

CleanSky2

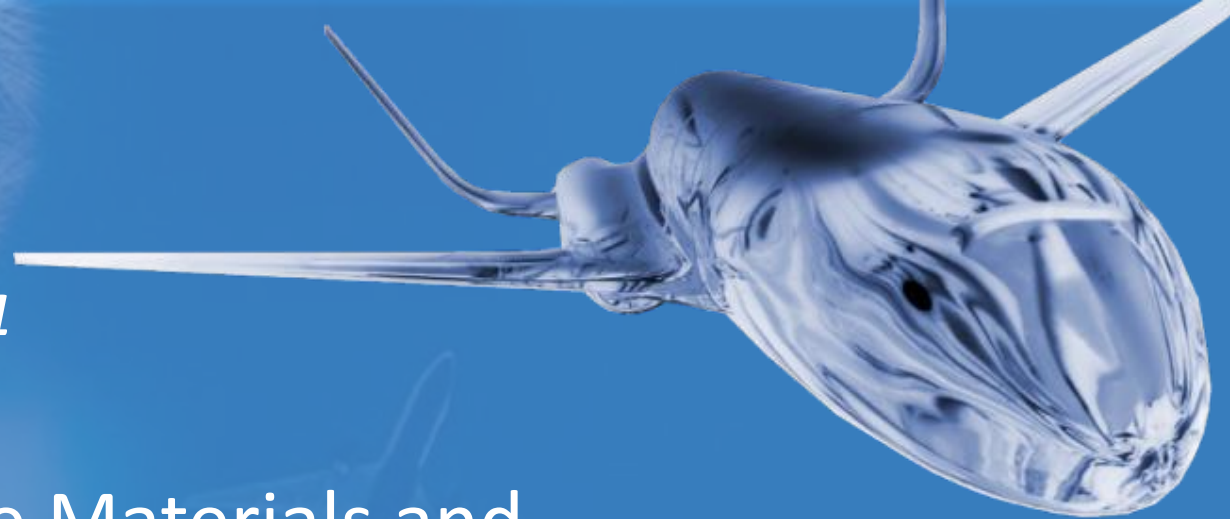
LPA - WP 1.4.4

## CS2 Composite Materials and Manufacturing Workshop

HLFC-WIN: Suction Rib Infusion –  
The Digital Infusion Center in Action

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**DLR, Institute of Composite Structures and Adaptive Systems**



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# HLFC-WIN Introduction

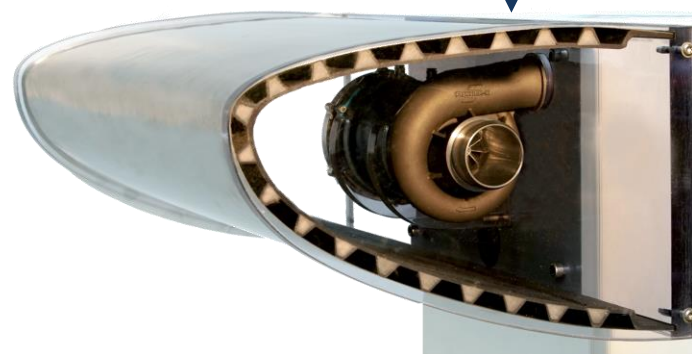
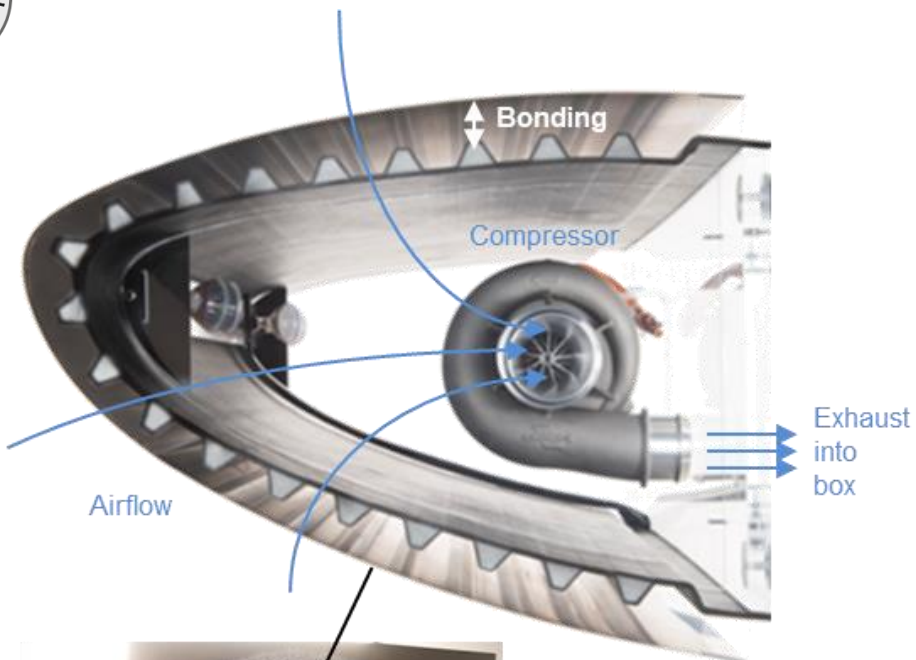


# LPA WP 1.4.4 HLFC-WIN Introduction

- Contributing Project: HLFC-HTP (CS2 WP 1.4.1)



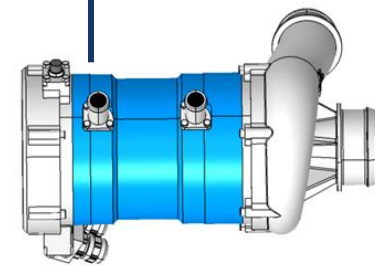
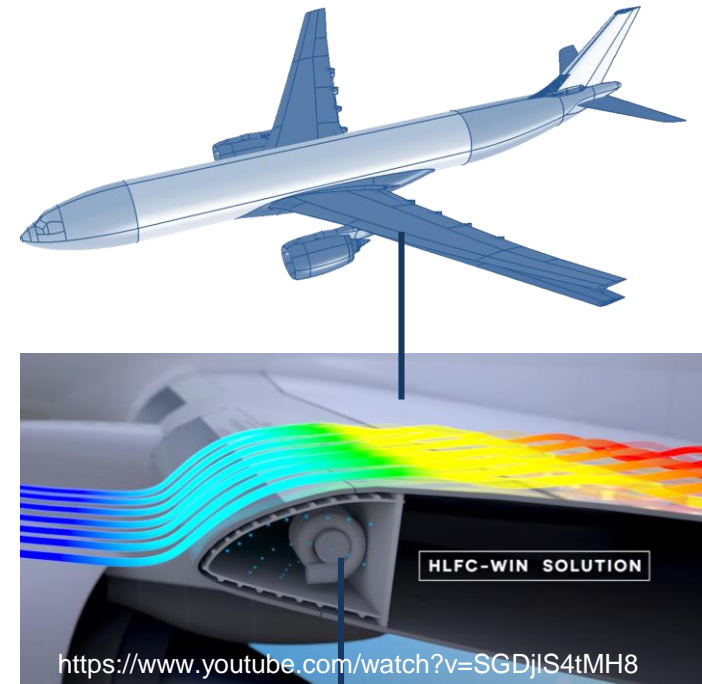
## HLFC (Hybrid Laminar Flow Control) on HTP (Horizontal Tail Plane)



