

Automation of Production Processes for CFRPs and Hybrids in Aerospace

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Knowledge for Tomorrow



Outline

Intro: Center for Lightweight Production Technology, Augsburg

1. Fiber Metal Laminates for a fuselage side shell
2. Examples for robotic lay-up systems
 - a. Gripper systems
 - b. Lightning Strike Protection - Tapelaying for 90 cm multilayer tapes
 - c. Autonomous cut-piece detection and path planning
3. Manufacturing and assembly of thermoplastic components

Summary



German Aerospace Center (DLR)

Locations and employees

About 8000 employees at
32 institutes and facilities at
■ 16 sites.

Offices in Brussels,
Paris and Washington.



Institute of Structures and Design Augsburg

Center for Lightweight Production Technology

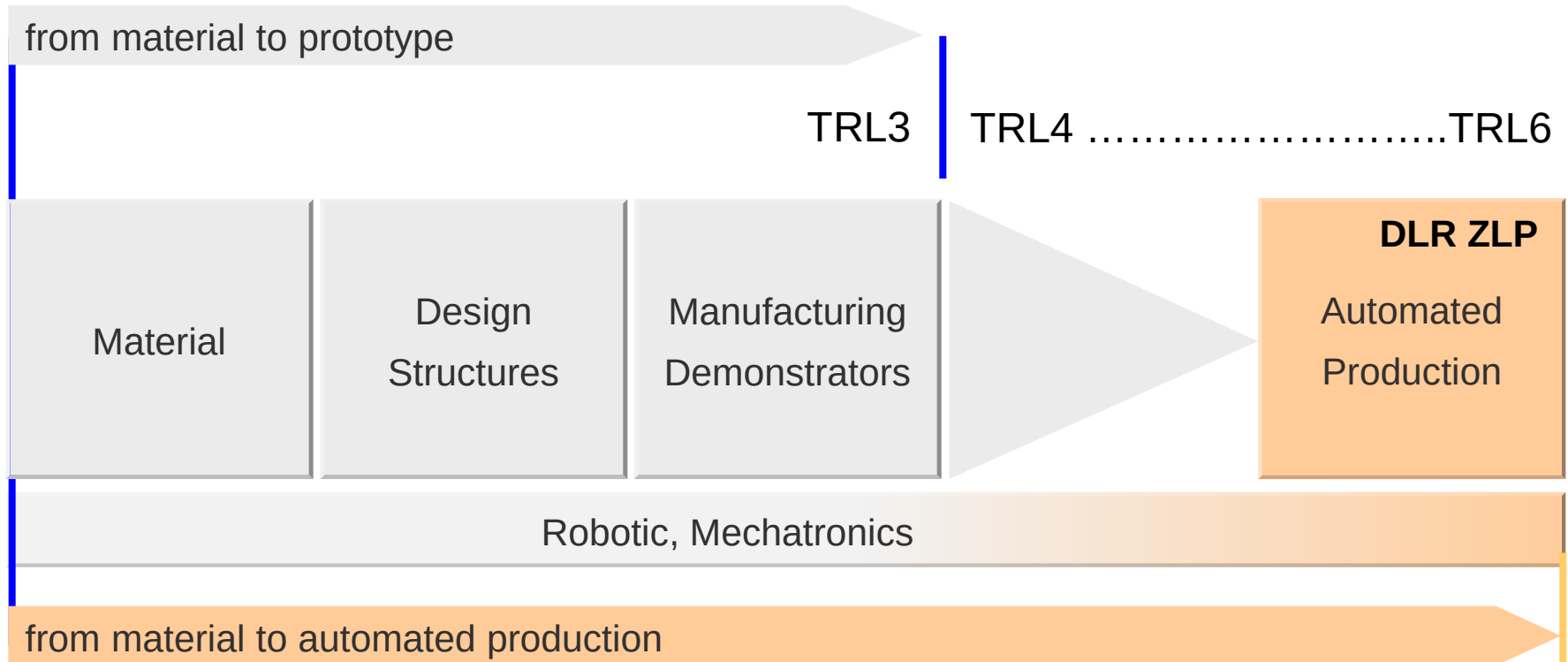
Employees: 51

Turn over: 7 M€



Center for Lightweight Production Technology

Technology Readiness for Industrialisation



For integrated production development, industrialisation topics become more important



Flexible Automation Systems at ZLP Augsburg (1/2)

- High accuracy manipulation and calibration
- Simulation and offline-programming
- Reconfigurable and multi-functional systems
- Autonomous process guidance and manufacturing execution systems
- Various independent work cells, linkable to flexible cutter and logistics system



Flexible Automation Systems at ZLP Augsburg (2/2)



- Wickert 4400 S Composite Press
 - 1800 x 1200 mm²
 - 450°C
 - 100 - 4400 kN
- Krelus Infrared Heating System
 - 2000 x 1500 mm²
 - 20 – 800°C
- Kuka Robot KR210 R3100 Ultra F
 - Range 3100 mm
 - Payload 210 kg
 - Linear axis 5,4 m



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Summary



1) Fiber Metal Laminates for a fuselage side shell

Status quo:

- Manual manufacturing process of a FML layup
- Post-manufacturing QA

Targets:

- Automation of aluminium layup
- Integration of glas prepreg and adhesive layup
- Integrated QA and automated assessment

