



## Onboard System Design Challenges of eVTOLs

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# — HorizonUAM —

- Urban Air Mobility (UAM) is the name for a new branch of aviation
  - Transporting people or goods in an urban environment by air
- HorizonUAM project (07/20-06/23) [1]: Research is being carried out at the German Aerospace Center (DLR) in the field of Urban Air Mobility (UAM)
  - Objective: Assessment of chances and risks of air taxis and UAM concepts
  - Main content
    - Forecast of UAM market share
    - Model-based UAM system simulation
    - **Air taxi vehicle system development**
    - Flight guidance concepts for vertidromes
    - Public acceptance
    - Airport integration of UAM traffic
    - Scaled flight demonstrations in model city

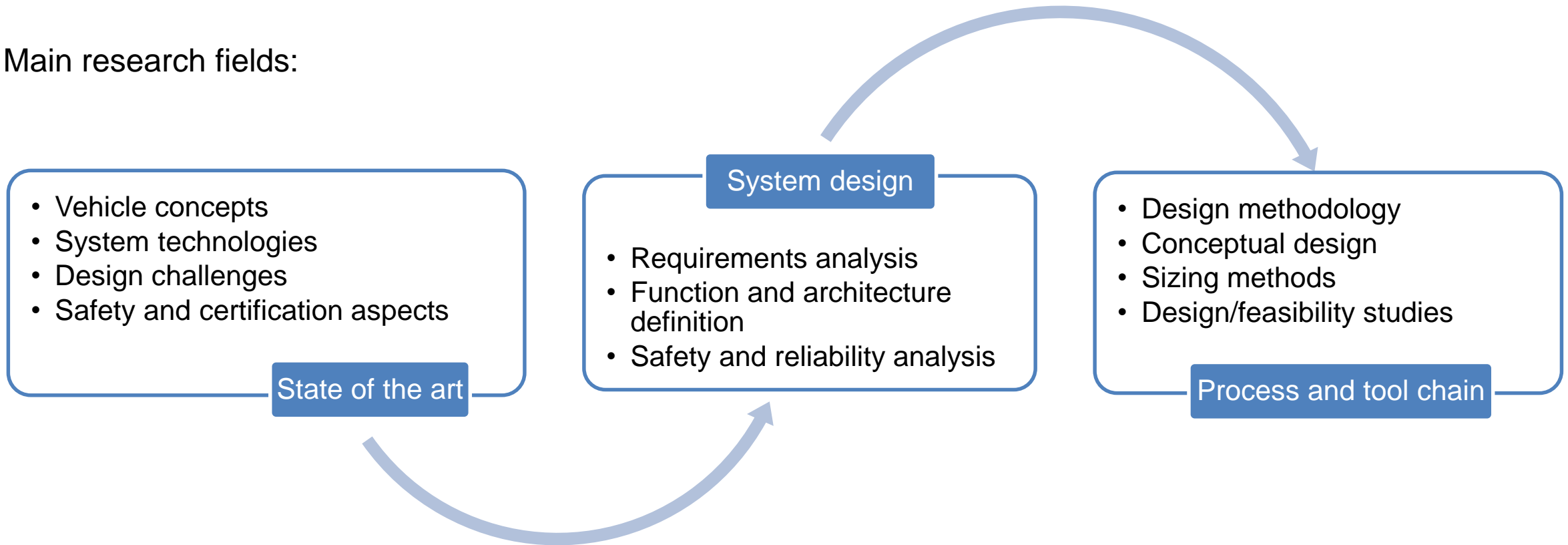


[1] B. Schuchardt. "HorizonUAM-Urban Air Mobility Research at the DLR German Aerospace Center". In: e-Flight Forum China 2020.

# Safe and Certifiable Onboard Systems for UAM Vehicles

Research at DLR - Institute of Flight Systems – Department Safety-Critical Systems & Systems Eng.

