

Germany's Option for a Moon Satellite

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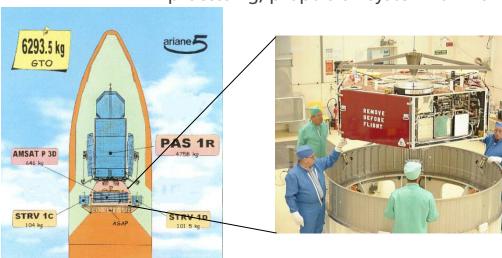


Background



7 AMSAT-DL:

- **▼** German non-profit amateur satellite organisation (~1200 members)
- >30 years experience in planning, building + operating satellites
- **▼** Low-cost missions in Earth orbit (LEO (800 km) and HEO (60000 km Apogee))
- **▼** Usage of commercial off-the-shelf (COTS) components whenever possible
- **▼** Focus on telecommunication (amateur radio)
- → P3-D (AO-40) launched in 2000 into GTO using the main payload launch adapter: 650 kg launch mass, high amount of radio transponders and digital signal processing, propulsion system for inclination changes





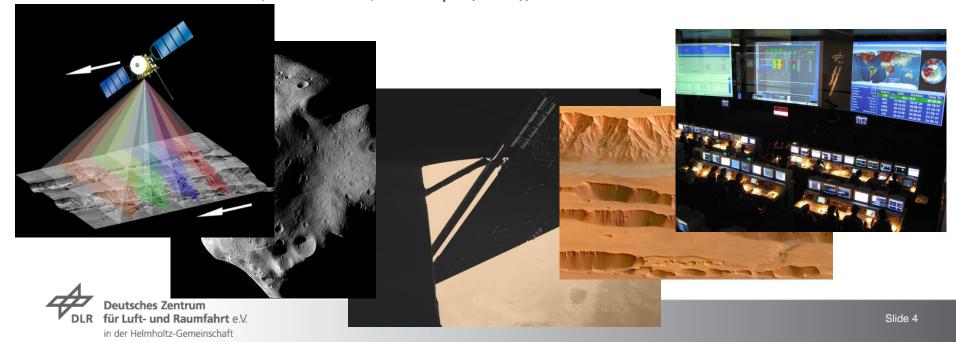


Background



DLR

- Germany's national research center for aeronautics and space (transportation and energy)
- → ~6500 employees at 29 institutes and facilities at 13 locations in Germany
- Scientific participation in e.g. Cassini-Huygens, Mars Express, Venus Express, Rosetta-Philae, SCIAMACHY, TerraSAR-X, TanDEM-X
- >35 experience in operations (e.g. AZUR, AEROS, HELIOS, GALILEO, CHAMP, BIRD, GRACE, TerraSAR-X, SAR-Lupe (LEOP))



Background





Deutsches Zentrum für Luft- und Raumfahrt e.V.

in der Helmholtz-Gemeinschaft

Goal:

go Mars with AMSAT-DL's P5A-mission!



Interest:

perform cost effective scientific missions

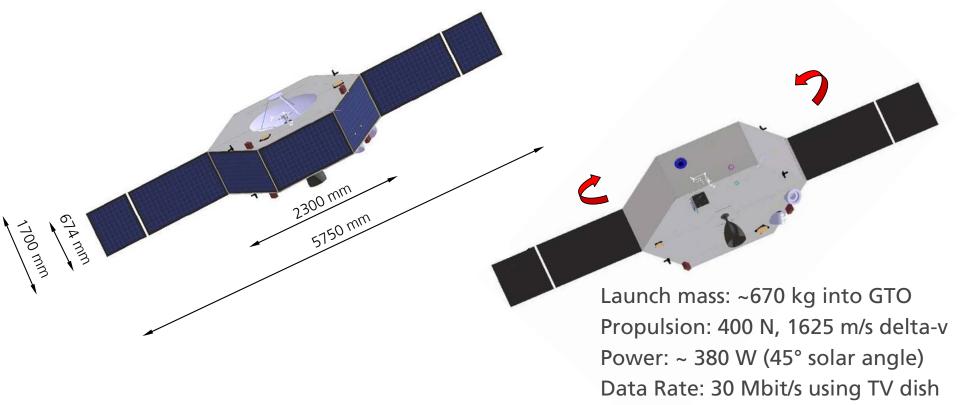
concept for a joint mission
to Mars and/or Moon
using the Concurrent Engineering Facility (CEF)
at DLR Bremen