# LPA WP 1.4.4 HLFC-WIN Introduction



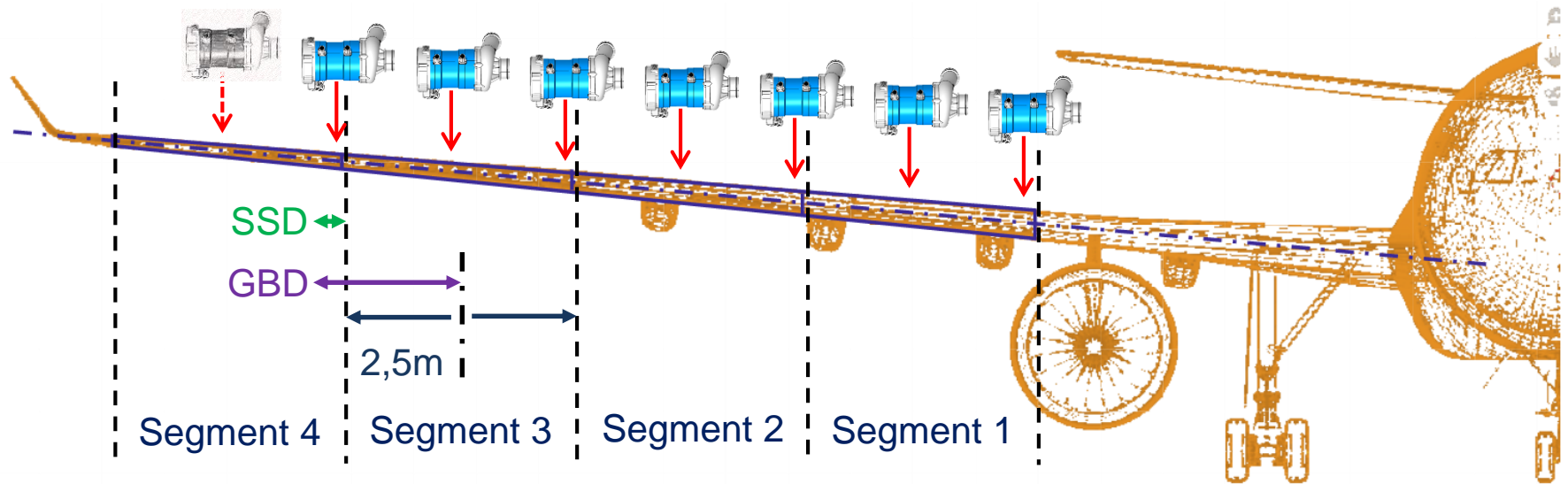
- **Target Aircraft Configuration:**  
**XRF1** with novel laminar wing
- **Laminarisation Approach:**  
**HLFC (Hybrid Laminar Flow Control)**
- **Innovation within HLFC-WIN:**
  - Modular wing leading leading edge
  - Exchangeable Suction Glove
  - Contact free inductive de-/anti-icing
  - Active suction (electrical compressors)
  - No-pipe approach with distributed compressors
  - Compressors are integrated in modified leading edge ribs → **“Suction Ribs”**



Picture: Fischer EMTC 120 Air

# LPA WP 1.4.4 HLFC-WIN Introduction

- The outer wing is divided into four technically similar, independent segments
- Compressors (two per segment) are distributed along the wing
- Eliminated pipe friction leads to significantly reduced power consumption



SSD: Small Scale Demonstrator (TRL3)

GBD: Ground Based Demonstrator (TRL4)