- Goal: Definition of an onboard system architecture as a contribution to the air taxi concept
- Main research fields:



# Design Challenges of UAM Vehicles

- Today, many prototypical UAM vehicle concepts exist
  - Only a few concepts are on the way to approval, such as the VoloCity
  - Most concepts still require a lot of research
- Various research areas for UAM vehicles were identified by NASA [2]
- In principle, aircraft design is
  - highly complex and multidisciplinary
  - with a wide variety of interactions and influences between the design disciplines
- Many design challenges also have to be solved for UAM vehicles

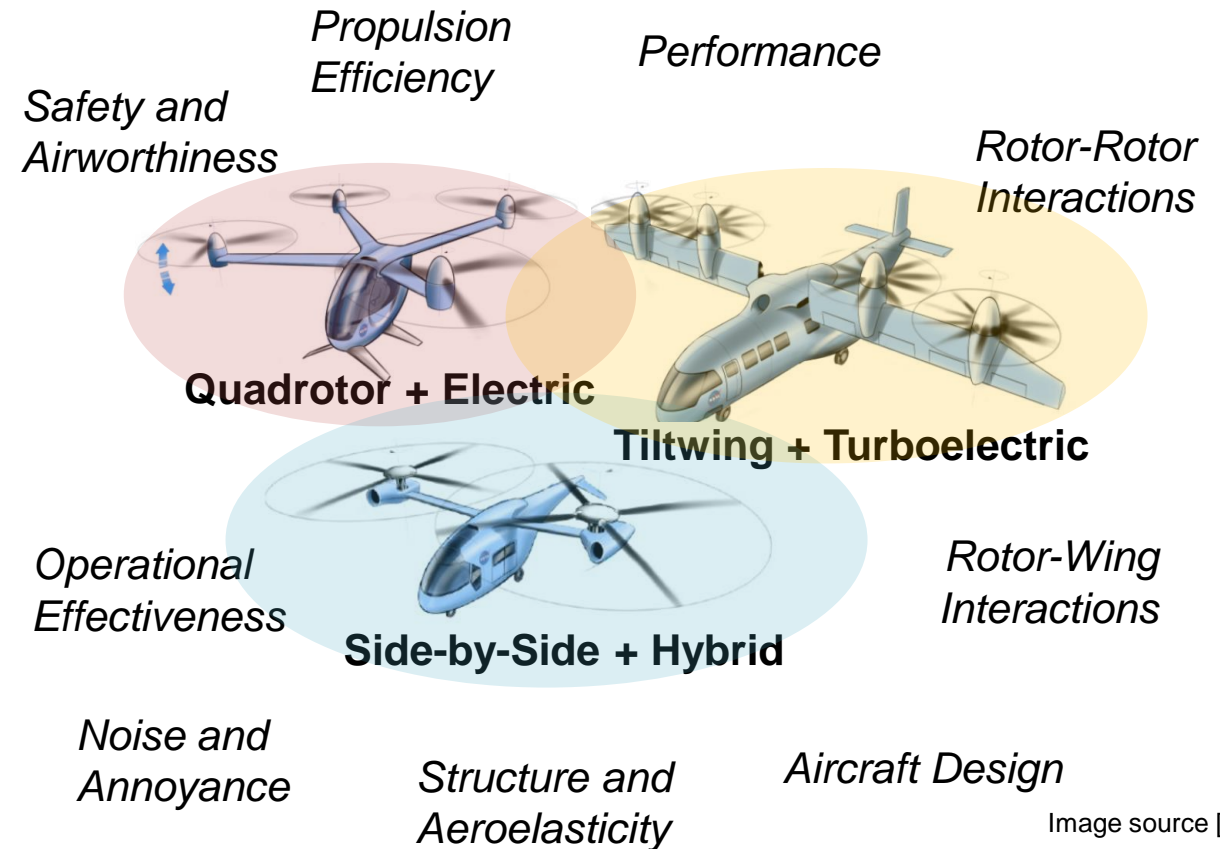
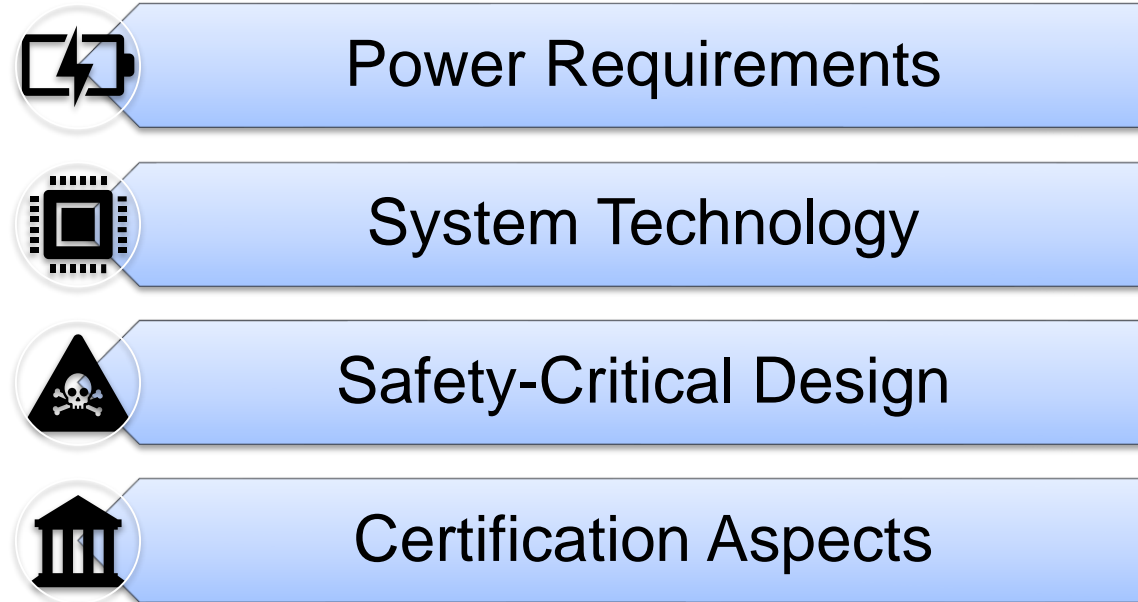


