



Some Experience Using SEN2COR



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Sen2Cor is the L2A-processor for **Sentinel-2** data. **Sentinel-2** is a polar orbiting satellite constellation of two units carrying each one an optical imaging sensor called MSI (Multi-Spectral Instrument). Sentinel-2A was launched on June 23, 2015.

The atmospheric correction software **Sen2Cor** was implemented by TPZ-D, TPZ-F and DLR on behalf of ESA. TPZ-F and DLR have teamed up in order to provide the calibration and validation of the Level-2A processor Sen2Cor.

Sen2Cor can be obtained downloading the S2 Toolbox (<http://step.esa.int/main/download>) and following plugins installation procedure.

Sen2Cor:

- Python application, Command line tool
- Processing configuration: XML-file
- Processing on granule level

- Terrain processing: DEM downloaded automatically
- Adjacency correction
- Cirrus removal option
- Empirical BRDF-correction option
- LUTs: rural aerosols

- Input: Level-1C ortho-image Top-Of-Atmosphere (TOA) reflectance products

- Output (60m, 20m, 10m):
 - Bottom-Of-Atmosphere (BOA) corrected reflectance
 - Aerosol Optical Thickness (AOT) map
 - Water Vapour (WV) map
 - Scene Classification (SC) map
 - Quality Indicators for cloud and snow probabilities

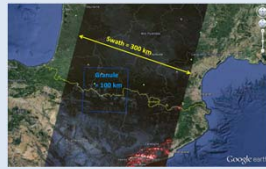


Figure 1: Swath and Granule
Image source: Annex_1-S2A_V00R_Image_quality_CNES_vf.pdf

Level	Classification
0	NO DATA
1	SATURATED OR DEFECTIVE
2	DARK_AREA_PIXELS
3	CLOUD_SHADOWS
4	WETLANDS
5	BARE_SOILS
6	WATER
7	CLOUD_LOW_PROBABILITY
8	CLOUD_MEDIUM_PROBABILITY
9	CLOUD_HIGH_PROBABILITY
10	THIN_CIRRUS
11	SNOW

Figure 2: SC color table

60m: BOA, quality 20m: BOA, quality 10m: BOA

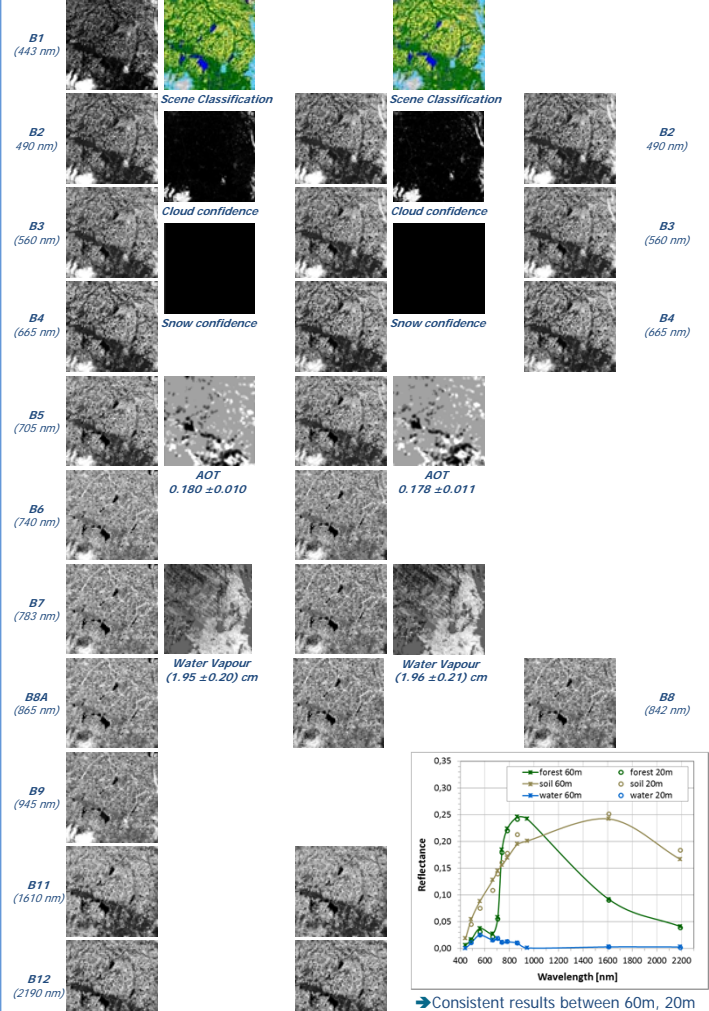
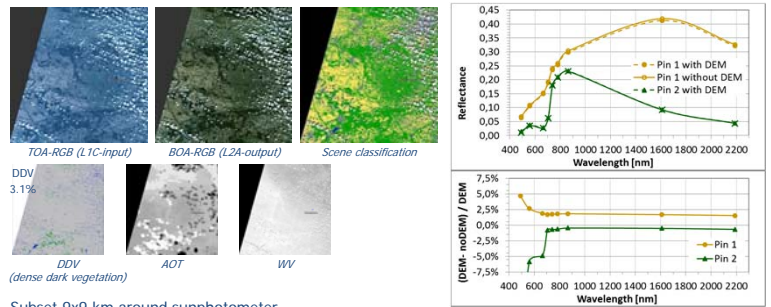