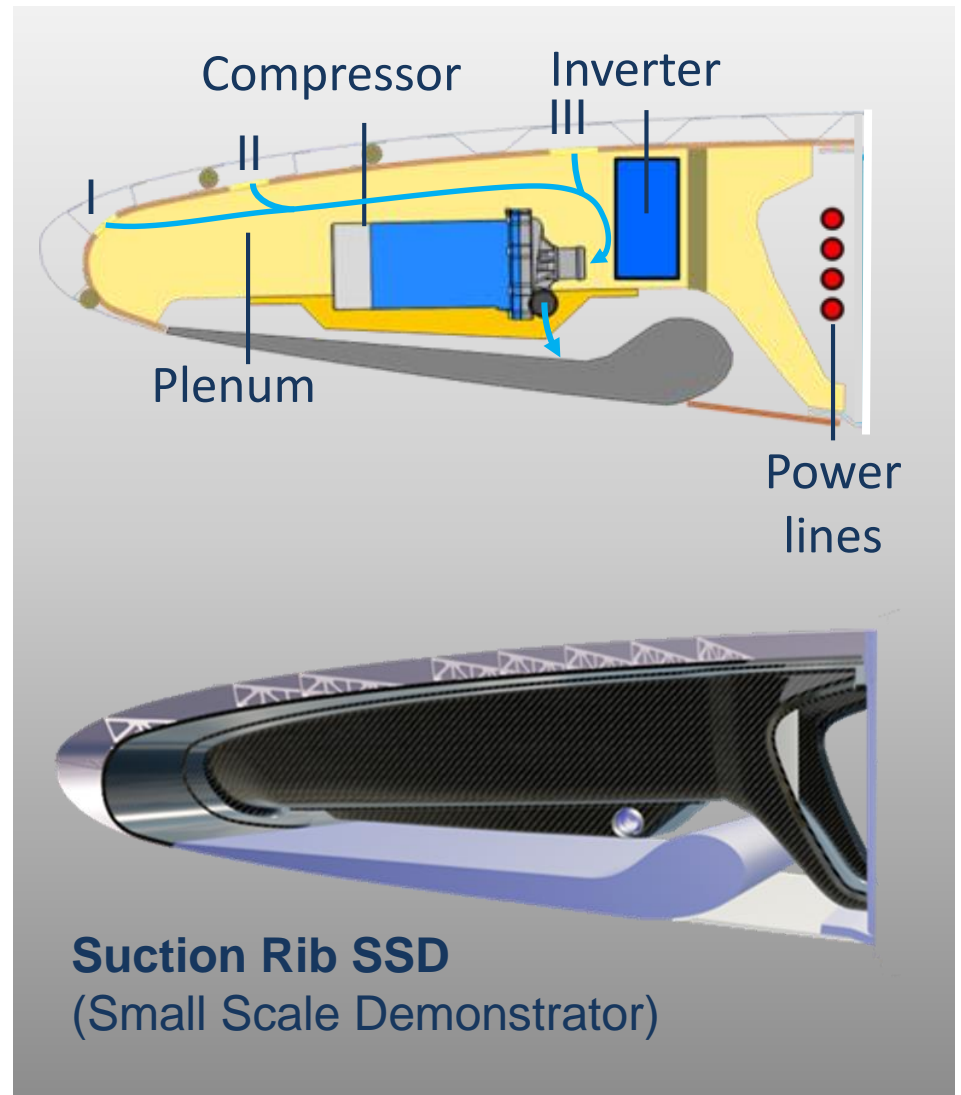


# HLFC-WIN Suction Rib SSD Design



# HLFC-WIN Suction Rib SSD Design

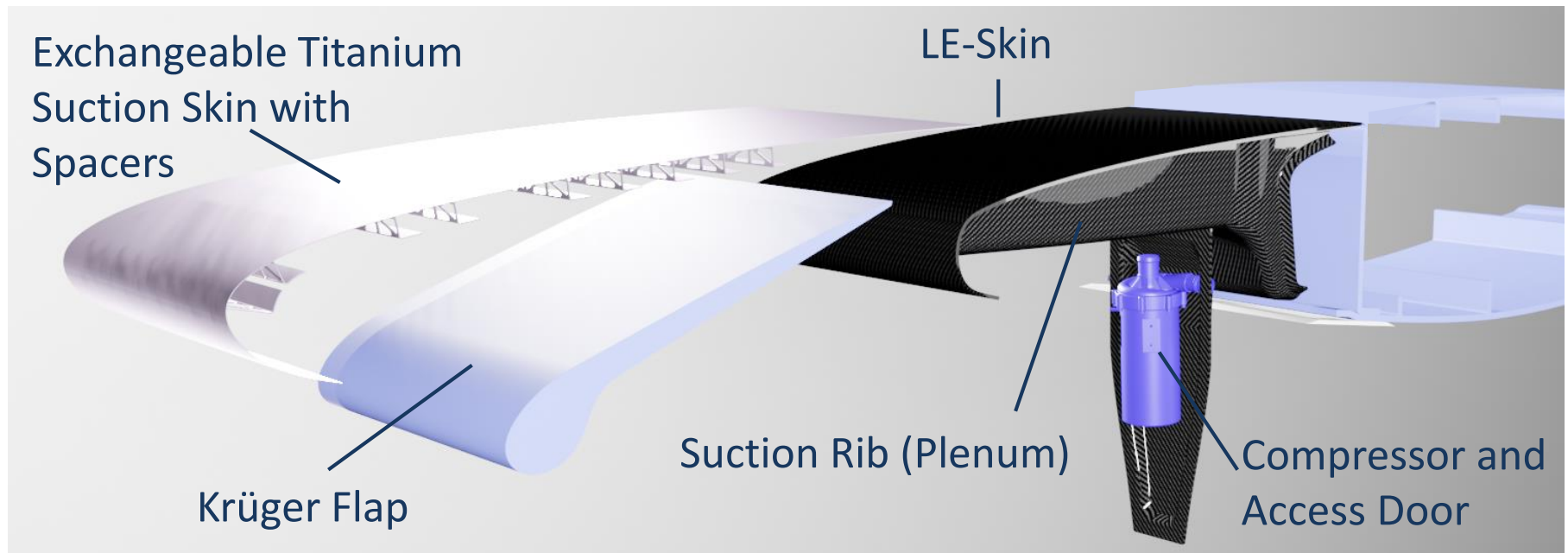
- **Basic Suction Rib Setup**
  - ➔ **Suction System**
    - Three (I,II,III) glove chambers with individual pressures
    - Low pressure plenum chamber in suction rib
    - Compressor with adjustable air flow
    - Simple compressor outlet into the Krüger chamber (option)
    - Airflow utilized to cool compressor and inverter



# HLFC-WIN Suction Rib SSD Design

## Basic Suction Rib Setup → Structural Elements

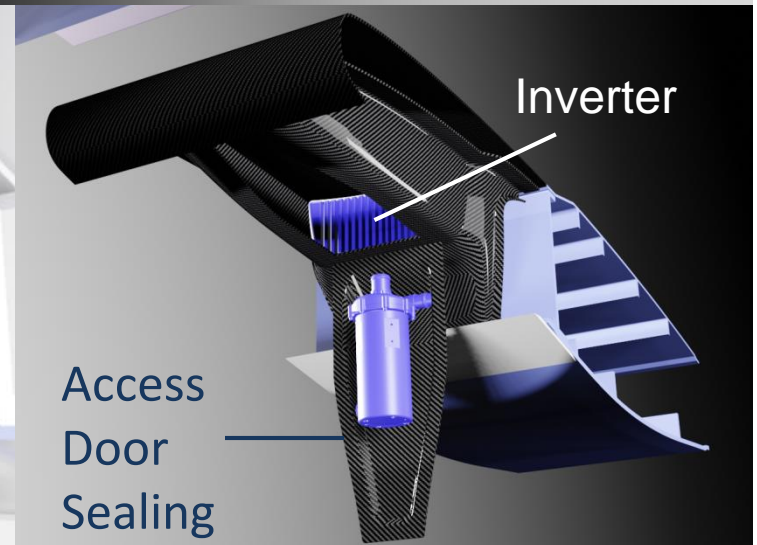
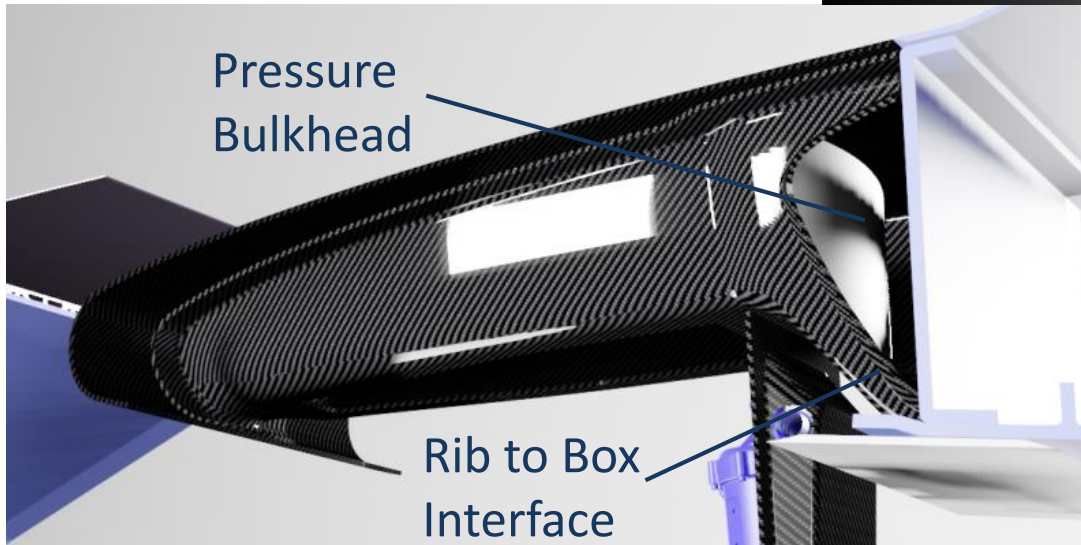
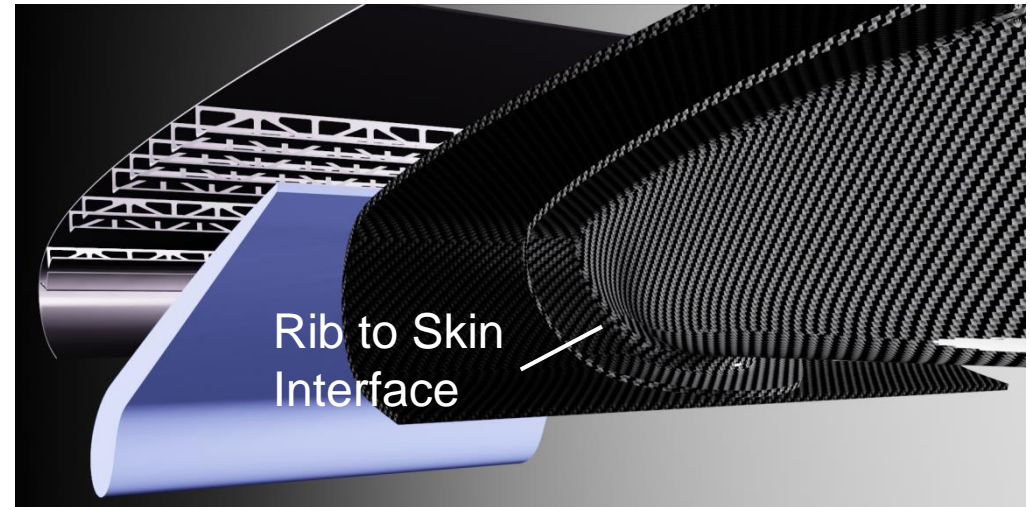
- Erosion resistant, exchangeable microdrilled Titanium glove with spacers
- Light weight CFRP leading edge skin and suction rib
- Easy to service plug-and-play compressor mounting