Image source [2]

→ **In this presentation a focus is set on electric powertrains of eVTOLs**  
 → **Goal is to give a brief overview of aspects and challenges that need to be considered in the design**

# Overview of System Design Challenges



# UAM Vehicle Flight Performance

- **UAM vehicle concepts** can be distinguished in:
  - Cruise architectures with rotary wings (e.g. multirotor, conventional and coaxial helicopters)
  - Cruise architectures with fixed wings (e.g. lift and cruise, tilt duct, tilt wing)
- From a **flight performance-based perspective**, these architectures can typically be characterized by their
  - Hover lift efficiency, i.e. disk loading (T/A) and
  - Cruise efficiency, i.e. lift-to-drag ratio (L/D)
- **Values** for these performance parameters can be found in the literature [3, 4] and can provide an initial estimate for the design space of potential aircraft architectures

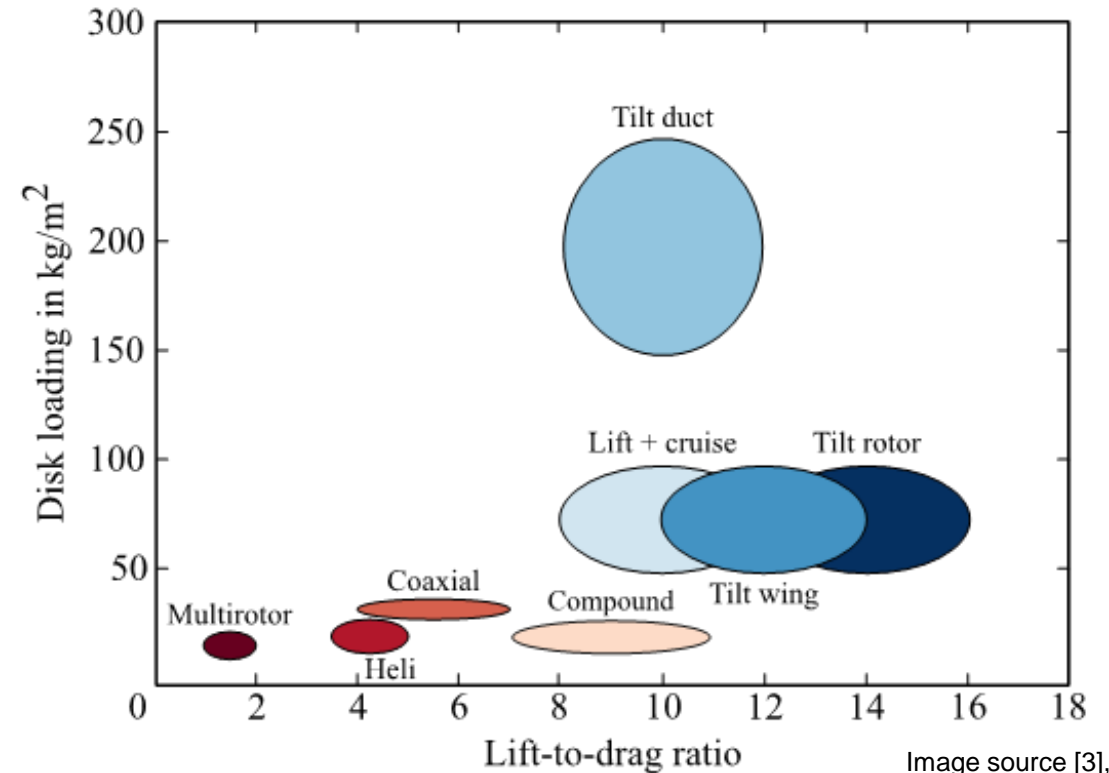
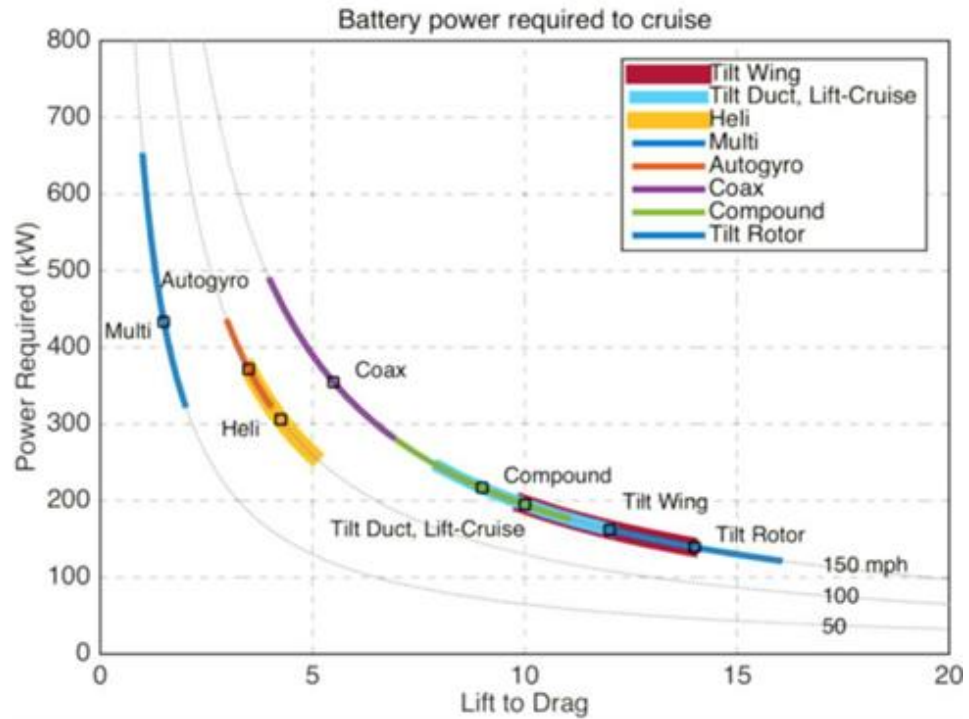