Figure 3: Test site Demmin (Germany): April 13, 2015: L2A-product at different spatial resolution

Level-2A processing: flat terrain



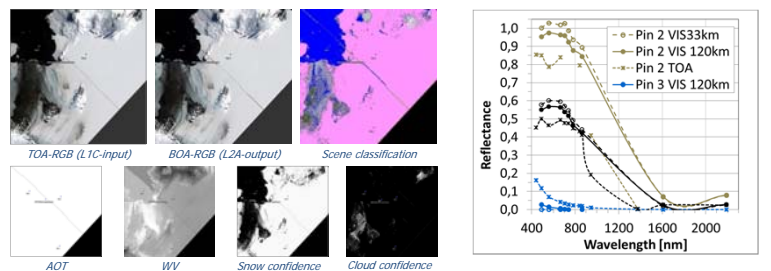
Subset 9x9 km around sunphotometer

AERONET: AOT = 0.23
Sen2Cor: AOT = 0.198 ± 0.001
AERONET: WV = 2.63 cm
Sen2Cor: WV = (2.46 ± 0.09) cm

- Good results for scene classification and atmospheric correction
- sufficient DDV-pixels available
- Processing without DEM differs less than 2% from processing with DEM in most bands.

Figure 4: Test site Belsk (Poland): August 14, 2015

Level-2A processing: configuration VIS_Update_Mode



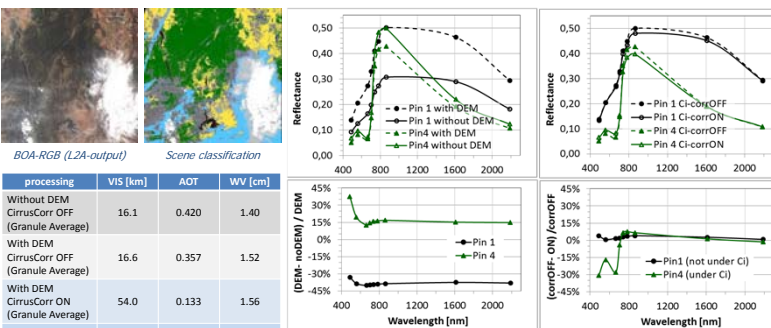
Subset 9x9 km around sunphotometer

AERONET: AOT = 0.03
Sen2Cor: AOT = 0.23
AERONET: WV = 0.29 cm
Sen2Cor: WV = (0.33 ± 0.07) cm

- Good results for scene classification
- Atmospheric correction is necessary
- VIS_Update_Mode = 1 (variable visibility)
- Aerosol estimation fails due to lack of DDV-pixels, but
- Always clear air over Antarctica with low AOT
- Good practise for processing atmospheric correction over Antarctica:
- VIS_Update_Mode = 0 (constant visibility)
- Process with visibility 120 km (AOT 550 = 0.08)

Figure 5: Test site McMurdo (Antarctica): February 06, 2016

Level-2A processing: cirrus correction



processing	VIS [km]	AOT	WV [cm]
Without DEM CirrusCorr OFF (Granule Average)	16.1	0.420	1.40
With DEM CirrusCorr OFF (Granule Average)	16.6	0.357	1.52
With DEM CirrusCorr ON (Granule Average)	54.0	0.133	1.56
With DEM CirrusCorr ON (subset 9x9km)		0.143	1.50±0.01
AERONET		0.100	1.75

- Good results for scene classification and atmospheric correction
- Good results for atmospheric correction with Cirrus correction ON, 5.1% DDV-pixels
- Processing with DEM has larger effect on BOA-product than cirrus correction

Figure 6: Test site Canberra (Australia): January 01, 2016

Outcome and credits

Scene classification works correctly with Sen2Cor. Atmospheric correction works accurate, if DDV pixels are existing in the granule. Aerosol estimation fails, if there are no DDV-pixels in the image.

We thank the PI investigators and their staff for establishing and maintaining the AERONET sites used in this investigation.