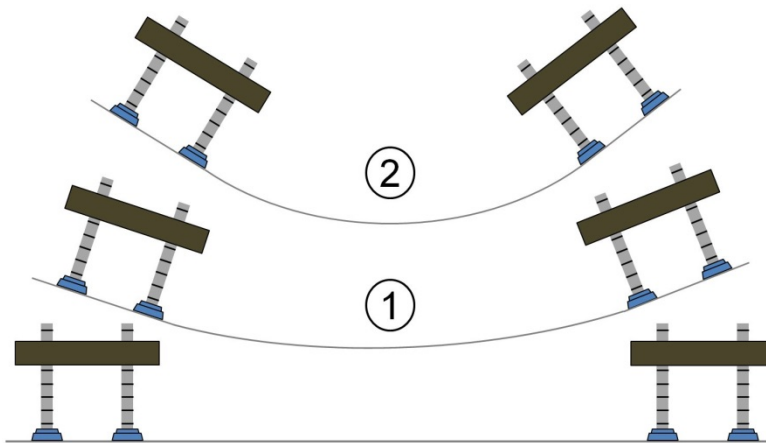


Quelle: PAG

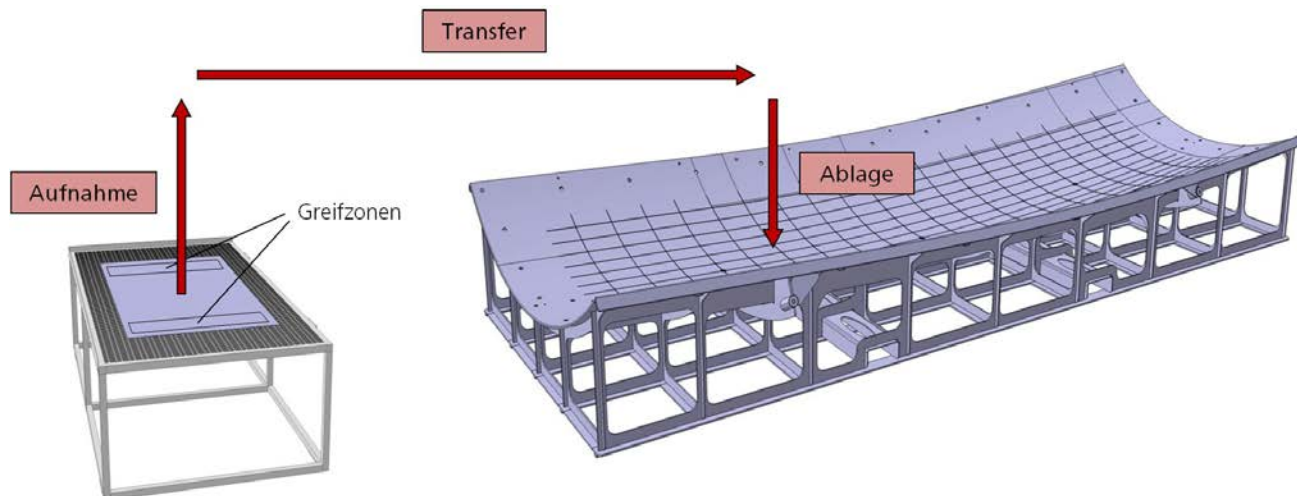


1) Fiber Metal Laminates for a fuselage side shell

Aluminium layup



Schematic of gripper positions and movements for cooperating robots

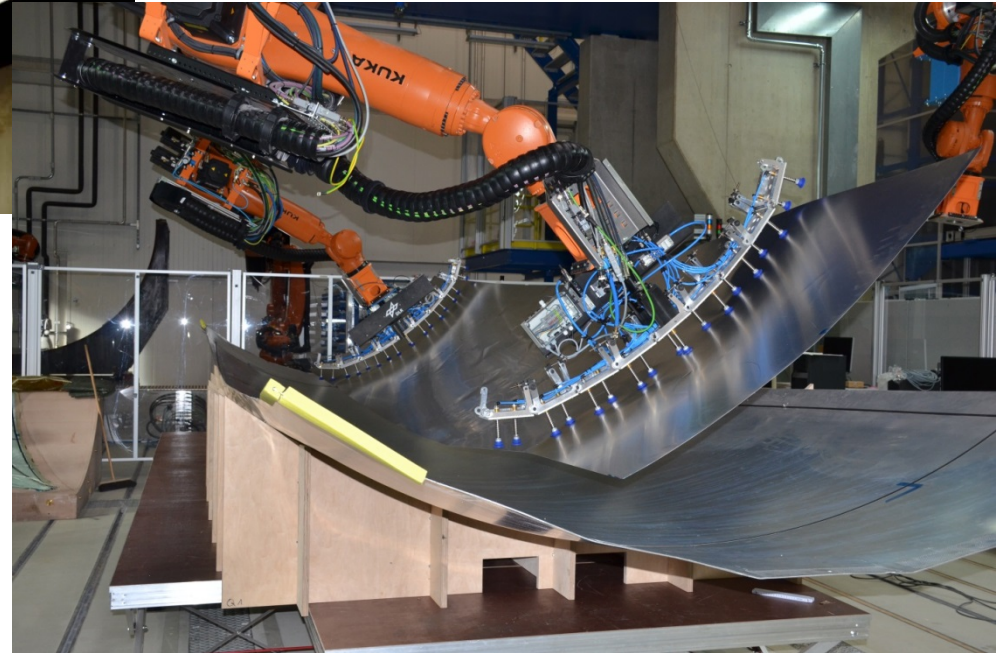
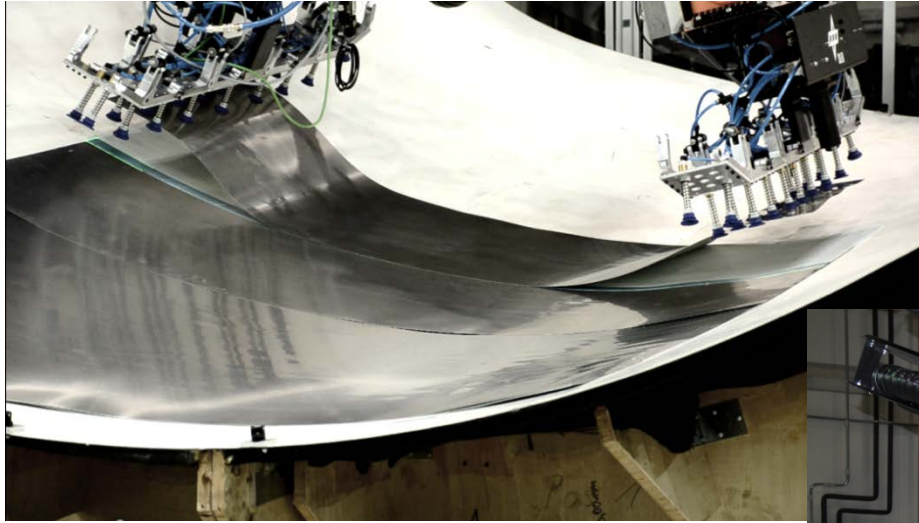


Transfer strategy



1) Fiber Metal Laminates for a fuselage side shell

Aluminium layup



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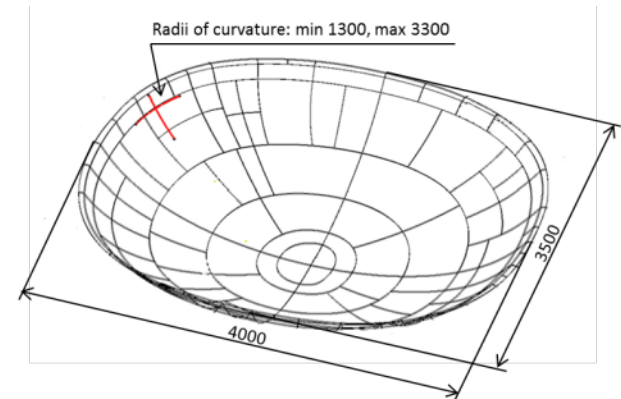
Summary



