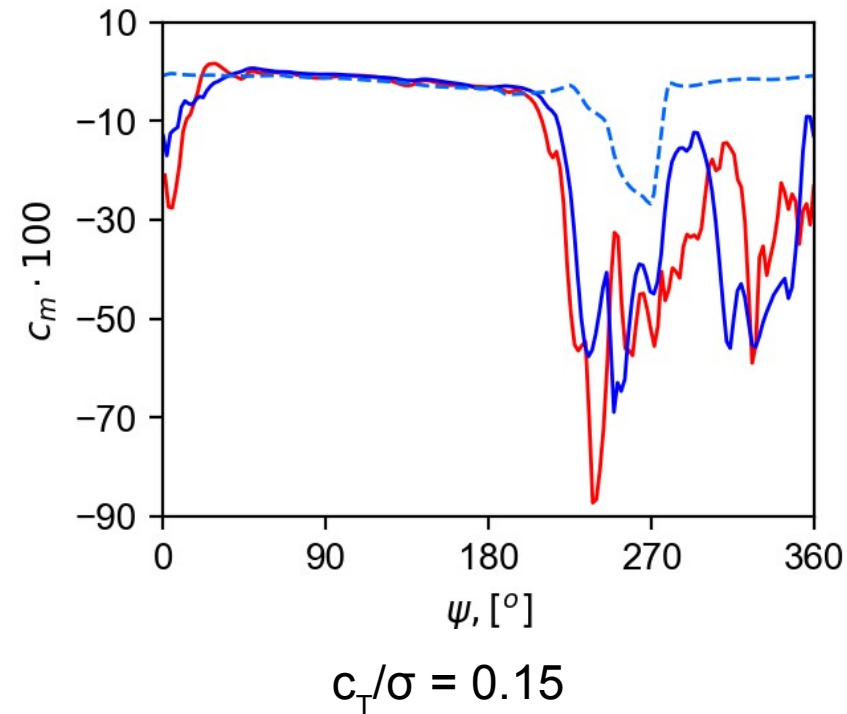
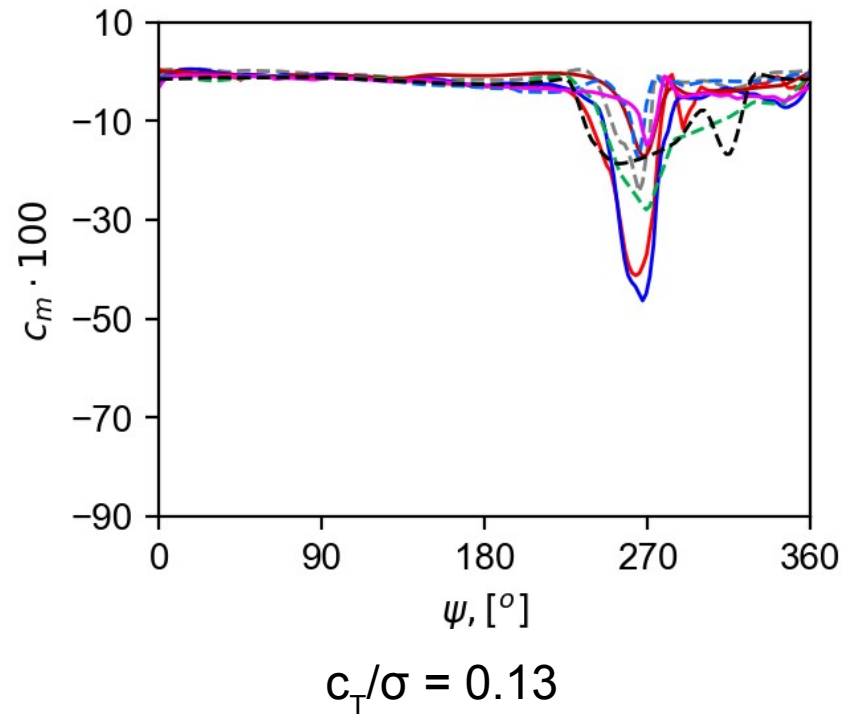
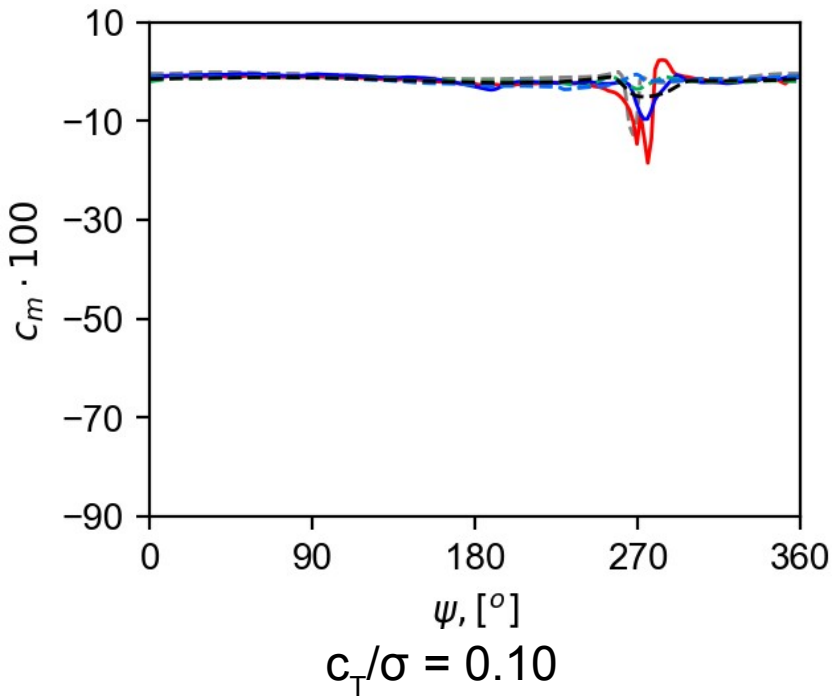


