

Generation of an Advanced Helicopter Experimental Aerodynamic Database for CFD Code Validation (GOAHEAD)

T. Schwarz, K. Pahlke

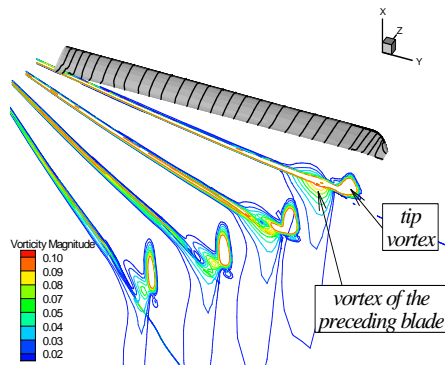
DLR

Braunschweig, Germany

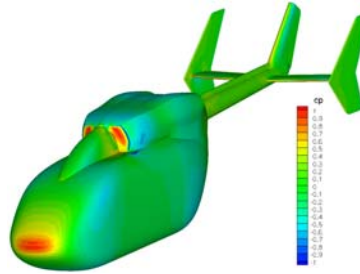


- Motivation
- The GOAHEAD project
- Wind tunnel experiment
- CFD activities
- Conclusions

State of the art in CFD in Europe 2005



Isolated rotors
hover/forw. flight



Isolated fuselages



Complete helicopter
first demonstration in Europe 2002

- before 2005 two RANS flow solvers have been applied to complete helicopters → elsA (ONERA) and FLOWer (DLR)
 - Demonstration of capability, not a careful validation
 - Considered was one test case only
 - Challenging because of high computational costs
- A lack of experimental validation data was observed. Previous wind tunnel experiments focussed on isolated rotors or fuselages, or complete helicopter experiments with focus on vibrations or acoustics.

⇒ set-up of the European „GOAHEAD“-Project

Objectives of GOAHEAD

- GOAHEAD = Generation Of Advanced Helicopter Experimental Aerodynamic Database for CFD code validation
- STREP, 6th Framework Program, total budget 5M€, EU-funding 3M€

Objectives of GOAHEAD

- To enhance the aerodynamic prediction capability with respect to complete helicopter configurations.
 - create an experimental database for the CFD-validation
 - evaluate and validate Europe's most advanced URANS solvers