2a) Examples for robotic lay-up systems

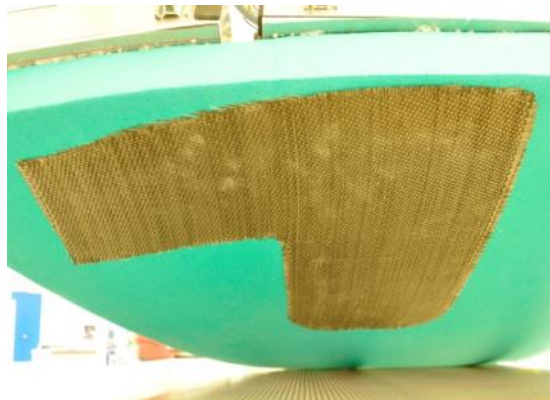
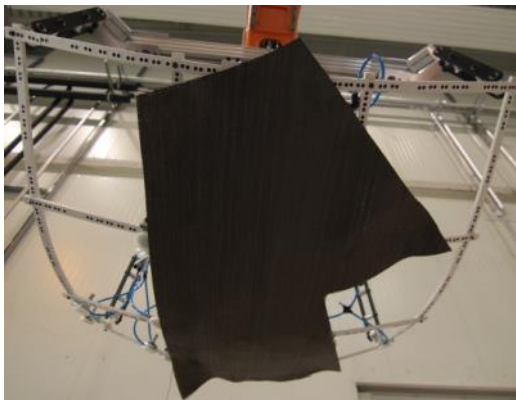
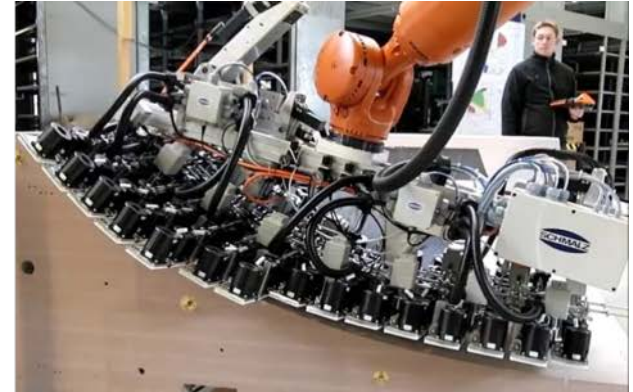
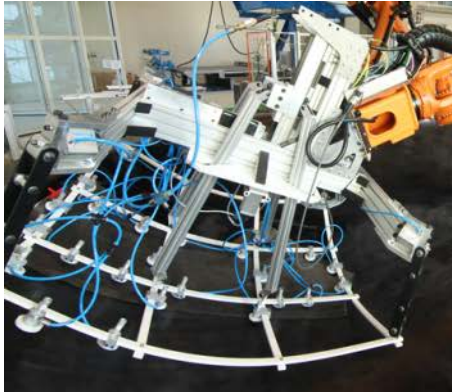
Gripper systems and draping strategies

- Target component: pressure bulkhead
 - Double curvature with radii 1.3 – 3.3 m
 - Overall dimensions 3.5 x 4.0 m
- Thermoset part
 - Female Tooling
 - Preform made of dry textiles & stiffeners
 - 25 cut-pieces vary in size & geometry



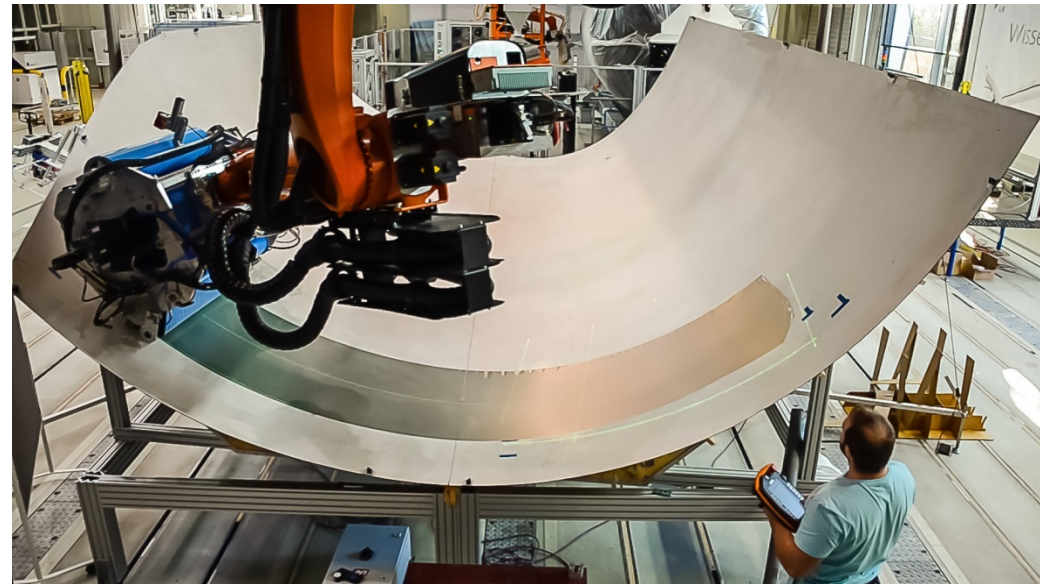
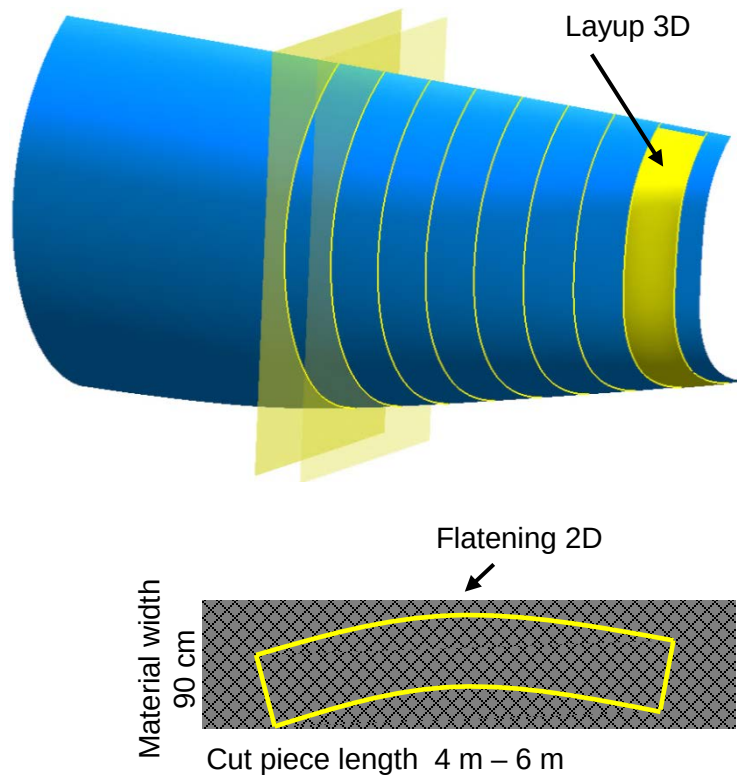
2a) Examples for robotic lay-up systems

