

Transmitter Beam Bias Verification for Optical Satellite Data Downlinks with Open-Loop Pointing – the 3-OGS-Experiment

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Knowledge for Tomorrow



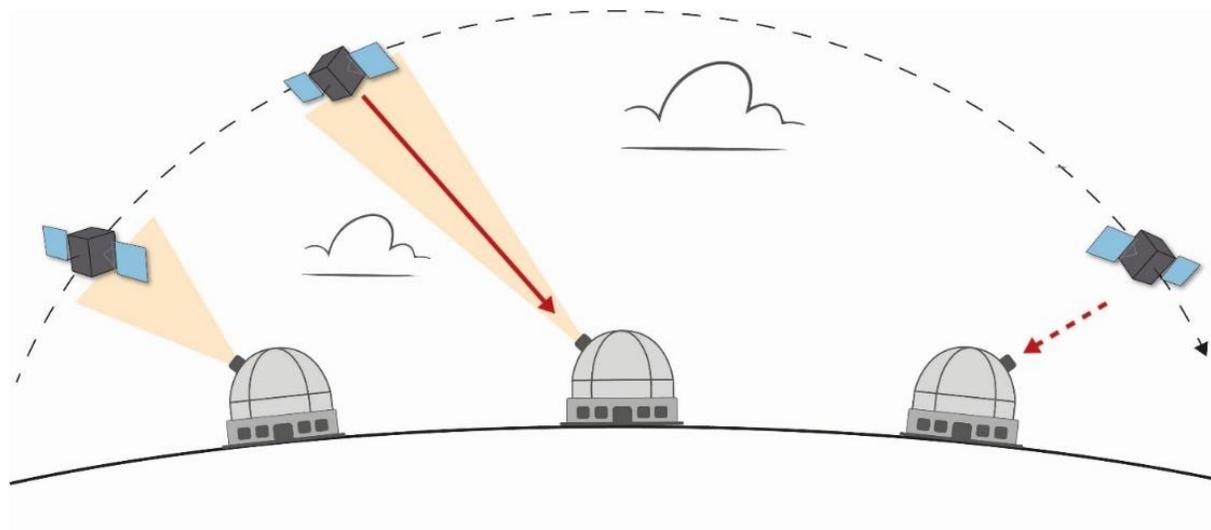
Content

- **Optical Data Downlinks from LEO Satellites**
- **The OSIRISv1 on Flying Laptop Satellite**
- **Scenario and the Three Ground Stations at DLR**
- **The verification trial and comparison with pointing error from star cams**
- **Summary**



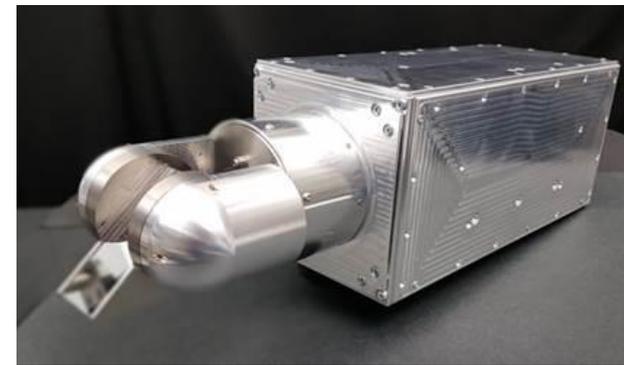
Why go for “LASER” in Data Downlinks from LEO Satellites?

- The RF frequency bands are already crowded from terrestrial mobile telecom and space links, much more traffic is expected in the next years
- Directed Optical Links allow smaller transmitter structures (lenses) and also ground receivers (telescopes)
- More power efficient and higher data rates possible: few Watt allow several GigaBit/s downlink speed
- Further optical technologies can be applied like Quantum Communications (QKD) or precise timing by optical intersatellite links, as well as coherent communication and sensor technologies
- Simple OLEODL: focus on Optical On/Off-Keying (OOK) transmission of up to 10Gbps onto bulk Avalanche Photo Detectors in the OGS



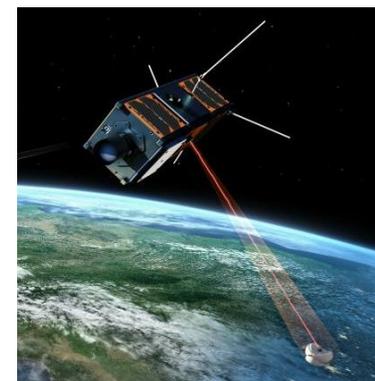
OLEODL: Optical Low Earth Orbit data DownLink
OGS: Optical Ground Station

Types of Laser Transmitters for OLEODL



a)
Terminal with Coarse-Pointing Assembly for hemispherical Field-of-View, and active tracking of a Beacon from Ground
→ *OSIRISv3 on Titania*

b)
Dynamic Coarse Body-Pointing by Satellite during OGS-overflight; only the Fine-Pointing by Tracking of the Beacon is done through the Optical Terminal
→ *OSIRIS4CUBE on PIXL*



c)
No tracking, full Body-Pointing through Satellite's attitude knowledge from star-camera sensors
→ *OSIRISv1 on Flying Laptop*