# HLFC-WIN Suction Rib SSD Design

## ■ Manufacturing Challenges

- Interface complexity
- Double curvature
- Back-cuts
- Required sealing face accuracy





# HLFC-WIN Suction Rib SSD Manufacturing

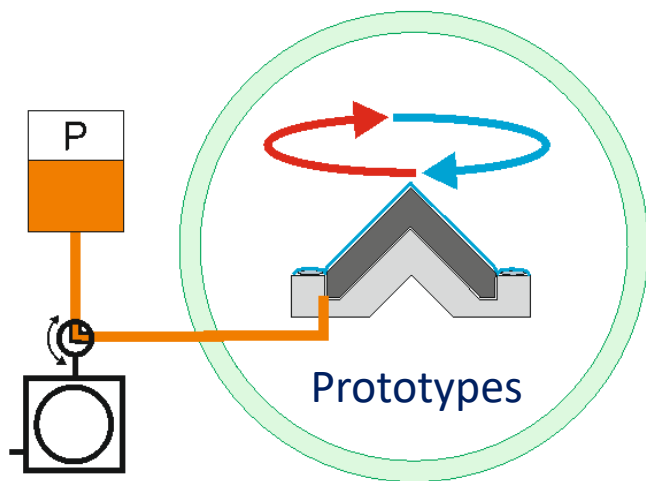


# HLFC-WIN Suction Rib SSD Manufacturing

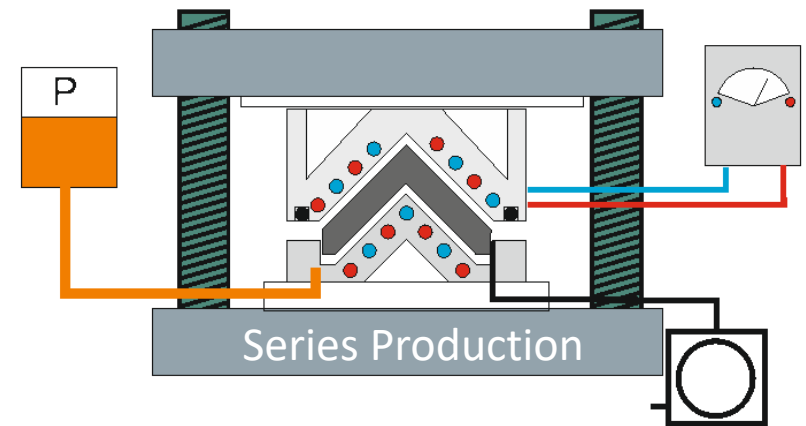
## ■ Manufacturing Approach

- Autoclave infusion  
for prototypes
- RTM (Resin Transfer Moulding)  
for later series production
- Pressure (P) assisted process

- Low Tooling Costs
- Flexibility
- Energy Efficiency
- Cycle Time
- Low Void Content
- Cycle Time



Autoclave Infusion / Open Mould

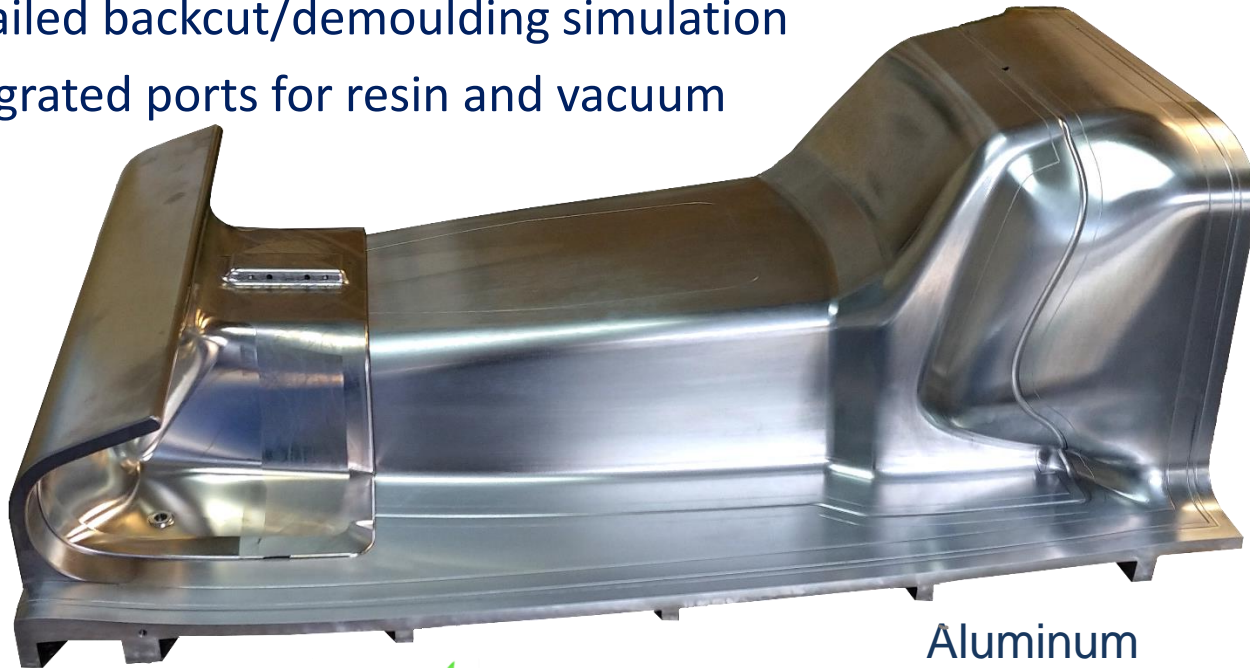
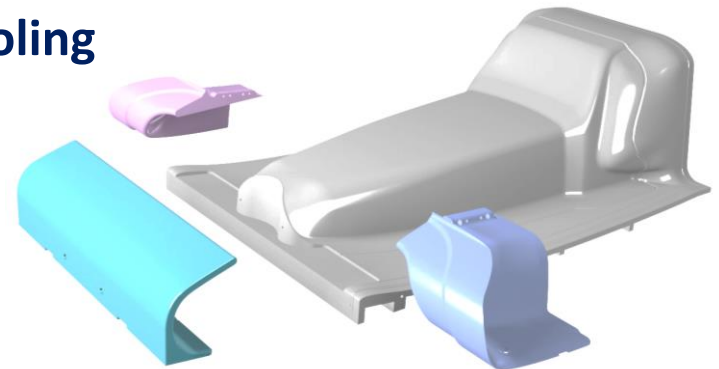