- At lower thrust, good agreement among the partners. Higher harmonic content depends on the tip vortex simulation – smaller core radii in CA or better conservation on the CFD lead to greater wiggles
- At higher thrust the discrepancies grow, at $c_T/\sigma = 0.15$, only three partners were able to trim the rotor





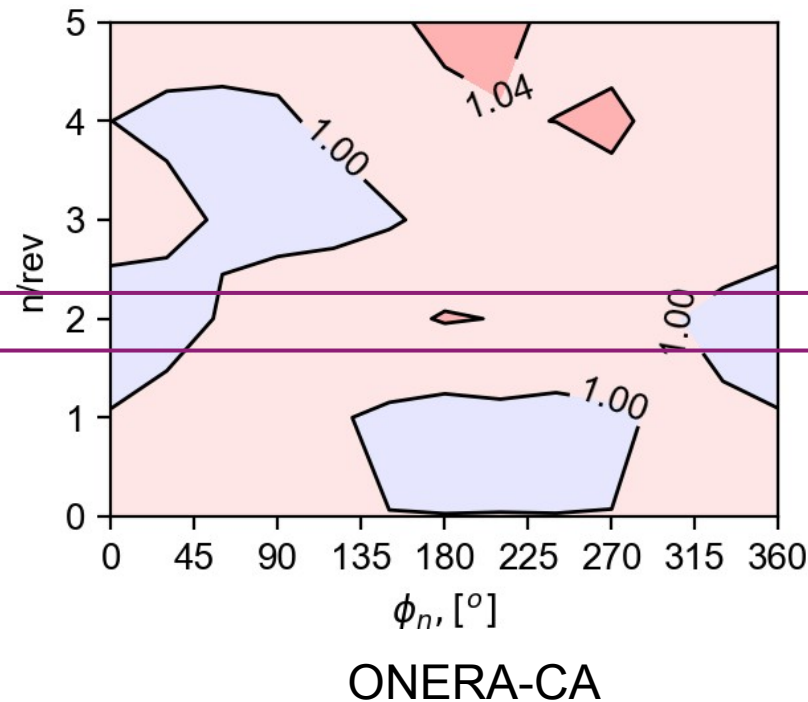
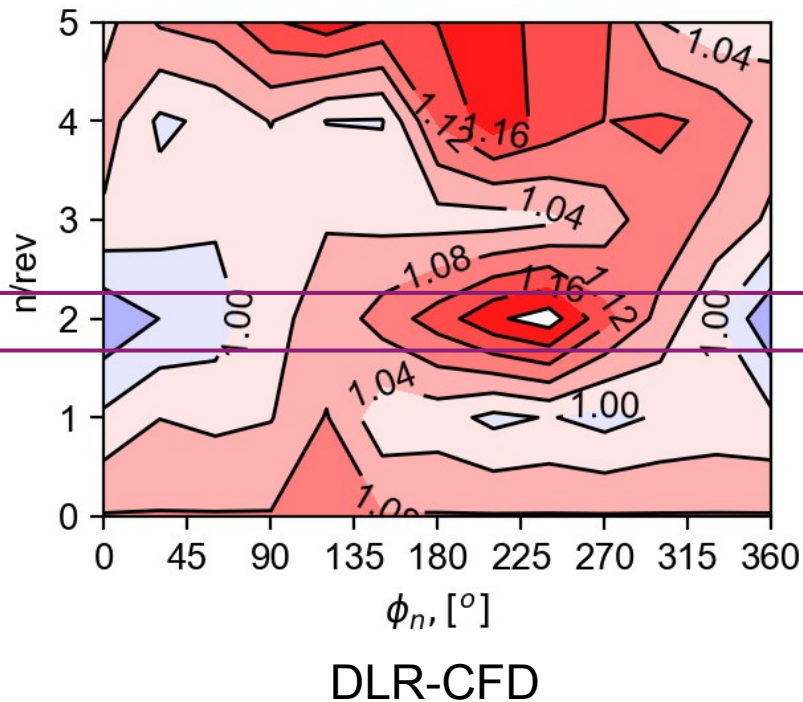
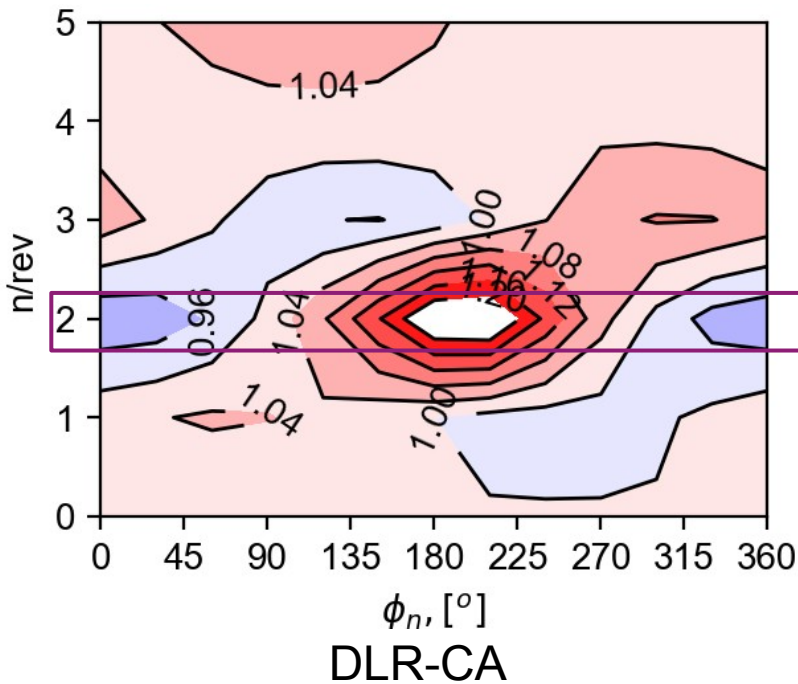
Thrust Sweep – Sectional Normal Force @ r/R = 0.67



- At lower thrust: no or very small onset of stall is observed on the retreating side
- DLR-CFD & JAXA-CFD capture strong dynamic stall at intermediate and high thrust.
- Higher harmonic content from the DLR-CFD (DDES) found again in the load plots, but little influence overall
- NOTE: c_m computed from $c_n M^2$ as unique inflow cannot be determined in CFD