Gripper systems and draping strategies



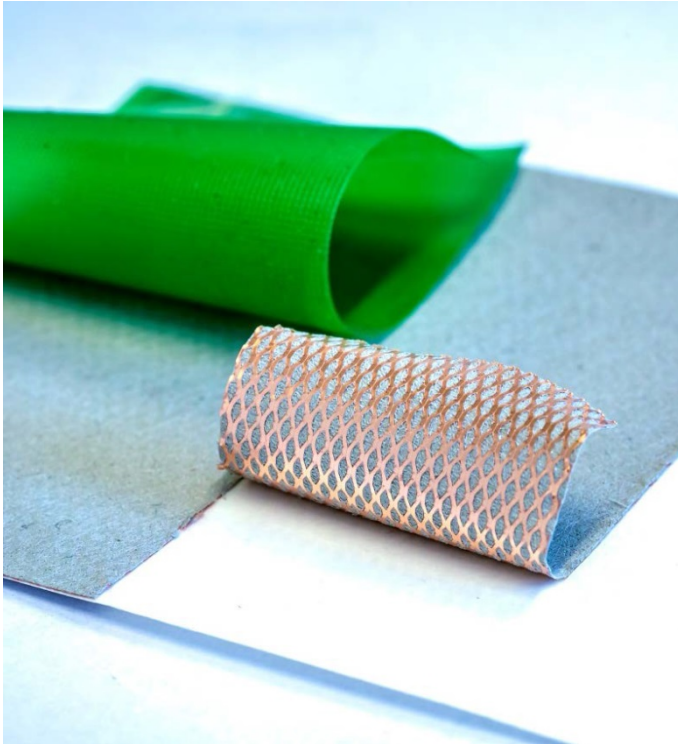
2b) Examples for robotic lay-up systems

Tapelayer for 90 cm lightning strike protection



2b) Examples for robotic lay-up systems

Tapelayer for 90 cm lightning strike protection

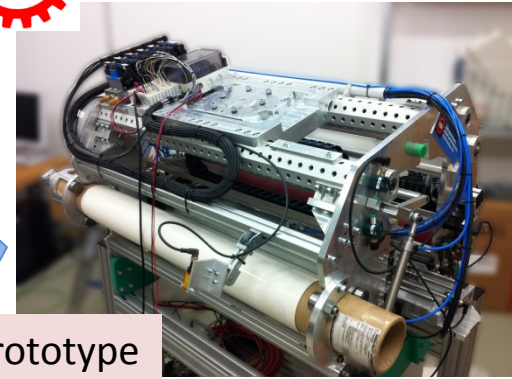
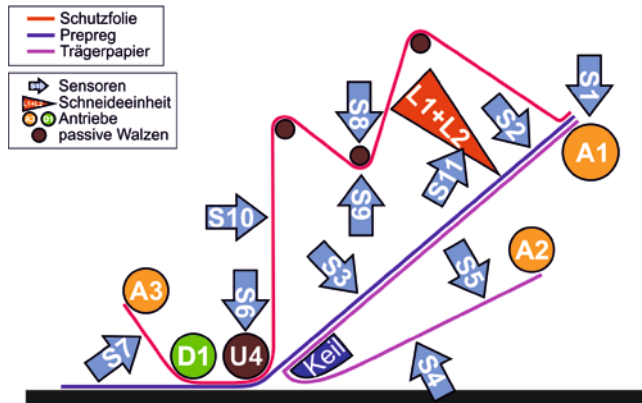


- 3 layer material (carrier, prepreg, foil cover)
- Prepreg made of copper mesh and thermoset matrix
- High draping forces required on doubly curved surfaces
- Compression results in waviness or even folds



