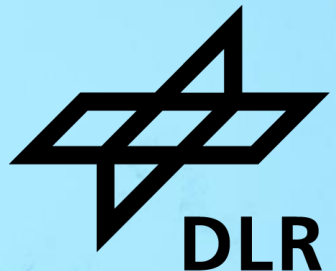


# **A MULTIOBJECTIVE VIEW ON CREATING COUNTERFACTUAL EXPLANATIONS FOR EXPLAINING UNCERTAINTY IN MACHINE LEARNING**

**EUROPT 2022, 30<sup>th</sup> July 2022**

**Julia Niebling**

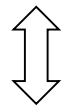
**German Aerospace Centre, Institute of Data Science, Jena, Germany**



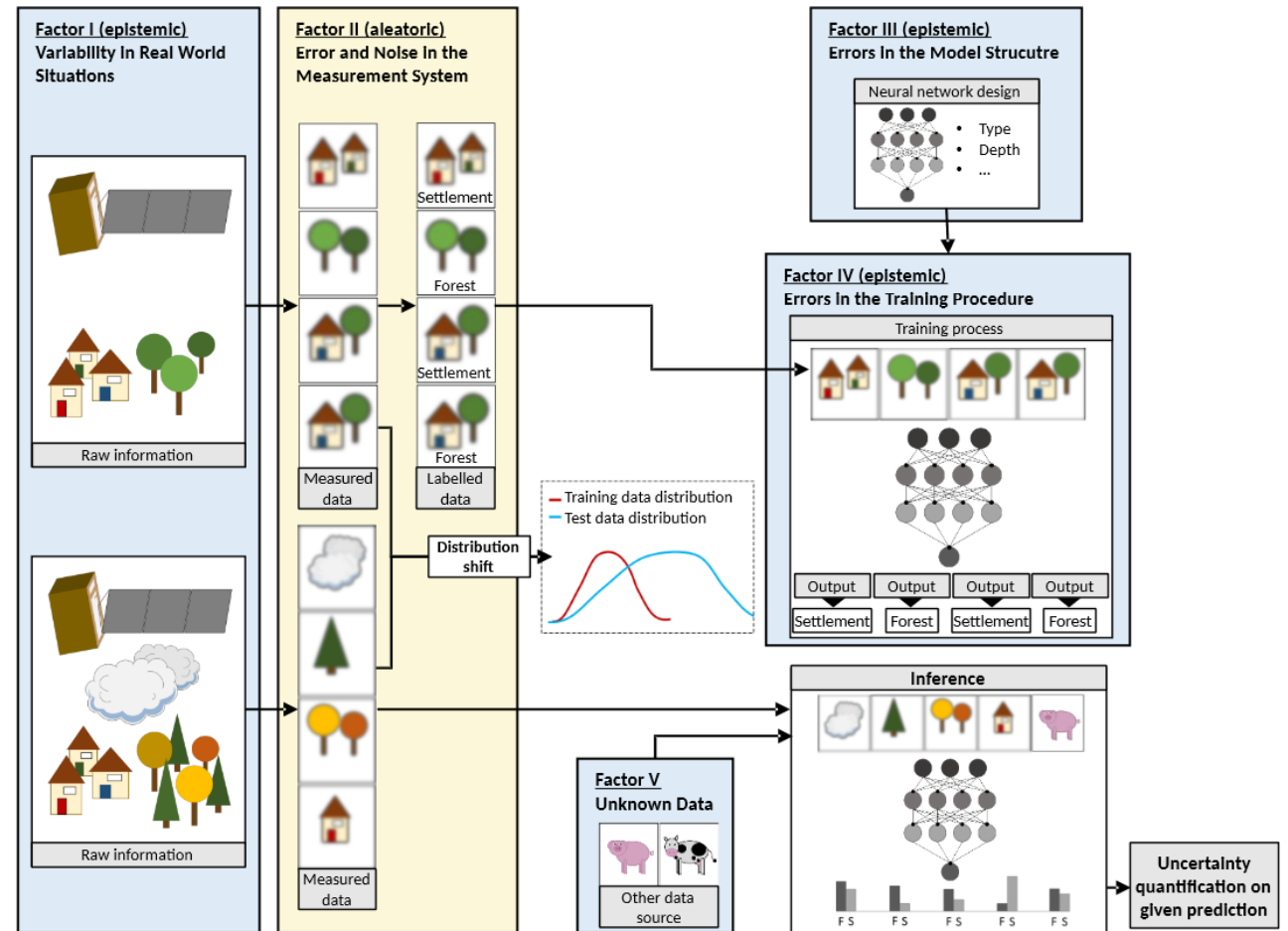
# Uncertainty in Machine Learning

- Quantification of uncertainty to
  - Understand models
  - Trust predictions
  - Develop robust methods