Image source [3],  
values based on [4]

[3] Prakasha, P. S., Ratei, P., Naeem, N., Nagel, B., & Bertram, O. (2021). "System of Systems Simulation driven Urban Air Mobility Vehicle Design". In AIAA Aviation 2021 Forum (p. 3200), <https://doi.org/10.2514/6.2021-3200>  
 [4] R. Gohit et al. Urban Air Mobility (UAM) Market Study - Booz Allen Hamilton. In: UAM Market Study - Technical Outbrief, 2018.

# Power Requirements



- Due to the different performance levels, different types of aircraft also have different electric power requirements
- Different mission, environmental conditions etc. will change these power requirements



# System Technology – Full Electric Powertrains

- **Full electric powertrains are key enablers** for the implementation of electric air taxi concepts (eVTOL)
  - Simpler than gas turbines and mechanical drive trains
  - Lower maintenance costs → Lower vehicle costs
  - Emission-free, low-noise\* and green (if sustainable energy is used)
- **Distributed electric propulsion (DEP)** concepts
  - Design flexibility
  - Can play a major role for safety and reliability
- **Easy motor control**
  - Instantaneous motor response compared to gas turbines
  - No power degradation with altitude (due to missing combustion cycle)
  - Can lead to challenging requirements for power electronics (e.g. switching frequency, high-voltage / power)