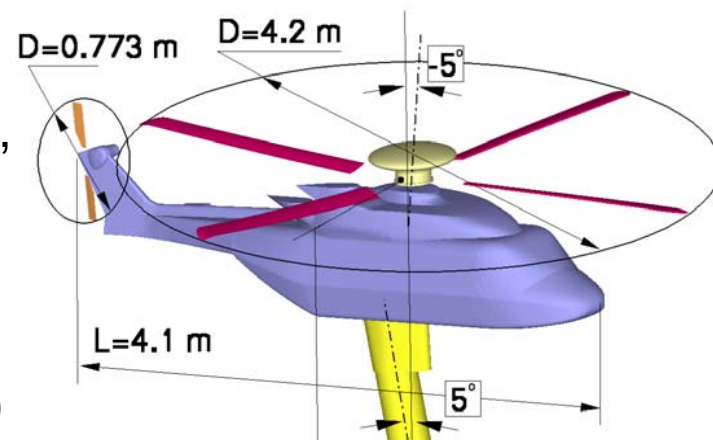
GOAHEAD consortium



Project
leader: DLR

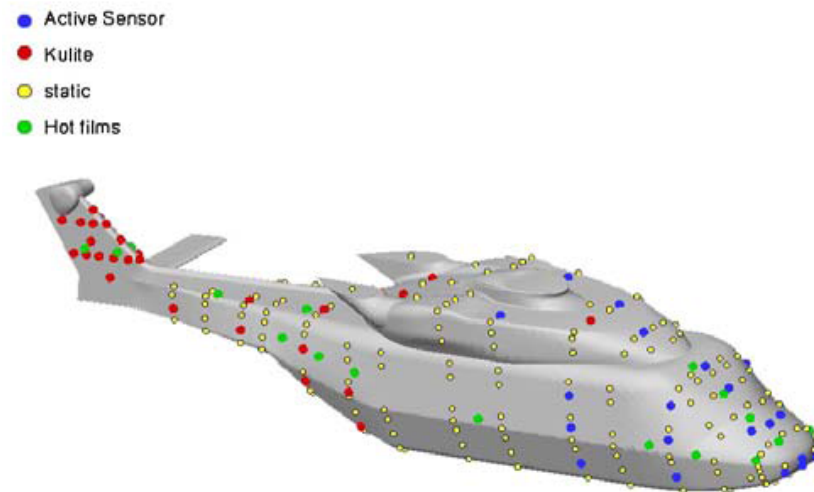
Configuration

- Generic Mach scaled model, similar to modern transport helicopter
- existing components are reused, in order to put high effort into measurements,
 - fuselage: slightly modified NH90
 - instrumented 4-bl. main rotor (7AD geometry)
 - instrumented 2-bl. tail rotor (BO 105)
- main rotor diameter 4.2 m: 1/3.9 scale
- model prepared by Agusta (fuselage shell), ONERA (rotor blades), DLR (assembly and testing)



Model Instrumentation

- Fuselage:
 - balances for the fuselage and the horizontal stabilizer
 - 130 unsteady pressure sensors, 292 steady transducers
 - 38 hot wires for detection of transition and flow separations
- Main rotor
 - rotor balance
 - 125 unsteady pressure sensors
 - 40 hot wires
 - 29 strain gauges for blade deformation measurements
- Tail rotor
 - 38 unsteady pressure sensors
 - 4 strain gauges for thrust measurement
 - Torque meter
- CAD data of configuration based on model scan with structured-light 3D scanner



Wind tunnel experiment

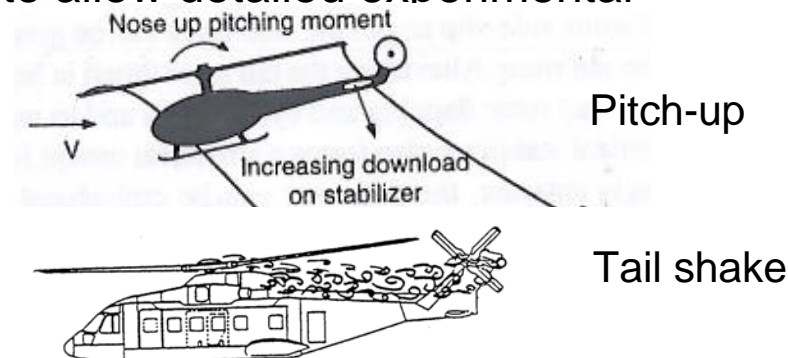
- Wind tunnel experiment in the DNW-LLF, Marknesse, The Netherlands
- Tests were performed in the 6m * 8m closed test section
- Duration: 14 days from March 28th to April 14th, 2008
- Model was operated by DLR
- Seven Partners involved in measurements
- Almost all data as originally planned were gathered during the experiment.

- Challenging wind tunnel experiment
 - Model could only be tested in lab conditions before
 - Model must be operated like a real helicopter based on measured loads



Executed Test matrix

- Only four flight states were considered to allow detailed experimental analysis
 - Low speed, pitch up ($M=0.059$)
 - Cruise / tail shake ($M=0.204$)
 - Dynamic stall ($M=0.259$)
 - High speed ($M=0.28$)
- Tests with and without rotors (→ isolated fuselage and complete helicopter)