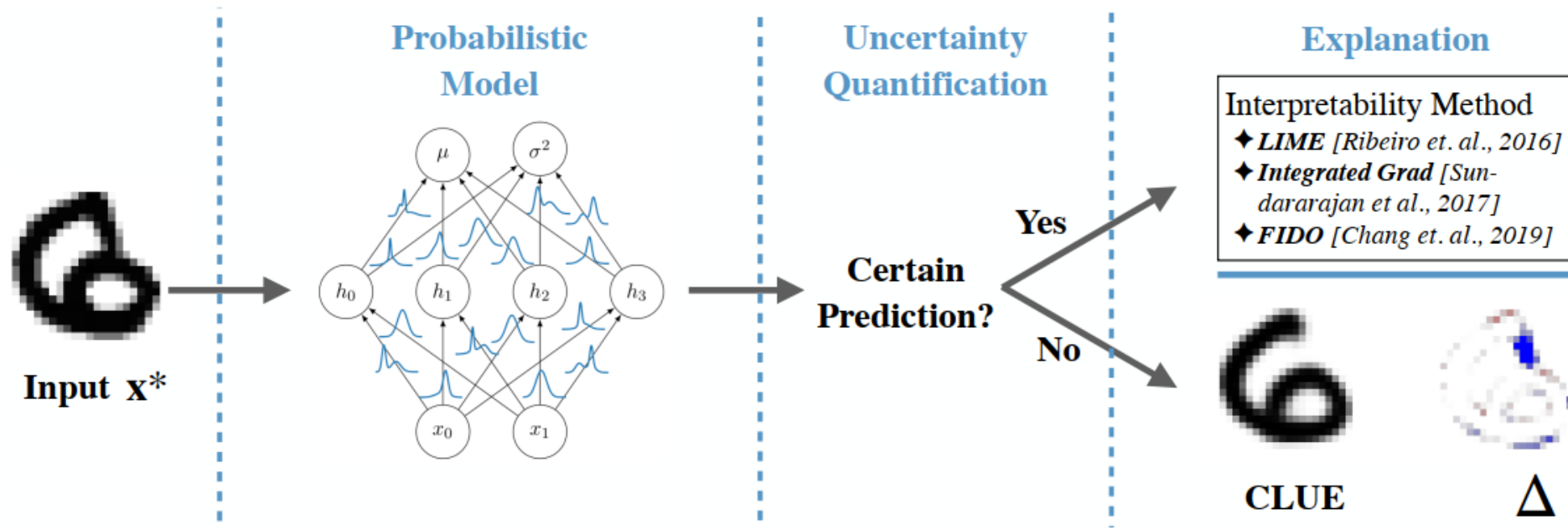
Aleatoric (data) uncertainty



Epistemic (model) uncertainty



# Getting a CLUE



CLUE = *Counterfactual Latent Uncertainty Explanations*

**Counterfactual Explanation** = *what should be different to change the outcome*

# Paraphrasing Optimization $\Leftrightarrow$ Machine Learning

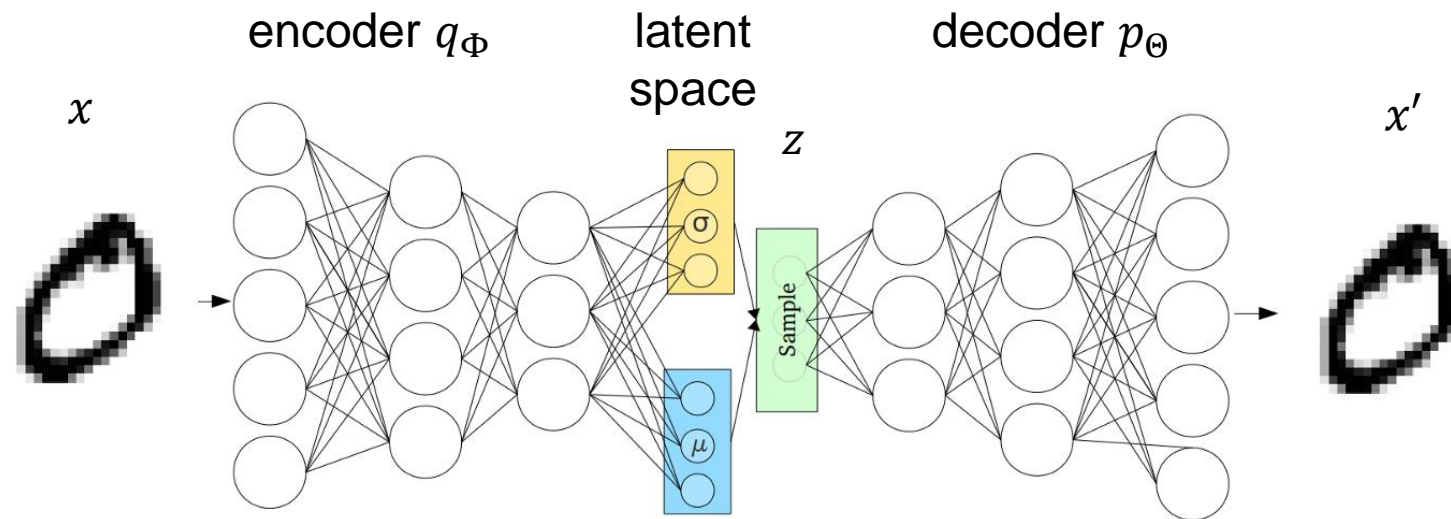


- Optimization is used in ML to train models, e.g. neural networks
- Further usage of optimization in ML possible

OPTIMIZATION	MACHINE LEARNING
objective function	loss function
to optimize	to train
iteration (e.g. of gradient descent)	epoch
$x \in \mathbb{R}^n$ (variables in search space)	e.g. $\theta, w \in \mathbb{R}^n$ (parameters of a NN when <i>training a NN</i> )