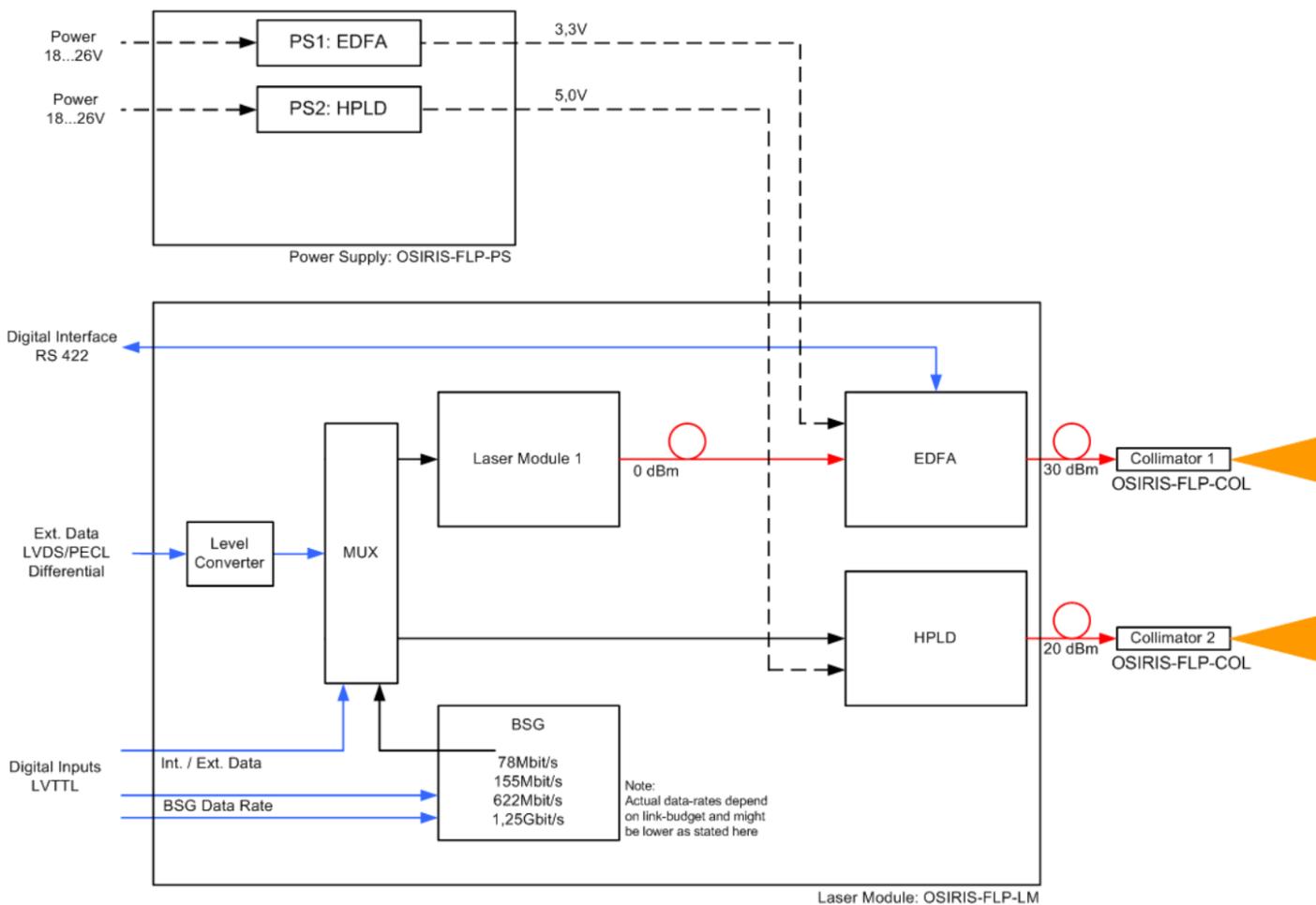


Find the angular offset between Star-Cameras and Laser-Direction, after shocks from rocket launch.