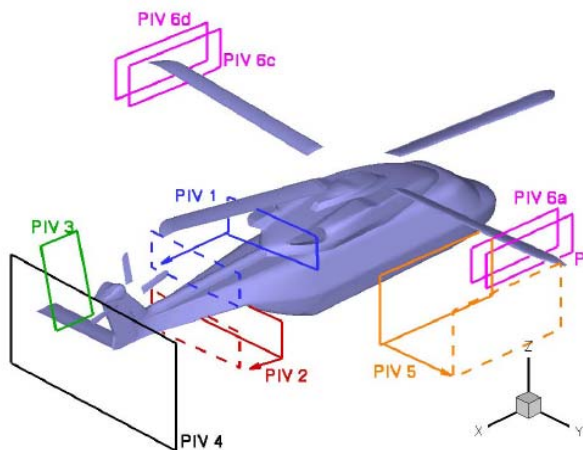


Experimental data base

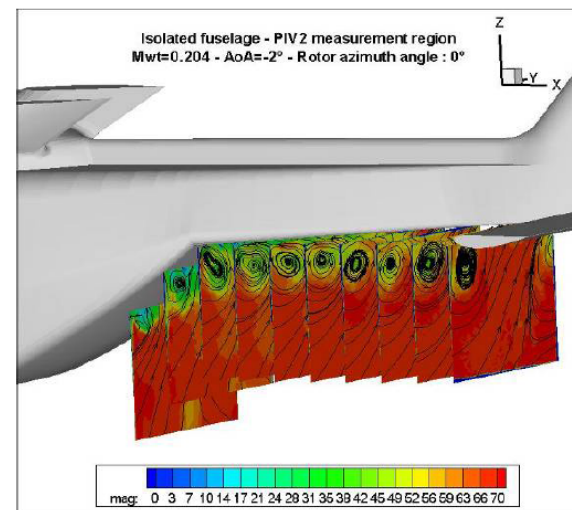
- data base with more than 400 GB data
- data postprocessor developed by Glasgow University
- comprehensive documentation available

M. Raffel et al.: “Generation of an advanced helicopter experimental aerodynamic database”, ERF 2009

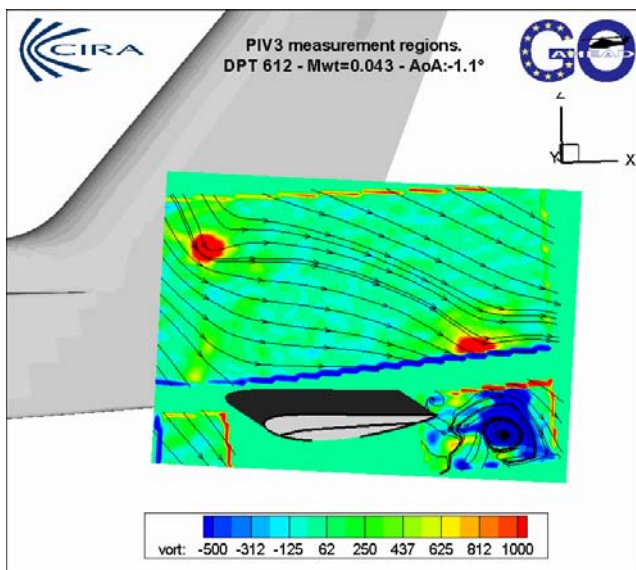
Experimental results - PIV



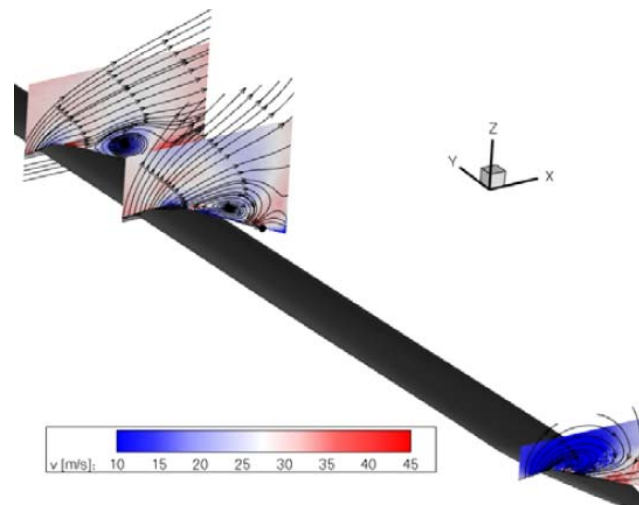
Detailed flow field analysis with particle image velocimetry (3C PIV)