# Notations

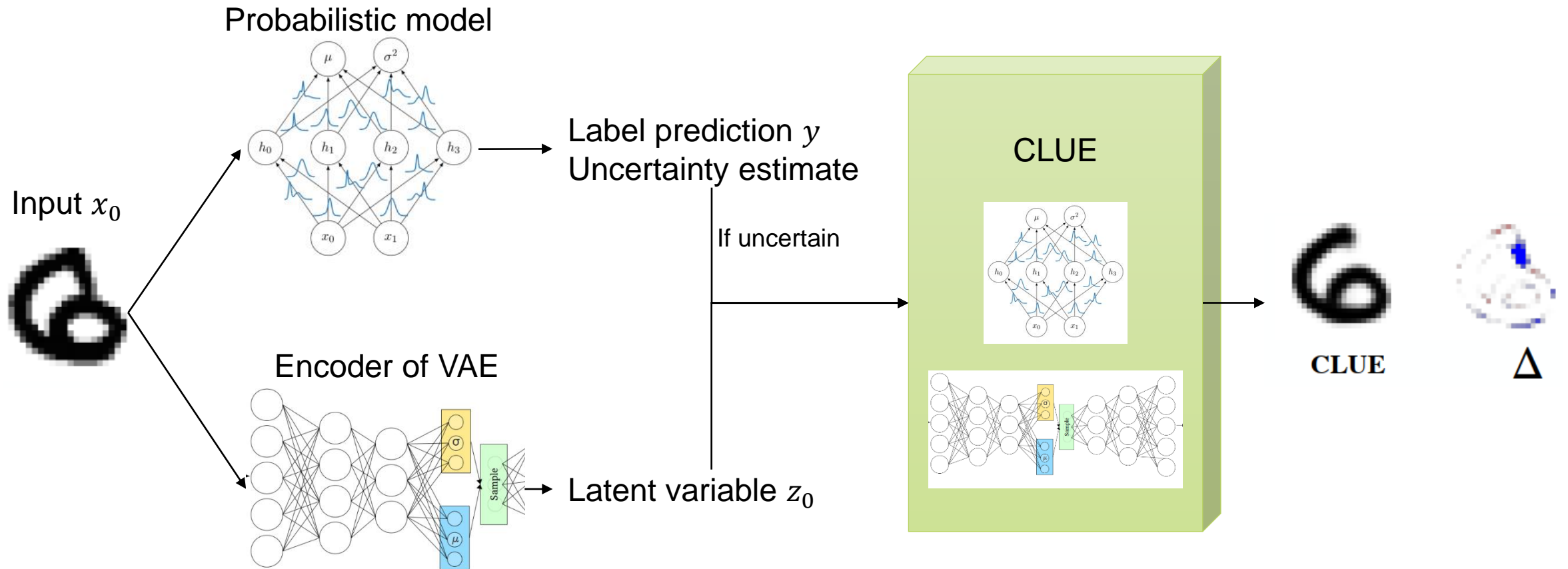
- data points  $x$ , labels  $y$ , latent space variables  $z$
- probabilistic model  $\mathcal{H}$ , differentiable, to estimate uncertainty of an observation, e.g. Bayesian NN
- variational autoencoder (VAE) consisting of encoder  $q_{\Phi}(x|z)$  and decoder  $p_{\Theta}(x|z)$  with parameters/weights  $\Phi, \Theta$



Cf.  
<https://towardsdatascience.com/intuitively-understanding-variational-autoencoders-1bfe67eb5daf>

- predictive means of decoder and encoder of VAE:  $E_{p_{\Theta}(x|z)}[x] =: \mu_{\Theta}(x|z)$ ,  $E_{q_{\Phi}(z|x)}[z] =: \mu_{\Phi}(z|x)$

# Pipeline



# The optimization problem in CLUE

$$\mathcal{L}(z) = \mathcal{H}(y|\mu_{\Theta}(x|z)) + d(\mu_{\Theta}(x|z), x_0)$$

## Uncertainty measure

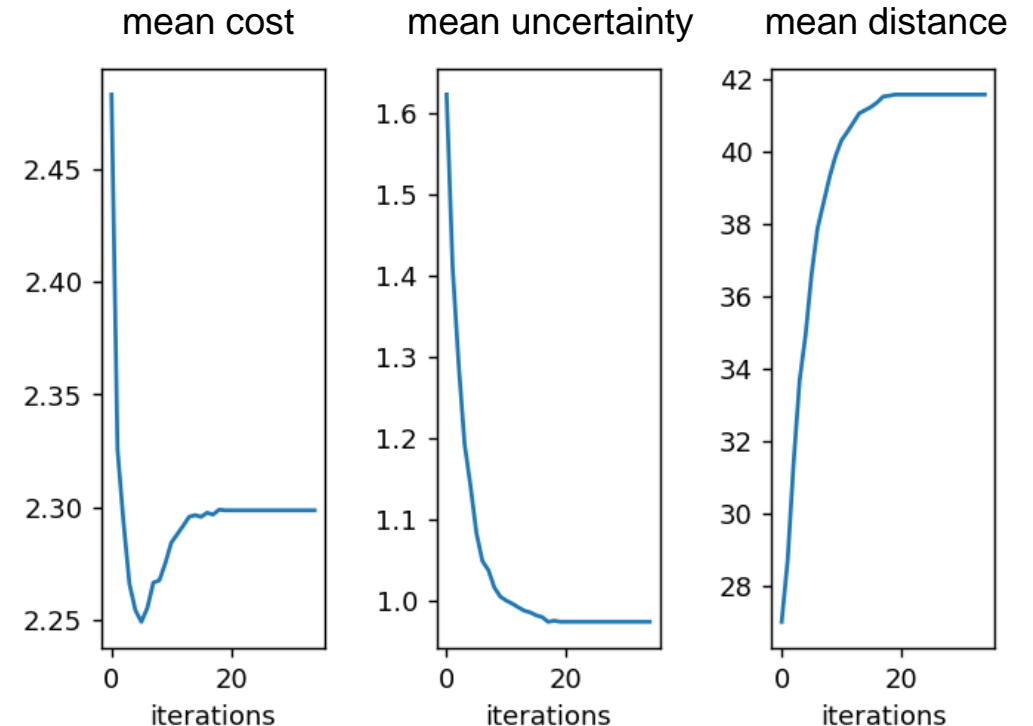
- Stochastic
- Given by trained probabilistic model (e.g. BNN)

## Distance metric

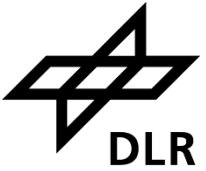
- Nearly deterministic, convex
- In sample space, latent space or prediction space

- Solver: Adam, with 35 iterations

Kingma and Ba. Adam: A method for stochastic optimization. (2014)



