DIGITAL BEAMFORMING TECHNIQUES FOR MULTI-CHANNEL SYNTHETIC APERTURE RADAR

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Abstract

SAR instruments with multiple transmit/receive channels allow for a variety of operation modes. The trade-space includes the instrument and antenna parameters designed to enable various operation modes. These are utilized to achieve a required SAR performance derived from the mission and user requirements. Finding a solution in this multi-dimensional trade space is not trivial and often involves the compromise of parameters. This paper addresses the topic of SAR instrument design tailored to a set of operation modes. It explains and compares the SAR techniques and gives the performance.

1. INTRODUCTION

In the last years a clear trend towards multi-digital-channel SAR systems has manifested itself. Examples are TerraSAR-X (two channels as a by-product of the redundancy concept), Radarsat-2 for ATI applications, ALOS-2 to increase the azimuth resolution. This step towards multi-channel SAR instruments marks a paradigm change as a consequence of research activity results in the last decade. The main innovative characteristic of forthcoming generations of SAR systems is the use of multiple elevation and/or azimuth receive channels combined with digital beamforming (DBF) capability [1, 2, 3]. This allows for the synthesis of multiple or dynamic digital receiver beams. Further, multiple transmit channels are being suggested as an extension to DBF systems.

The virtue of Multi-Channel SAR is that it extends the dimensionality of the trade-space. This allows the conception of new systems which overcome the “fundamental limitation” of conventional SAR. A good example is the simultaneous High-azimuth-Resolution and Wide-Swath SAR known as HRWS [4], which improves two performance parameters without sacrificing others [5, 6].

The aim of this paper is to introduce the trade-space of multi-channel SAR and show potential instrument designs. The approach is to introduce the system and performance parameters and show how they can be traded by virtue of system examples. The instrument description remains at a conceptual level to avoid irrelevant technical details.

2. SYSTEM REQUIREMENTS AND TRADE-SPACE PARAMETERS

The most relevant system and performance parameters for the L-band SAR considered in this paper are shown in Fig. 1. Here the system parameters basically describe the instrument both in terms of quantities fixed by the system design such as antenna dimensions, and parameters which can be altered during operation (e.g. the Pulse Repetition Frequency: PRF).

The system parameters will be altered for the various implementations considered later, however, to allow for a “fair” comparison (and to limit the trade space dimension), three system parameters will be fixed. As shown in Fig. 1 these are the center frequency, total average Tx power, and orbit height (resulting, for the chosen swath width of 400 km in an incidence angle range from 25° to 45°).
Others may simply be a result of the system parameters, such as the range resolution assuming, here, that the chirp bandwidth is fixed. The actual values of the performance parameters result from a model- or simulation-based system analysis and obviously depend on the system parameters. To achieve the desired performance, various “MIMO” techniques might be used. Thus, for example the data rate (performance) depends on the system (chirp bandwidth) but also shows how efficiently the system is operated (techniques).

The emphasis of this paper is on the various SAR techniques, depicted in Fig. 1, that can be utilized for multi-channel instruments to yield a desired performance.

3. SAR SYSTEM OPTIONS

In this section various SAR instrument and antenna options are investigated. The presented system designs should be understood as conceptional in the sense that further optimization would improve performance by several dBs. However, here the intention is to show how the various techniques can be utilized and to report on their system efficiency, which is a measure understood here as an indication of how efficiently the system resources are used to achieve the required performance.

3.1. Single Swath Stripmap Mode

A straightforward approach to reach the required swath width and azimuth resolution is shown in Fig. 2 and consists of dimensioning the Rx antenna so as to yield the swath width while utilizing Multiple Azimuth Channels (MACs) to reach the azimuth resolution. By this the resolution is decoupled from the total antenna length.

Fig. 2. Improving the azimuth resolution while maintaining the swath width by using MACs technique.

The system parameters are obtained by determining the PRF which allows imaging a \( W_{\text{sw}} = 400 \text{ km} \) swath. This gives 430 Hz when using the approximation

\[
PRF \leq \frac{c_0}{2W_{\text{sw}} \sin \eta_i} \tag{1}
\]

where \( \eta_i \) is the incidence angle and \( c_0 \) the velocity of light. The total antenna length is determined according to the condition of uniform azimuth sampling [2]

\[
L_{R_x}^{\text{unif}} = \frac{2v_{\text{sat}}}{PRF} \tag{2}
\]

which yields a considerable value of \( L_{R_x} = 34 \text{ m} \). Knowing that the individual azimuth element must cover a Doppler bandwidth corresponding to the azimuth resolution (or just applying the known approximation for the azimuth resolution \( \delta_{az} = L_{R_x}/2N \)) leads to \( N = 4 \) of azimuth channels.

The performance parameters of the system are quite good, however, such a system can practically not be realized due to the tremendous antenna length.

3.2. Single Swath Sub-Pulse Mode

A possibility to reduce the antenna length of the previous system to approximately half is to use sub-pulse techniques [7]. The basic idea is to illuminate the wide swath by two sub-pulses from two different azimuth positions by using two Tx antennas. Adding the second Tx antenna [8, 9] allows the system to be operated such that two pulses are transmitted within each Pulse Repetition Interval (PRI) where typically each sub-pulse is delayed by a small fraction of the PRI with respect to previous one as shown in Fig. 3.