OSIRIS: Optical Space InfraRed downlink System

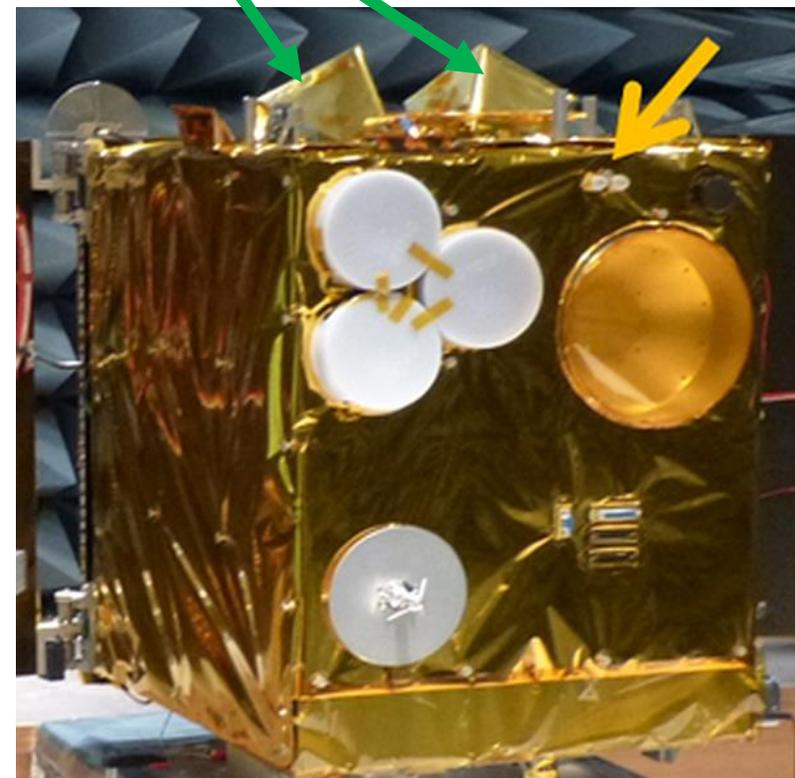


The OSIRISv1 on Flying Laptop



Star Cameras

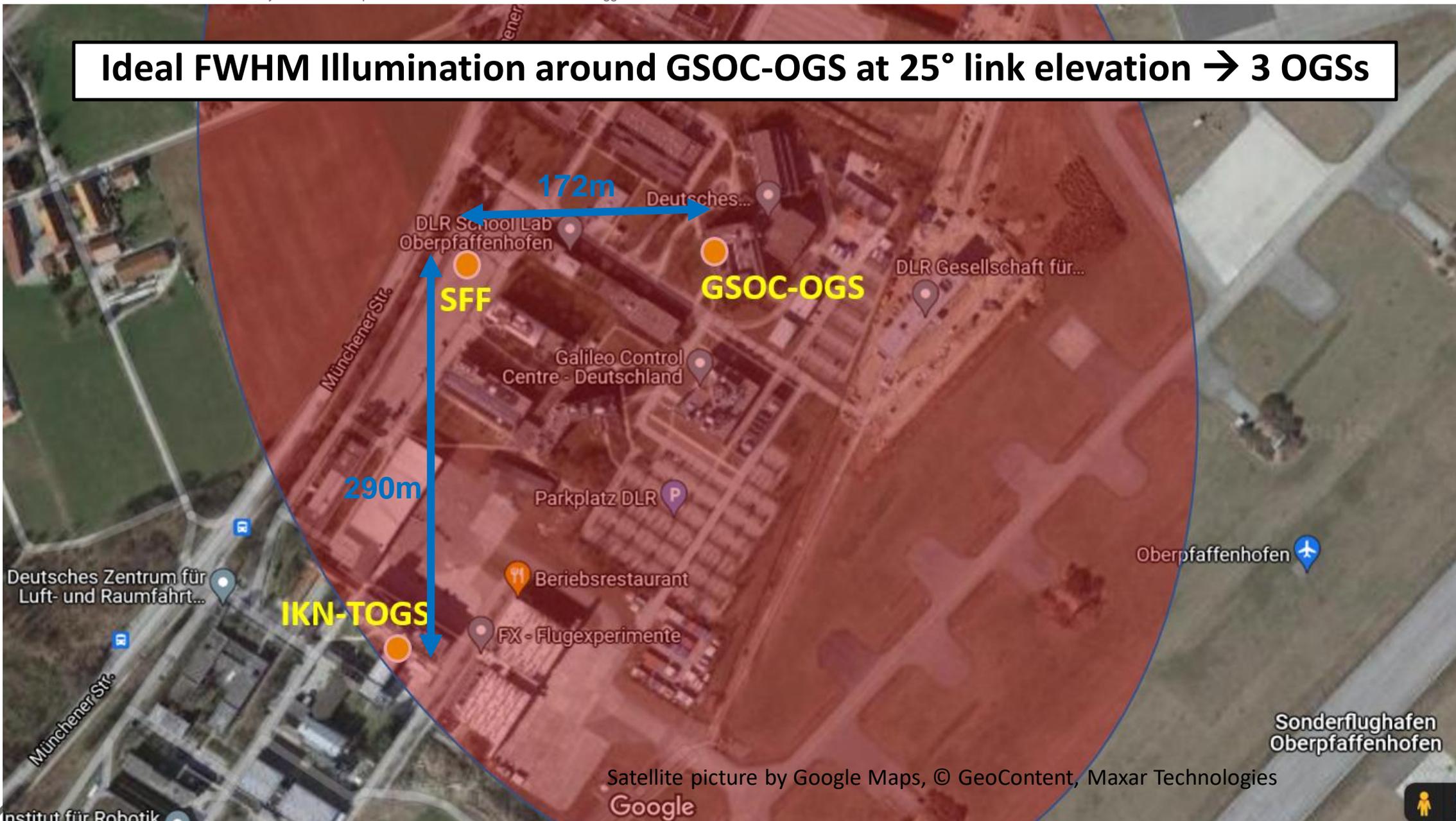
Divergence of Collimators is 1mrad FWHM



Flying Laptop Satellite, OSIRIS-transmitters: Collimators below arrow

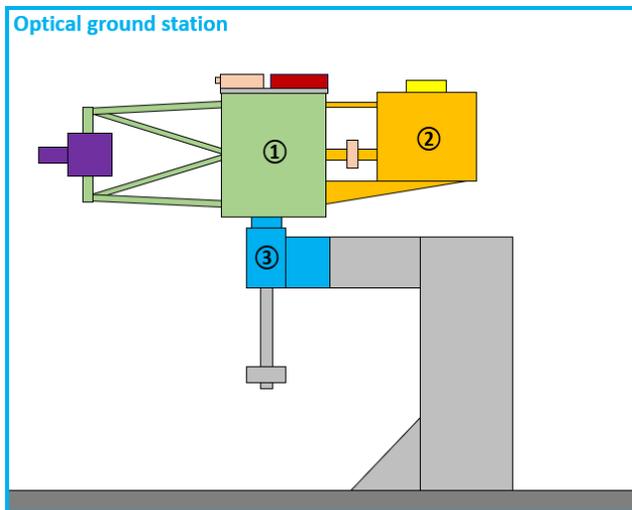