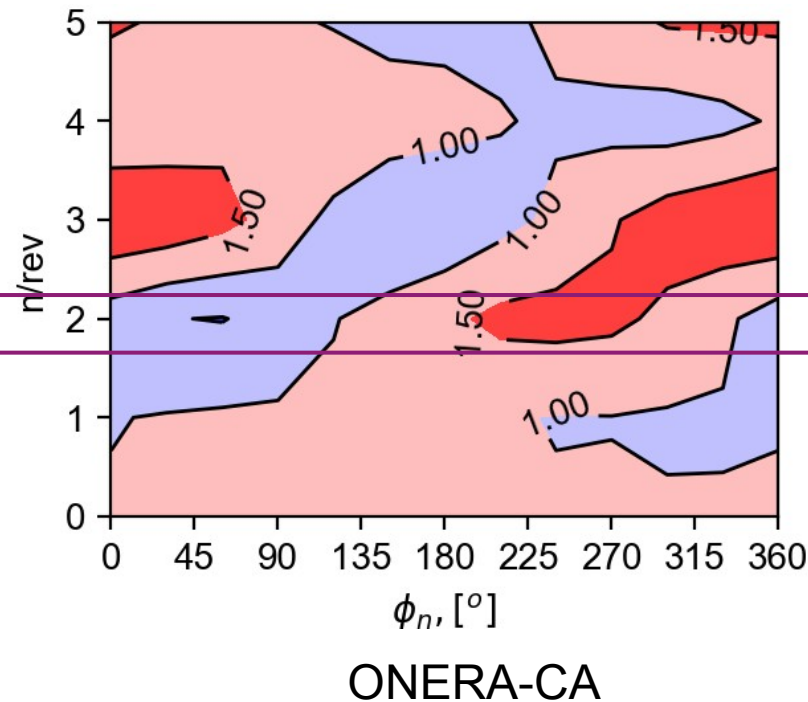
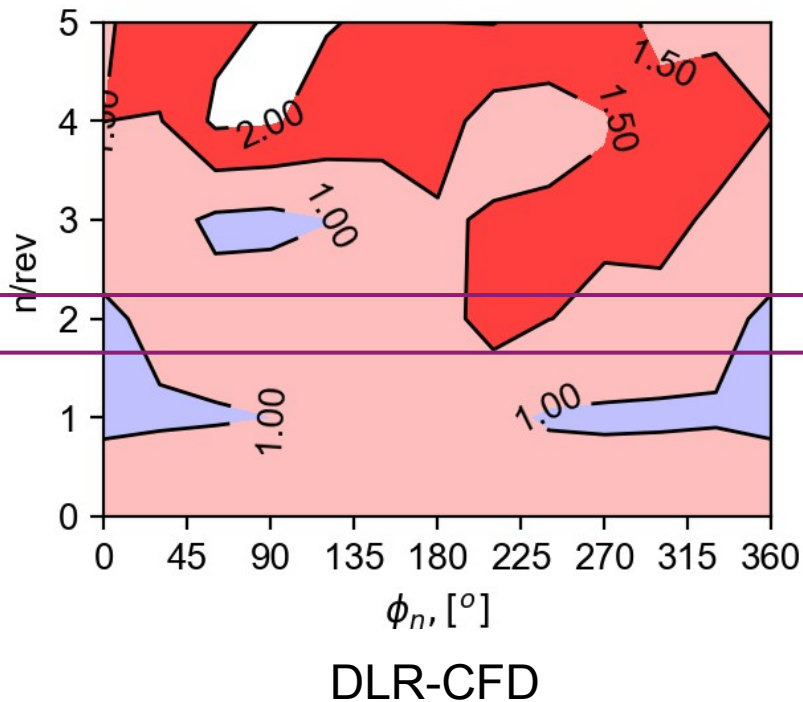
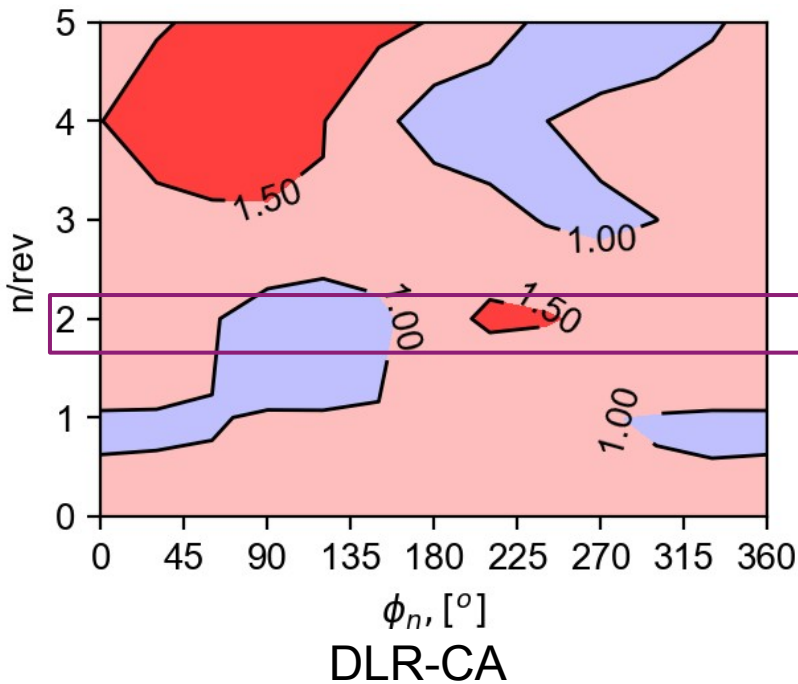
Actuation Sweeps – Full Sweep on Required Power