Isolated fuselage, Vortices behind back door

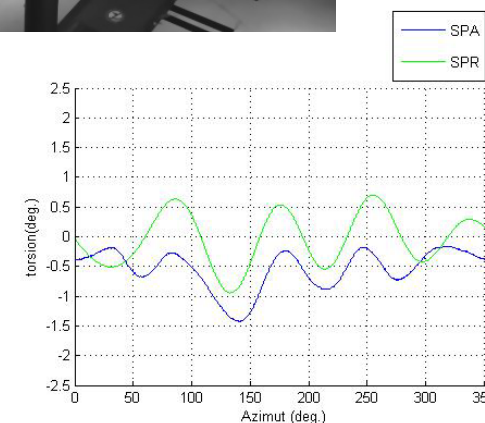
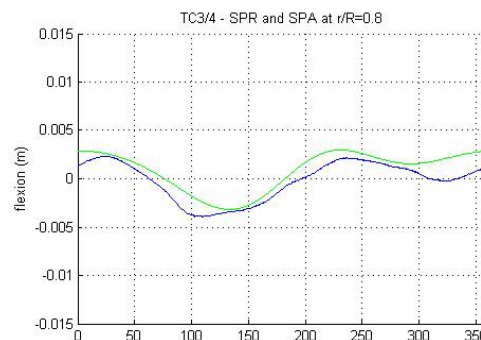
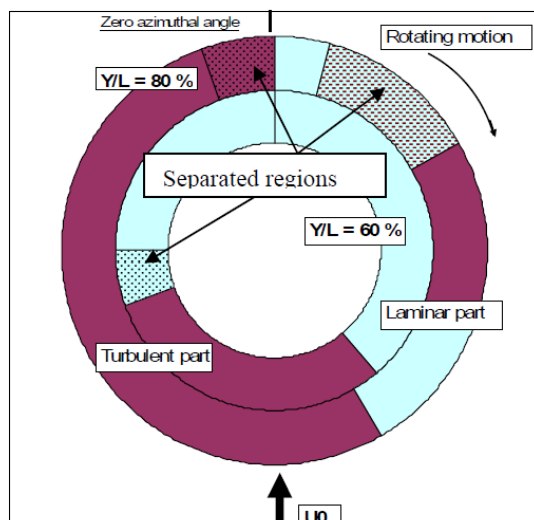
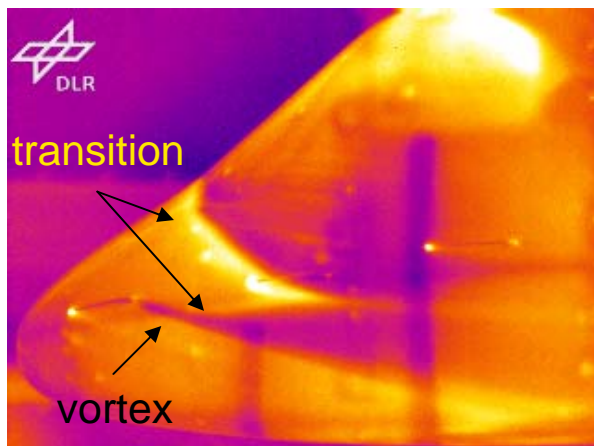


pitch up-condition



Dyn. Stall on highly loaded rotor

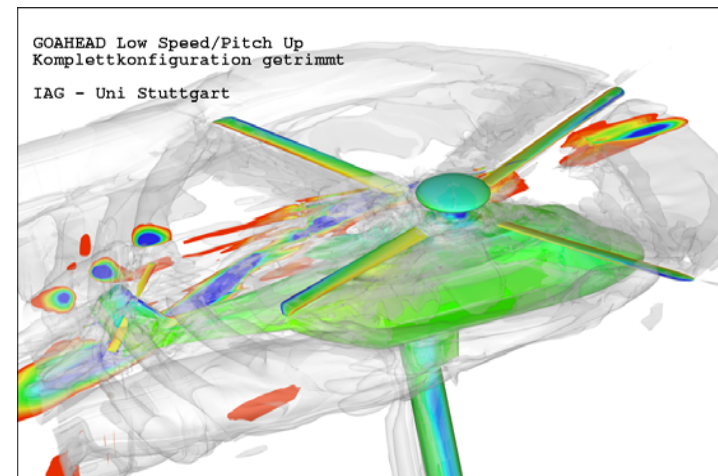
Experimental results



- Transition detection, top: IR, bottom: hot films on main rotor
- Blade deformation measurements with Strain Pattern Analysis (SPA) and Stereo Pattern recognition (SPR)
- Top : SPR markers, bottom: bending and torsion ($r/R = 0.8$, cruise condition)