# The **multiobjective** optimization problem in CLUE



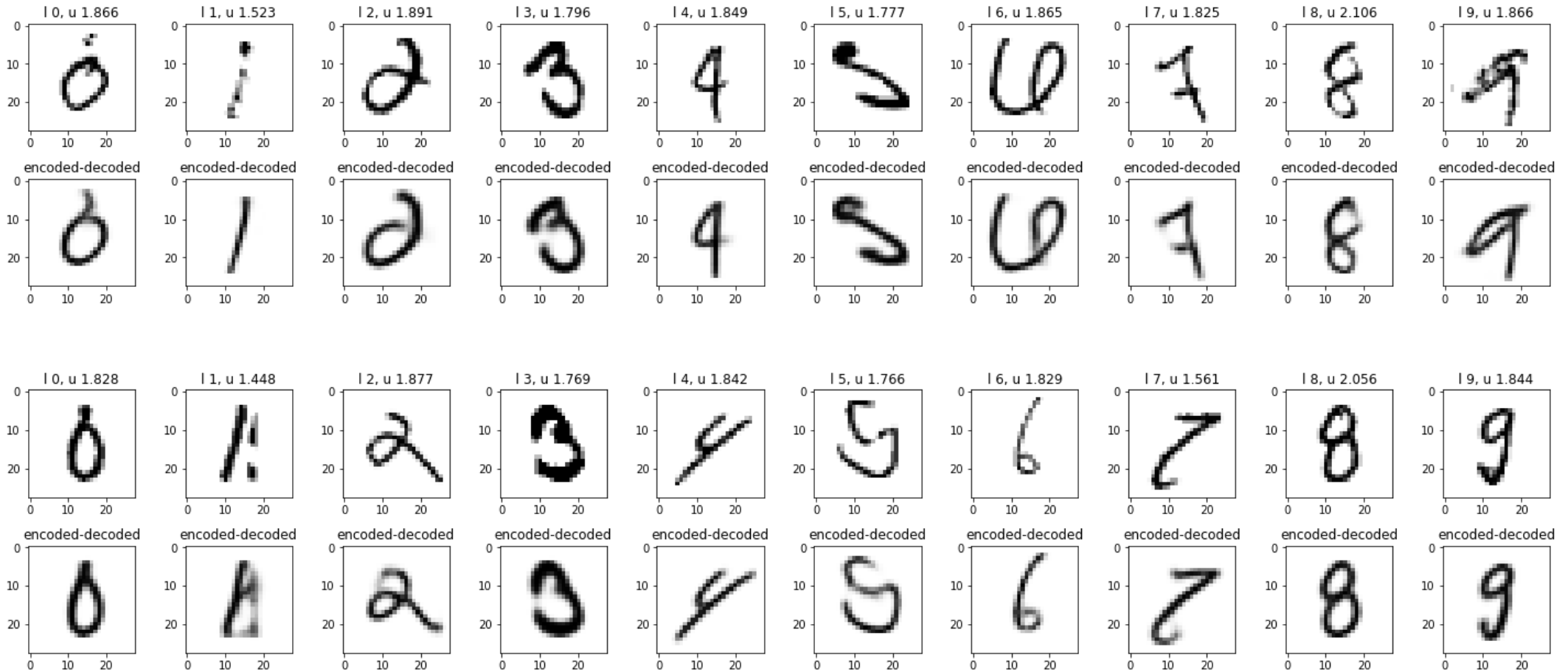
$$\mathcal{L}(z) = \mathcal{H}(y|\mu_{\Theta}(x|z)) + d(\mu_{\Theta}(x|z), x_0) \quad \rightarrow \quad \mathcal{L}(z) = \begin{pmatrix} \mathcal{H}(y|\mu_{\Theta}(x|z)) \\ d(\mu_{\Theta}(x|z), x_0) \end{pmatrix}$$

- Two objectives summed up with weight 1
- Different weights to
  - Indicate preferences of decision maker
  - Give more insights to possible solutions
  - ...?
- Solving with weighted sum approach

$$\mathcal{L}(z) = \lambda \cdot \mathcal{H}(y|\mu_{\Theta}(x|z)) + (1 - \lambda) \cdot d(\mu_{\Theta}(x|z), x_0), \\ \lambda \in \{0, 0.1, 0.2, \dots, 1\}$$



# Considered uncertain test samples

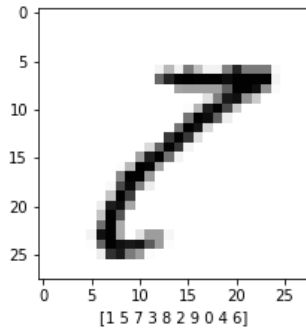




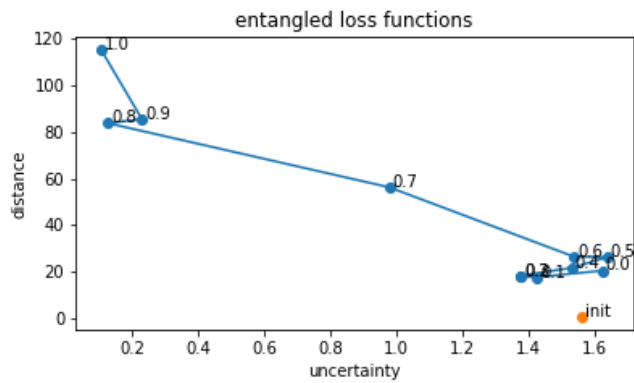
# Exemplary results for number 7



label:

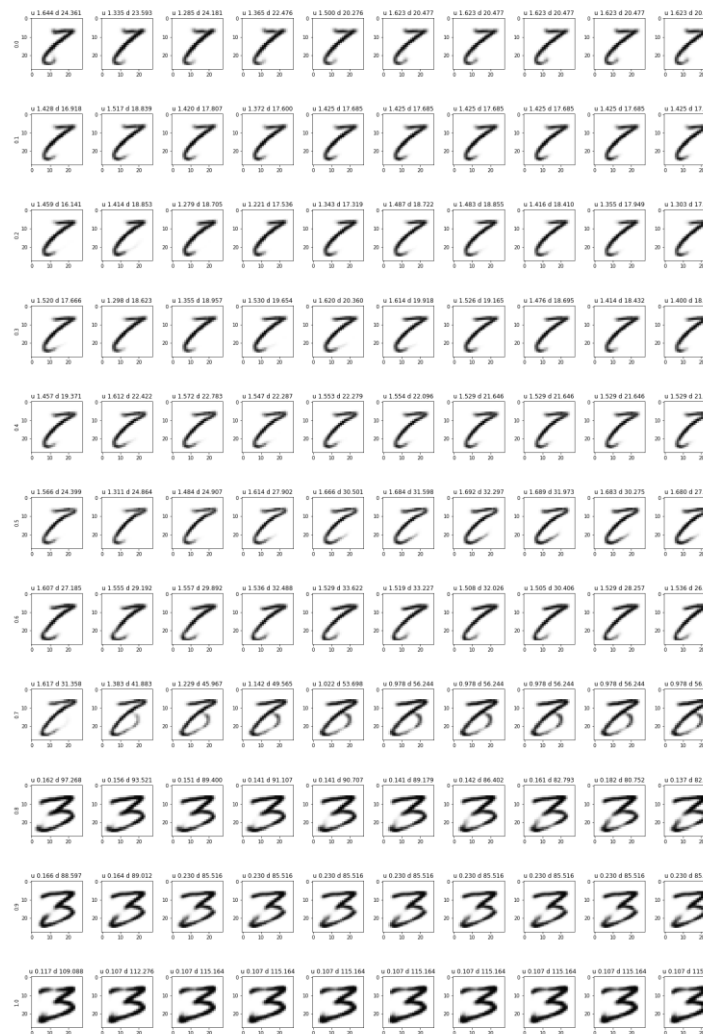


Original sample,  
predicted label 1

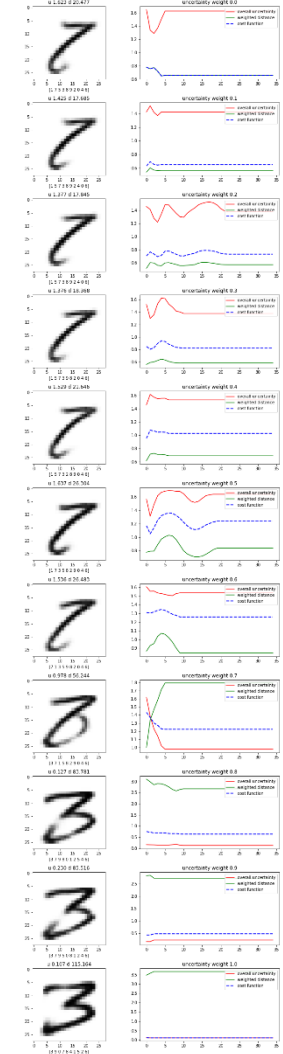


iterations

$\lambda$



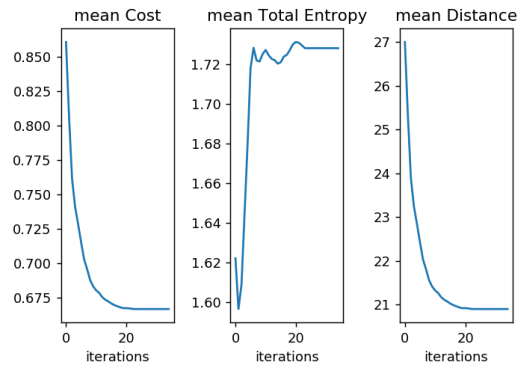
...



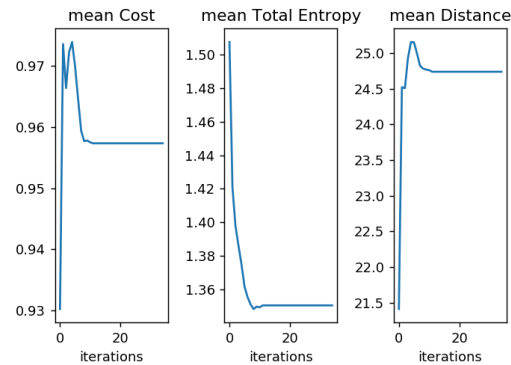
- 1
- 1
- 1
- 1
- 1
- 1
- 7
- 3
- 3
- 3
- 3