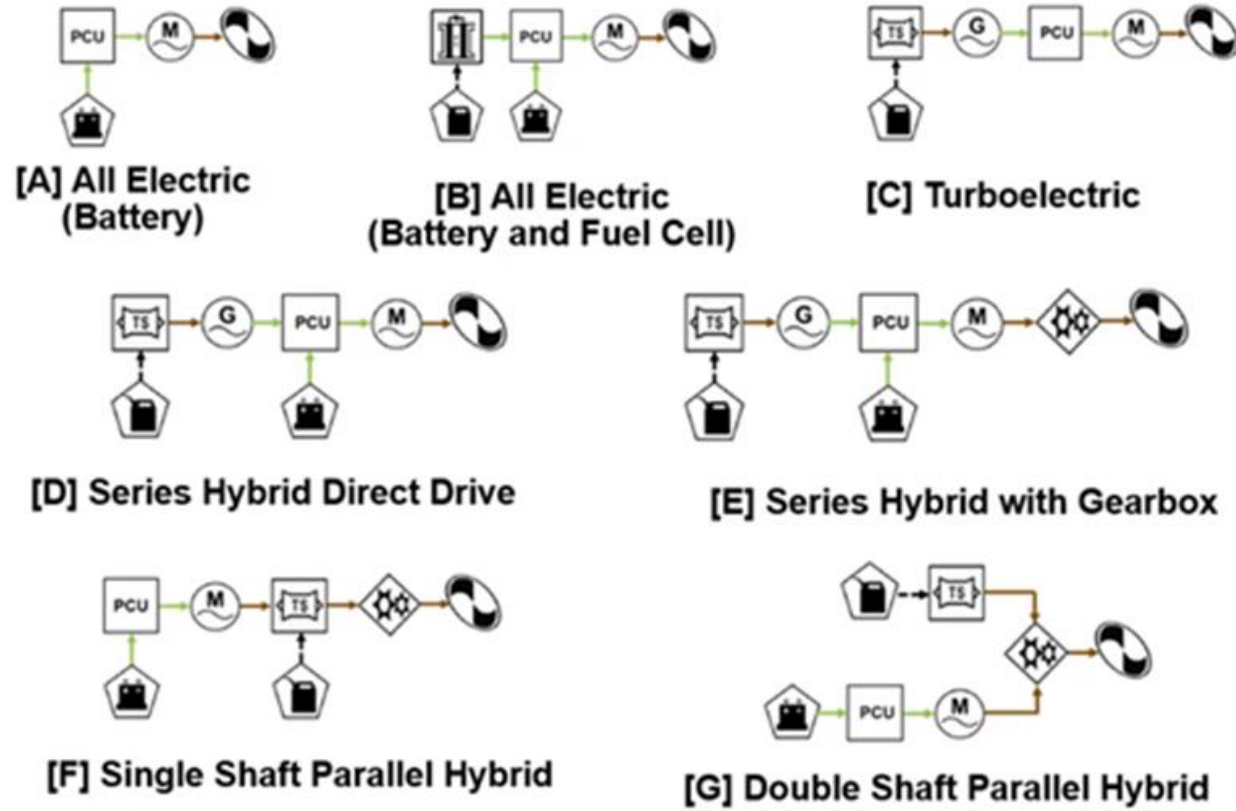
\*Rotor noise is not considered here





# System Technology – Turbo- or Hybrid-Electric Powertrains

- Alternatively **turbo- or hybrid-electric powertrain** concepts can be seen as bridge technology
  - more complex system
  - less powertrain efficiency



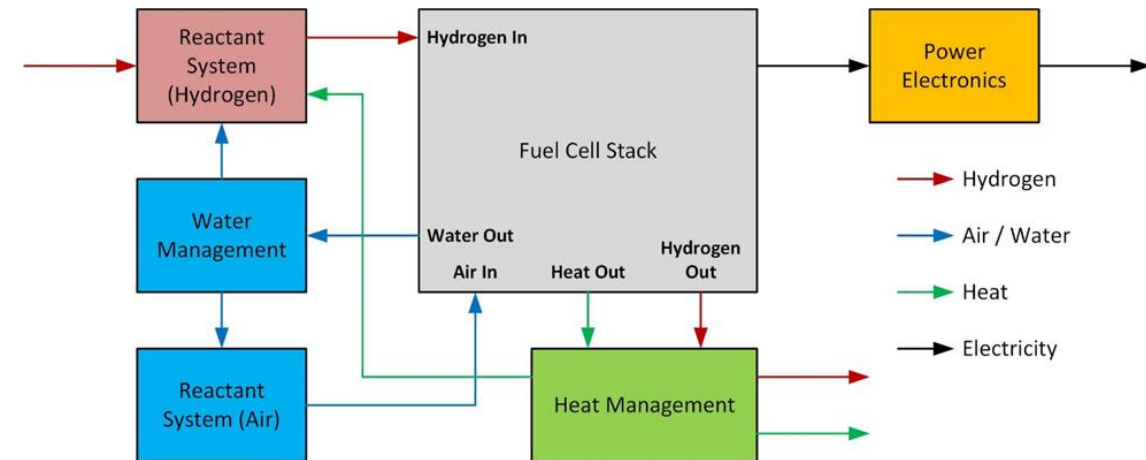
# System Technology – Battery Technologies

- Today's available **battery technology** is typically used as **electrical energy source** and is related to the benefits of electric powertrains
- Battery **costs are falling continuously** due to the high demand and production in the automotive industry
- Results in a relatively **high component weight** with reduced payload capacity
  - Power requirements drives the battery size and weight → ~30 to 40% of aircraft empty weight
  - Battery-powered eVTOLs are heavier than conventional ones, but eVTOL concepts are feasible
  - Enables only short flight times and/or ranges in eVTOL applications due to specific energy and energy density
  - Major impact on the vehicle design, on operational aspects of the individual eVTOL and entire eVTOL fleet (→ System of systems)
- **Active thermal management** → Leads to additional components and weight