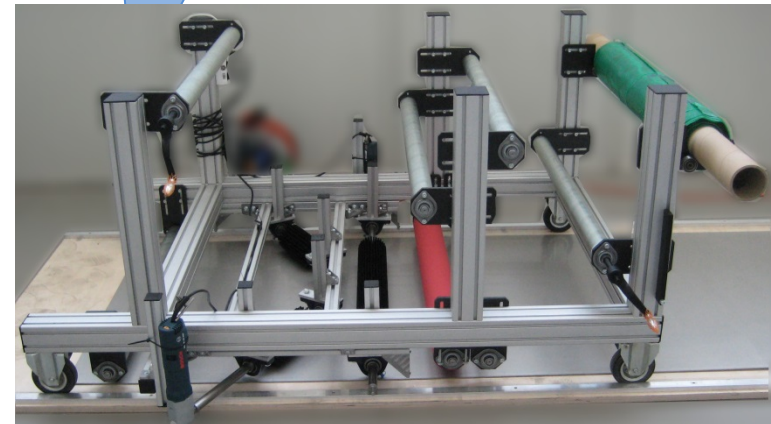
2b) Examples for robotic lay-up systems

Tapelayer development



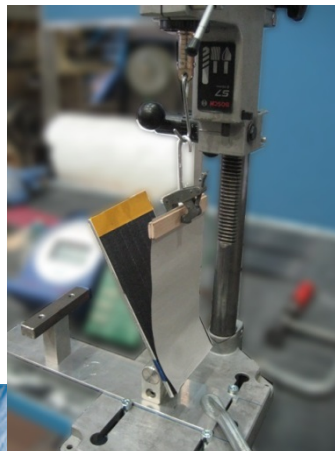
Prototype

Test vehicle



Material properties

Process analysis



AEROTECH

2b) Examples for robotic lay-up systems

Tapelayer development

Implementation in robotic cell and pre-testing



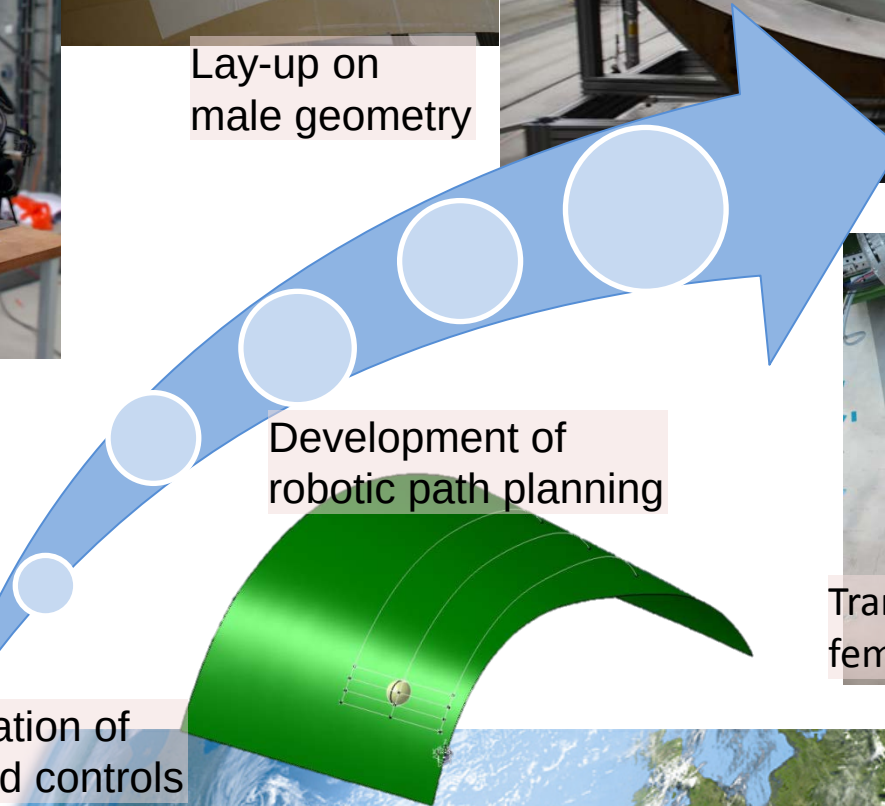
Lay-up on male geometry



Validation on full-scale female demonstrator



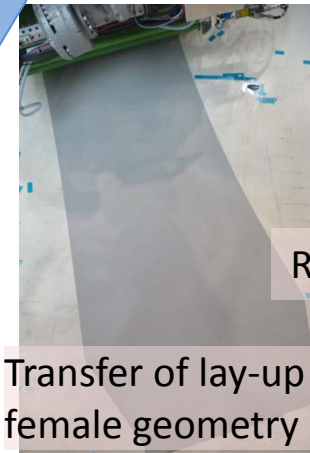
Development of robotic path planning



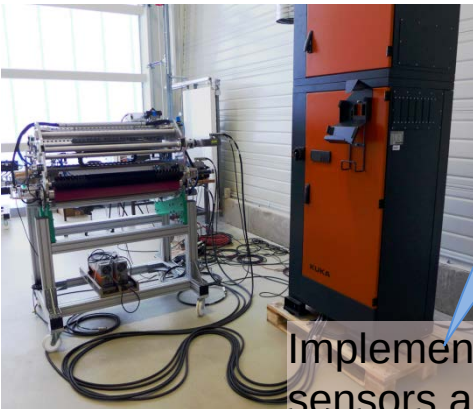
Reconfiguration



Transfer of lay-up to female geometry



Implementation of sensors and controls



2c) Examples for robotic lay-up systems

Autonomous Gripper

Challenge:

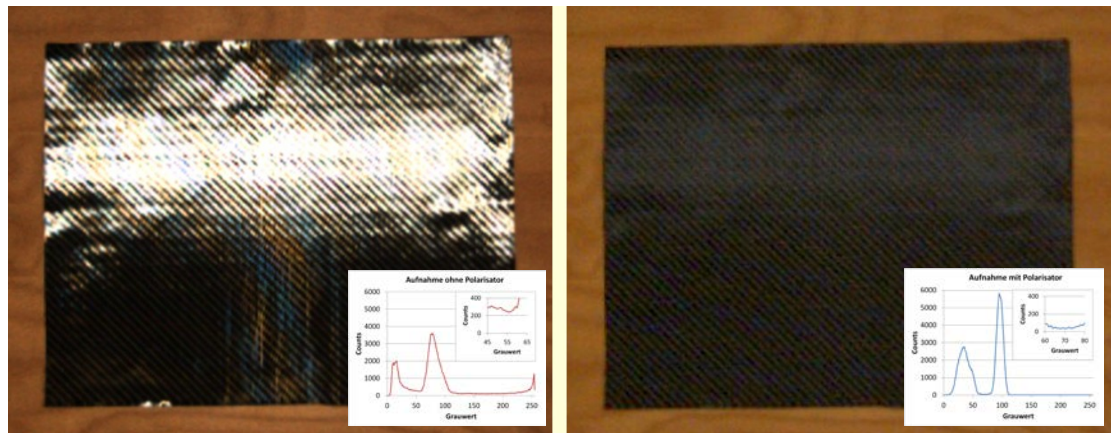
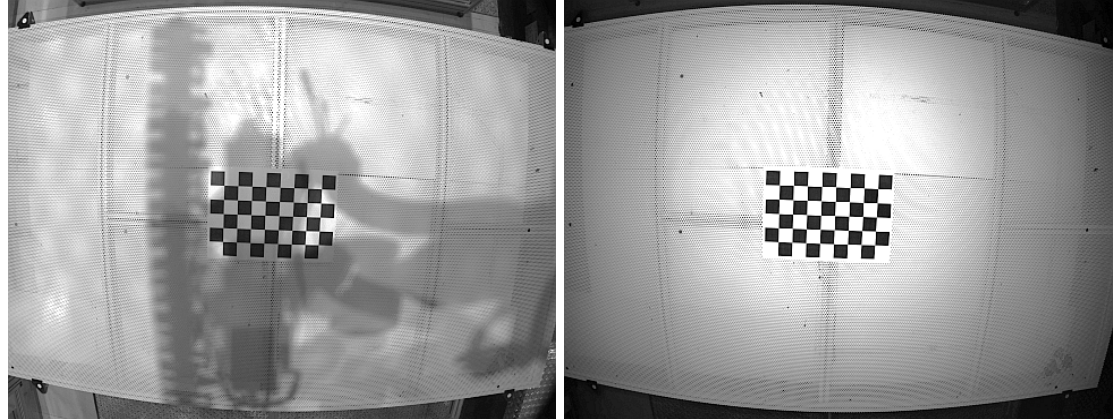
- Process chains not fully automated
- Provide textile cut-pieces with high accuracy
- Robust pick-and-place process