Press RTM / Closed Mould

# HLFC-WIN Suction Rib SSD Manufacturing

## ■ Hybrid (open/closed mould) Suction Rib Tooling

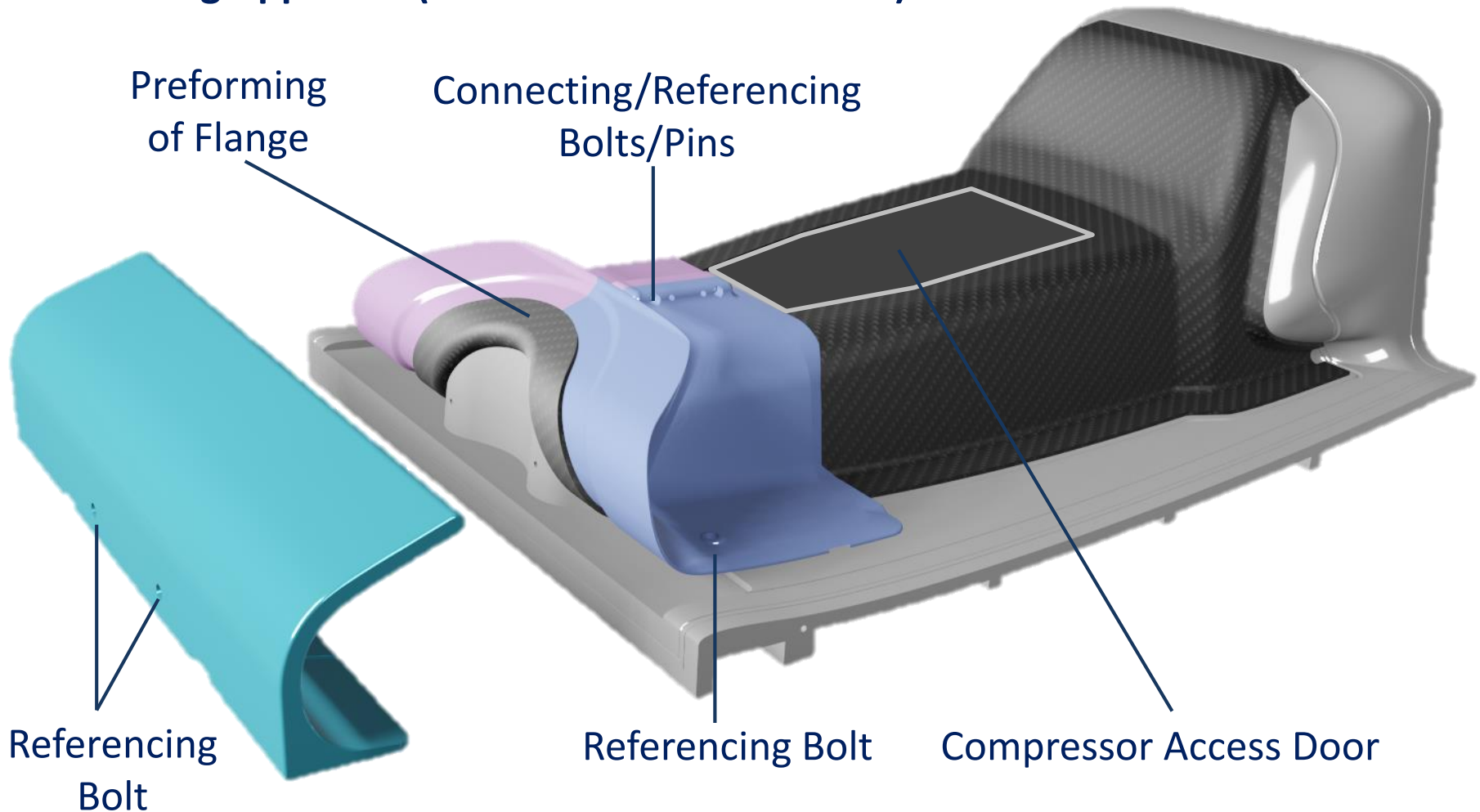
- Modular preforming and infusion mould
- Closed mould elements in front section
- Base tool machined from single block to ensure vacuum tightness
- Detailed backcut/demoulding simulation
- Integrated ports for resin and vacuum



Aluminum

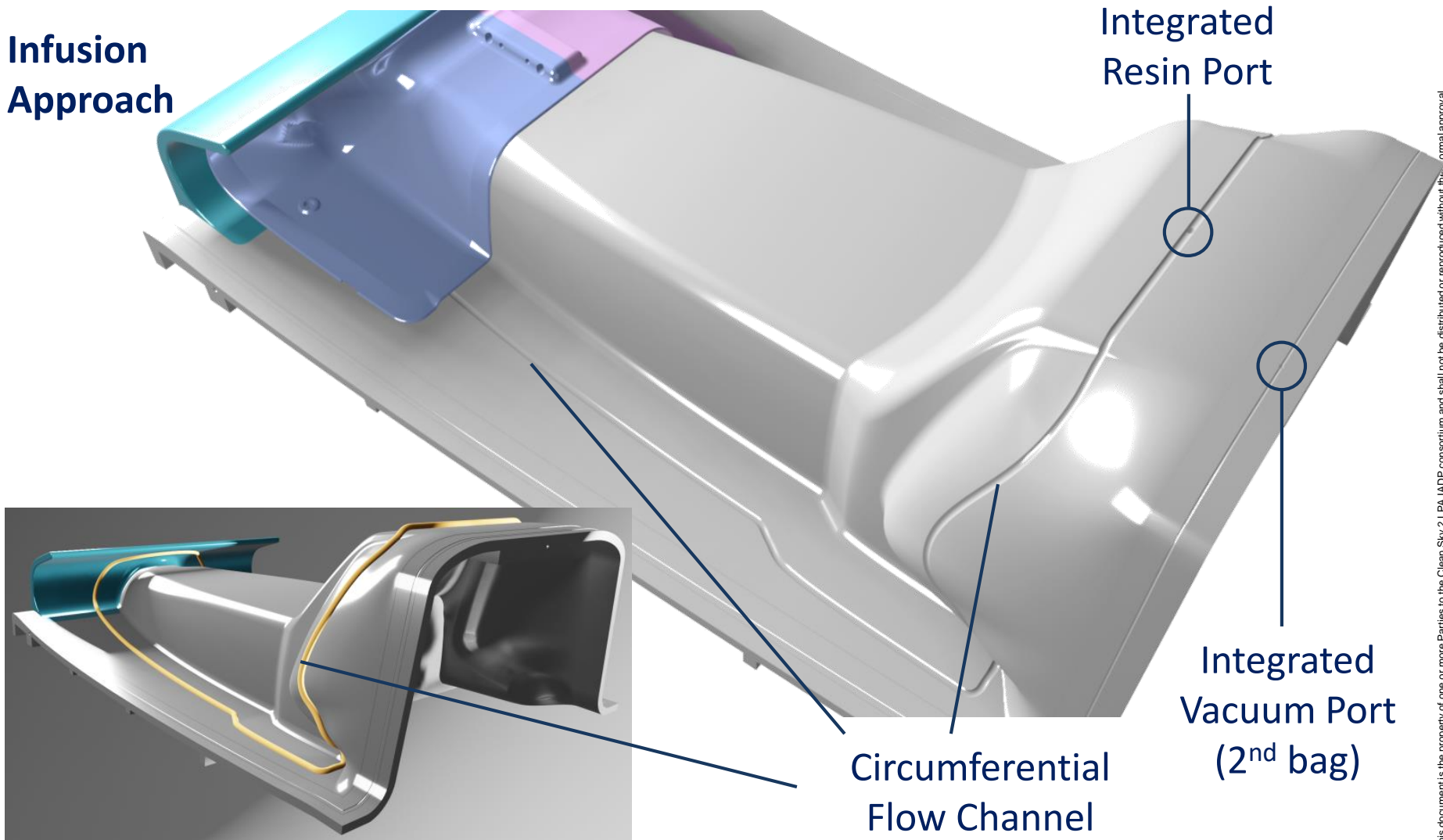
# HLFC-WIN Suction Rib SSD Manufacturing