# System Technology – Fuel Cell Systems

- **Fuel cell systems** → Alternative electrical energy source
  - Enables a continuous electrical energy output for higher endurance of the vehicle
  - Short-term peak performance (e.g. during take-off or landing) can be provided in conjunction with a battery system
  - Reaction process → pollutant-free, environmentally friendly, noiseless functionality
- **Challenges** of fuel cell systems
  - Requirements for new subsystems (cooling, tank)
  - Crash safety of the hydrogen-carrying components
  - Liquid or gaseous storage of hydrogen incl. A/C integration
  - Fuel cell system control and thermal management
  - Limited service life
  - Higher system weight (for short mission ranges)



# Safety-Critical Design Aspects

## Electric propulsion systems face aircraft designers and safety engineers with new and unknown challenges

**Lithium batteries** can fail in seemingly more complex modes

- Main danger: thermal runaway → external fire, toxic gases
- Reasons: deep discharge, overcharging, and internal short circuits
- Crash safety must be guaranteed

### Electrical high-voltage systems

- In flight: Energy release through short circuits and arcs → external fire, deterioration in powertrain system performance
- On ground: Pose also a high risk for maintenance and ground handling personnel

### Electromagnetic compatibility (EMC)

- Danger for other aircraft systems and passengers
- Through imperfect or faulty behaviour of electrical components

### Interconnection of propulsion system with flight control system

- Failure may influence flight control function and lift
- DEP requires intelligent control and power management

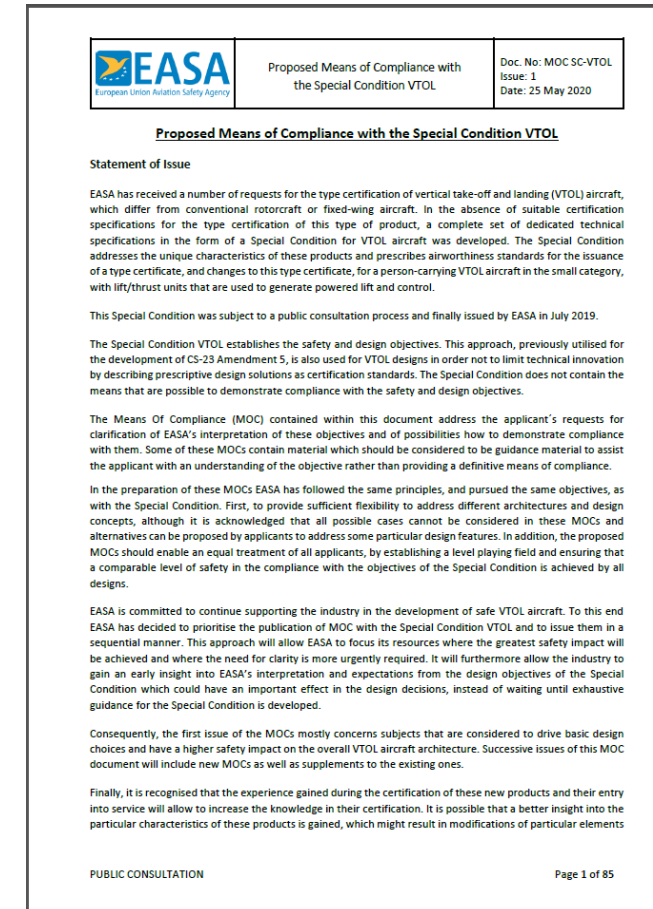
Electric powertrain systems offer new potential for **increasing safety**, e.g. DEP

- More tolerant against bird strikes and engine losses
- Failure-tolerant system architectures
- Redundantly designed functional components
- More options of redistributing the power to other drives in the event of a component failure → Simpler, less complicated and more effective system architectures