Ideal FWHM Illumination around GSOC-OGS at 25° link elevation → 3 OGSs



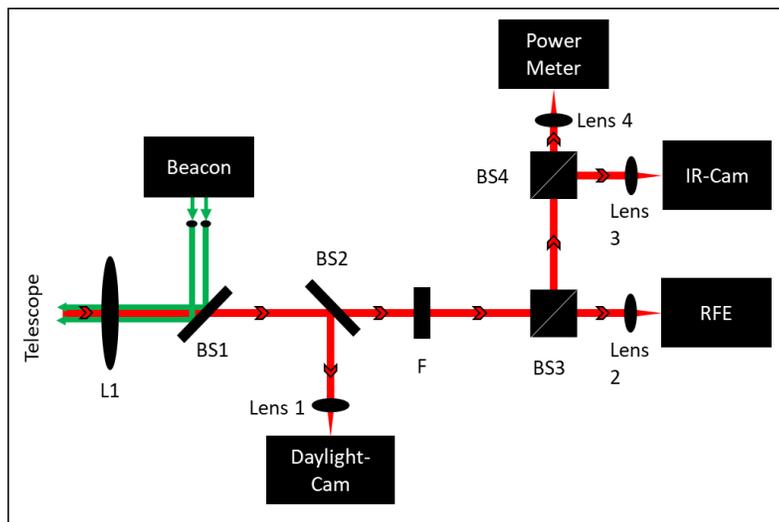
[1] GSOC-OGS

30cm telescope aperture



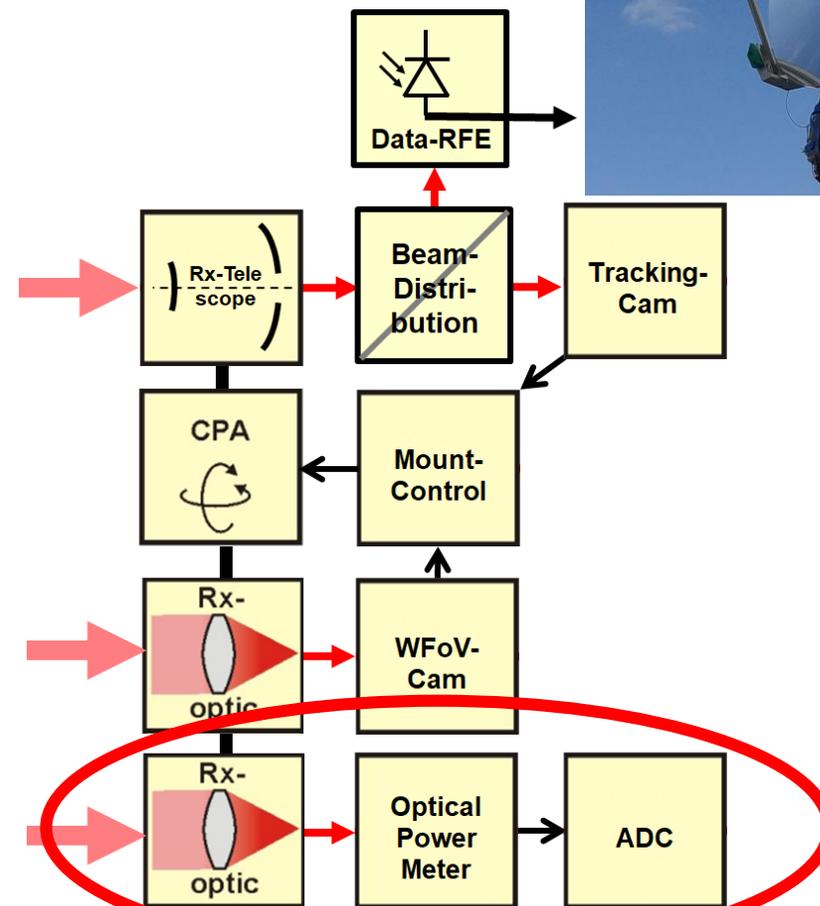
① Telescope ② Benchtop SOFA ③ Alt-Alt-Mount

SOFA:
Small OGS
Focal Assembly



[2] IKN-TOGS

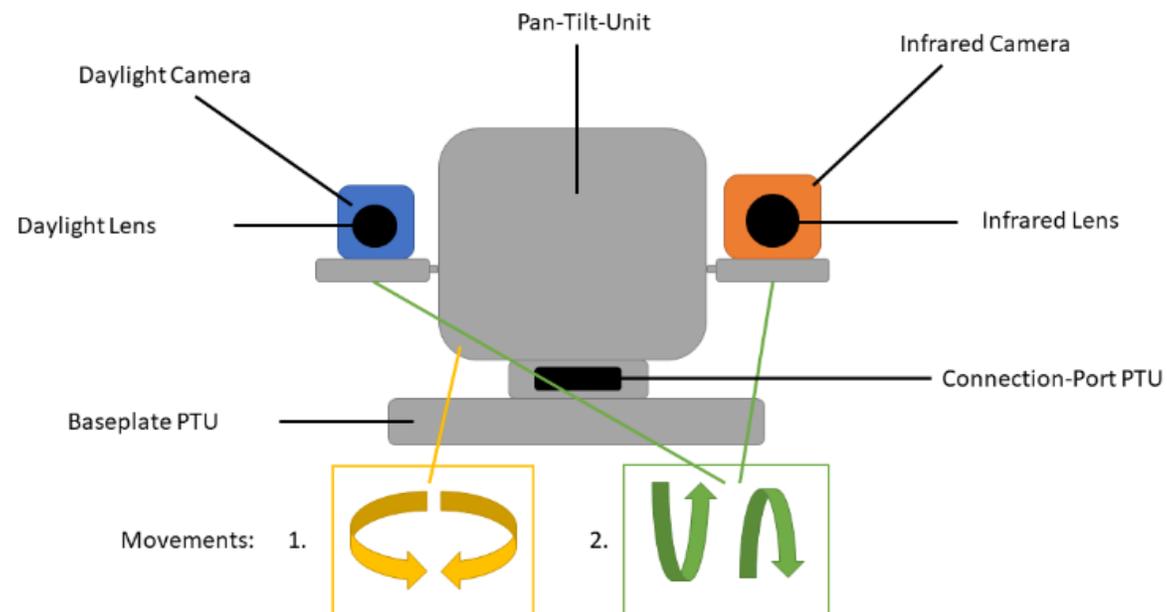
60cm telescope aperture



[3] Satellite Flash Finder (SFF)