## Preforming Approach (Hexcel G0926 with binder)



# HLFC-WIN Suction Rib SSD Manufacturing

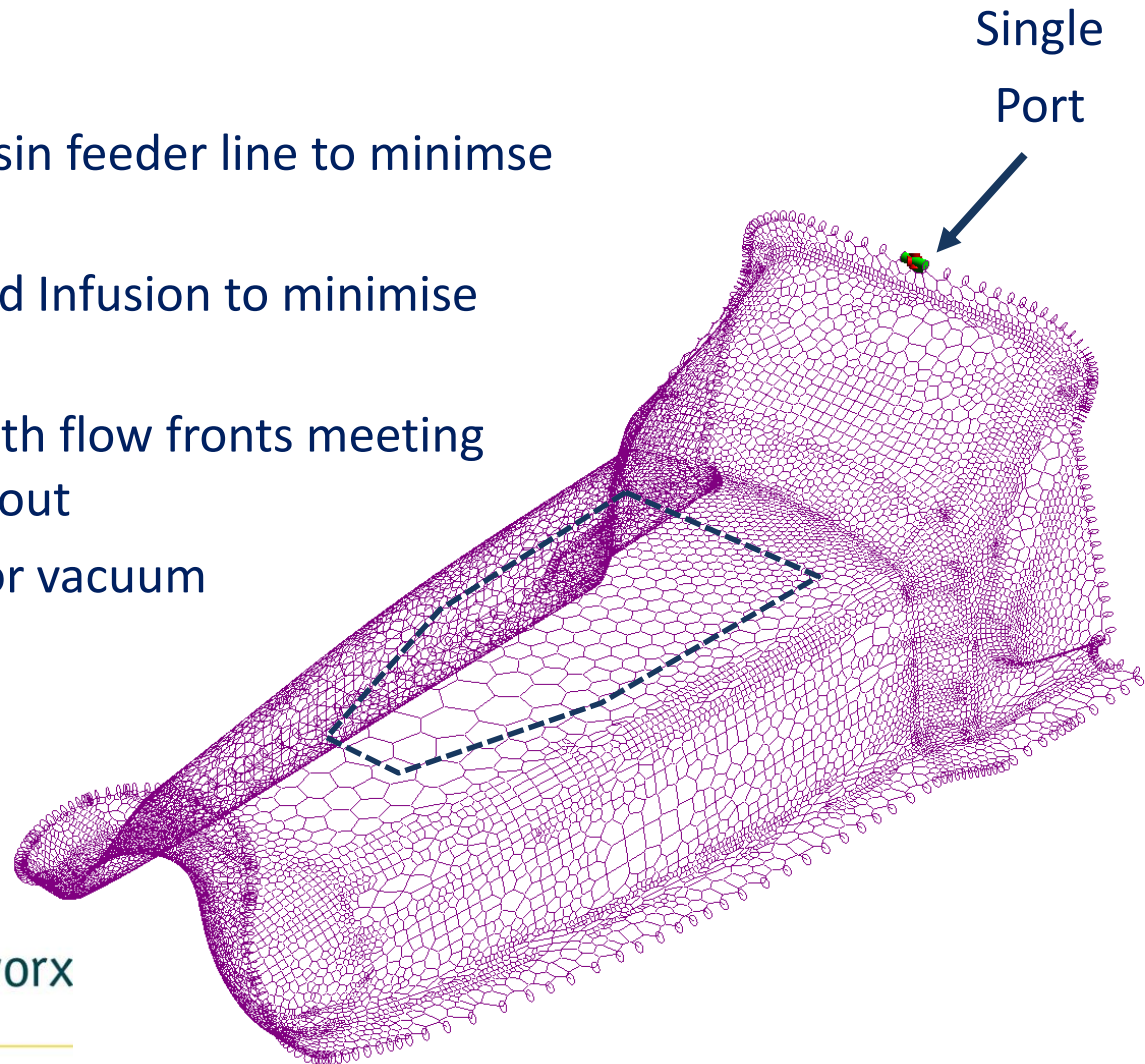
**Infusion Approach**



# HLFC-WIN Suction Rib Manufacturing

## ■ Infusion Strategy

- Circumferential resin feeder line to minimise flow length
- Pressure supported Infusion to minimise infusion time
- Robust infusion with flow fronts meeting at access hole cut out
- Single Port used for vacuum and infusion





# Digital Infusion Center



# Digital Infusion Center

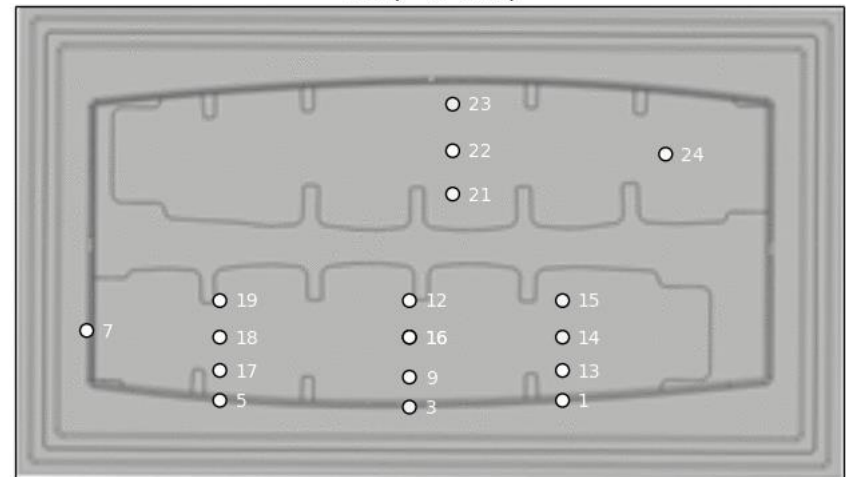
- Contributing Projects: LOCOMACHS (EU, FP7)  
**Autoclave Infusion Wing Rib**
  - Sensor controlled Infusion
  - Control of gelation and glass transition
  - Adjustment of fibre content (thickness)
  - Minimisation of PID scatter  
(PID: Process Induced Deformation)