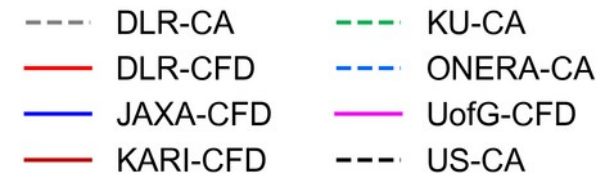
- Not all partners could compute the trend with all actuation results – results are relative to baseline at $c_T/\sigma = 0.13$
- 0/rev is only static offset, 1-5/rev computed in phase steps of 30°
- Most consistent and pronounced results found for 2/rev actuation – also greatest power reduction predicted by all partners



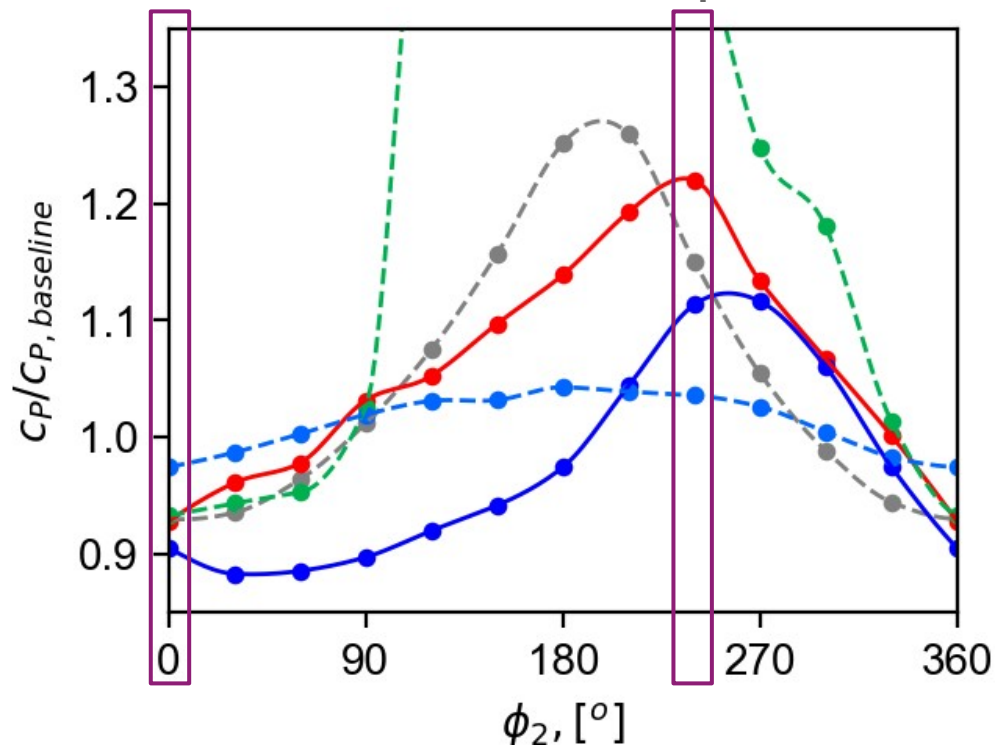
Actuation Sweeps – Full Sweep on Vibration Intrusion Index



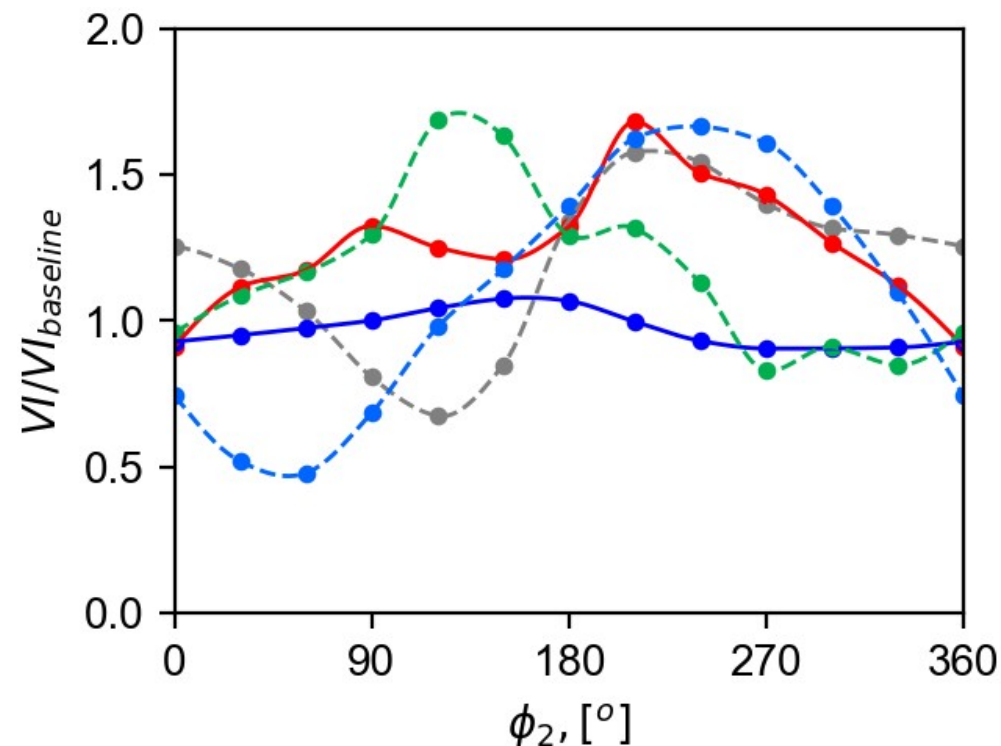
- Vibration Intrusion Index less consistent than required power
- This trend has already been observed for the thrust sweep
- However, the 2/rev actuation seems to be the common denominator for vibration reduction