Goal:

- Flexibility and robustness in an intelligent system

Requirements:

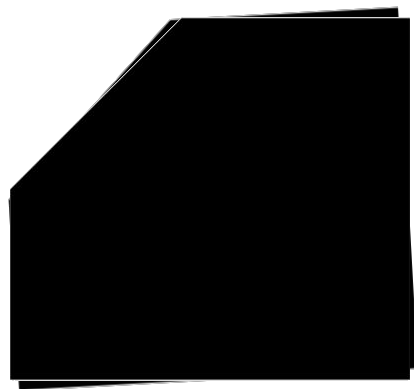
- No obstacles
- Wide field of view
- Independent from ambient light
- Independent from reflections on cut-piece surface
- Closed casing to protect from carbon fibers



2c) Examples for robotic lay-up systems

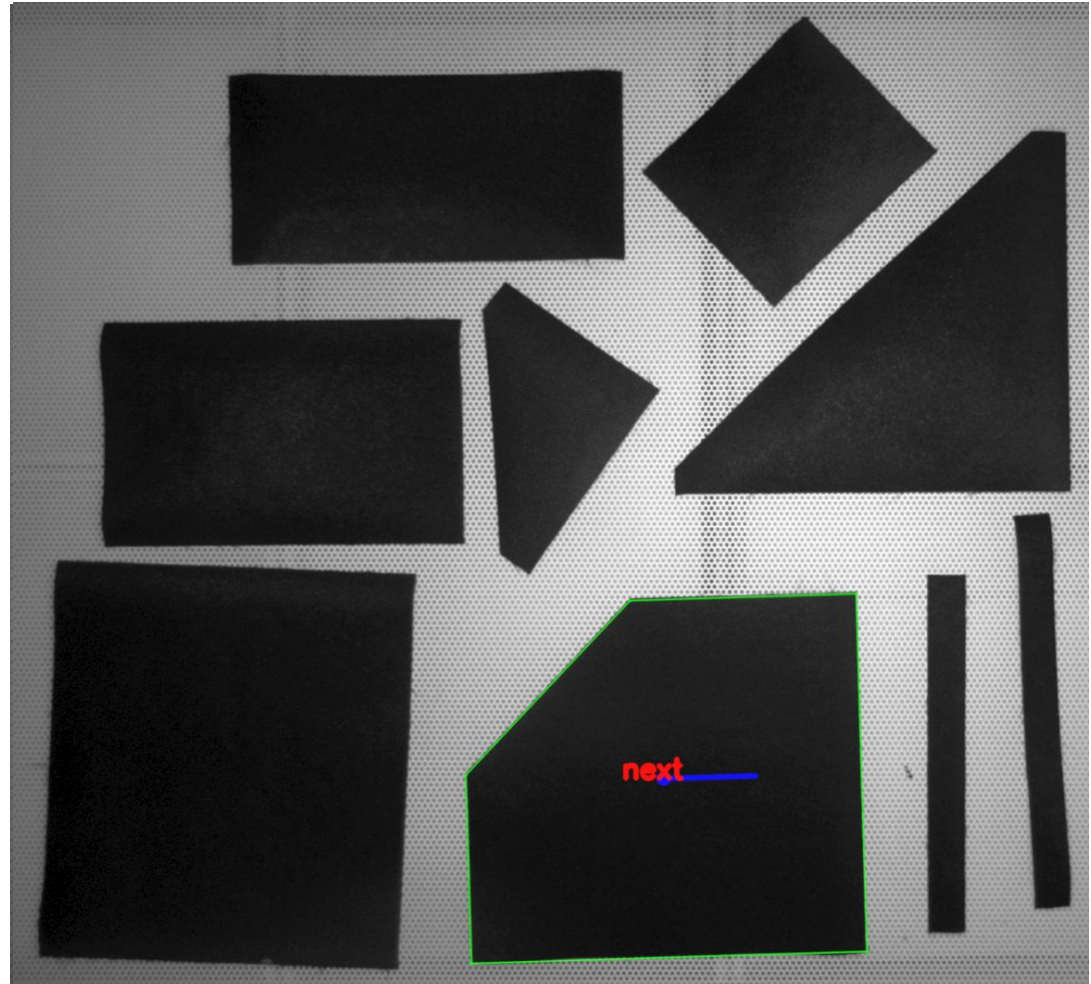
Template-Matching for rotating Objects

- Produce rotating bitmaps from CAD-data (plybook)
- Comparison to camera view

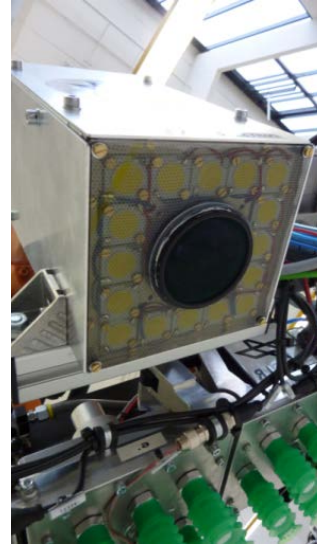
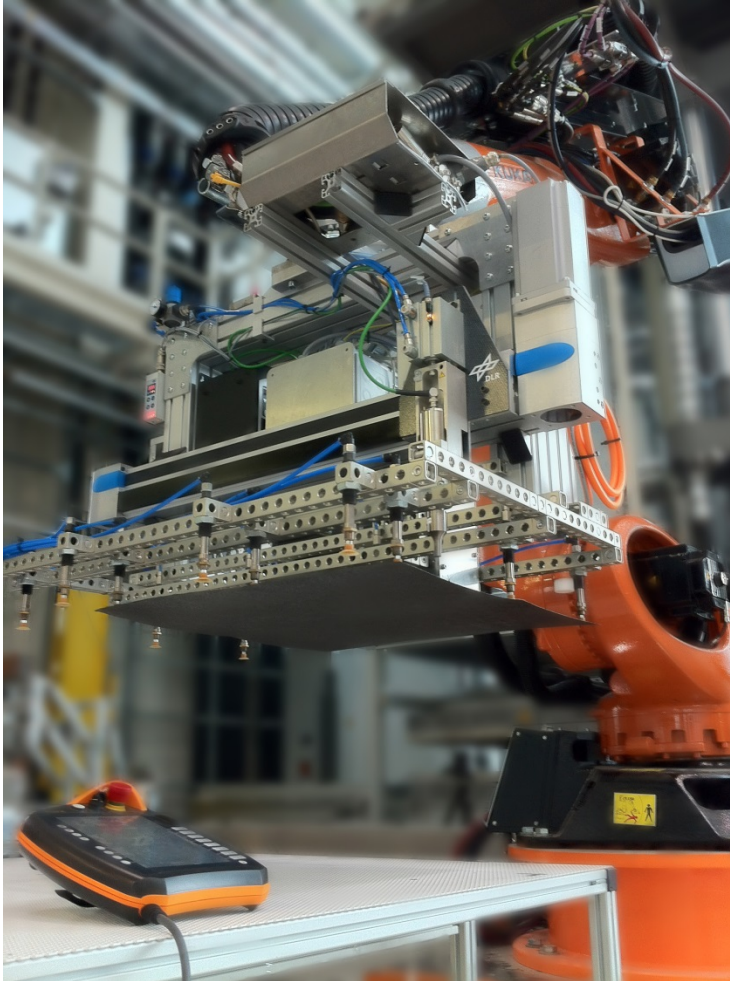


MATCH

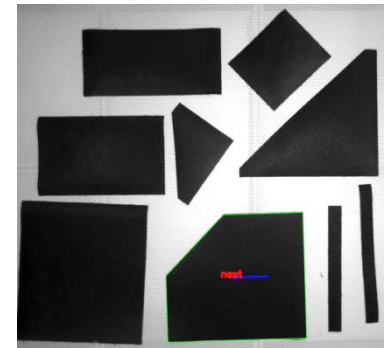
- Advantage: Robustness regarding waviness and reflections



2c) Examples for robotic lay-up systems



- Automated camera based ply-detection
- End effector for the automated stacking of tailored laminates
- Ultrasonic spot welding of laminate stacks



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3. Manufacturing and assembly of thermoplastic components

Summary



3) Manufacturing + Assembly of Thermoplastic Components

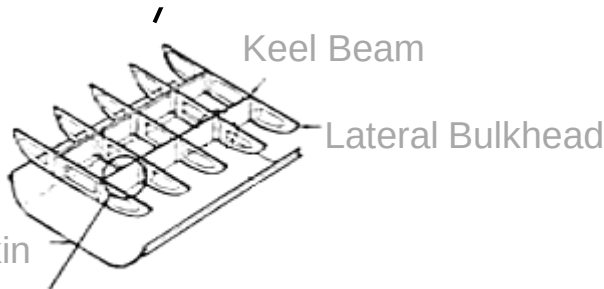
Use Case: Sine Wave Beam

- Sine wave beam as generic crash-absorber to demonstrate entire process chain from design to automated production
- Assembly of sine wave beam consists of 7 parts with 3 different geometries with high degree of deformation