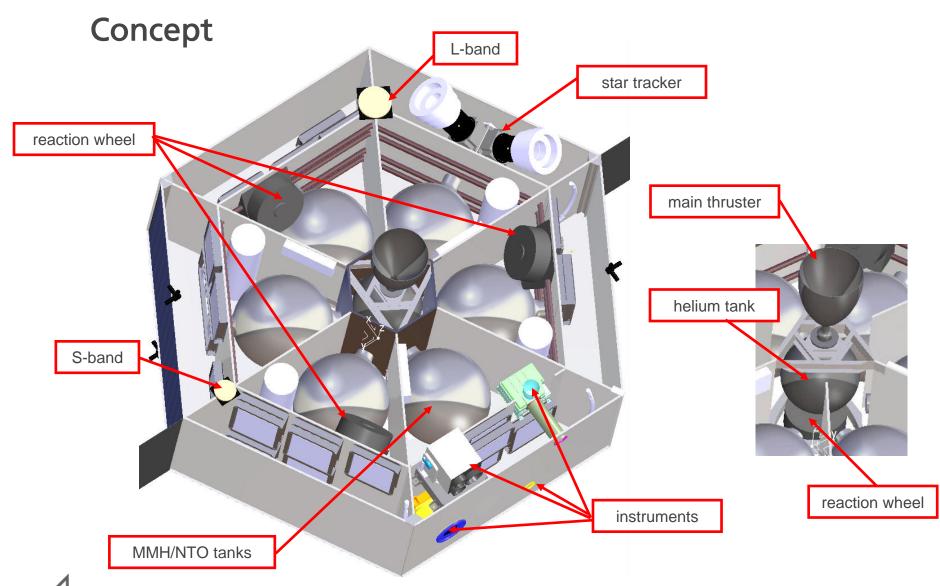


Concept

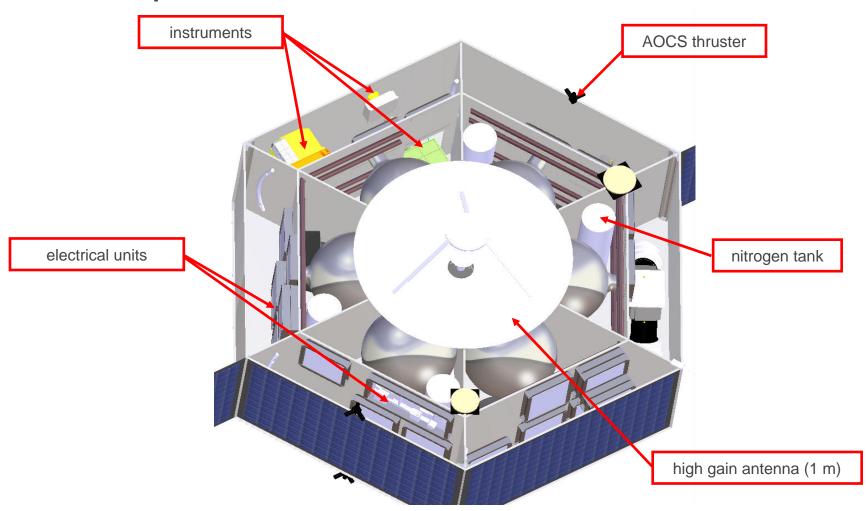
Design strongly based on the flight proven P3-D