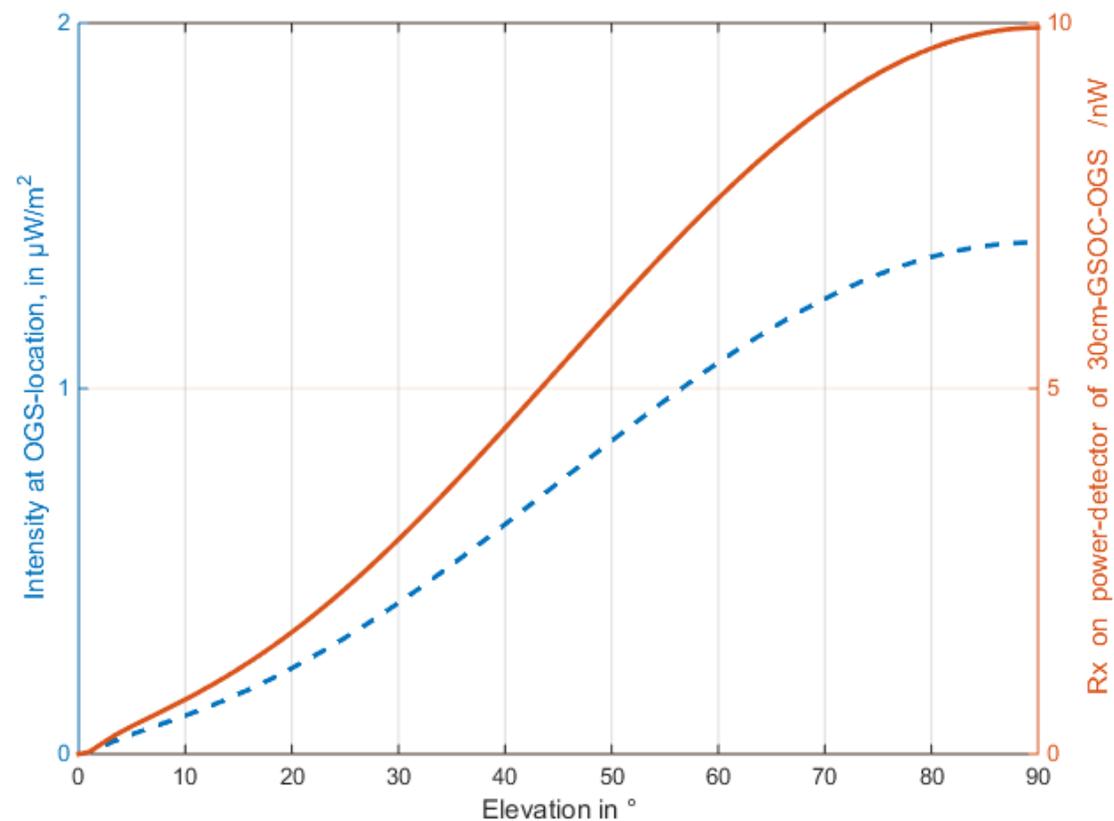
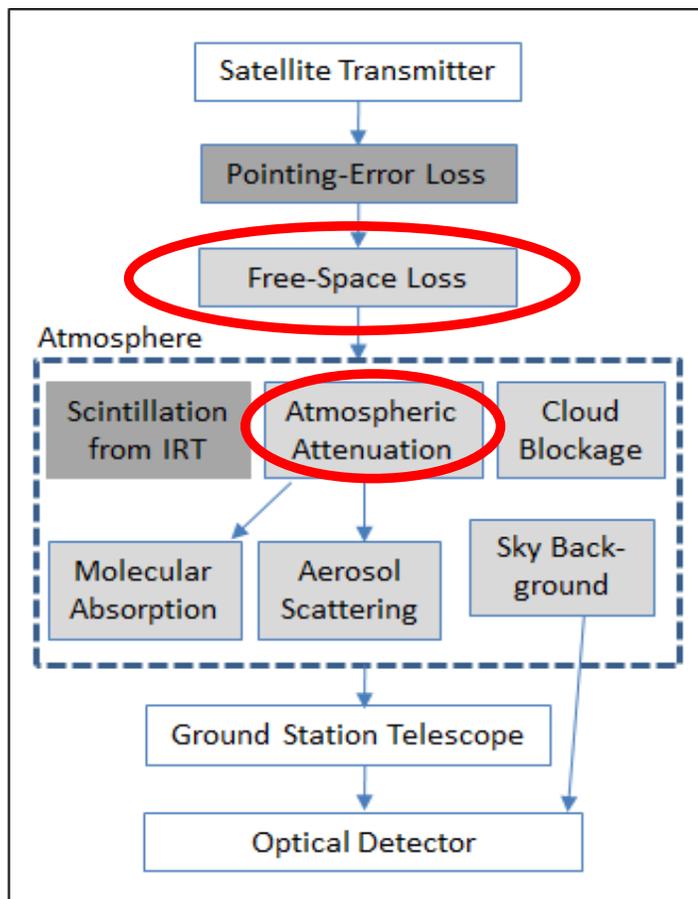
2cm Rx-lens aperture



- Primary development-goal was an automated (unattended) hardware to find a first “Flash” from a (scanning) new *OSIRIS* terminal, and identify by time the intended pointing direction of the satellite
- SFF now also serves as a simple and automated intensity sensor, by using the infrared camera and calculating power