# Certification Aspects – SC-VTOL

- Due to growing numbers of inquiries to air taxi certification requirements EASA released
    - the “Special Condition Vertical Take-Off and Landing (VTOL) Aircraft” (SC-VTOL) in July 2019 [5]
    - the „Proposed Means of Compliance with the Special Condition VTOL” in May 2020 [6]
    - the „Electric/Hybrid Propulsion System (SC E-19)“ in April 2021 [7]
  - **Concept of the SC-VTOL** is analogous to developments in the area of CS-23
    - Performance-based safety goals (“Objective Requirements”) instead of design-specific requirements
    - Independent of aircraft design and adapted to complexity, performance and operating mode
    - Design-specific requirements are located in the (proposed) means of compliance in the form of overarching aviation standards
  - Two VTOL categories
    - Category “enhanced” for operation over metropolitan areas or commercial transport of people
    - Category “basic” for all other applications
- **Air taxis are assigned to the “enhanced” category**



[5] EASA. “Special Condition for VTOL Aircraft”. 2019

[6] EASA. “Proposed Means of Compliance with the Special Condition VTOL”. 2020

[7] EASA. “Electric/Hybrid Propulsion System (SC E-19)”. 2021

# Certification Aspects – Safety Requirements

- Safety requirements correspond to those for civil aircraft
- **Failure condition classification „catastrophic“**
  - Failures that lead to one or more deaths or the incapacity for work of a cockpit crew member in connection with a crash of the aircraft
  - All failures that prevent the aircraft from safely continuing its flight and landing
- **No single failure can lead to a catastrophic event**
  - Evidence through the application of established processes for safety assessment
  - (→ ARP4754A, ARP4761)
- Systems whose failure condition could lead to a catastrophic or hazardous event must be able to be monitored by means of **suitable monitoring during operation.**

		Failure Condition Classifications			
		Minor	Major	Hazardous	Catastrophic
Maximum Passenger Seating Configuration		Allowable Qualitative Probability			
		Probable	Remote	Extremely Remote	Extremely Improbable
		Allowable Quantitative Probability (Note C and D)			
		Development Assurance Level			
Category Enhanced	-	$\leq 10^{-3}$ FDAL D (see Note B)	$\leq 10^{-5}$ FDAL C	$\leq 10^{-7}$ FDAL B	$\leq 10^{-9}$ FDAL A
Category Basic	7 to 9 passengers (Basic 3)	$\leq 10^{-3}$ FDAL D (see Note B)	$\leq 10^{-5}$ FDAL C	$\leq 10^{-7}$ FDAL B	$\leq 10^{-9}$ FDAL A
	2 to 6 passengers (Basic 2)	$\leq 10^{-3}$ FDAL D (see Note B)	$\leq 10^{-5}$ FDAL C	$\leq 10^{-7}$ FDAL C (see Note A)	$\leq 10^{-8}$ FDAL B (see Note A)
	0 to 1 passenger (Basic 1)	$\leq 10^{-3}$ FDAL D (see Note B)	$\leq 10^{-5}$ FDAL C	$\leq 10^{-6}$ FDAL C (see Note A)	$\leq 10^{-7}$ FDAL C (see Note A)

[Quantitative safety objectives are expressed per flight hour]

*The failure rates to be verified and the “Function Development Assurance Level” (FDAL) to be used for the individual failure categories can be found in the safety objectives table [6]*

# Summary

- In HorizonUAM an air taxi system concept will be developed
- Goal was to give an overview over system design challenges with emphasis on electrical powertrains
- Electric powertrains and battery technology are key enablers for eVTOLs today
- In addition to the benefits and potentials, aircraft designers and system engineers are faced with new and unknown challenges
- Safety and other requirements must be met in accordance to the SC-VTOL (and others SCs) and its proposed MoCs
- There are, of course, a lot of more design challenges related to other onboard systems (e.g. avionics...)



**Thank you for your attention!**



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