Actuation Sweep @ 2/rev & $c_t/\sigma = 0.13$ – Integral Values

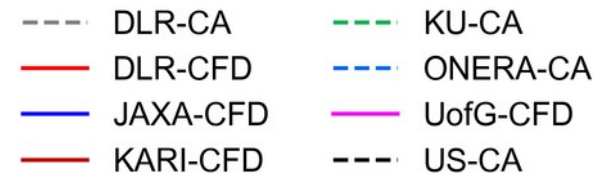


Required power (KU-CA cropped)

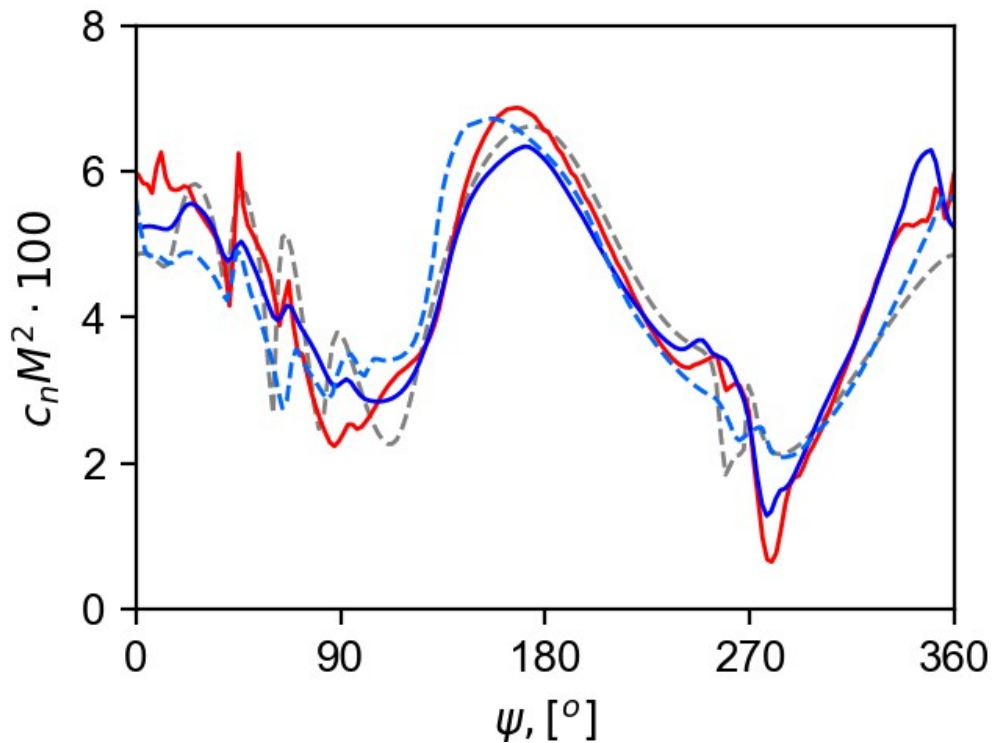


Vibration intrusion index

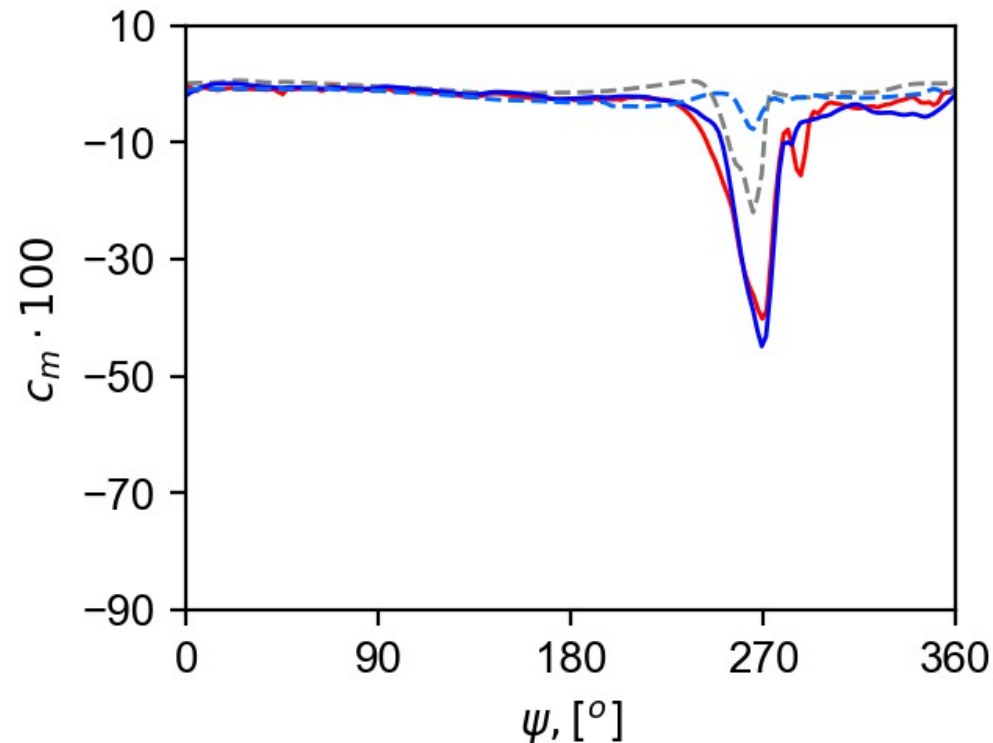
- Greatest benefit observed for required power for a phase around 330-60° for all partners
- A more diverse picture for VI, but likely reduced for a phase around 0° as well