Sensors: - US-Sensors (Transmission)  
- US-Sensors (Impuls-Echo)

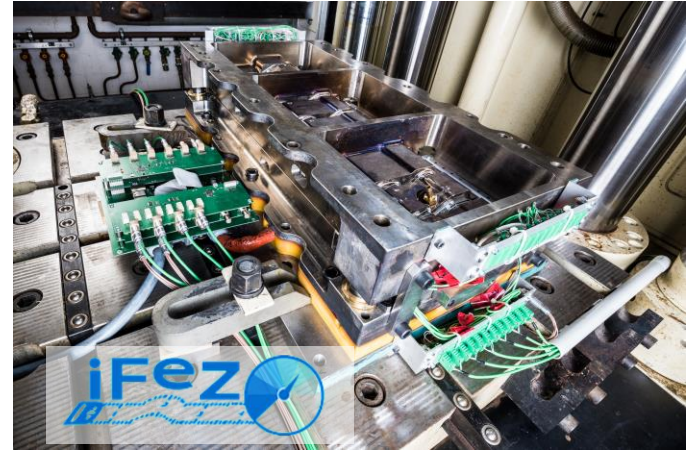


1 s (= 0 min)



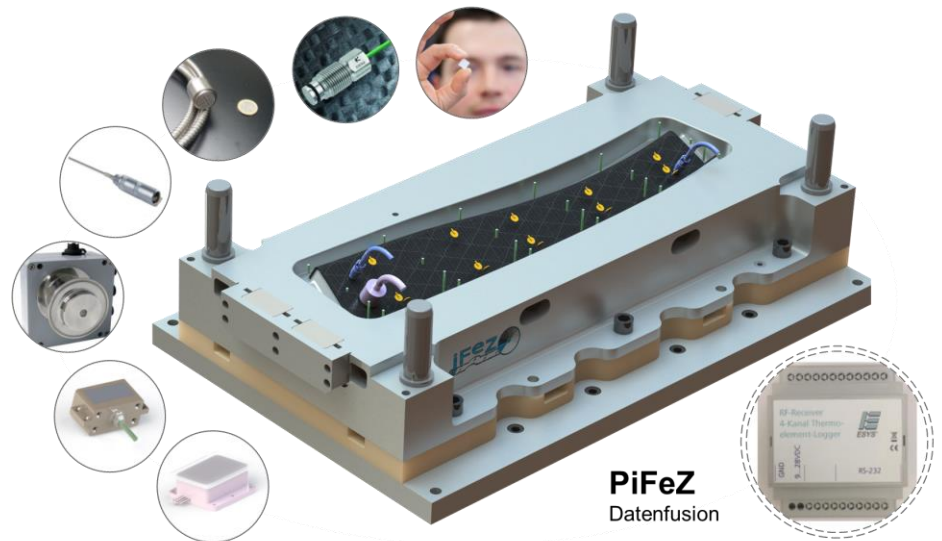
# Digital Infusion Center

- Contributing Projects: iFeZ (German LUFO)  
**RTM Fuselage Frame Segment**
  - Fully functional multi sensor network
  - Wireless data transmission
  - Sensor sensitivity and robustness
  - Constantly updated flow simulation



- Sensors:
- US-Sensors
  - Pressure Sensors
  - Dielectric Sensors
  - Thermocouples
  - Eddy Current Sensors

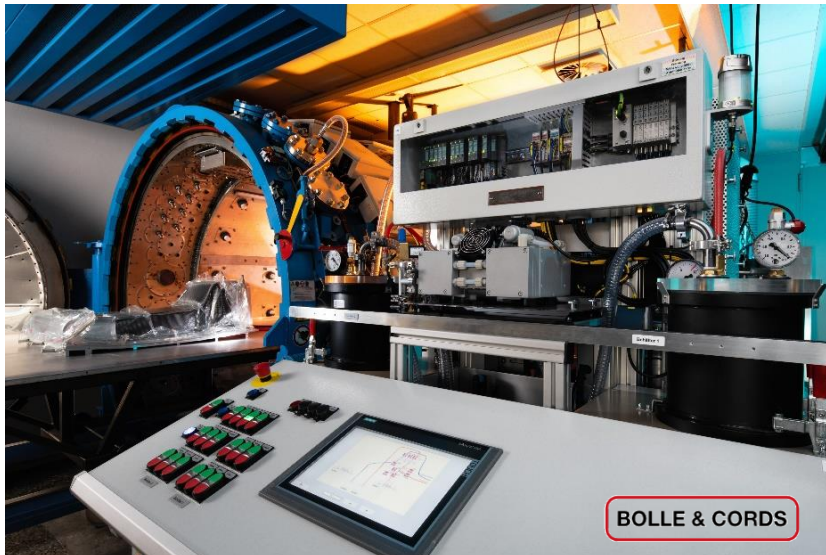
Data Fusion: Raspberry Pi based



# Digital Infusion Center

## ■ The Digital Infusion Center

- Hot-swappable double container (continuous infusion option)
- Powerful, energy efficient and highly responsive microwave resin heating
- Sensor controlled automatic mode and fully manual, experimental mode
- Full network integration / interface for tooling sensors
- Part of a fully controllable environment (press, oven and autoclave)





# Suction Rib Results



# Suction Rib Results

- **Trial 1**, Pre-Trial (Sicumed RT resin )
  - Out of autoclave approach
  - Reduced laminate thickness
  - Room temperature curing resin
  - Test of digital infusion center
  - **Various problems**
- **Trial 2**, Verification-Test (Hexcel RTM 6)
  - 6 bar autoclave infusion process
  - Programmed automatic infusion
  - 30 min infusion (as simulated)
  - Ca. 290 min total cycle time
  - **TRL 3 verification successful**



Trial 1



Trial 2

# Suction Rib Results

## ■ Trial 1, Out Of Autoclave (ambient pressure) Infusion Log

- Start with infusion center in automatic mode
- Insufficient resin flow (deviation from simulation)
- **Updated simulation shows that filling is impossible**
- Infusion center switched to manual mode
- Applying overcritical (>1 bar) infusion pressure
- Flow increases but resin slowly inflates bagging
- Exothermal resin temperature increase in container
- Infusion terminated after enough resin has been forced into the vacuum bag
- Vertical positioning of tooling to utilise gravity
- Remaining dry spot only in access door cut out

**Creative measures saved demonstrator after more than 5 hours of infusion.  
Error tracing: Partially blocked infusion port caused the resin flow problem.**