CFD codes applied in GOAHEAD

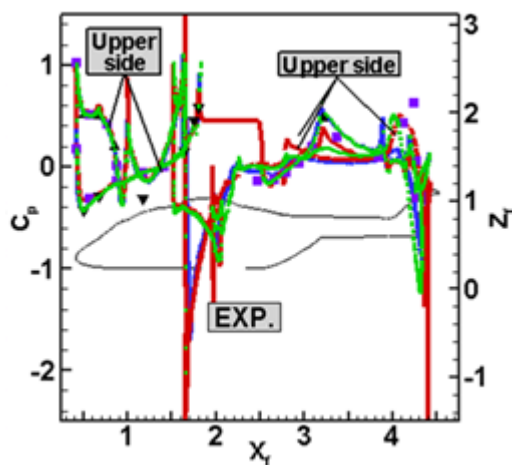
CFD Code	Research organisations	Helicopter industry
elsA	ONERA	EC SAS
FLOWer	<u>DLR</u> , CU, USTUTT-IAG,	ECD
HMB	ULIV	WHL
ROSITA	PoliMi	Agusta
ENSOLV	NLR	
FORTH in house	FORTH	



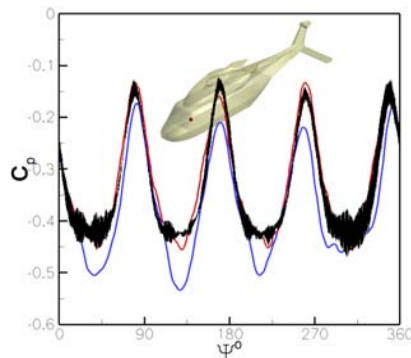
- Codes were applied in a blind test phase in order to assess the prediction capabilities and a post test phase to refine CFD results
- At the end of the project with all codes complete helicopter simulations were performed
- Budget in GOAHEAD for CFD-validation only, significant activities for code improvement paid by internal funding of partners

CFD validation, cross plots

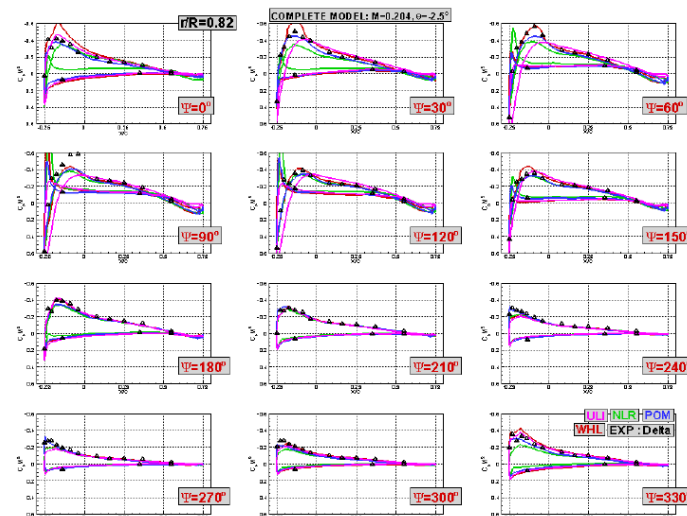
- Application of several codes to same test cases allowed to assess different solution approaches
e.g. Chimera / sliding meshes, rigid / elastic blades, turbulence models, ...
- Best practice guidelines have been established



top: pressures in symmetry plane, isolated fuselage (ECD, NLR, CUN)



Unsteady pressures on fuselage (cruise condition, DLR, POM)



main rotor pressures at $r/R = 0.82$, (cruise condition, ULI, NLR, POM, WHL)

Boelens et al.: "The blind test activity of the GOAHEAD project", ERF 2007

Antoniadis et al.: Assessment of CFD methods against experimental flow measurements for helicopter flows", ERF 2010