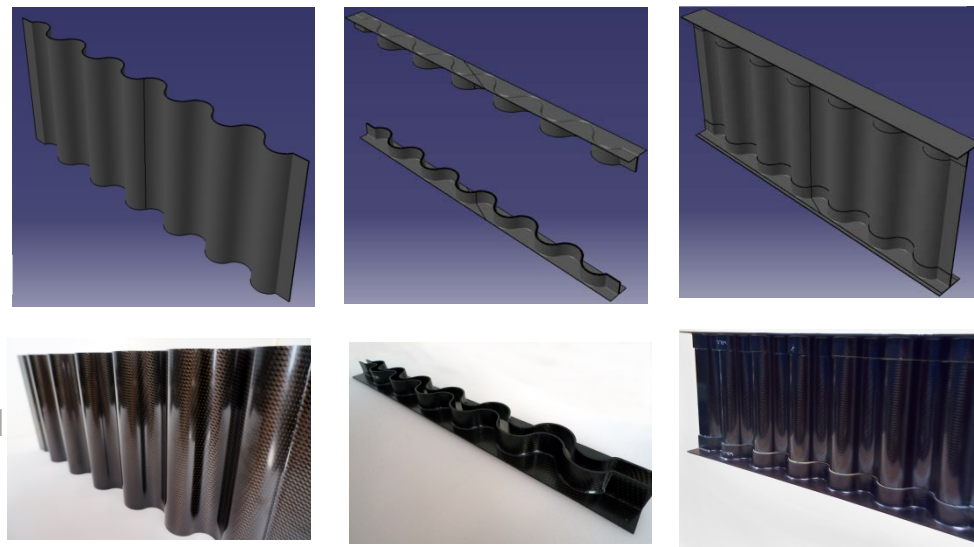
HELICOPTER FUSELAGE



SUBFLOOR STRUCTURE



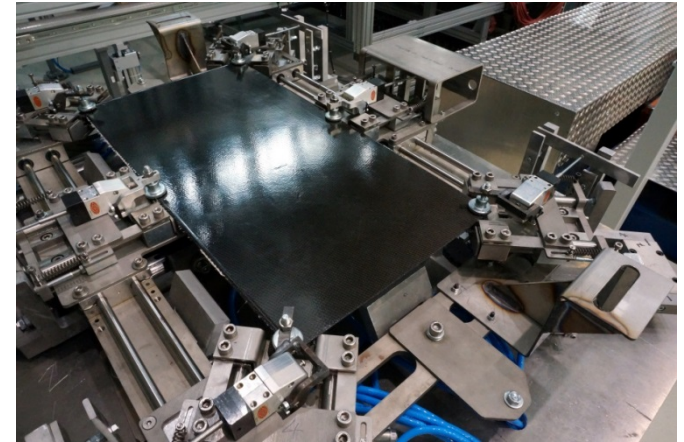
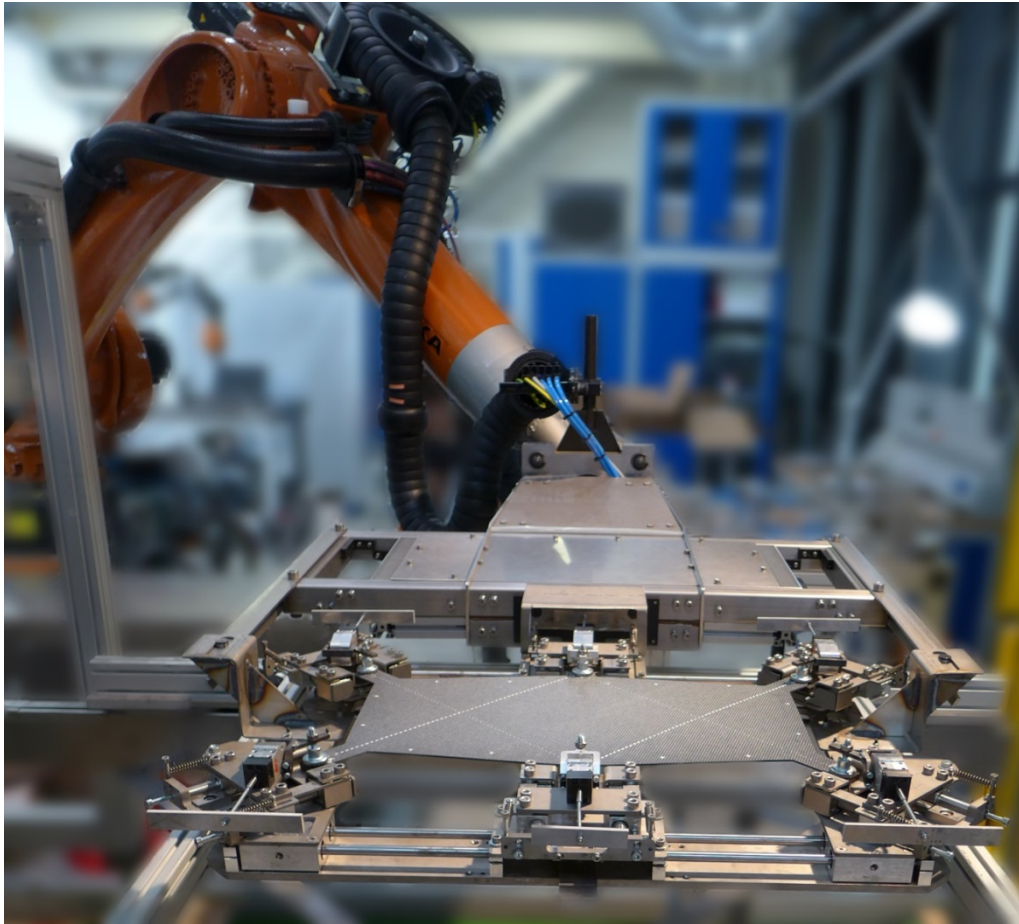
ENERGY ABSORBING BEAM



[Kindervater and Georgi, 1993]

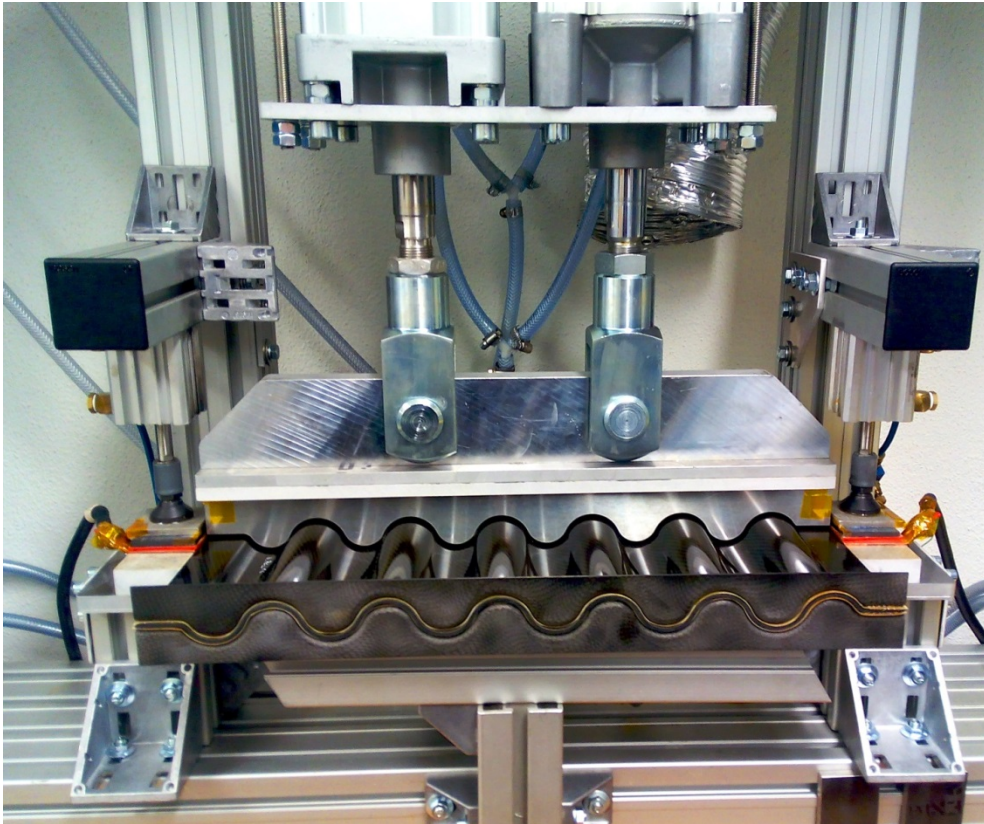
3) Manufacturing + Assembly of Thermoplastic Components

Automated Clamping Frame



3) Manufacturing + Assembly of Thermoplastic Components

Resistance Welding



- Resistance welding of CF/PEI parts for the sine wave beam assembly
- Test stand to establish process parameters at the Institute of Structures and Design (DLR BT) in Stuttgart
- Welding element made of stainless steel glasfiber semipreg developed at DLR BT in Stuttgart



Summary

1. Automation of production processes in Aerospace
 - a. Production rates of 10 – 60 per month
 - b. Dimensions with variability 0.5 – 10.0 m
 - c. Accuracy in layups regarding positions and fiber angles
2. Shown examples
 - a. Fiber Metal Laminates for a fuselage side shell
 - b. Draping systems for double curvature
 - c. Tape layer for 90 cm multilayer tapes
 - d. Autonomous cut-piece detection and path planning
 - e. Manufacturing and assembly of thermoplastic components



Acknowledgements

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