Actuation @ 2/rev, $c_T/\sigma = 0.13$, $\phi = 0^\circ$, $r/R = 0.67$



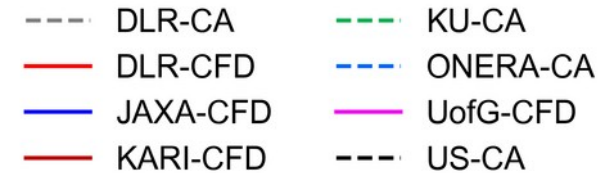
Normal load



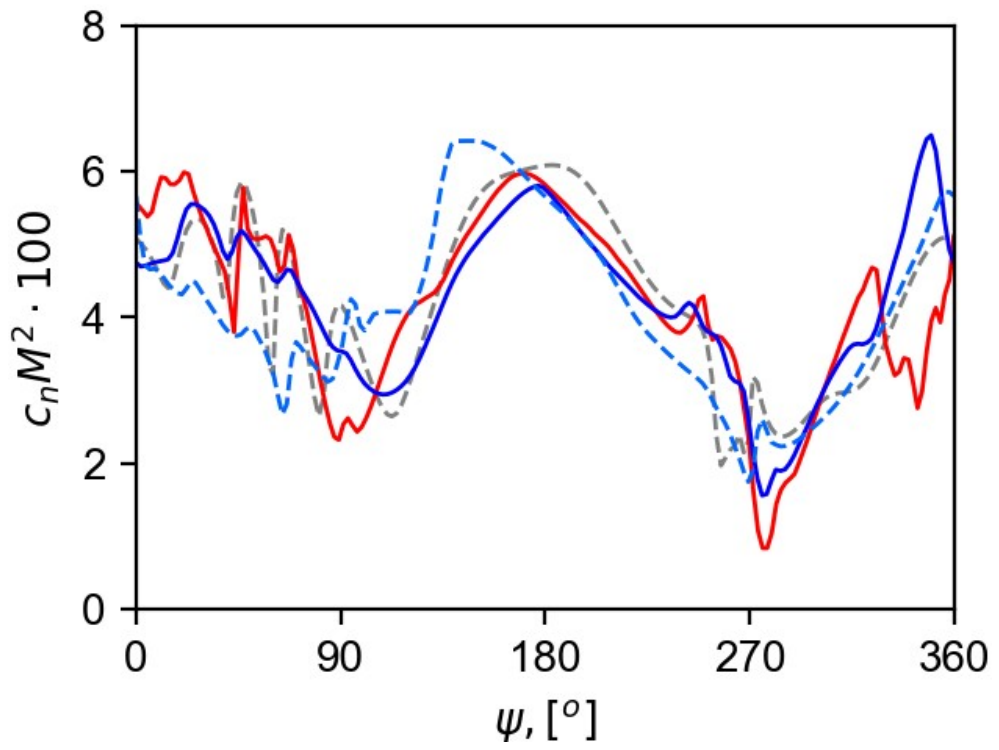
Pitching moment

- Reduction of pitching moment stall for all partners
- DLR-CFD and JAXA-CFD in good agreement, DLR-CA in between ONERA-CA and CFD

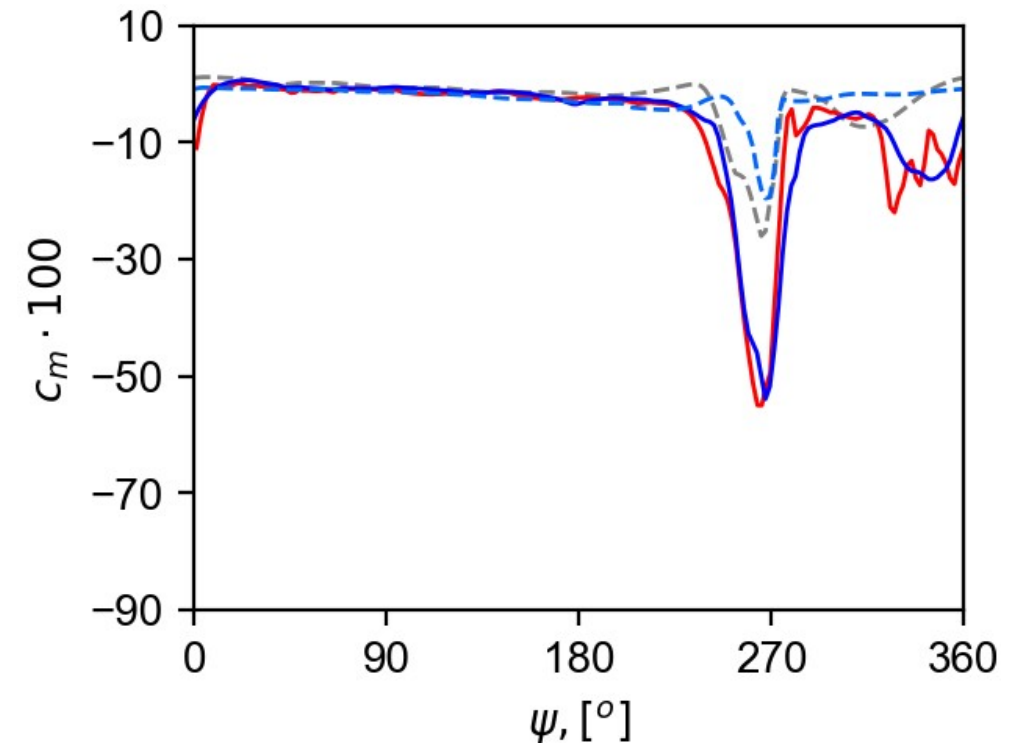




Actuation @ 2/rev, $c_T/\sigma = 0.13$, $\varphi = 240^\circ$, $r/R = 0.67$



Normal load



Pitching moment

- Increasing of pitching moment stall over baseline case
- Again, good agreement of DLR-CFD and JAXA-CFD with DLR-CA better on the normal loads, but similar to ONERA-CA on the pitching moment



Summary

- Investigated vortex induced stall test case at reduced RPM - “blind tested” prior of the wind tunnel test
- Thrust sweep
 - At the lower thrust regions, where no or little stall occurs, results are well aligned among the partners
 - Curves show a kink at the onset of stall
 - Post stall behavior often similar, but at different thrusts
- Actuation sweeps
 - Some agreement found, 2/rev actuation most promising as it is the common denominator
 - Required power and vibrations may be reduced at a phase of $\varphi \approx 0^\circ$
- Generally, the overall trends were captured by most partners, but questions remain, which may only be answered by the wind tunnel experiment
- CA results deliver good trends in minutes to hours, whereas CFD results are produced in the order of days to weeks