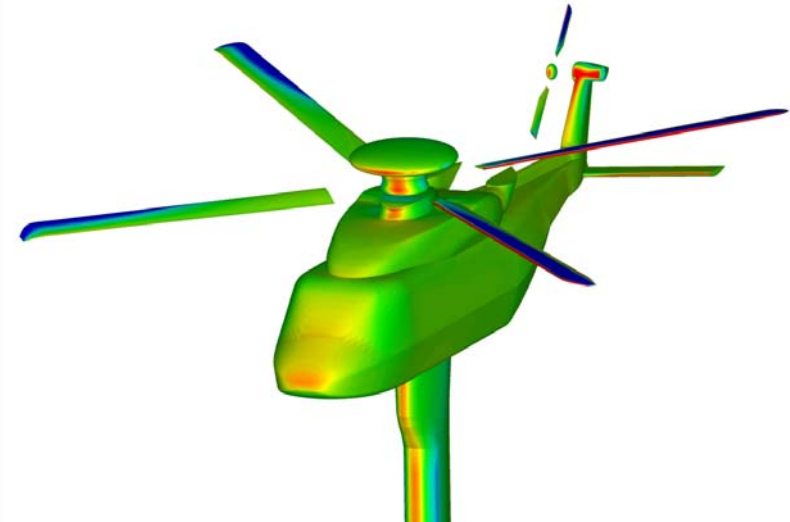
Conclusions (1/2)

- Within the GOAHEAD project a comprehensive data base with high quality data and documentation for complete helicopters has been generated.
 - A full understanding of the data base will require many more years of research and data analysis like for any other experimental data base.
- All CFD-solvers are capable to simulate the unsteady flow about complete helicopters with good accuracy for certain features. Interaction phenomena are partly captured. This is a big step forward having in mind that the first successful RANS helicopter simulations in Europe have been published in 2002.
 - due to the complexity and instationarity of the flow the solution accuracy has not reached the same level like for fixed wing applications. Further CFD developments and validation is required in order to further improve the CFD software, e.g. coupling of CFD methods to structural mechanics and flight mechanics, turbulence and transition modelling, and CPU time reduction.
 - CFD-simulations for complete helicopters are still a challenge
 - Access to modern supercomputers is crucial

Conclusions (2/2)

- The European helicopter industry took advantage from the improvements and validation of their URANS-CFD tools. By working jointly with research centers industry extended the range of applications for in-house simulations.
 - However, due to the large computational effort complete helicopter simulations will not be routinely run in near future in industry.

Thank you



GOAHEAD

Generation Of Advanced Helicopter Experimental
Aerodynamic Database for CFD code validation

 = application of CFD

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Work plan of GOAHEAD



	05	2006				2007				2008				2009				effort
Definition model & test matrix																		9 PM
Model manufacturing																		79 PM
Model assembly and testing																		
Wind tunnel experiment																		
CFD blind test phase																		127 PM
CFD post test phase																		
Experimental data analysis																		76 PM
Comparison Exp-CFD																		

- Total planned effort (including project management 14PM): 305 PM = 25.4 PY
- Real effort significantly higher (many partners used internal funding)

Partners in GOAHEAD

Short Name	Legal Name	Country
DLR	Deutsches Zentrum für Luft- und Raumfahrt e.V.	Germany
ONERA	Office National d'Etudes et de Recherches Aéronautiques	France
CIRA	Centro Italiano Ricerche Aerospaziali S.C.P.A.	Italy
FORTH	Foundation for Research and Technology	Greece
NLR	Stichting Nationaal Lucht-en Ruimtevaartlaboratorium	NL
ECD	EUROCOPTER Deutschland G.m.b.H.	Germany
EC SAS	EUROCOPTER S.A.	France
Agusta	Agusta S.p.A.	Italy
WHL	Westland Helicopters	UK
UG	University of Glasgow	UK
CU	Cranfield University	UK
PoliMi	Politecnico di Milano	Italy
USTUTT-IAG	Institut für Aerodynamik und Gasdynamik Uni Stuttgart	Germany
ULIV	University of Liverpool	UK
AS	Aktiv Sensor GmbH	Germany

Thank you



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Preparation for 3D surface scan