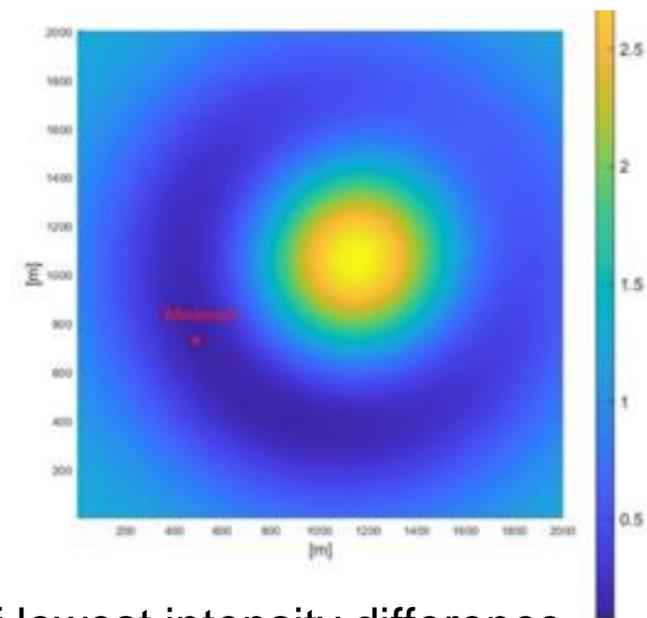
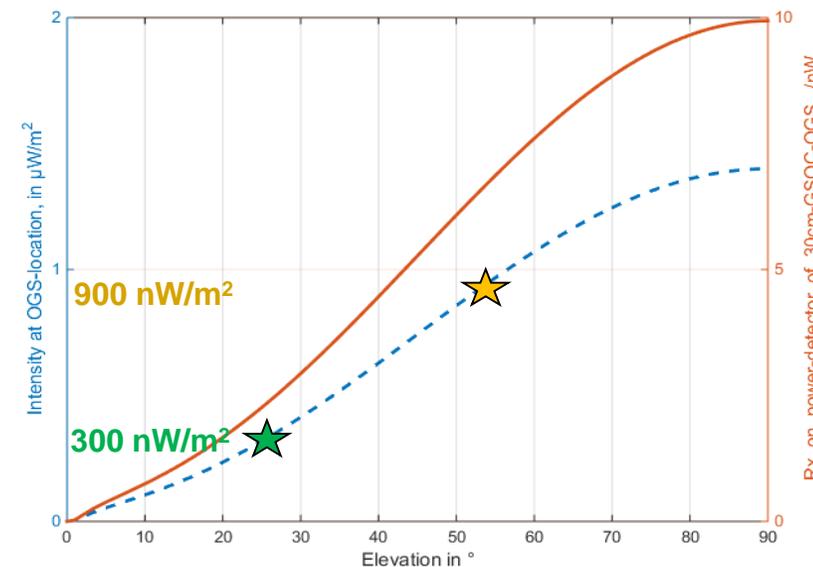
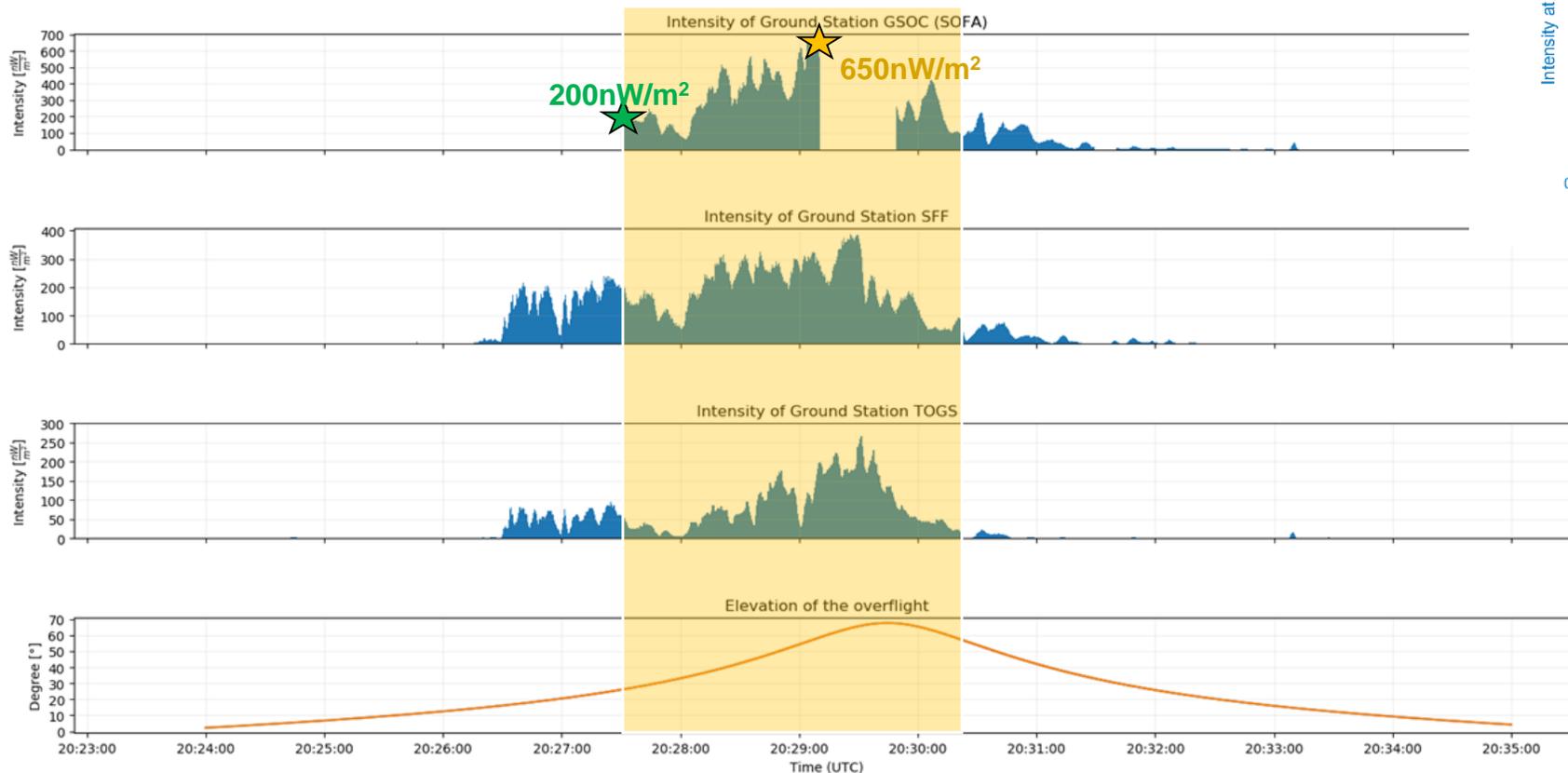
Expected Received-Intensity Estimation from LinkBudget