![Fig. 3. Two sub-pulses showing that the position of the spatial samples depends on the Tx antenna separation and the PRI.](image)

Doubling the number of Tx pulses within the same time interval consumes twice the power [7], but the number of received samples per PRI (i.e. the spatial sampling) is doubled which, here, allows reducing the Rx antenna length to half the values given by (2), i.e. \( L_{R_x} = L_{R_x}^{\text{unif}}/2 = 17.4 \text{ m} \). The spatial distance between the azimuth samples of the two sup-pulses is mainly determined by phase center separation of the Tx antennas. Uniform sampling is achieved when \( \Delta_{T_x} = L_{R_x}^{\text{unif}}/2 \), which, for a single Tx/Rx antenna aperture, requires that the length of each Tx antenna be \( L_{T_x} = L_{R_x}^{\text{unif}}/2 = 8.7 \text{ m} \).

The echo signals of the two sub-pulses arrive at nearly the same time at the receiver. To separate the two echoes multi-SCORE is utilized here, where two receive beams are generated, each one maximized to the direction of arrival of one sub-pulse while suppressing the energy of the other [8, 9]. The Rx antenna height \( H_{R_x} \) required to place a pattern null at the interfering sup-pulse is computed according to [3]:

\[
H_{R_x} = \frac{2\lambda r \tan \eta_i}{c_0 \Delta \tau} \tag{3}
\]
where $r$ is the slant range and $\Delta \tau$ is the time delay between the the start of the two sub-pulses, respectively. Taking a single sub-pulse duty cycle of 6% gives $H_{\text{Rx}} = 13.4 \text{ m necessary}$ to suppress the pulses at far range (worst case).

The SAR performance is shown in Fig. 4 in terms of the NESZ and Doppler pattern. The azimuth performance is comparable to the previous single-swath stripmap system, although here a total of 3 azimuth channels are used (effectively increasing the azimuth sampling) to compensate for the shorter Tx antenna length.

Fig. 4. Noise-equivalent sigma-zero and azimuth pattern for single swath stripmap system utilizing sub-pulses.

3.3. Multi-Azimuth ScanSAR

Alternatively the ScanSAR burst mode may be used to cover the wide swath while utilizing multiple azimuth channels (MACs) for the required azimuth resolution [10], as has been suggested within the Sentinel-1 follow-on Study [11]. Here, a design is presented which results in an Rx antenna dimension of $12.2 \text{ m} \times 2.8 \text{ m}$ and 8 azimuth channels. As shown in the timing diagram of Fig. 5a the system is operated in $n_{\text{burst}} = 4$ bursts, which is the minimum number needed if nadir echoes are taken into account by the timing considerations.

Fig. 5b shows that the NESZ variation within the swath is smaller compared to the previous modes, which is a result of the reduced sub-swath width. However, there is a Doppler dependent variation (scalloping) which is indicated by the different curves. The range performance is acceptable but for the extreme far range of the swath; nevertheless it is believed that a pattern optimization can yield the required performance, i.e. the antenna height is sufficient to allow for ambiguity suppression.

The burst mode operation has some advantages. Since only part of the swath is illuminated for each burst, the power density can be increased taking advantage of the high gain Tx antenna (assuming a Tx/Rx antenna configuration with TRM), which more or less compensates the reduced power density due to the wider illumination in azimuth. For the same reason the PRF can be increased and by this the total antenna length reduced. The ScanSAR mode is suitable for interferometric applications [12]. The disadvantage is somehow the required increase of the covered Doppler bandwidth by a factor of $n_{\text{burst}} + 1$, which at the end results in a reduced Rx antenna gain due to the larger azimuth beamwidth. In total, the ScanSAR mode has an acceptable system efficiency.

3.4. Multi-Azimuth Multi-Elevation Two Burst ScanSAR

An alternative technique to cover a wide swath is the two-burst ScanSAR mode. Here multiple sub-swathes are imaged simultaneously taking advantage of DBF on-receive. To fill the gaps occurring due to the transmit instances, a burst mode operation is utilized, for which two PRFs/bursts are sufficient as seen in Fig. 6a.

Here the receive antenna dimensions are chosen to be $6.8 \text{ m} \times 5.5 \text{ m}$. This mode gives some flexibility in deciding on the antenna dimensions as long as the minimum antenna area does not go below a critical value. Here, the number of azimuth channels is $N = 3$, which is determined by the length of the antenna element necessary to cover the system Doppler bandwidth.

The azimuth performance, cf. Fig. 6b, is good, mainly due to the oversampling effect. It is seen that the even numbered sub-swathes have a worse performance; this a result of the PRF values (cf. (2)), which result in a 3% non-uniform azimuth sampling [13]. The elevation performance (RASR) does not satisfy the requirement, as seen from Fig. 6c. Nevertheless, the antenna height of $5.5 \text{ m}$ is considered sufficient for ambiguity suppression if a dedicated beam-forming tech-
Fig. 6. Timing diagram and SAR performance of the 2-burst ScanSAR MACs system.

4. CONCLUSION

The paper presented various techniques suitable for multi-channel SAR systems. The SAR performance of these modes were shown for an exemplary L-band SAR required to image a 400 km swath. The main purpose was to show how the trade-space parameters of multi-channel SAR can be utilized and to explain their impact on the system design.

5. REFERENCES