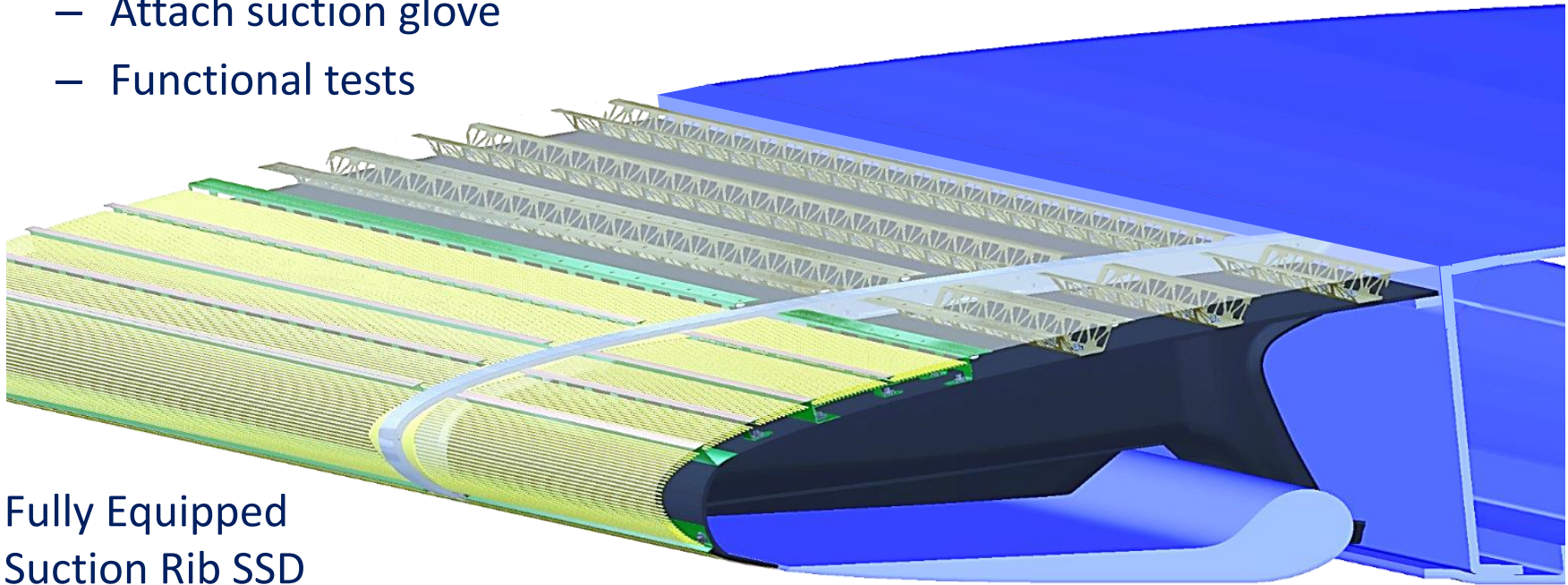
# Outlook



# Outlook

## ▪ Suction Rib SSD

- Build and assemble remaining CFRP components
- Install inverter and compressor
- Install inductive de-/anti-icing dummy
- Attach suction glove
- Functional tests



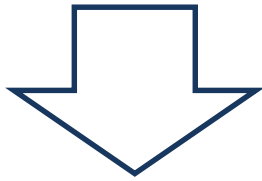
Fully Equipped  
Suction Rib SSD

# Outlook

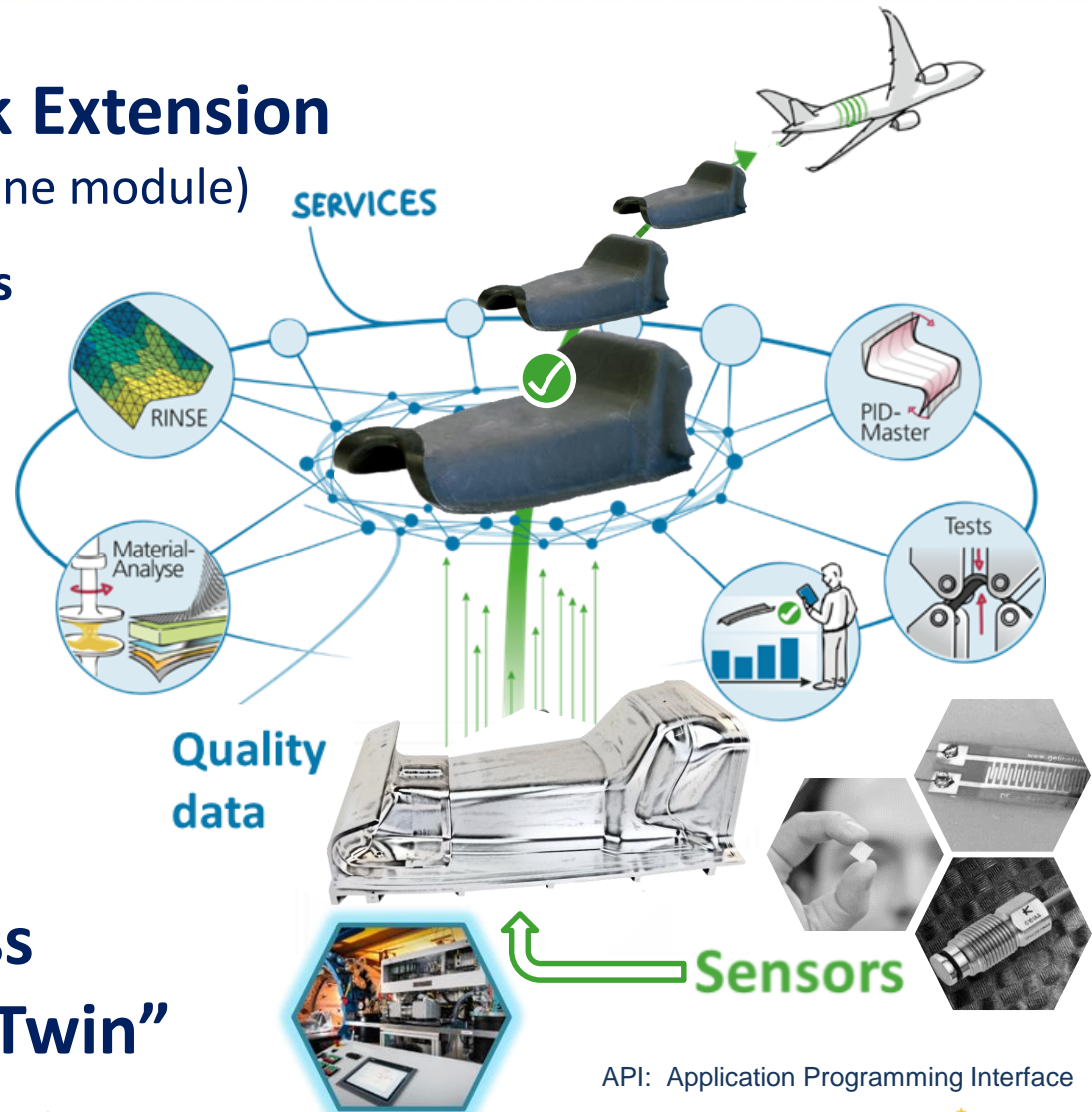
## ■ API Based Network Extension

(Digital Infusion Centre is one module)

- Equipment Capabilities
- Process Sensors
- Software Services



**Continuously  
Optimised  
Production Process  
logged in “Digital Twin”**



API: Application Programming Interface



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- Disclaimer

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