A precise estimation of the axial intensity is required for the algorithm to work accurately

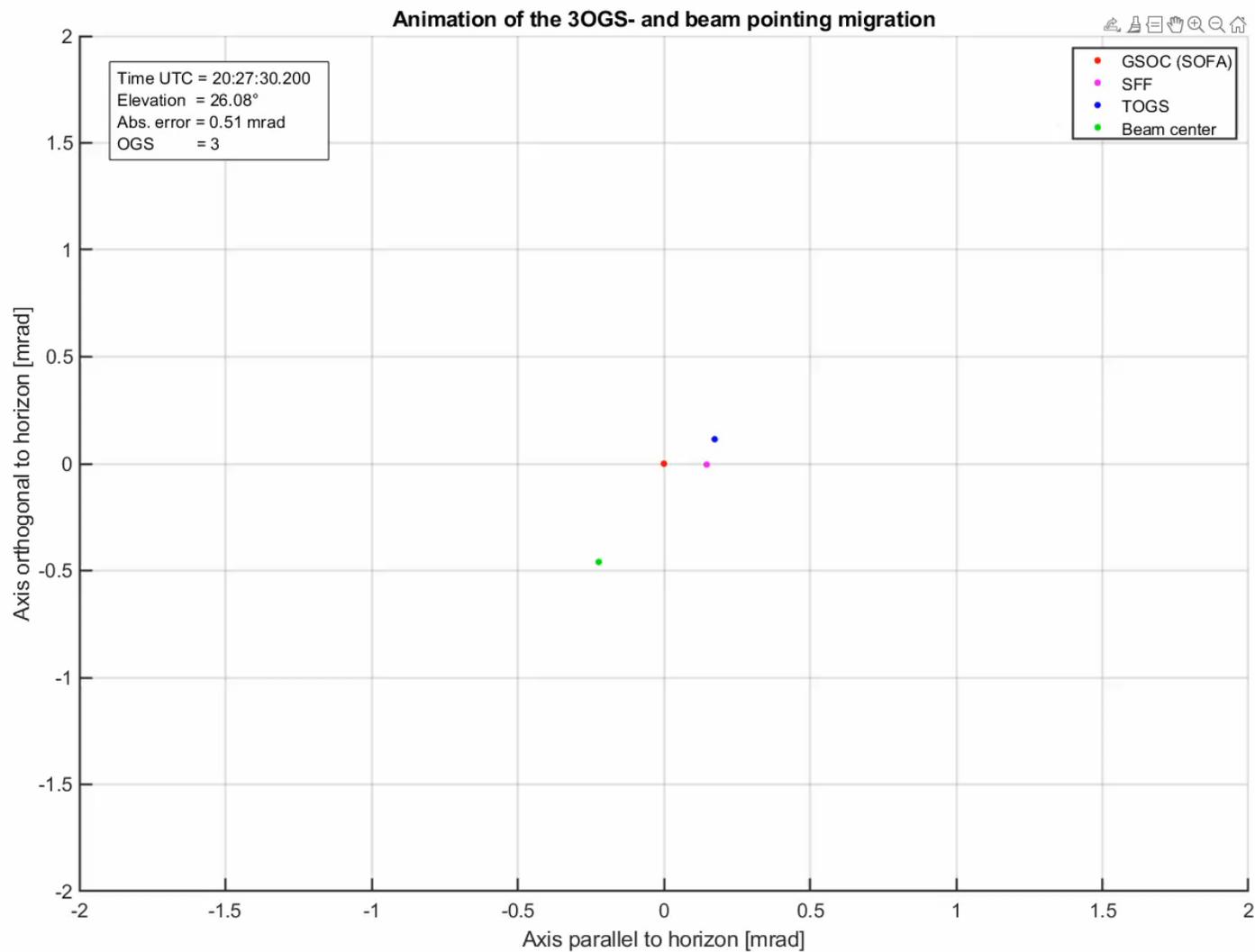


Three Measured *Intensity* Vectors over Time, Downlink on 20th October 2021, centered on GSOC-OGS



Find offset of lowest intensity difference, between measured and numerical estimation