Comm.: X-, S-, L-Band and UHF



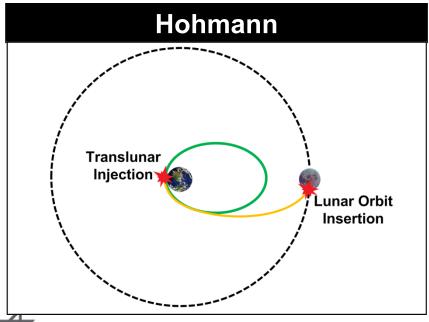
Concept

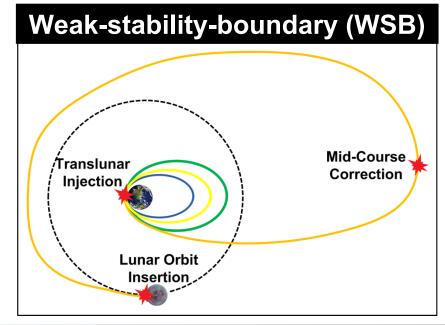


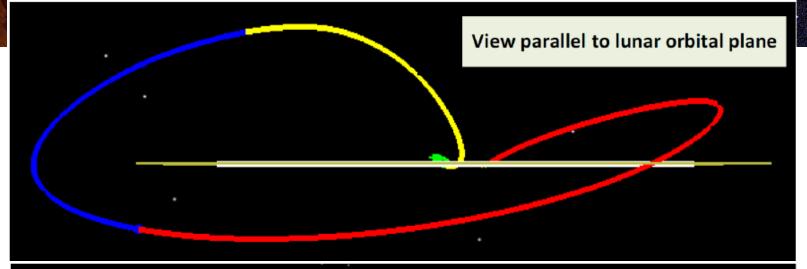


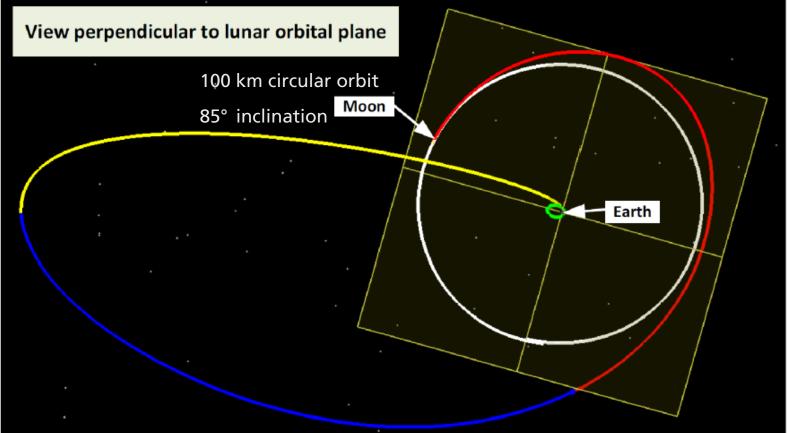
Transfer to the Moon

Transfer trajectory options		
	Hohmann	WSB
ΔV (for worst-case launch date)	~2200 m/s	~1600 m/s
Duration	~5 days	80 to 120 days
Largest distance from Earth	0.4 million km	1.5 million km











Instruments

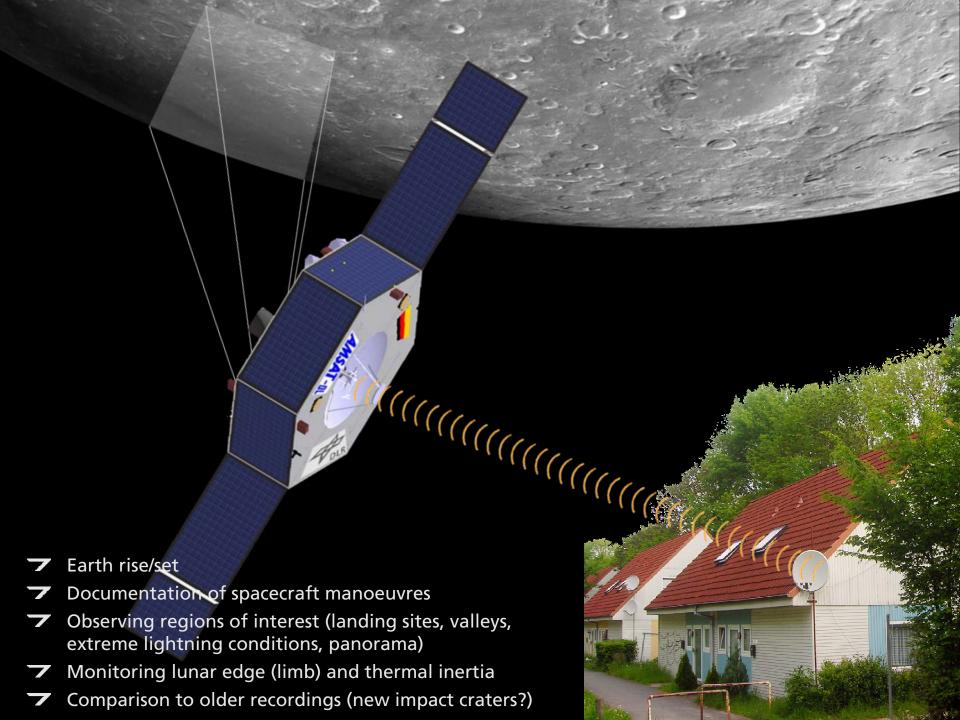
- Criteria for instrument selection:
 - **→** Unique feature
 - Scientific value
 - **→** Cost
 - National interest
 - → (public visibility, technology readiness, demand on mass/power/volume)
- → No outperforming of Kaguya/Chandrayaan/LRO