# Loss functions and interpretation

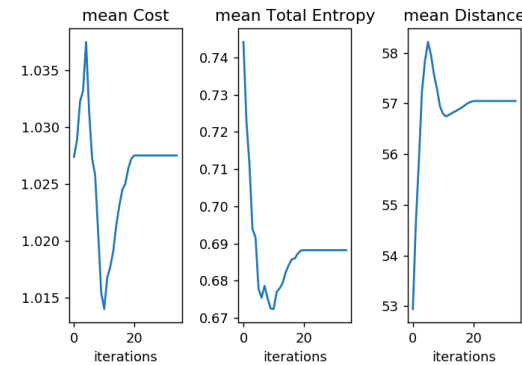
$\lambda = 0.0$



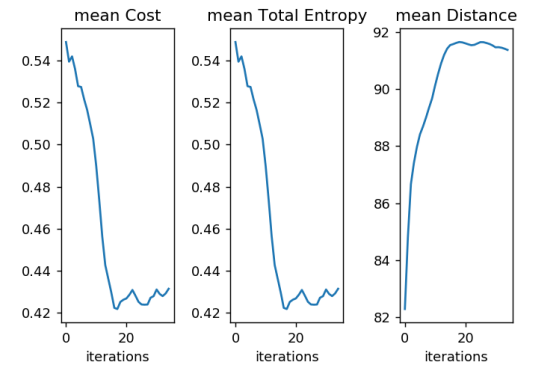
$\lambda = 0.3$



$\lambda = 0.7$



$\lambda = 1.0$



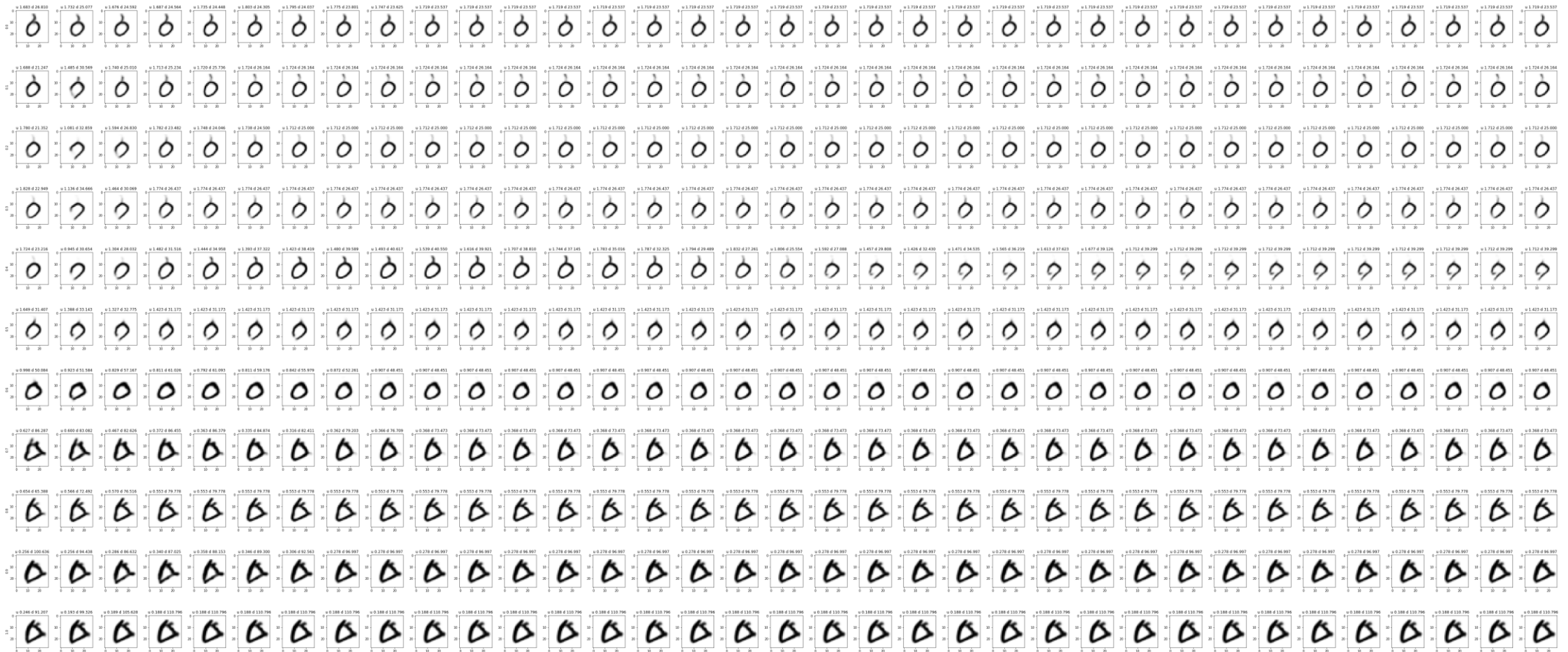
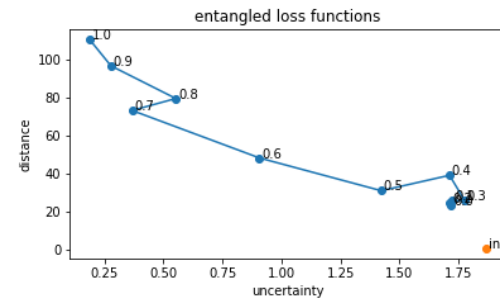
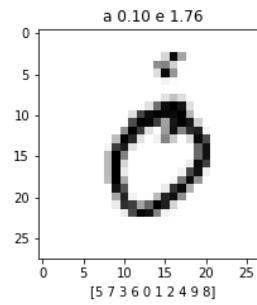
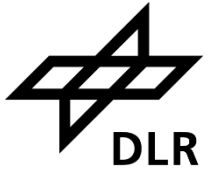
- More weight on distance: more similar CLUEs, often no change in predicted label
- More weight on uncertainty: less similar CLUEs, change in label possible

- local solutions!
- first iteration (1 step of Adam) step brings most visually
- too much weight to one objective often not that useful