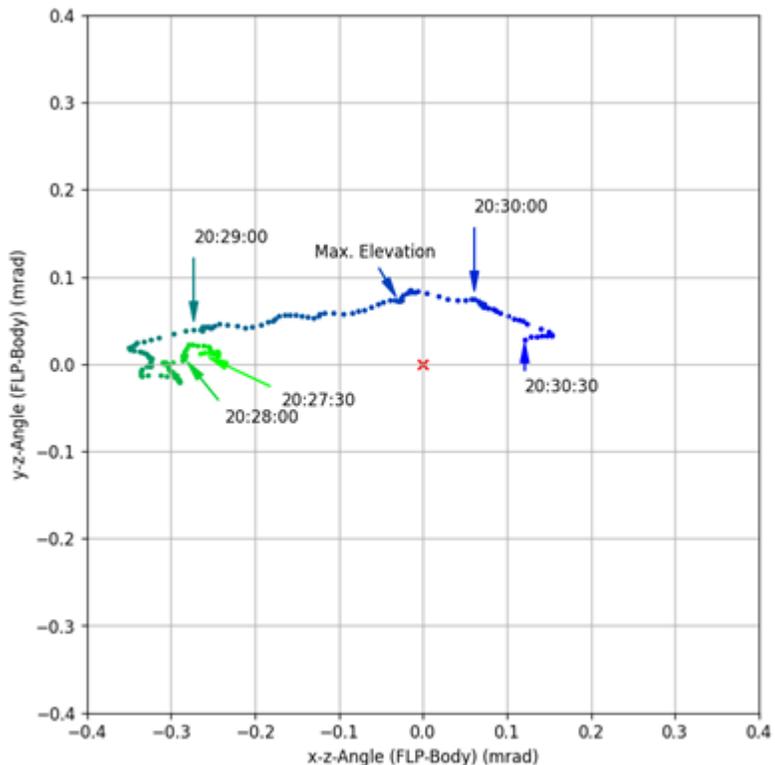




Video:
The 3 OGSs as seen from
FLP-satellite, during part of
this downlink



Residual spot axis migration derived from 3OGS measurements and estimated by Flying Laptop

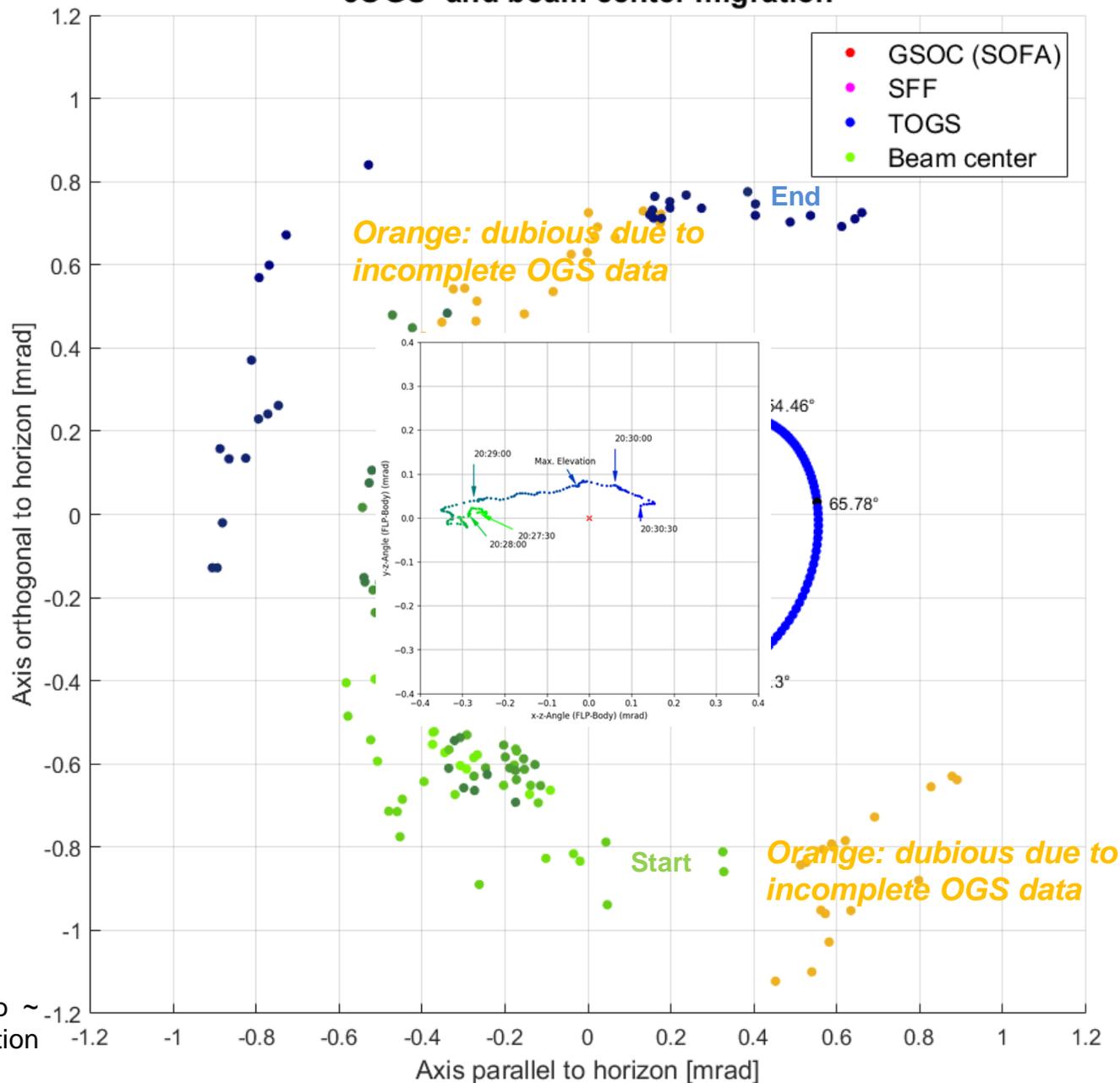


FLP estimates its residual pointing error through its Star-Cam data, to $\sim 300 \times 100 \mu\text{rad}$

... but 3OGS verification on ground estimates up to $\sim 600 \times 800 \mu\text{rad}$, and a rather constant offset direction



3OGS- and beam center migration



Conclusion and Outlook

- This specific downlink showed a rather fixed offset from the satellite, pointing **$\sim 0.6\text{mrad North}$** to GSOC-OGS, plus additional dynamic variation
- This remaining Pointing Offset we think stems from downlink-individual thermal offset of the laser collimator versus the star cameras attitude
- Knowledge of maximum intensity is most crucial for the algorithm, this can be ambiguous through uncertain atmospheric attenuation
- An automated SatFlashFinder shall be used for identifying first Laser Signal from any new OSIRIS
- Then use **Three common SFF Sensors** for Pointing Calibration, instead of different OGS-types
- ... larger spacing of these 3 sensors is required for better decorrelation of intensities and observing larger offset angles