→ 4 instruments: Video Imager System, MORTIS, SPOSH, ATON

Instruments – Video Imager System

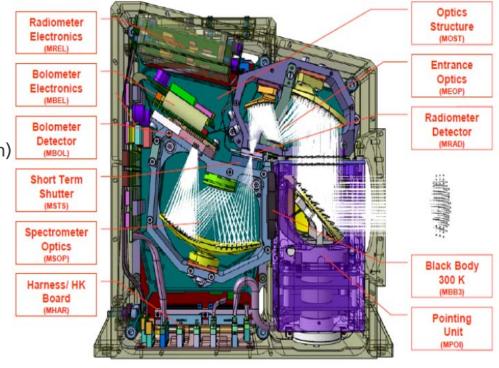
- → Video Imager System:
 - **→** HDTV video system
 - RGB CMOS APS detector
 - **7** 3 camera heads with fix focal distance
 - **▼** Slewable in 2 axis
 - **→** Based on LEVIS/LEO
 - **→** Designed by IDA TU Braunschweig
- → Combined with high gain antenna
- → allows direct TV from Moon on Earth





Instruments – MORTIS

- MORTIS (MOon Radiometer and Thermal infrared Imaging Spectrometer):
 - **y** Spectrometer (7-14 μm)
 - **→** Thermal radiometer (7-14 μm)
 - **→** Push broom imager principle
 - Monitoring of lunar surface and 3 calibration targets
 - ▼ Based on MERTIS (Bepi Colombo)/SERTIS (LEO)



Instruments – MORTIS

→ Goals of MORTIS:

- **▼** Identification of rock forming siliceous minerals
- **▼** Investigation of the lunar surface composition
- ▼ Mapping of lunar surface mineralogy
- **▼** Evolution of lunar volcanism and magma composition
- **→** Measurement of surface temperatures
- **→** Mapping of thermal inertia
- **▼** Modelling of thermo physical properties of regolith



Instruments – SPOSH-VIS

- **→** SPOSH (Smart Panoramic Optical Sensor Head):
 - **→** Wide angle camera (120° x 120° FOV)
 - Autonomous data processing on board
 - **▼** Based on SPOSH study for LEO (DLR-PF/TUB/DJO)
 - **▼** 4 bread boards in routinely operation on Earth

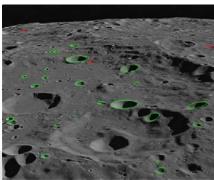


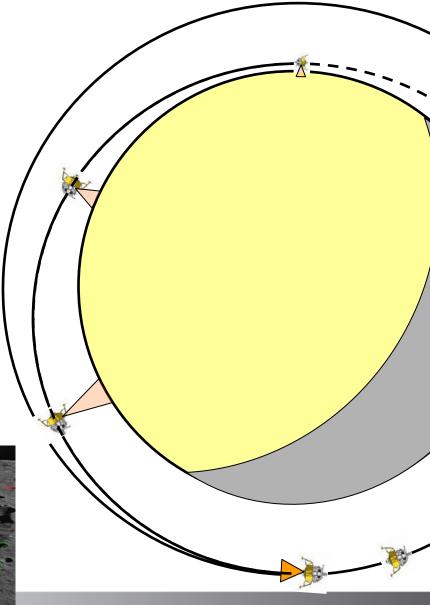
→ Goals of SPOSH:

- Monitoring of impact flashes on lunar night side caused by meteoroid impact events
- Impact rate per time unit and area
- Magnitudes distribution of detected flashes
- Daytime and seasonable variation and showers
- Interpretation of data concerning orbital parameters of meteoroids
- **▼** Verification of scaling law
- **7** Detection of dust in exosphere at Moon limb by forward dispersion

Instruments – ATON

- ATON (Autonomous Terrain based Optical Navigation):
 - Sensor for autonomous navigation in lunar orbit and during landing (in this case impacting)
 - → Precise determination of position during parking orbit and descent orbit (Hohmann from 100 10 km)
 - Principle: detection and identification of craters
 - → Developed by DLR-RY





Instruments – ATON

- **→** Goals of ATON:
 - **T** Technology demonstration →qualification to TRL 7
 - → Autonomous determination of the position of the DLR-AMSAT P5 Moon satellite
 in orbit in order a few 100 m
 - Preparation for exploration missions to Mars, asteroids, other moons



Conclusion

- Non-industrial Moon satellite concept that could be launched as piggyback load on Ariane 5 into GTO
- → Due to the fact, that the satellite would be built by space enthusiasts the mission costs would remain low (comparable to an Earth satellite mission)
- → Otherwise the scientific and public output would be high using that satellite bus for the promising instrument ensemble contributed by DLR

→ DLR-AMSAT P5 Moon satellite is a feasible option for a German Moon mission