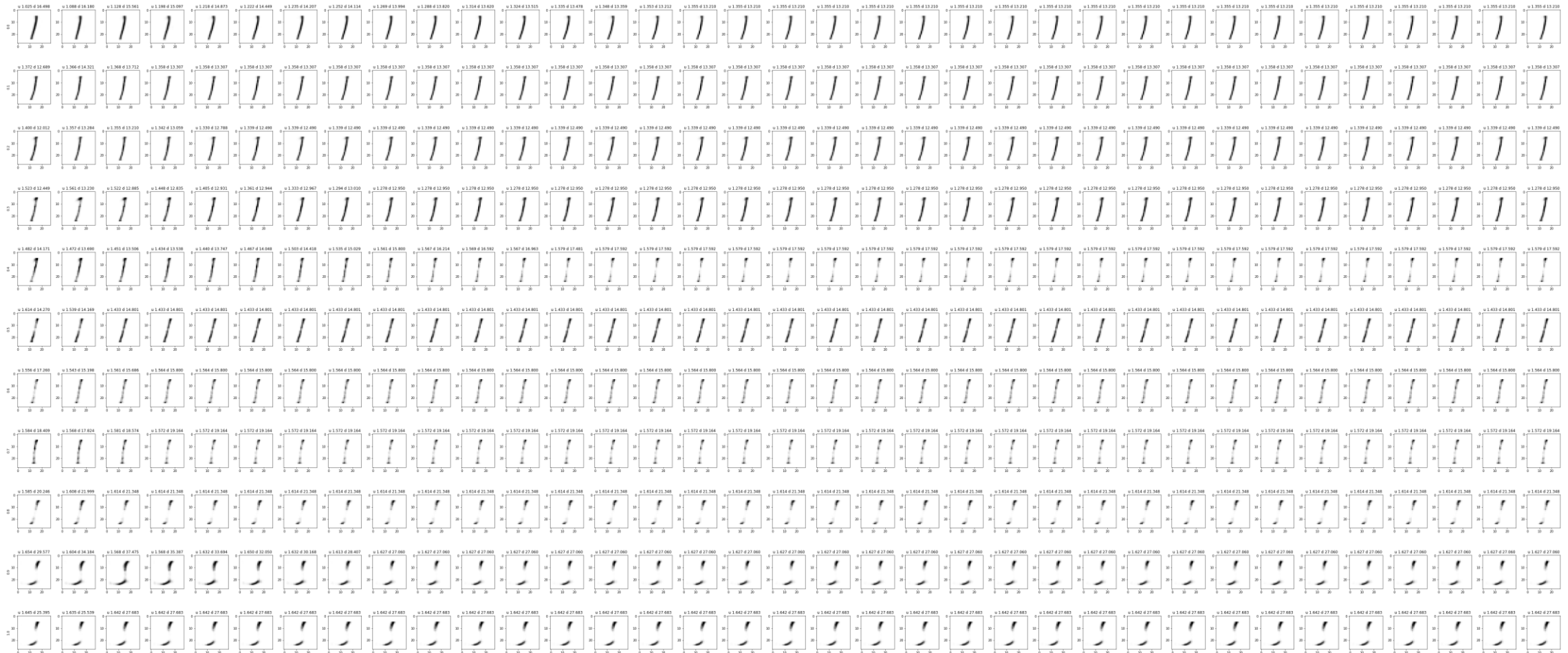
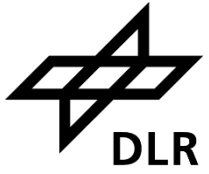
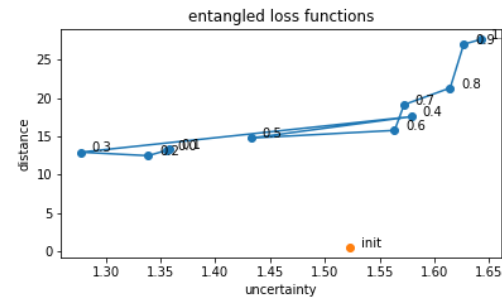
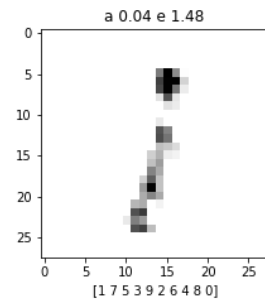
- More extensive studies, different data sets
  
- Solving methods for multiobjective optimization problems
  - Local:
    - Better initialization/starting points for CLUE → make use of previous computed solutions
    - Stochastic gradient descent methods for multiobjective problems (?)
  
  - Global: Evolutionary algorithms, e.g. NSGA-II

Thank you for your attention!

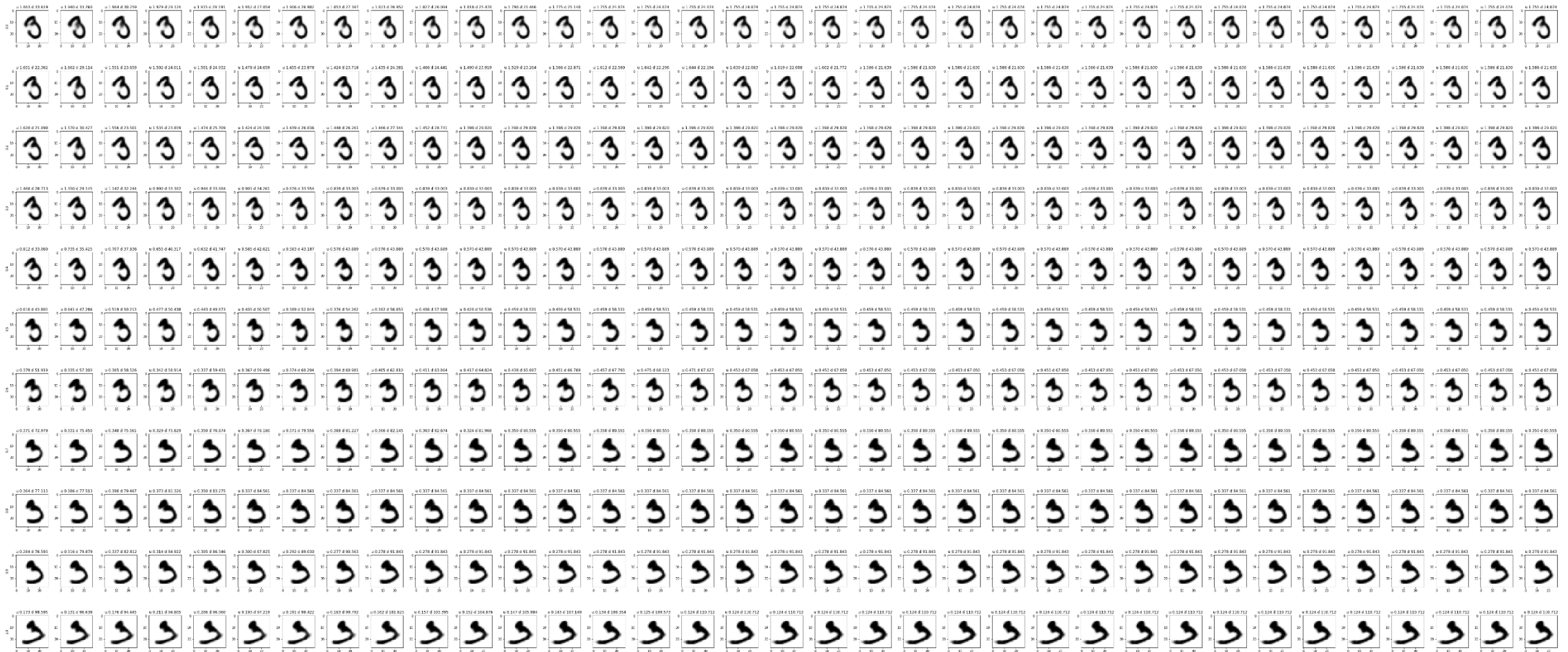
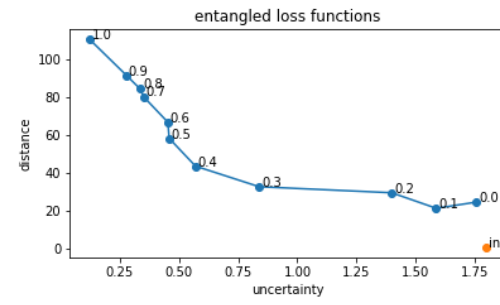
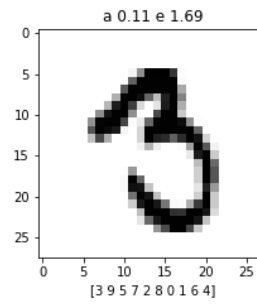
# Further examples



