Tasking Framework: An open-source software development library for on-board software systems
Embedded System Week 2020
Zain Hammadeh
Agenda

- Introduction to the tutorial and agenda (pre-recorded)
- Tasking Framework in a nutshell: motivation and basic features (pre-recorded)
- Tasking Framework from A to Z (pre-recorded)
- Tasking Framework in practice: clone from github + build + write your first example (pre-recorded)
- Outlook on development process and invitation to contribute (pre-recorded)
- Discussion and closing (on-line session)
Speakers

- Dr. Zain Hammadeh
  - Institute for Software Technology, German Aerospace Center (DLR)
  - Zain.hajhhammadheh@dlr.de

- Dr. Olaf Maibaum
  - Institute for Software Technology, German Aerospace Center (DLR)
  - Olaf.maibaum@dlr.de
German Aerospace Center (DLR)

Source: dlr.de/en
Onboard Software Systems (OSS)
Onboard Software Systems (OSS)
Research and development for on-board software

Mission:
Provide dependable real-time software for space systems

Research focus:
• Model-driven software development
• (Real-time) execution platforms
• Reconfigurable distributed on-board systems
• Verification/Validation and Software Quality Assurance

On-board Applications
Middleware
(Real-time) Operating Systems
Embedded Programming / Driver
Our use cases

• New On-board Computer Architectures
  • OBC-NG / ScOSA / ScOSA Flight Experiment
• Guidance, Navigation, and Control Software
  • BIRD
  • OOV-TET and BIROS Eu:CROPIS
  • SHEFEX II
  • CALLISTO and ReFEx
  • ATON
  • MMX
  • HAP
• Command & Data Handling
  • Eu:CROPIS
  • MAIUS 1, 2, 3 / BECCAL
  • Compasso
• Payload Software
  • MAIUS 1, 2, 3 / BECCAL
• Software Product Assurance
  • PLATO, GALA & JANUS (JUICE)
  • GALILEO
Our capabilities w.r.t. on-board software engineering

• Software engineering and development for space systems

• Software quality / product assurance

• Base software development

• Software integration

• Model-driven software development

• Design of dependable software systems
Are you interested to know more?

Projects
Publications
Collaboration

Website: [https://www.dlr.de/sc/srv](https://www.dlr.de/sc/srv)

ResearchGate: OSS
Live Q&A session

Sunday 20.09.2020
at 11:00 – 12:00 am EDT
at 05:00-06:00 pm Berlin

See you later!

Tutorial 4: Tasking Framework: An open-source software development library for on-board software systems

11:00am - 12:00pm, Sep 20

* This tutorial is a live Q&A session with pre-recorded videos made available before the event.

Tasking Framework is a C++ software development library and an event-driven multithreading execution platform. It is developed by the Institute for Software Technology, German Aerospace Center (DLR). Tasking Framework is dedicated to improve the reusability in developing embedded software systems and to reconcile the embedded software with model-driven software development. It can be used to develop, but not dedicated for, critical as well as non-critical embedded software on single-core as well as parallel architectures. Tasking Framework gives software developers the ability to implement their applications as task graphs with arbitrary activation patterns (periodic, aperiodic and sporadic) using a set of abstract classes with virtual methods. It is compatible with the POSIX-based operating systems, mainly Linux and RTEMS. The Tasking Framework was successfully used in, for instance, the attitude orbit control systems of several satellites.

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