# Further examples

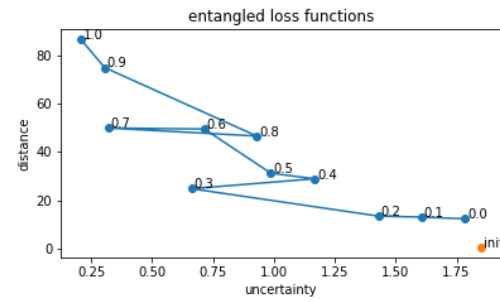
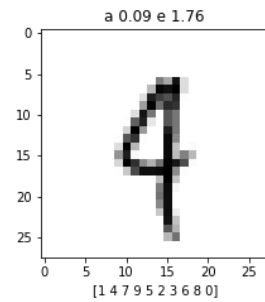
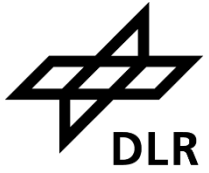


# Further examples

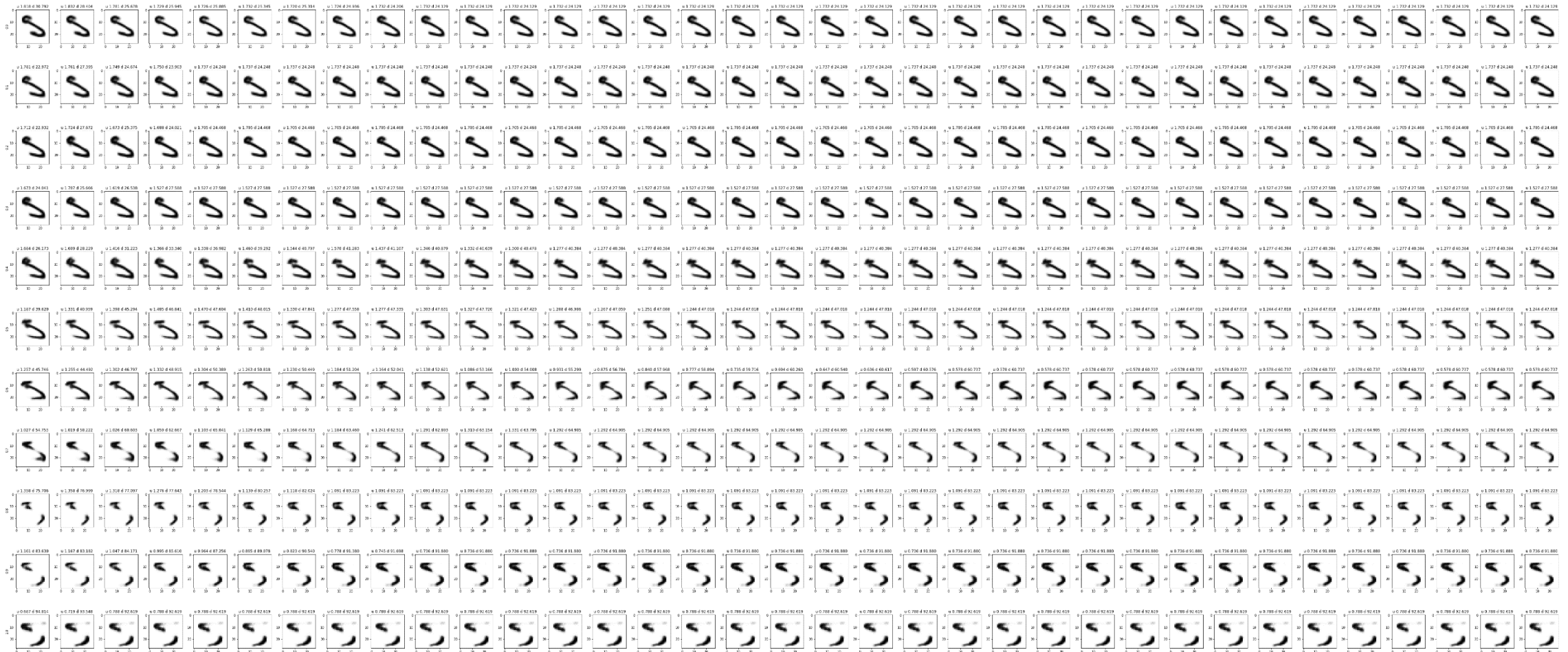
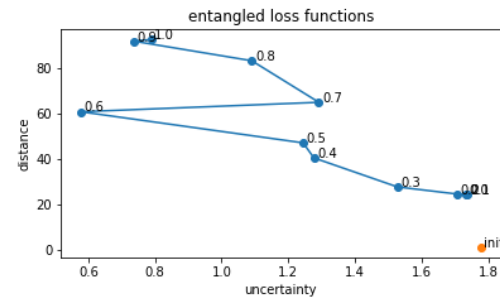
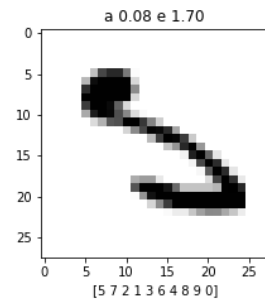
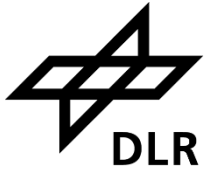




# Further examples



# Further examples







# Further examples

